

Compositional Imprecise Probability

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Computer Science > Programming Languages

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Compositional imprecise probability

Jack Liell-Cock, Sam Staton

Imprecise probability is concerned with uncertainty about which probability distributions to use. It has applications in robust statistics and machine learning. We look at programming language models for imprecise probability. Our desiderata are that we would like our model to support all kinds of composition, categorical and monoidal; in other words, guided by dataflow diagrams. Another equivalent perspective is that we would like a model of synthetic probability in the sense of Markov categories. Imprecise probability can be modelled in various ways, with the leading monad-based approach using convex sets of probability distributions. This model is not fully compositional because the monad involved is not commutative, meaning it does not have a proper monoidal structure. In this work, we provide a new fully compositional account. The key idea is to name the non-deterministic choices. To manage the renamings and disjointness of names, we use graded monads. We show that the resulting compositional model is maximal and relate it with the earlier monadic approach, proving that we obtain tighter bounds on the uncertainty.

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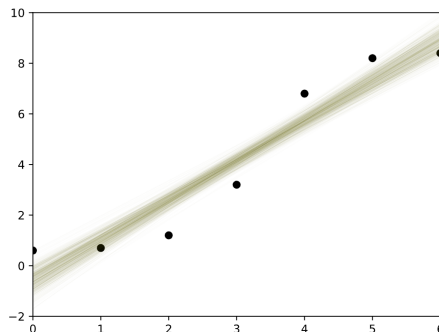


Context

Probabilistic programming: [S. Dash et al. 2023]

- Programming languages designed to encode statistical models
- Commands for sampling from distributions and conditioning

```
regress :: Double -> Prob (a -> Double) -> [(a, Double)] -> Meas (a -> Double)
regress sigma prior dataset =
  do
    f <- sample prior
    forM_ dataset \(x, y) -> score $ normalPdf (f x) sigma y
  return f
```



Overview

This work:

- Design a fully compositional probabilistic programming language with Bernoulli and Knightian uncertainty
- Using a graded perspective and named Knightian choices
- **Theorem 1:** This gives a refined bound on uncertainty
- **Theorem 2:** It is maximal among compositional accounts

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- Design a fully compositional probabilistic programming language with Bernoulli and Knightian uncertainty
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Not this work:

- There is a broader interest in combining non-determinism and probability [Swaraj Dash and Staton 2021; Swaraj Dash and Staton 2020; Dahlqvist et al. 2018; Keimel et al. 2017; Swaraj Dash 2024; Kozen et al. 2023; Varacca et al. 2006; Jacobs 2021]
- Our focus is in the setting of imprecise probability

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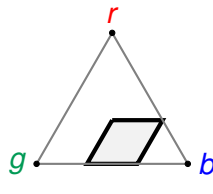
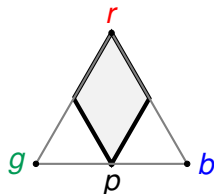
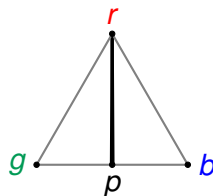
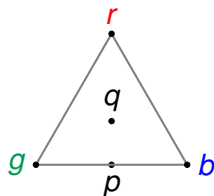
- ① Imprecise Probability
- ② Desiderata
- ③ Monads
- ④ The Problem
- ⑤ The Solution: Named Knightian Choices
- ⑥ Results

Outline

- 1 Imprecise Probability
- 2 Desiderata
- 3 Monads
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Imprecise Probability

- **Probability** = point in simplex
- **Imprecise probability** = convex set of points



Wider applicataions:

- Statistical robustness [Walley 1991; Huber 1981],
- Economics [Amarante et al. 2007; Battigalli, Cerreia-Vioglio, et al. 2015; Battigalli, Corrao, et al. 2019; Cerreia-Vioglio et al. 2023; Vicig 2008; Pavlidis et al. 2011]
- Engineering [Ferson et al. 2003; Aslett et al. 2022; Vasile 2021; Krpelík et al. 2021]

In machine learning:

- Bayesian learning [Caprio et al. 2024]
- Reinforcement learning [Oren et al. 2024; Zanger et al. 2023]
- Conformal prediction [Stutz et al. 2023; Javanmardi et al. 2024]
- Foundations of safe AI [Dalrymple 2024; Dalrymple et al. 2024]

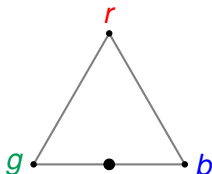
A First Language

Our prototype language for imprecise probability will have:

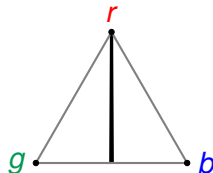
- If-then-else statements;
 - if b then t else u
- Let bindings;
 - $x \leftarrow t ; u$
- Two commands returning booleans:
 - ***bernoulli***: a fair Bernoulli choice;
 - ***knight***: a Knightian choice.

