

# Valuing American Options by Simulation

## ■ Least Square and Machine learning Approaches

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**UNIVERSITY OF WATERLOO**  
FACULTY OF MATHEMATICS

# AMERICAN OPTION

## OVERVIEW

- A general class of continuous-time American option pricing problems can be formulated by specifying a process  $U(t)$ ,  $0 < t < T$ , representing the discounted payoff from exercise at time  $t$ , and a class of admissible stopping times  $\tau_0$  with values in  $[0, T]$ . The problem, then, is to find the optimal expected discounted payoff

$$\sup_{\{\tau \in \tau_0\}} E[U(\tau)]$$

- We focus on American put options. In this case, consider a put with strike price  $K$  on a single underlying asset  $S(t)$ . The risk-neutral dynamics of  $S$  are modeled as geometric Brownian motion  $GBM(r, \sigma^2)$ , with  $r$  a constant risk-free interest rate. Suppose the option expires at  $T$ , its value at time 0 is then

$$\sup_{\{\tau \in \tau_0\}} E[e^{-r\tau} (K - S(\tau))^+]$$



# AMERICAN OPTION

## OVERVIEW

- Traditional ways:
  1. Black-Scholes: Due to the optimal stopping problem, this is technically impossible.
  2. Lattice Tree
  3. Finite difference
  4. Monte Carlo
- Machine Learning methods:
  1. Gaussian Process Regression
  2. Least Square Policy Iteration
  3. Fitted Q-iteration



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# OPTIMAL STOPPING PROBLEM

## OVERVIEW

- Optimal Stopping problem for Stochastic Process  $X_t$

$$V(x) = \sup_{\tau \in \tau_0} E[U(X_\tau) | X_0 = x]$$

- Where  $\tau$  is a set of stopping times of  $X_t$ ,  $V_t$  is called the Value function, and  $G$  is the Reward function.
- American option pricing is an optimal stopping problem.
  - $X_t$  is the stochastic process for underlying security's price
  - $x$  is underlying security's current price
  - $\tau$  is set of exercise times corresponding to various stopping policies
  - $V(\cdot)$  is American option price as function of underlying current price
  - $U(\cdot)$  is the discounted option payoff.



# MARKOV DECISION PROCESSES

## OVERVIEW

American Option Pricing is Optimal Stopping, and hence an MDP , So can be tackled with Dynamic Programming or RL algorithms.

- We formulate Stopping Time problems as Markov Decision Processes
- State is a suitable function of the history of Stochastic Process  $X_t$
- Action is Boolean: Stop or Continue
- Reward always 0, except upon Stopping (when it is  $= G(X_\tau)$ )
- State-transitions governed by Underlying Price Stochastic Process



# INGREDIENTS FOR APPROACHES

LSA

Before showing the pseudo-codes, below are the symbols used:

- $m$  Monte-Carlo paths indexed  $i = 0, 1, \dots, m - 1$
- $n + 1$  time steps indexed  $j = n, n - 1, \dots, 1, 0$
- Infinitesimal risk-free rate at time  $t_j$  denoted  $r_{t_j}$
- Simulation paths of prices of underlying as input 2-dim array  $SP[i, j]$
- At each time step,  $CF[i]$  is PV of current+future cashflow for path  $i$
- $s_{i,j}$  denotes state for  $(i, j) := (\text{time } t_j, \text{price history } SP[i, : (j + 1)])$
- $\text{Payoff}(s_{i,j})$  denotes Option payoff at  $(i, j)$
- $\phi_0(s_{i,j}), \dots, \phi_{r-1}(s_{i,j})$  represents feature functions (of state  $s_{i,j}$ )
- $w_0, \dots, w_{r-1}$  are the regression weights
- Regression function  $f(s_{i,j}) = w \cdot \phi(s_{i,j}) = \sum_{I=0}^{r-1} w_I \cdot \phi_I(s_{i,j})$
- $f(\cdot)$  is estimate of continuation value for in-the-money states



