

Del. no.	Deliverable name	WP	Type ¹	Dissemination level ²	Delivery date	Task involved	Responsible	Person Month
D1.3	Software for dealing with compliant contacts.	1	SW	PU	M36	T1.4 T4.1 T1.3 T3.3 T3.4	UB	16
D2.2	Models of human whole body motions in contact with rigid and compliant support surfaces.	2	R	PU	M36	T2.2 T2.3	JSI	66
D3.2	Local solver in compliant-world cases.	3	R	PU	M36	T3.1 T3.2 T3.3	UPMC	26
D4.1	Learning approaches for operational space control with contacts.	4	R	PU	M36	T4.1 T4.2	TUD	50
D5.3	Validation scenario 3: balancing on compliant environmental contacts.	5	R	PU	M36	T5.3	IIT	15

¹ Nature of the deliverable:

R = Report, **P** = Prototype, **D** = Demonstrator, **SW** = Software, **O** = Other

² Dissemination level:

PU = Public

PP = Restricted to other programme participants (including the Commission Services).

RE = Restricted to a group specified by the consortium (including the Commission Services).

CO = Confidential, only for members of the consortium (including the Commission Services).