Examples

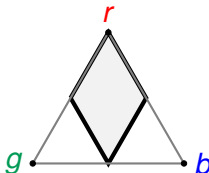
$z \leftarrow \text{bernoulli};$
if z then g else b



$x \leftarrow \text{knight}; z \leftarrow \text{bernoulli};$
if z then (if x then r else g)
else (if x then r else b)



$x \leftarrow \text{knight}; y \leftarrow \text{knight}; z \leftarrow \text{bernoulli};$
if z then (if x then r else g)
else (if y then r else b)



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Desiderata

Desideratum (1)

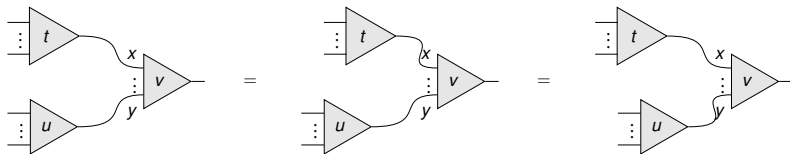
The language should be commutative:

$$x \leftarrow t ; y \leftarrow u ; v = y \leftarrow u ; x \leftarrow t ; v$$

for $x \notin \text{free}(u)$ and $y \notin \text{free}(t)$; and affine:

$$x \leftarrow t ; u = u$$

for $x \notin \text{free}(u)$.



Desideratum (2)

Standard equational reasoning about if/then/else should apply:

$$\text{if } b \text{ then } (x \leftarrow t ; u) \text{ else } (x \leftarrow t ; v)$$
$$=$$
$$x \leftarrow t ; \text{if } b \text{ then } u \text{ else } v$$

for $x \notin \text{free}(b)$.

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Monads

- A *monad* is a mathematical abstraction that captures computational effects in programming languages [Moggi 1989; Moggi 1991]
- Consider programs as functions into computational contexts rather than pure values

$$[X \Rightarrow Y] \quad \rightsquigarrow \quad [X \Rightarrow T(Y)]$$

- Additional structure for composition (satisfying some laws...) is required

$$\begin{aligned} [X \Rightarrow Y] &\rightarrow [X \Rightarrow T(Y)] \\ [X \Rightarrow T(Y)] \times [Y \Rightarrow T(Z)] &\rightarrow [X \Rightarrow T(Z)] \\ [X \Rightarrow T(Y)] \times [X' \Rightarrow T(Y')] &\rightarrow [X \times X' \Rightarrow T(Y \times Y')] \end{aligned}$$

Example: Non-determinism

- Non-determinism is given by the (non-empty) powerset monad
- Rather than a single result, programs can return a set of results

$$\begin{array}{ccc} [X \Rightarrow Y] & \rightsquigarrow & [X \Rightarrow \mathcal{P}(Y)] \\ [x \mapsto y] & \rightsquigarrow & [x \mapsto \{y_1, y_2, y_3\}] \end{array}$$

- Additional structure given by singletons, unions and products

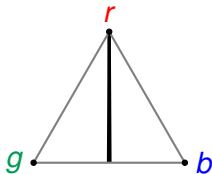
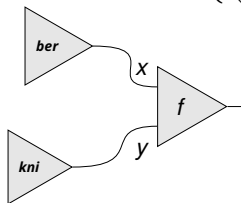
$$\begin{aligned} [x \mapsto y] &\rightarrow [x \mapsto \{y\}] \\ [x_1 \mapsto \{y_1, y_2\}] \times \left[\begin{array}{l} y_1 \mapsto \{z_1, z_2\} \\ y_2 \mapsto \{z_2, z_3\} \end{array} \right] &\rightarrow [x_1 \mapsto \{z_1, z_2, z_3\}] \\ [x \Rightarrow \{y_1\}] \times [x' \mapsto \{y'_1, y'_2\}] &\rightarrow [(x, x') \mapsto \{(y_1, y'_1), (y_1, y'_2)\}] \end{aligned}$$

Outline

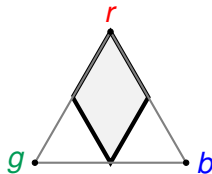
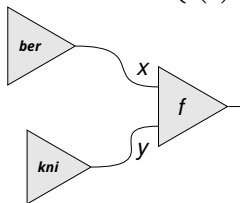
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The Problem: Convex powerset doesn't work

bernoulli interpreted as $\left\{ \begin{pmatrix} 0.5 \\ 0.5 \end{pmatrix} \right\}$



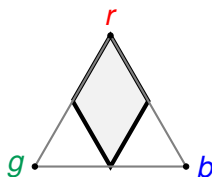
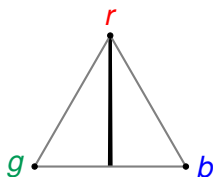
knight interpreted as $\left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$



$$f(x,y) = \text{if } x \text{ then (if } y \text{ then } r \text{ else } g \text{)}$$
$$\text{else (if } y \text{ then } r \text{ else } b \text{)}$$

The Problem

Theorem: Any semantic model that satisfies our desiderata cannot distinguish the following convex sets of distributions.