# LONGSTAFF-SCHWARTZ ALGORITHM

ALGORITHMS

```
input  :  $SP[0 : m, 0 : n + 1]$ 
output: option price at  $t = 0$ 

1  $CF[0 : m] \leftarrow [Payoff(s_{i,n}) \text{ for } i \text{ in range}(m)];$ 
2 for  $j \leftarrow n - 1$  to 1 do
3    $CF[0 : m] \leftarrow CF[0 : m] * e^{-r_{t_j}(t_{j+1} - t_j)};$ 
4    $X \leftarrow [\phi(s_{i,j}) \text{ for } i \text{ in range}(m) \text{ if } Payoff(s_{i,j}) > 0];$ 
5    $Y \leftarrow [CF[i] \text{ for } i \text{ in range}(m) \text{ if } Payoff(s_{i,j}) > 0];$ 
6    $w \leftarrow (X^T \cdot X)^{-1} \cdot X^T \cdot Y;$ 
7   for  $i \leftarrow 0$  to  $m - 1$  do
8     if  $Payoff(s_{i,j}) > w \cdot \phi(s_{i,j})$  then
9        $CF[i] \leftarrow Payoff(s_{i,j})$ 
10    end
11  end
12  Return  $e^{-r_{t_0}(t_1 - t_0)} \cdot \text{mean}(CF[0 : M])$ 
13 end
```

Algorithm 1: Least Square Approach





# GAUSSIAN PROCESS REGRESSION

## ALGORITHMS

```
input  :  $SP[0 : m, 0 : n + 1]$ 
output: option price at  $t = 0$ 

1 CF[0 : m]  $\leftarrow$  [Payoff( $s_{i,n}$ ) for  $i$  in range( $m$ )];
2 for  $j \leftarrow n - 1$  to 1 do
3   CF[0 : m]  $\leftarrow$  CF[0 : m] *  $e^{-r_{t_j}(t_{j+1}-t_j)}$ ;
4    $X \leftarrow [\phi(s_{i,j})$  for  $i$  in range( $m$ ) if Payoff( $s_{i,j}) > 0$ ];
5    $Y \leftarrow$  [CF[ $i$ ] for  $i$  in range( $m$ ) if Payoff( $s_{i,j}) > 0$ ];
6    $GPR \leftarrow$  fit( $X, Y$ );
7   for  $i \leftarrow 0$  to  $m - 1$  do
8     if Payoff( $s_{i,j}) > GPR(s_{i,j})$  then
9       CF[ $i$ ]  $\leftarrow$  Payoff( $s_{i,j}$ )
10    end
11  end
12  Return  $e^{-r_{t_0}(t_1 - t_0)} \cdot \text{mean}(CF[0 : M])$ 
13 end
```

Algorithm 2: Kriging Approach



# LEAST SQUARES POLICY ITERATION APPROACH

## ALGORITHMS

```
input :  $SP[0 : m, 0 : n + 1]$ 
output: option price at  $t = 0$ 

Comment:  $s_{i,j}$  is short-hand for state at  $(i, j)$ ;
Comment:  $A$  is an  $r \times r$  matrix,  $b$  and  $w$  are  $r$ -length vectors;
Comment:  $A \leftarrow \phi(s_{i,j}) \cdot (\phi(s_{i,j}) - \gamma \mathbb{I}_{w \cdot \phi(s_{i,j+1}) \geq \text{Payoff}(s_{i,j+1})} * \text{Payoff}(s_{i,j+1}))^T$ ;
Comment:  $b_{i,j} \leftarrow \gamma \mathbb{I}_{w \cdot \phi(s_{i,j+1}) < \text{Payoff}(s_{i,j+1})} * \text{Payoff}(s_{i,j+1}) * \phi(s_{i,j})$ ;

1  $A \leftarrow 0, B \leftarrow 0, w \leftarrow 0$ ;
2 for  $i \leftarrow 0$  to  $m - 1$  do
3   for  $j \leftarrow 0$  to  $n - 1$  do
4      $Q \leftarrow \text{Payoff}(s_{i,j+1})$ ;
5     if  $j < n - 1$  &  $Q \leq w \cdot \phi(s_{i,j+1})$  then
6        $P \leftarrow \phi(s_{i,j+1})$ ;
7     else
8        $P \leftarrow 0$ ;
9     end
10    if  $Q > w \cdot P$  then
11       $R \leftarrow Q$ ;
12    else
13       $R \leftarrow 0$ ;
14    end
15     $A \leftarrow A + \phi(s_{i,j}) \cdot (\phi(s_{i,j}) - e^{-r_{t_j}(t_{j+1}-t_j)} * P)$ ;
16     $B \leftarrow B + e^{-r_{t_j}(t_{j+1}-t_j)} * R * \phi(s_{i,j})$ ;
17  end
18  if  $(i + 1) \% \text{Batch Size} == 0$  then
19     $w \leftarrow A^{-1} \cdot b, A \leftarrow 0, b \leftarrow 0$ 
20  end
21 end
```

