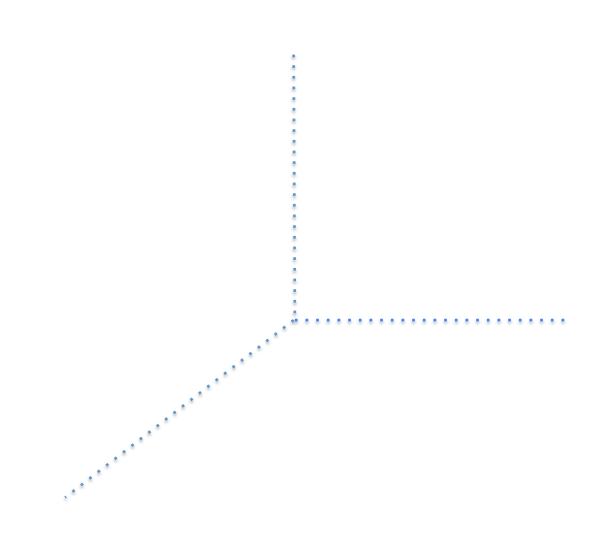
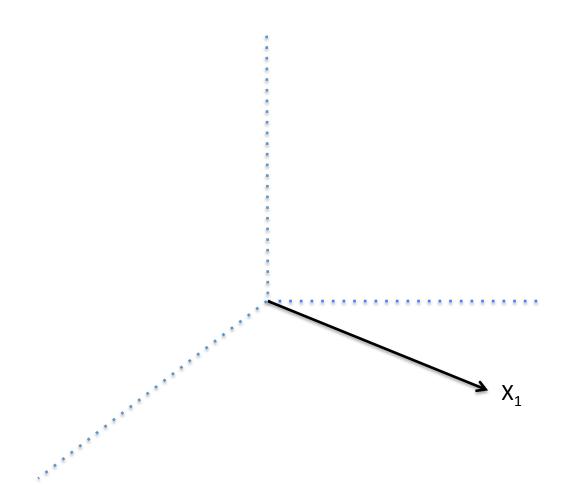
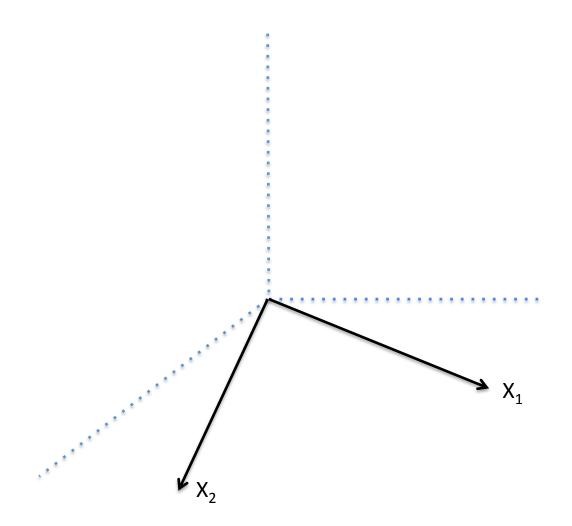
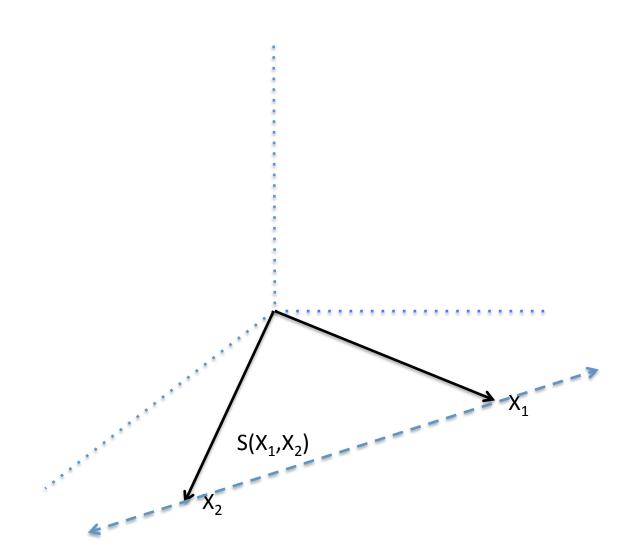
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- Ingredients of a linear regression:
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 - $X = [x_1, ..., x_k]$ regressors
- y and $x_1, ..., x_k$ can be thought of as vectors in N dimensional Euclidean space E^N







