

# 预训练模型和训练

GUPAO TECH

秋如此愿景

推动每一次人才升级

我如此使命

让每个人的职业生涯不留遗憾



### 下载ngc

wget "https://ngc.nvidia.com/downloads/ngccli\_cat\_linux.zip -P /home/ljy/cv\_samples\_v1.4.0/ngccli"

unzip -u
"/home/ljy/cv\_samples\_v1.4.0/ngccli/ngccli\_cat\_linux.zip" -d
/home/ljy/cv\_samples\_v1.4.0/ngccli/

把ngc命令加入路径 export PATH=\$PATH:/home/ljy/cv\_samples\_v1.4.0/ngcoli/



### 查询预训练模型

ngc registry model list nvstaging/tao/pretrained\_object\_detection:\* 官方给的查询命令是错的

#### 正确的是:

ngc registry model list nvidia/tao/pretrained\_object\_detection:\*



# 查询预训练模型

(launcher			sktop:~\$	ngc reg	istry mod	del list	nvidia/	tao/preti	rained_o
Versi   on	Accur acy	Epoch s	Batch   Size	GPU   Model	Memor   y Foo   tprin   t	File   Size	Statu s	Creat   ed   Date	
vgg19	77. 56	80   	1	V100	153. 7	153.7 2 MB	UPLOA D_COM PLETE	   Aug   18,   2021	-   
vgg16	77. 17	80	1	V100	113. 2	113.1 6 MB	UPLOA D_COM PLETE	Aug 18, 2021	S英
squee zenet	65. 13	80	1	V100	6.5	6.46 MB	UPLOA D_COM PLETE	Aug   18,   2021	
resne	77. 91	80	1	V100	294.2	294.2 MR	UPLOA D. COM	Aug 18	



### 下载预训练模型

# Pull pretrained model from NGC

官方给的错误:

ngc registry model download-version <a href="nvstaging">nvstaging</a>/tao/pretrained\_object\_e --dest /home/ljy/cv\_samples\_v1.4.0/yolo\_v4\_tiny/pretrainee

#### 正确的如下:

ngc registry model download-version <a href="nvidia/tao/pretrained\_object\_dete">ngc registry model download-version <a href="nvidia/tao/pretrained\_object\_dete">nvidia/tao/pretrained\_object\_dete</a>
--dest /home/ljy/cv\_samples\_v1.4.0/yolo\_v4\_tiny/pretrained



# 修改配置文件

yolo\_v4\_tiny\_train\_kitti.txt文件 改为

```
target_class_mapping {
   key: "car"
   value: "car"
target_class_mapping {
   key: "pedestrian"
   value: "pedestrian"
target_class_mapping {
   key: "cyclist"
   value: "cyclist"
target_class_mapping {
   key: "van"
   value: "car"
target_class_mapping {
   key: "person_sitting"
    value: "pedestrian"
validation_data_sources: {
    tfrecords_path: "/workspace/tao-experiments/data/val/tfrecords/val*"
    image_directory_path: "/workspace/tao-experiments/data/val"
```

```
target_class_mapping {
    key: "pingpang"
    value: "pingpang"
}
```



## 修改配置文件

#### yolo\_v4\_tiny\_train\_kitti.txt文件 改为

```
output_height: 384
     output channel: 3
     randomize_input_shape_period: 10
     mosaic prob: 0.5
71
     mosaic_min_ratio: 0.2
72 }
73 dataset_config {
     data_sources:
           tfrecords path: "/workspace/tao-experiments/data/training/tfrecords/train*"
75
76
           image_directory_path: "/workspace/tao-experiments/data/pingpang.v2i.coco/
     include_difficult_in_training: true
     image_extension: "jpg"
     target_class_mapping {
80
           key: "pingpang"
82
           value: "pingpang"
83
84
     validation_data_sources: {
           tfrecords nath: "/worksnace/tao-experiments/data/val/tfrecords/val*"
85
           image_directory_path: "/workspace/tao-experiments/data/pingpang.v2i.coco/"
86
87
88
```



# 修改配置文件

yolo\_v4\_tiny\_train\_kitti.txt文件 改为: 我3060 12G显存只能1

```
18 training_config {
     visualizer {
20
           enabled: False
           num_images: 3
22
     batch size per gpu 1
     num_epochs: 80
     enable gat: true
     checkpoint_interval: 10
     learning_rate {
        soft_start_cosine_annealing_schedule {
           min_learning_rate: 1e-7
           max_learning_rate: 1e-4
           soft start: 0.3
     regularizer
        type: L1
        weight: 3e-5
     optimizer
        adam {
           epsilon: 1e-7
           beta1: 0.9
           beta2: 0.999
           amsgrad: false
     pretrain_model_path: "/workspace/tao-
   experiments/yolo_v4_tiny/pretrained_cspdarknet_tiny/pretrained_object_detection_vcspdar
48 eval_config {
     average_precision_mode: SAMPLE
     batch_size 1
     matching_iou_threshold: 0.5
52 }
   nms_config {
     confidence_threshold: 0.001
     clustering_iou_threshold: 0.5
```



#### TAO 训练模型

```
!mkdir -p $LOCAL_EXPERIMENT_DIR/experiment_dir_unpruned
```

```
tao yolo_v4_tiny train -e $SPECS_DIR/yolo_v4_tiny_train_kitti.txt \
-r $USER_EXPERIMENT_DIR/experiment_dir_unpruned \
-k $KEY \
```

--gpus 1



# 训练过程 模型信息

```
In [14]: print ("To run with multigpu, please change --gpus based on the number of available GPUs in your machine.")
          !tao yolo_v4_tiny train -e $SPECS_DIR/yolo_v4_tiny_train_kitti.txt \
                             -r $USER_EXPERIMENT_DIR/experiment_dir_unpruned \
                             -k $KEY \
                              --gpus 1
          rror: could not get source code
          /usr/local/lib/python3.6/dist-packages/keras/engine/saving.py:292: UserWarning: No training configuration found in save fil
          e: the model was *not* compiled. Compile it manually.
            warnings.warn('No training configuration found in save file: '
          INFO: Log file already exists at /workspace/tao-experiments/yolo_v4_tiny/experiment_dir_unpruned/status.json
          Layer (type)
                                           Output Shape
                                                                            Connected to
          Input (InputLayer)
                                           (None, 3, None, None 0
                                                                            Input [0] [0]
          Input_qdq (QDQ)
                                           (None, 3, None, None 1
                                                                            Input_qdq[0][0]
          conv_0 (QuantizedConv2D)
                                           (None, 32, None, Non 864
                                                                            conv_0[0][0]
          conv 0 bn (BatchNormalization)
                                           (None, 32, None, Non 128
                                           (None, 32, None, Non 0
                                                                            conv_0_bn[0][0]
          conv_0_mish (ReLU)
                                                                            conv_0_mish[0][0]
          conv_0_mish_qdq (QDQ)
                                           (None, 32, None, Non 1
```



# 谢谢观赏

GUPAO TECH

● 替换小标题文字,或简要说明

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