Algorithm 3: Least Squares Policy Iteration Approach



# FITTED Q-ITERATION APPROACH

## ALGORITHMS

```
input :  $SP[0 : m, 0 : n + 1]$ 
output: option price at  $t = 0$ 

Comment:  $s_{i,j}$  is short-hand for state at  $(i, j)$ ;
Comment:  $A$  is an  $r \times r$  matrix,  $b$  and  $w$  are  $r$ -length vectors;
Comment:  $A \leftarrow \phi(s_{i,j}) \cdot (\phi(s_{i,j}))^T$ ;
Comment:  $b_{i,j} \leftarrow \gamma \max(\text{Payoff}(s_{i,j+1}), w \cdot \phi(s_{i,j+1})) * \phi(s_{i,j})$ ;

1  $A \leftarrow 0, B \leftarrow 0, w \leftarrow 0$ ;
2 for  $i \leftarrow 0$  to  $m - 1$  do
3   for  $j \leftarrow 0$  to  $n - 1$  do
4      $Q \leftarrow \text{Payoff}(s_{i,j+1})$ ;
5     if  $j < n - 1$  then
6        $P \leftarrow \phi(s_{i,j+1})$ ;
7     else
8        $P \leftarrow 0$ ;
9     end
10     $A \leftarrow A + \phi(s_{i,j}) \cdot (\phi(s_{i,j}))^T$ ;
11     $B \leftarrow B + \max(\text{Payoff}(s_{i,j+1}), w \cdot P) * \phi(s_{i,j})$ 
12  end
13  if  $(i + 1) \% \text{Batch Size} == 0$  then
14     $w \leftarrow A^{-1} \cdot b, A \leftarrow 0, b \leftarrow 0$ 
15  end
16 end
```

Algorithm 4: Fitted Q-Iteration Approach



# NUMERICAL EXAMPLES

- Simple American Put
- Heston Model

In the pricing framework, we will be using Heston 2-dimensional model to depart from Black-Scholes 1-dimensional dynamics and to show the performance the Kriging method on a multidimensional asset. Heston model is a mathematical model which assumes a non-constant volatility of an underlying asset and was first introduced by Heston [6]. Let  $S_t$  be the underlying asset under risk neutral measure with variance  $v_t$  that follows a CIR process:

$$\begin{aligned}d \ln S_t &= \left(r - \frac{1}{2}v_t\right)dt + \sqrt{v_t}dW_{1,t}^Q \\dv_t &= \kappa(\theta - v_t)dt + \sigma\sqrt{v_t}dW_{2,t}^Q \\< dW_{1,t}^Q, dW_{2,t}^Q > &= \rho dt\end{aligned}\tag{1}$$

where  $S_0 \geq 0, v_0 > 0$  are initial value of the asset and its variance and  $W_{1,t}^Q, W_{2,t}^Q$  are standard Wiener process with the following parameters:  $r$ - risk free rate,  $|\rho| < 1$ - correlation of  $W_{1,t}^Q$  and  $W_{2,t}^Q$ ,  $\kappa > 0$ - mean reverting rate of variance,  $\theta > 0$ - long run variance, and  $\sigma > 0$ - volatility of variance.