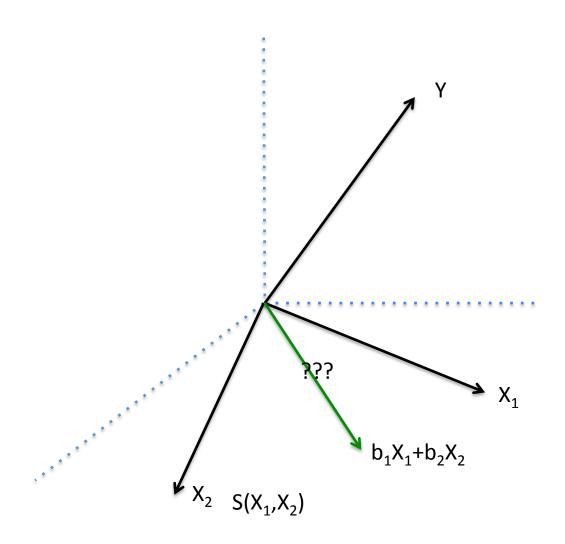
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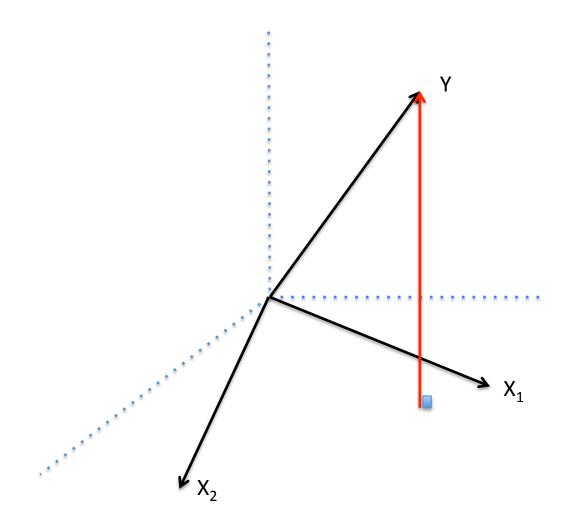
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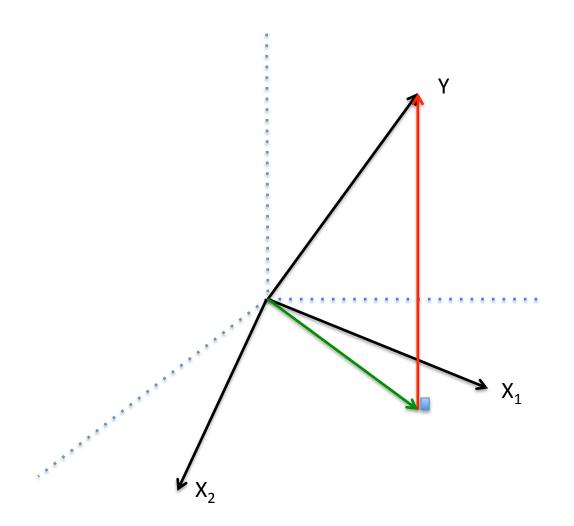
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- dim(S(X)) = rank(X)
- Define $S^o(X)$ as the orthogonal complement of S(X), which is the set of all points w in E^N such that w'z = 0 for $z \in S(X)$.

