

Vehicle Telematics

Description: Drivers, fleet owners, transport operations, insurance companies are stakeholders of vehicle monitoring applications which need to have analytical reporting on the mobility patterns of their vehicles, as well as real-time views in order to support quick and efficient decisions towards eco-friendly moves, cost-effective maintenance of vehicles, improved navigation, safety and adaptive risk management.

Vehicle sensors do continuously provide data, while on-the-move, they are processed in order to provide valuable information to stakeholders. Applications identify speed violations, abnormal driver behaviors, and/or other extraordinary vehicle conditions, produce statistics per driver/vehicle/fleet/trip, correlate events with map positions and route, assist navigation, monitor fuel consumptions, and perform many other reporting and alerting functions.

In this project we consider that each vehicle reports a position event every 30 seconds with the following format: *Time, VID, Spd, XWay, Lane, Dir, Seg, Pos*

Being *Time* a timestamp (integer) in seconds identifying the time at which the position event was emitted,

VID is an integer that identifies the vehicle,

Spd (0 - 100) is an integer that represents the speed mph (miles per hour) of the vehicle,

XWay (0 . . .L-1) identifies the highway from which the position report is emitted

Lane (0...4) identifies the lane of the highway from which the position report is emitted (0 if it is an entrance ramp (ENTRY), 1 - 3 if it is a travel lane (TRAVEL) and 4 if it is an exit ramp (EXIT)).

Dir(0...1) indicates the direction (0 for Eastbound and 1 for Westbound) the vehicle is traveling.

Seg (0 . . . 99) identifies the segment from which the position report is emitted

Pos (0...527999) identifies the horizontal position of the vehicle as the number of meters from the westernmost point on the highway (i.e., Pos = x)

The goal of this project is to **develop a Java program using Flink implementing the following functionality:**

- Speed Radar: detects cars that overcome the speed limit of 90 mph
- Average Speed Control: detects cars with an average speed higher than 60 mph between segments 52 and 56 (both included) in both directions. If a car sends several reports on segments 52 or 56, the ones taken for the average speed are the ones that cover a longer distance.
- **Accident Reporter:** detects stopped vehicles on any segment. A vehicle is stopped when it reports at least 4 consecutive events from the same position.

Notes:

- All metrics must take into account the direction field.
- A given vehicle could report more than 1 event in the same segment.
- Event time must be used for timestamping.
- Cars that do not complete the segment (52-56) are not taken into account by the average speed control. For example 52->54 or 55->56.
- A car can be stopped on the same position for more than 4 consecutive events.
 An accident report must be sent for each group of 4 events. For example, the next figure shows
 8 events for the car with identifier VID=3:

```
870,3,0,0,1,0,26,139158

900,3,0,0,1,0,26,139158

930,3,0,0,1,0,26,139158

960,3,0,0,1,0,26,139158

990,3,0,0,1,0,26,139158

1020,3,0,0,1,0,26,139158

1050,3,0,0,1,0,26,139158

1080,3,0,0,1,0,26,139158
```

The accident reporter should generate 5 accident alerts. (870->960, 900->990, 930->1020, 960->1050, 990->1080).

<u>Input:</u> The Java program will read the events from a CSV with the format: *Time, VID, Spd, XWay, Lane, Dir, Seq, Pos*

An example file is available at lsd11.ls.fi.upm.es/traffic-3xways-new.7z

Output to be generated:

The program must generate 3 output CSV files.

• speedfines.csv: stores the output of the *speed radar*

- o format: Time, VID, XWay, Seg, Dir, Spd
- avgspeedfines.csv: stores the output of the average speed control
 - o format: Time1, Time2, VID, XWay, Dir, AvgSpd, where *Time1* is the time of the first event of the segment and *Time2* is the time of the last event of the segment.
- accidents.csv: stores the output of the accident detector.
 - o format: Time1, Time2, VID, XWay, Seg, Dir, Pos, where *Time1* is the time of the first event the car stops and *Time2* is the time of the fourth event the car reports to be stopped.

Requirements:

The application must be developed using the versions of the software: Oracle Java 8, Flink 1.3.2 and deployed using Ubuntu.

The program must be optimized to run on a *Flink* cluster with 10 task manager slots available. **The** parallelism for the write operation to the files must be 1.

The Flink program must be configured with the flink-quickstart-java maven artifact.

The main class of the project must be named **master2018.flink.VehicleTelematics**, your application will be tested using the following procedure from the root folder of your project:

- mvn clean package -Pbuild-jar
- flink run -p 10 -c master2017.flink.VehicleTelematics target/\$YOUR_JAR_FILE
 \$PATH_TO_INPUT_FILE \$PATH_TO_OUTPUT_FOLDER

The input file and the output folder will exist on all nodes of the cluster running the Flink Task Managers.

Submission:

- Deadline: 11th November 2018 at 23:55
- Where: All the required files must be uploaded to Moodle by the deadline. The file must be named ID.rar (ID is the id of the students provided by the instructor). The structure of your delivery will be:
 - o ID.tar.gz
 - flinkProgram
 - pom.xml
 - src/
- **Groups:** The project is implemented by 2 persons from the same master program. Please, send an email to mpatino@fi.upm.es and vvianello@fi.upm.es with subject: "master 2018 flinkProject" with full name of the two students of the group and name of their master program by 24/10/2018. The group id will be assigned replaying to this email.