# SIMPLE AMERICAN PUT

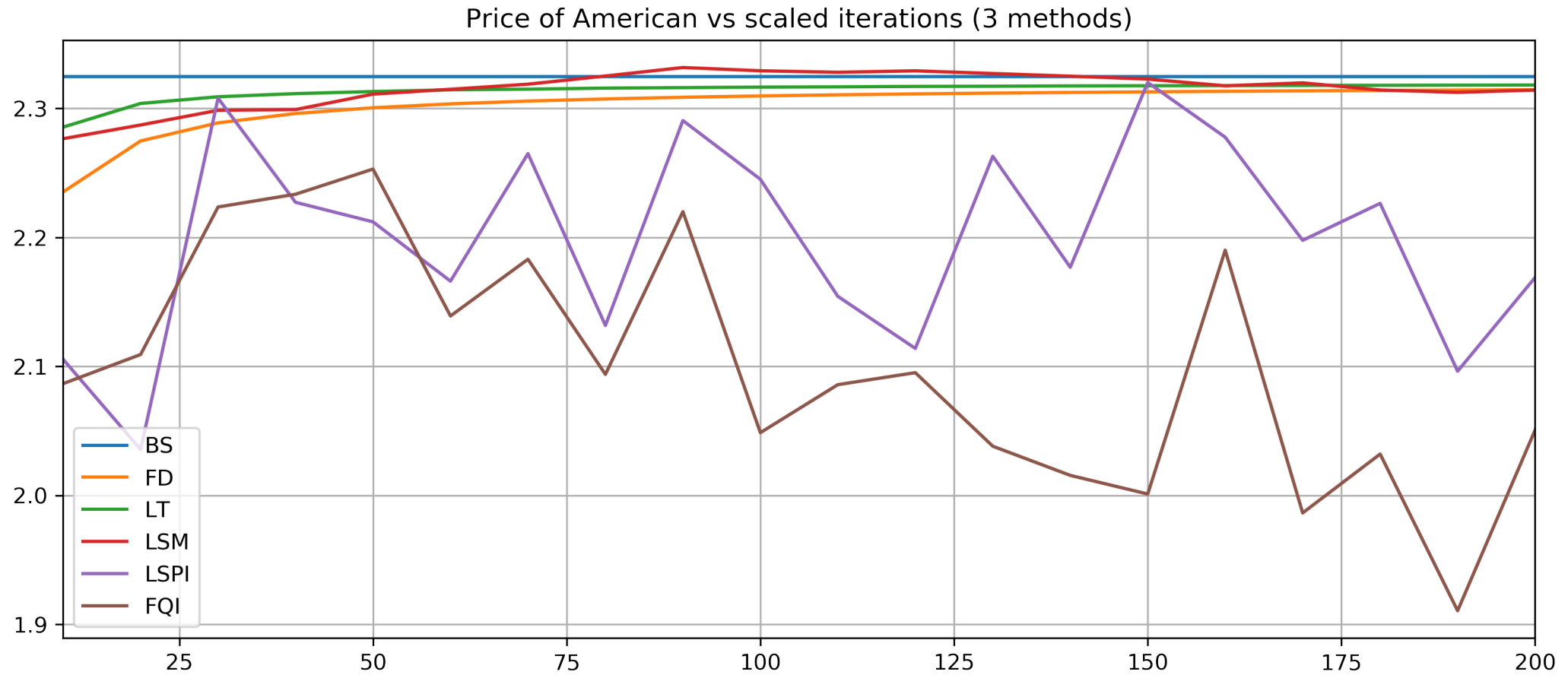
Step 4

S0	sigma	T	BS	LT	FD	LSM	GPR	FQI	LSPI
36	0.2	1	4.4840	4.48 (0.01%)	4.46 (-0.44%)	4.48 (0.02%)	4.38 (-2.38%)	4.38 (-2.37%)	4.37 (-2.53%)
36	0.2	2	4.8501	4.85 (-0.08%)	4.83 (-0.44%)	4.83 (-0.31%)	4.81 (-0.91%)	4.85 (0.01%)	4.79 (-1.15%)
36	0.4	1	7.1098	7.1 (-0.14%)	7.08 (-0.47%)	7.09 (-0.21%)	6.8 (-4.38%)	6.87 (-3.39%)	6.78 (-4.64%)
36	0.4	2	8.5195	8.51 (-0.14%)	8.49 (-0.40%)	8.51 (-0.13%)	8.2 (-3.70%)	7.94 (-6.77%)	8.22 (-3.56%)
38	0.2	1	3.2568	3.25 (-0.12%)	3.24 (-0.64%)	3.25 (-0.24%)	3.14 (-3.47%)	3.17 (-2.78%)	3.01 (-7.46%)
38	0.2	2	3.7540	3.75 (-0.15%)	3.73 (-0.54%)	3.74 (-0.26%)	3.65 (-2.90%)	3.57 (-4.90%)	3.67 (-2.17%)
38	0.4	1	6.1533	6.18 (0.44%)	6.12 (-0.51%)	6.13 (-0.30%)	5.87 (-4.66%)	5.89 (-4.28%)	5.86 (-4.73%)
38	0.4	2	7.6713	7.69 (0.23%)	7.65 (-0.34%)	7.69 (0.20%)	6.91 (-9.88%)	6.89 (-10.13%)	7.41 (-3.35%)
40	0.2	1	2.3245	2.31 (-0.49%)	2.3 (-1.03%)	2.31 (-0.58%)	2.21 (-4.77%)	2.25 (-3.08%)	2.21 (-4.84%)
40	0.2	2	2.8965	2.89 (-0.39%)	2.87 (-0.77%)	2.89 (-0.23%)	2.58 (-10.88%)	2.55 (-11.94%)	2.77 (-4.21%)
40	0.4	1	5.3260	5.3 (-0.44%)	5.29 (-0.74%)	5.32 (-0.21%)	5.1 (-4.32%)	5.08 (-4.68%)	5.1 (-4.30%)
40	0.4	2	6.9351	6.91 (-0.31%)	6.89 (-0.60%)	6.94 (0.04%)	7.05 (1.60%)	6.86 (-1.06%)	7.32 (5.51%)
