

# Compositional Imprecise Probability

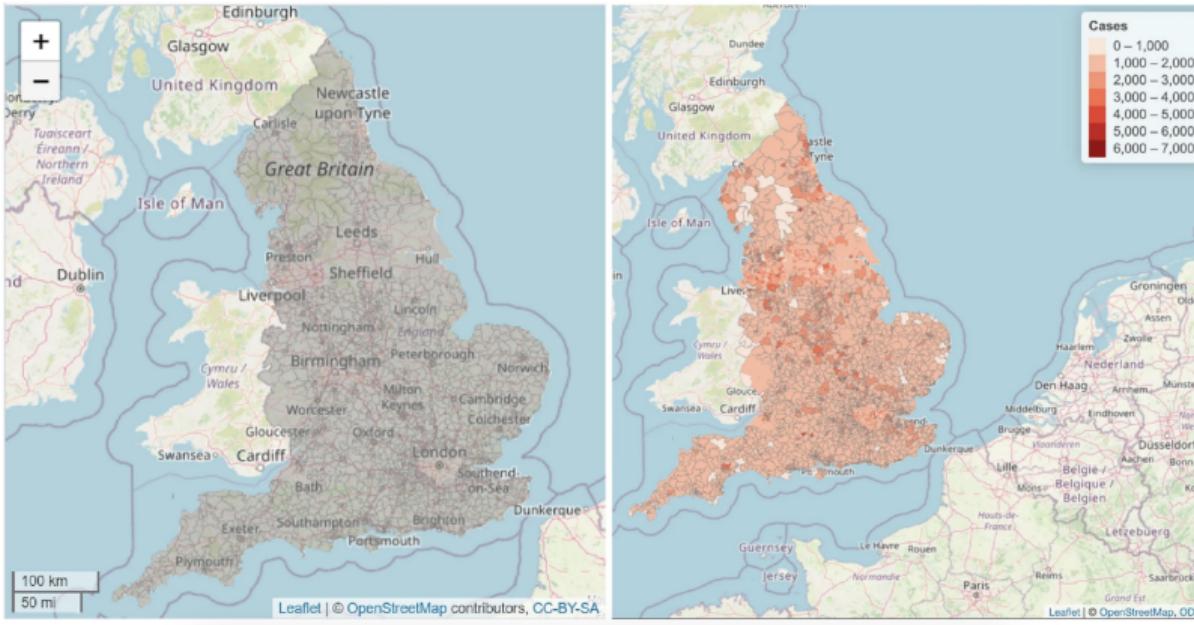
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# Context

- Probabilistic programming for modelling
- Programs model phenomena allowing automatic inference
- Successes in areas like UK covid predictions



# Overview

This work:

- Design a fully compositional probabilistic programming language with Bernoulli and Knightian uncertainty
- Using graded monads and named Knightian choices
- **Theorem 1:** This gives a refined bound on uncertainty
- **Theorem 2:** It is maximal among compositional accounts



# Overview

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Not this work:

- Wider interest in probability with non-determinism [Dash and Staton 2020; Dahlqvist et al. 2018; Keimel et al. 2017; Dash 2024; Kozen et al. 2023; Varacca et al. 2006; Jacobs 2021]
- Our focus is in the setting of imprecise probability

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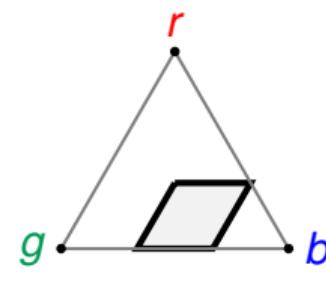
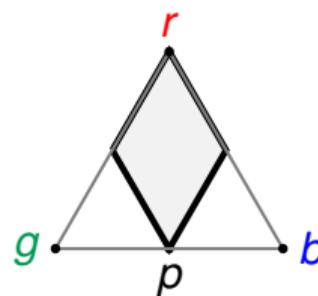
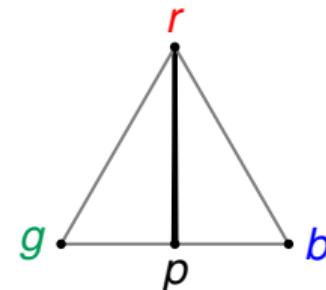
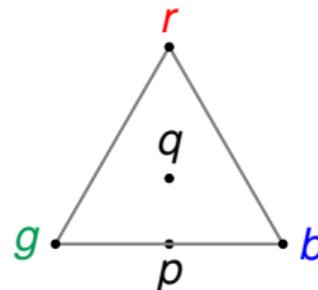
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- ② Desiderata
- ③ The Problem
- ④ The Solution: Named Knightian Choices
- ⑤ Results