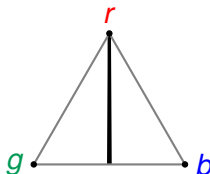
$z \leftarrow \textit{bernoulli}$;
if z then (if $x \leftarrow \textit{knight}$; x then r else g)
else (if $x \leftarrow \textit{knight}$; x then r else b)

Outline

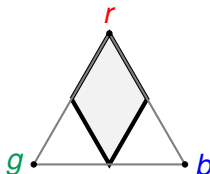
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The Solution: Named Knightian choices

```
z ← bernoulli ;  
if z then ( if x ← knight(a1) ; x then return r else return g )  
else ( if x ← knight(a1) ; x then return r else return b )
```



```
z ← bernoulli ;  
if z then ( if x ← knight(a1) ; x then return r else return g )  
else ( if x ← knight(a2) ; x then return r else return b )
```



The Solution: Named Knightian choices

- Reader monad transformer of finite distributions monad

$$T_{2^A}(X) = [2^A \Rightarrow D(X)]$$

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$$T_{2^A}(X) = [2^A \Rightarrow D(X)]$$

- **Bernoulli** choices given by *distributions*

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- Reader monad transformer of finite distributions monad

$$T_{2^A}(X) = [2^A \Rightarrow D(X)]$$

- **Bernoulli** choices given by *distributions*
- **Knightian** choices given by *reading*

The Solution: Named Knightian choices

- Reader monad transformer of finite distributions monad

$$T_{2^A}(X) = [2^A \Rightarrow D(X)]$$

- **Bernoulli** choices given by *distributions*
- **Knightian** choices given by *reading*
- We generalise the Knightian choices 2^A to arbitrary sets B

$$T_B(X) = [B \Rightarrow D(X)]$$

The Solution: Named Knightian choices

- Reader monad transformer of finite distributions monad

$$T_{2^A}(X) = [2^A \Rightarrow D(X)]$$

- **Bernoulli** choices given by *distributions*
- **Knightian** choices given by *reading*
- We generalise the Knightian choices 2^A to arbitrary sets B

$$T_B(X) = [B \Rightarrow D(X)]$$

- Convex powerset recovered by pushing forward all possible distributions on B

$$\llbracket t \rrbracket_B = \{p \gg_D t \mid p \in D(B)\} \in \text{CP}(X).$$

A graded monad

Definition

T is the **FinStoch**_{Surj}-graded version of:

$$T_A(X) = [A \Rightarrow D(X)]$$

T supports finite probability and finite non-determinism:

- **bernoulli** $\in T_1(2)$ given by $\begin{pmatrix} 0.5 \\ 0.5 \end{pmatrix}$
- **knight** $\in T_2(2)$ given by $\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

Function and monoidal composition use independent non-deterministic branches:

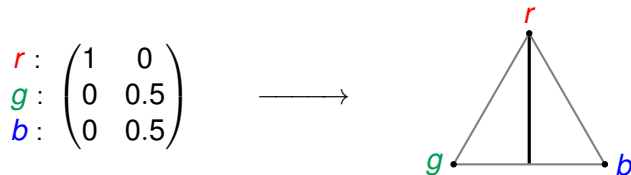
$$\circ_{A,B} : [X \Rightarrow T_A(Y)] \times [Y \Rightarrow T_B(Z)] \rightarrow [X \Rightarrow T_{A \times B}(Z)]$$

$$\otimes_{A,B} : [X \Rightarrow T_A(Y)] \times [X' \Rightarrow T_B(Y')] \rightarrow [X \times X' \Rightarrow T_{A \times B}(Y \times Y')]$$

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Theorem 1: Improved Bounds



- There is a mapping $\llbracket - \rrbracket : T_A(X) \rightarrow \text{CP}(X)$ by taking the convex hull of the image
- This induces an 'op-lax functor':

$$R : [X \Rightarrow T_A(Y)] \rightarrow [X \Rightarrow \text{CP}(Y)]$$

- That is, composition in our framework gives tighter bounds on the *Knightian uncertainty* than composition with CP

$$R(g \circ f) \subseteq R(g) \circ R(f)$$

Theorem 2: Maximality

- The mapping into convex powersets is not injective
- There is “more stuff” in our theory than in convex powersets
- So can we quotient our theory any further?
- Not without:
 - Breaking connection with convex subsets (and imprecise probability); or
 - Compromising the compositional structure

Conclusion

This work:

- Using graded perspective and naming Knightian choices we give a fully compositional account of Bernoulli and Knightian uncertainty together
- **Theorem 1:** This gives a refined bound on uncertainty
- **Theorem 2:** It is maximal among compositional accounts

Future work:

- Iteration and infinite dimensional structures
- Function spaces via quasi-Borel spaces
- Implementation and approximation of bounds

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