42	0.2	1	1.6204	1.62 (0.22%)	1.61 (-0.94%)	1.62 (-0.10%)	1.59 (-1.94%)	1.59 (-1.94%)	1.6 (-1.13%)
42	0.2	2	2.2187	2.22 (-0.07%)	2.2 (-0.71%)	2.23 (0.31%)	1.86 (-16.38%)	1.85 (-16.70%)	2.06 (-7.24%)
42	0.4	1	4.5884	4.61 (0.55%)	4.56 (-0.67%)	4.59 (0.10%)	4.43 (-3.38%)	4.41 (-3.91%)	4.43 (-3.36%)
42	0.4	2	6.2464	6.26 (0.29%)	6.22 (-0.42%)	6.27 (0.38%)	5.65 (-9.60%)	5.3 (-15.17%)	5.96 (-4.63%)
44	0.2	1	1.1118	1.12 (0.84%)	1.1 (-1.02%)	1.12 (0.30%)	1.12 (0.65%)	1.13 (1.30%)	1.09 (-1.82%)
44	0.2	2	1.6921	1.7 (0.31%)	1.68 (-0.62%)	1.69 (0.17%)	1.43 (-15.38%)	1.33 (-21.44%)	1.47 (-13.36%)
44	0.4	1	3.9529	3.96 (0.22%)	3.92 (-0.72%)	3.96 (0.17%)	3.87 (-2.12%)	3.86 (-2.29%)	3.87 (-1.98%)
44	0.4	2	5.6511	5.65 (0.01%)	5.62 (-0.62%)	5.67 (0.26%)	4.93 (-12.76%)	4.64 (-17.83%)	5.29 (-6.41%)



# SIMPLE AMERICAN PUT OPTION

Step 4



# Summary

- The non machine learning method is more stable and efficient in time.
- The machine learning method is fair enough but needs a lot of parameter tuning. Takes longer time and may result in fluctuated estimation.
- Machine learning performs better when it is in high-dimensional case, but still, much slower than the mainstream way.
- Future work:
  - Control variate
  - Low discrepancy points.





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THANKS FOR LISTENING