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- Math Problem: $\min_b (y Xb)'(y Xb)$
- Let \hat{b} be the minimizer. $y X\hat{b} \in S^o(X)$.
- Which is equivalent to $X'(y X\hat{b}) = 0$, first-order conditions of OLS.
- Solving, we get:

$$\hat{b} = (X'X)^{-1}X'y$$

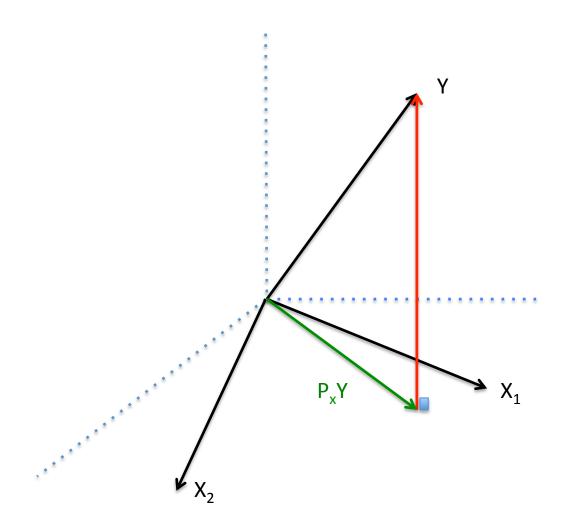
• if X'X is full rank (for N > 3).

• Look at the representation of y in S(X), the "predicted" y

•
$$X\hat{b} = X(X'X)^{-1}X'y = P_Xy$$

$$P_X = X(X'X)^{-1}X'$$

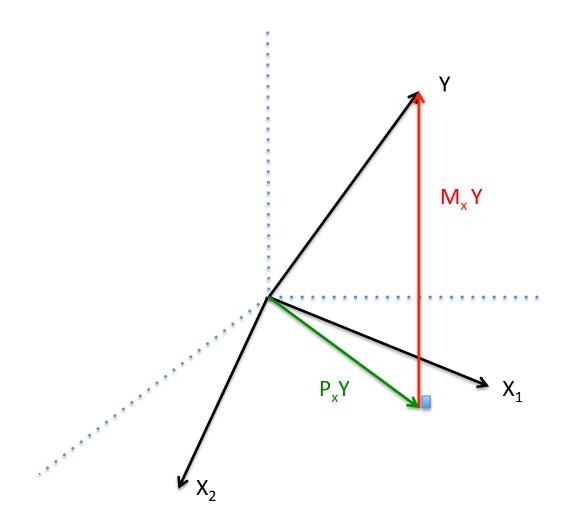
• This is the *projection* matrix that maps y onto S(X).



- Now consider $y X\hat{b}$, the "prediction error"
- $Y X\hat{b} = (I P_X)y$, with

$$M_X = I - P_X = I - X(X'X)^{-1}X'$$

- M_X projects y onto $S^o(X)$
- $y = M_X y + P_X y$, its orthogonal decomposition
- Note: $P_X P_X = P_X$, $M_X M_X = M_X$ (Why?)
- Also: $P_X M_X = 0$ (Why?)



- In the regression context, $P_X y$ is the vector of fitted values from the regression
- $M_X y$ is the vector of regression residuals.
- Residuals are orthogonal to fitted values $(P_X y)'(M_X y) = 0$.

Long vs Short Regressions

• Suppose we run regression 1:

$$y = X_1\beta_1 + X_2\beta_2 + e_1$$

• Then we run regression 2:

$$M_1y=M_1X_2\beta_2+e_2$$

where
$$M_1 = I - X_1(X_1'X_1)^{-1}X_1'$$
.

Frisch-Waugh-Lovell Theorem

- Claim 1: β_2 is numerically the same across the two regressions.
- Proof: Premultiply Reg 1 by $X_2'M_1$.
- This gives $X_2' M_1 y = X_2' M_1 X_2 \beta_2$ (Why?)
- Solve for $\beta_2 = (X_2'M_1X_2)^{-1}(X_2'M_1)y$ which is the formula for β_2 in the second regression

Frisch-Waugh-Lovell Theorem II

- Claim 2: The residuals from Reg 1 and Reg 2 are identical
- Proof: Premultiply Reg 2 by M_1 .
- This gives $M_1y = M_1X_2\beta_2 + M_1M_Xy$
- Which is $M_1y = M_1X_2\beta_2 + M_Xy$ (What is M_1M_X ?)
- i.e. the residual term in Reg 2 is the same as in Reg 2.