# Outline

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# Imprecise Probability

- **Probability** = point in simplex
- **Imprecise probability** = convex set of points



# Applications of Imprecise Probability

Wider applications:

- Statistical robustness [Walley 1991; Huber 1981],
- Economics [Amarante et al. 2007; Battigalli, Cerreia-Vioglio, et al. 2015; Battigalli, Corrao, et al. 2019; Cerreia-Vioglio et al. 2023; Vicig 2008; Pavlidis et al. 2011]
- Engineering [Ferson et al. 2003; Aslett et al. 2022; Vasile 2021; Krpelík et al. 2021]

In machine learning:

- Bayesian learning [Caprio et al. 2024]
- Reinforcement learning [Oren et al. 2024; Zanger et al. 2023]
- Conformal prediction [Stutz et al. 2023; Javanmardi et al. 2024]
- Foundations of safe AI [Dalrymple 2024; Dalrymple et al. 2024]

# A First Language for Imprecise Probability

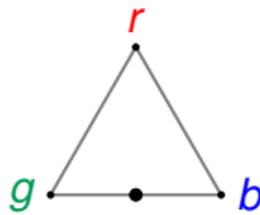
Our prototype language for imprecise probability will have:

- If-then-else statements;
  - if  $b$  then  $t$  else  $u$
- Let bindings;
  - $x \leftarrow t ; u$
- Two commands returning booleans:
  - ***bernoulli***: a fair Bernoulli choice;
  - ***knight***: a Knightian choice.

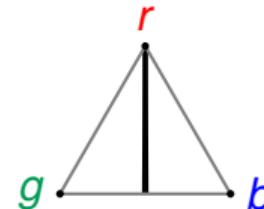


# Examples with the Language

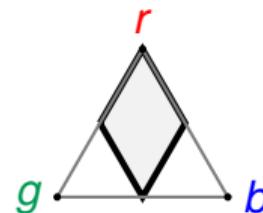
$z \leftarrow \text{bernoulli} ;$   
if  $z$  then  $g$  else  $b$



$x \leftarrow \text{knight} ; z \leftarrow \text{bernoulli} ;$   
if  $z$  then ( if  $x$  then  $r$  else  $g$ )  
else ( if  $x$  then  $r$  else  $b$ )



$x \leftarrow \text{knight} ; y \leftarrow \text{knight} ; z \leftarrow \text{bernoulli} ;$   
if  $z$  then ( if  $x$  then  $r$  else  $g$ )  
else ( if  $y$  then  $r$  else  $b$ )



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# Desiderata of the Language

## Desideratum (1)

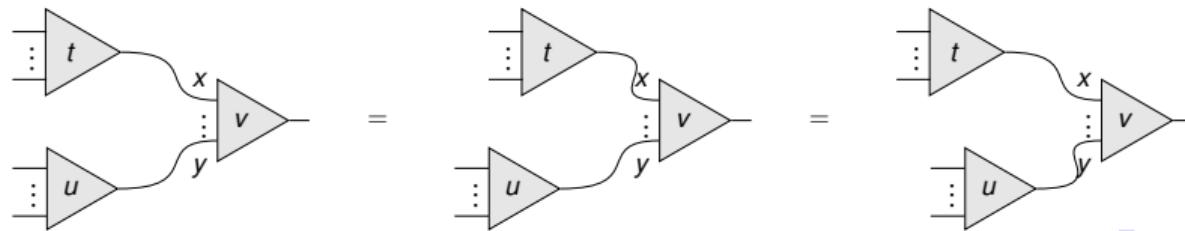
*The language should be commutative:*

$$x \leftarrow t ; y \leftarrow u ; v = y \leftarrow u ; x \leftarrow t ; v$$

for  $x \notin \text{free}(u)$  and  $y \notin \text{free}(t)$ ; and affine:

$$x \leftarrow t ; u = u$$

for  $x \notin \text{free}(u)$ .



