# 训练出自己目标识别模型

产生自己的数据集训练出自己的模型

## 目录

• 产生自己的数据集

• 下载预训练模型

• 训练模型

# docker 运行显示usb摄像头 (注意是video1)

- docker中显示图形化程序
- --network host -e DISPLAY=\$DISPLAY -v /tmp/.X11-unix/:/tmp/.X11-unix -v /etc/enctune.conf:/etc/enctune.conf
- 实例:
- 先运行
- xhost +
- 在运行
- docker run -it --rm --runtime nvidia -v ~/jetson-inference/data/:/jetson-inference/data/ -v /dev/video1:/dev/video1 --device /dev/video1 --network host -e DISPLAY=\$DISPLAY -v /tmp/.X11-unix/:/tmp/.X11-unix -v /etc/enctune.conf:/etc/enctune.conf 7a7d343029a2 /bin/bash

### 验证摄像头

- import cv2
- cap=cv2.VideoCapture(1)
- while True:
- success,img=cap.read()
- cv2.imshow("Video",img)
- if cv2.waitKey(1)&0xFF==ord('q'):
- break

#### docker 运行显示csi摄像头 (注意是video0)

- docker中显示图形化程序
- --network host -e DISPLAY=\$DISPLAY -v /tmp/.X11-unix/:/tmp/.X11-unix -v /etc/enctune.conf:/etc/enctune.conf
- 实例:
- 先运行
- xhost +
- 在运行
- docker run -it --rm --runtime nvidia -v ~/jetson-inference/data/:/jetson-inference/data/ -v /tmp/argus\_socket:/tmp/argus\_socket -v /dev/video0:/dev/video0 --device /dev/video0 --network host -e DISPLAY=\$DISPLAY -v /tmp/.X11-unix/:/tmp/.X11-unix -v /etc/enctune.conf:/etc/enctune.conf 7a7d343029a2 /bin/bash

#### 训练数据集目录说明

- 我们训练数据集例如为乒乓球: pingpang
- 本地路径 ~/detection/data/pingpang
- 训练数据存放目录
- /jetson-inference/python/training/detection/ssd/data/pingpang
- 本地路径 ~/detection/models/pingpang
- 模型存放路径
- /jetson-inference/python/training/detection/ssd/models/pingpang

# 产生训练数据

• camera-capture

- usb摄像头
- camera-capture
  - --camera=/dev/video1



### 下载预训练模型

- cd ~/detection/models
- wget https://nvidia.box.com/shared/static/djf5w54rjvpqocsiztzaandq1m3a vr7c.pth -O models/mobilenet-v1-ssd-mp-0\_675.pth

### 新命令启动容器

• docker run -it --rm --runtime nvidia -v ~/jetsoninference/data/:/jetson-inference/data/-v /tmp/argus socket:/tmp/argus socket -v /dev/video0:/dev/video0 -device /dev/video0 --network host -e DISPLAY=\$DISPLAY -v /tmp/.X11-unix/:/tmp/.X11-unix -v /etc/enctune.conf:/etc/enctune.conf -v ~/detection/data:/jetsoninference/python/training/detection/ssd/data -v ~/detection/models:/jetsoninference/python/training/detection/ssd/models 7a7d343029a2 /bin/bash

# 训练数据采集程序camera-capture

- --input-flip=horizontal
- --input-flip=vertical
- camera-capture --help

# 训练非常耗内存【在宿主机上执行】

- 增加内存交换分区 防止训练时内存溢出
- 增加交换内存 Mounting Swap
- sudo systemctl disable nvzramconfig
- sudo fallocate -l 4G /mnt/4GB.swap
- sudo mkswap /mnt/4GB.swap
- sudo swapon /mnt/4GB.swap
- /etc/fstab 最后一行增加
- /mnt/4GB.swap none swap sw 0 0
- 运行 swapon -s 验证效果

# 训练非常耗内存【在宿主机上执行】

• 把图形化界面关闭了, 训练完后在可以恢复

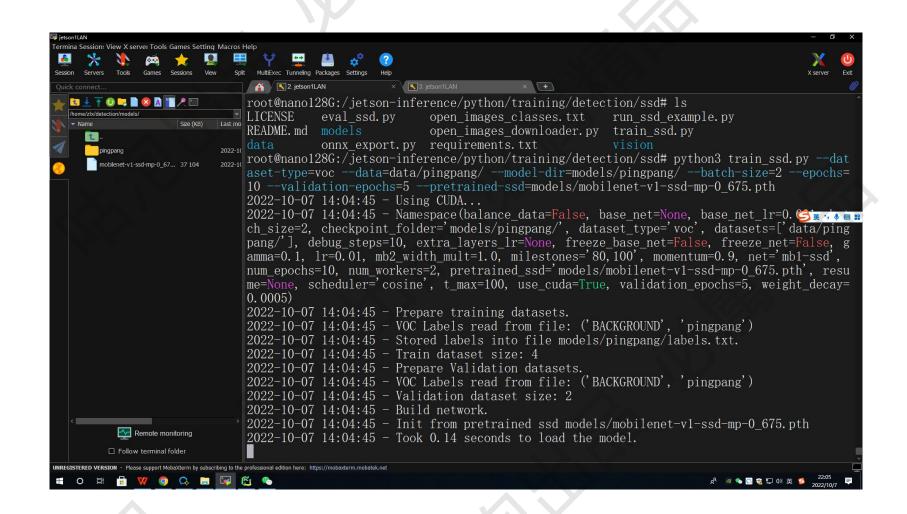
sudo init 3 # stop the desktop

sudo init 5 # restart the desktop

### 训练命令

• python3 train\_ssd.py --dataset-type=voc --data=data/pingpang/ -- model-dir=models/pingpang/ --batch-size=1 --epochs=30 --validation-epochs=5 --pretrained-ssd=models/mobilenet-v1-ssd-mp-0\_675.pth

