

TABLE 1. DELIVERABLES

Del. no.	Deliverable name	WP no.	Nature	Delivery date from Annex I (proj month)	Actual / Forecast delivery date	Planned effort (from Annex I)	Comments
D1.1	Enhanced iCub simulator for whole-body contact simulation.	1	SW	M12	M12	21	
D2.1	Review of human postural control and whole body motion in contact.	2	R	M12	M12	10	
D5.1	Validation scenario 1: balancing on multiple rigid contact points.	5	R	M12	M12	13	
D6.1	Website and repository online.	6	O	M3	M3	8.6	
D7.1	Dissemination and exploitation plan.	7	O	M12	M12	5	
D7.2	Standard database with support materials.	7	O	M6	M6	2	