# Desiderata of the Language

## Desideratum (2)

*Standard equational reasoning about if-then-else should apply:*

$$\begin{aligned} \text{if } b \text{ then } (x \leftarrow t ; u) \text{ else } (x \leftarrow t ; v) \\ = \\ x \leftarrow t ; \text{ if } b \text{ then } u \text{ else } v \end{aligned}$$

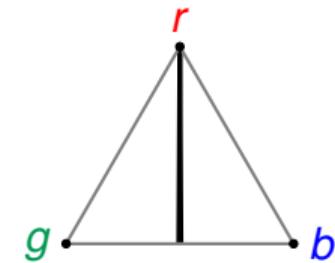
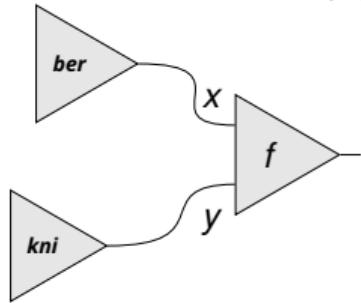
for  $x \notin \text{free}(b)$ .

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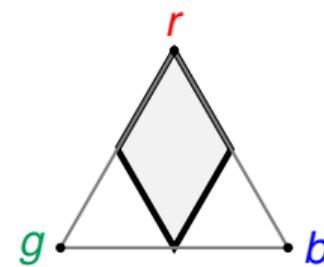
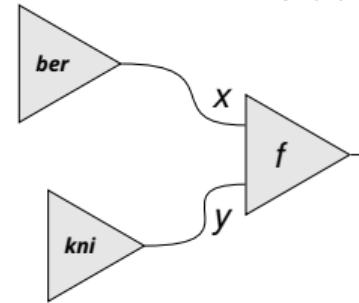
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# The Problem: Convex Powerset doesn't work

**bernoulli** interpreted as  $\left\{ \begin{pmatrix} 0.5 \\ 0.5 \end{pmatrix} \right\}$



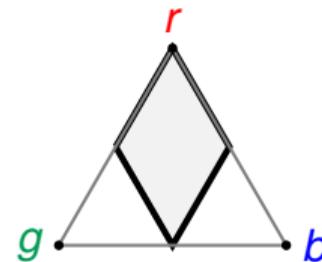
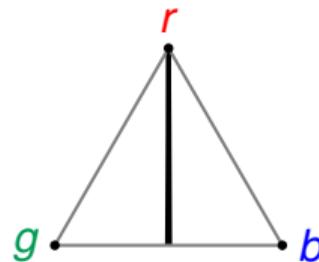
**knight** interpreted as  $\left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$



$$f(x,y) = \text{if } x \text{ then ( if } y \text{ then } r \text{ else } g \text{ )} \\ \text{else ( if } y \text{ then } r \text{ else } b \text{ )}$$

# The Problem: Nothing Works

**Theorem:** Any semantic model that satisfies our desiderata cannot distinguish the following convex sets of distributions.



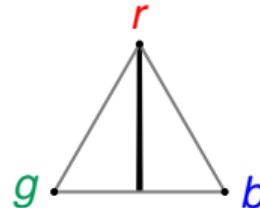
```
z ← bernoulli ;  
if z then ( if x ← knight ; x then r else g )  
else ( if x ← knight ; x then r else b )
```

# Outline

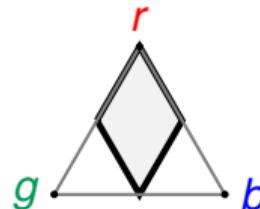
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# The Solution: Named Knightian choices

```
z ← bernoulli ;  
if z then ( if x ← knight(a1) ; x then return r else return g )  
else ( if x ← knight(a1) ; x then return r else return b )
```



```
z ← bernoulli ;  
if z then ( if x ← knight(a1) ; x then return r else return g )  
else ( if x ← knight(a2) ; x then return r else return b )
```