### 训练开始



### 训练可能会显存不足

```
File "/usr/local/lib/python3.6/dist-packages/torch/utils/data/dataloader.py", line 359,
 in iter
   return self. get iterator()
 File "/usr/local/lib/python3.6/dist-packages/torch/utils/data/dataloader.py", line 305,
 in get iterator
   return MultiProcessingDataLoaderIter(self)
 File "/usr/local/lib/python3.6/dist-packages/torch/utils/data/dataloader.py", line 918,
 in init
   w. start()
                                                                                 三英,∮⊞
 File "/usr/lib/python3.6/multiprocessing/process.py", line 105, in start
   self. popen = self. Popen(self)
 File "/usr/lib/python3.6/multiprocessing/context.py", line 223, in Popen
   return _default_context.get_context().Process._Popen(process_obj)
 File "/usr/lib/python3.6/multiprocessing/context.py", line 277, in Popen
   return Popen (process obj)
 File "/usr/lib/python3.6/multiprocessing/popen fork.py", line 19, in init
   self. launch (process obj)
 File "/usr/lib/python3.6/multiprocessing/popen fork.py", line 66, in launch
   self.pid = os.fork()
OSError: [Errno 12] Cannot allocate memory
root@nano128G:/jetson-inference/python/training/detection/ssd#
root@nano128G:/jetson-inference/python/training/detection/ssd#
root@nano128G:/jetson-inference/python/training/detection/ssd# sudo systemctl disable nvz
ramconfig
bash: sudo: command not found
root@nano128G:/jetson-inference/python/training/detection/ssd#
```

### 训练成功

```
2022-10-07 14:22:48 - Start training from epoch 0.
/usr/local/lib/python3.6/dist-packages/torch/optim/lr scheduler.py:134: UserWarning: Dete
cted call of `lr scheduler.step()` before `optimizer.step()`. In PyTorch 1.1.0 and later,
 you should call them in the opposite order: optimizer.step() before Ir scheduler.step
 (). Failure to do this will result in PyTorch skipping the first value of the learning
rate schedule. See more details at https://pytorch.org/docs/stable/optim.html#how-to-adju
st-learning-rate
  "https://pytorch.org/docs/stable/optim.html#how-to-adjust-learning-rate", UserWarning)
/usr/local/lib/python3.6/dist-packages/torch/nn/ reduction.py:42: UserWarning: si
ge and reduce args will be deprecated, please use reduction='sum' instead.
 warnings. warn (warning. format (ret))
2022-10-07 14:23:35 - Epoch: 0, Validation Loss: 12.1162, Validation Regression Loss 6.43
85. Validation Classification Loss: 5.6777
2022-10-07 14:23:36 - Saved model models/pingpang/mb1-ssd-Epoch-0-Loss-12.11621642112732.
pth
2022-10-07 14:23:46 - Epoch: 5, Validation Loss: 53.8248, Validation Regression Loss 40.6
696, Validation Classification Loss: 13.1552
2022-10-07 14:23:47 - Saved model models/pingpang/mb1-ssd-Epoch-5-Loss-53.824838638305664
.pth
2022-10-07 14:24:05 - Epoch: 9, Validation Loss: 18.0107, Validation Regression Loss 8.05
96, Validation Classification Loss: 9.9511
2022-10-07 14:24:05 - Saved model models/pingpang/mb1-ssd-Epoch-9-Loss-18.010716438293457
.pth
2022-10-07 14:24:05 - Task done, exiting program.
root@nano128G:/jetson-inference/python/training/detection/ssd#
root@nano128G:/jetson-inference/python/training/detection/ssd#
```

### 看一下训练出来的文件

• 大坑: 关注 models 下面的labels.txt 和我们数据那边的 labels.txt 是不同的 多了一个 BACKGROUND

### jtop 性能查看工具

- 安装pip3
- sudo apt install python3-pip
- 安装
- sudo -H pip3 install -U jetson-stats
- ·运行jtop服务
- sudo systemctl restart jetson\_stats.service

### 导出模型 为 onnx

- --input
- --output
- --labels
- --batch-size=1

 python3 onnx\_export.py --input models/pingpang/mb1-ssd-Epoch-29-Loss-6.877338358334133.pth --output models/pingpang/pingpang.onnx -labels=models/pingpang/labels.txt --batch-size=1

### 使用模型

 detectnet --model=models/pingpang/pingpang.onnx -labels=models/pingpang/labels.txt --input-blob=input\_0 --output-cvg=scores --output-bbox=boxes data/IMG\_20220920\_181652.jpg data/out.jpg

#### 总结

- 用 camera-capture 产生测试数据
- train\_ssd.py 训练出 xxx.pth 的模型 (pytorch的模型)
- onnx\_export.py 把 xxx.pth 模型转换为 xxx.onnx 模型
- •运行 detectnet 把 xxx.onnx 模型 转换为 xxx.engine 文件