# The Solution: Named Knightian choices

- Reader monad transformer of finite distributions monad

$$T_{2^A}(X) = [2^A \Rightarrow D(X)]$$

- **Bernoulli** choices given by *distributions*
- **Knightian** choices given by *reading*
- We generalise the Knightian choices  $2^A$  to arbitrary sets  $B$

$$T_B(X) = [B \Rightarrow D(X)]$$

- Convex powerset recovered by taking convex hull of the image



# A Graded Monad for Imprecise Probability

## Definition

$T$  is the  $\mathbf{FinStoch}_{\text{Surj}}$ -graded version of:

$$T_A(X) = [A \Rightarrow D(X)]$$

$T$  supports finite probability and finite non-determinism:

- $\mathbf{bernoulli} \in T_{2^\emptyset}(2)$  given by  $\begin{pmatrix} 0.5 \\ 0.5 \end{pmatrix}$
- $\mathbf{knight}(a) \in T_{2^{\{a\}}}(2)$  given by  $\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

Function and monoidal composition use independent non-deterministic branches by the graded multiplication:

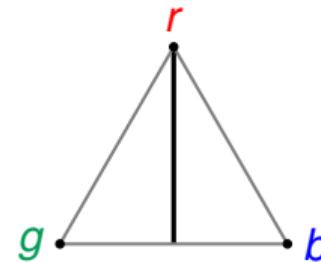
$$\mu_{A,B} : T_A \circ T_B \rightarrow T_{A \times B}$$

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# Theorem 1: Improved Uncertainty Bounds

$$\begin{aligned} \textcolor{red}{r} &: \begin{pmatrix} 1 & 0 \\ 0 & 0.5 \\ 0 & 0.5 \end{pmatrix} \\ \textcolor{green}{g} &: \begin{pmatrix} 0 & 0.5 \\ 0 & 0.5 \end{pmatrix} \\ \textcolor{blue}{b} &: \begin{pmatrix} 0 & 0.5 \\ 0 & 0.5 \end{pmatrix} \end{aligned}$$



- There is a mapping  $T_A(X) \rightarrow \text{CP}(X)$  by taking the convex hull of the image
- This induces an “op-lax functor”:

$$R : [X \Rightarrow T_A(Y)] \rightarrow [X \Rightarrow \text{CP}(Y)]$$

- That is, composition in our framework gives tighter bounds on the *Knightian uncertainty* than composition with CP

$$R(g \circ f) \subseteq R(g) \circ R(f)$$

## Theorem 2: Maximality of the Theory

- The mapping into convex powersets is not injective
- There is "more stuff" in our theory than in convex powersets
- So can we quotient our theory any further?
- Not without:
  - Breaking connection with convex subsets (and imprecise probability); or
  - Compromising the compositional structure

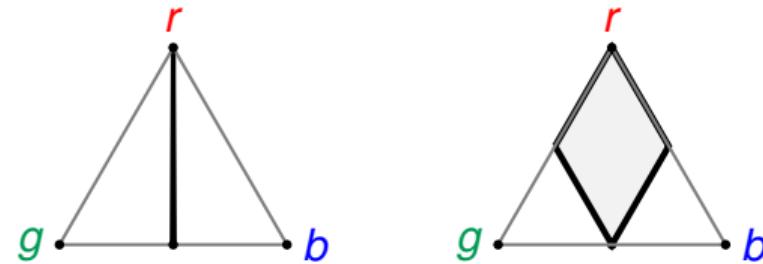
# Conclusion

This work:

- Using graded monads and named Knightian choices we give a fully compositional account of Bernoulli and Knightian uncertainty together
- **Theorem 1:** This gives a refined bound on uncertainty
- **Theorem 2:** It is maximal among compositional accounts

Future work:

- Iteration and infinite dimensional structures
- Function spaces via quasi-Borel spaces
- Implementation and approximation of bounds



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