Regression on a constant:

- What does it mean to regress on a constant?
- *i* is a column of ones. $P_i y = ?$

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Regression on a constant:

- What does it mean to regress on a constant?
- i is a column of ones. $P_i y = i(i'i)^{-1}i'y = \bar{y}$
- What is $M_i y$?

Applications II

Regression on dummy variables:

- $D_n = 1$ if the n-th patient receives the drug, $D_n = 0$ if not.
- D is column of zeros and ones. $P_D y = ?$

Applications III

• Seasonality/group correction: suppose we run regression 1:

$$y = X\beta + D\gamma + e_1$$

where D is a set of dummies for the various seasons/groups.

- Suppose instead of this, we calculate seasonal/group averages for X and y, and subtract these from y and X. We then run the regression for seasonally corrected variables (regression 2).
- How are the β s different across regressions 1 and 2?

• A formula for individual regression coefficients:

$$\beta_k = (\tilde{X}_k' \tilde{X}_k)^{-1} \tilde{X}_k' Y$$

where $\tilde{X}_k = M_{-k}X_k$ is the residual of the regression of X_k on all other regressors (X_{-k}) .

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• Since \tilde{X}_k is a vector, the formula boils down to (if the set of other regressors includes a constant)

$$\beta_k = \frac{Cov(\tilde{X}_k, Y)}{Var(\tilde{X}_k)}$$

• Omitted variable bias: suppose our true model is

$$Y = \beta_0 + \beta_1 T + \beta_2 X_2 + \beta_3 X_3 + \varepsilon$$

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So

$$Cov(Y, \tilde{T}) = \beta_1 Var(\tilde{T}) + \beta_3 Cov(X_3, \tilde{T})$$

(why?) and

$$\tilde{\beta}_1 = \beta_1 + \beta_3 \delta_{31}$$

where δ_{31} is the coefficient on T when X_3 is regressed on T and X_2 (why?)



- Suppose Y is wages, T is years of schooling and X_3 is (unobserved) ability.
- Which way do we think the coefficient in our schooling regression (without ability) is biased?

OLS when Y and X are random

- Let Y be a random outcome variable, and X be a random vector of regressors.
- Let \hat{Y} , a predictor of Y, be a function of X.
- With $e = Y \hat{Y}$, the prediction error, we want to minimize the expected loss

$$\min_{\hat{y}} E[L((Y-\hat{Y})|X]$$

where L(.) is the loss function.

• If $L(e) = e^2$, then the predictor minimizing the expected loss is

$$\hat{Y}(x) = E[Y|X = x]$$

the conditional expectation function.



OLS and conditional expectation

Ex: (Y, X) jointly normal

$$E(Y|X = x) = \left(\mu_y - \left(\frac{\sigma_{xy}}{\sigma_x^2}\right)\mu_x\right) + \left(\frac{\sigma_{xy}}{\sigma_x^2}\right)x$$
$$= \beta_0 + \beta_1 x$$

- What is the connection with the OLS estimate?
 - In reality, you see N realizations, (y_i, x_i) from (Y, X). You do not know $\mu_Y, \mu_X, \Sigma_{XY}$.
 - However, you can form an *estimate* of E(Y|X=x) by regressing Y on X and a constant
 - In the *jointly normal* case, OLS will give you a consistent estimator of the function E(Y|X=x)

OLS as best linear predictor of E(Y|X)

- More generally, if the conditional expectation function is linear in X, i.e. $E[Y|X=x]=x'\beta$, then $x'\hat{\beta}_{OLS}$ is a consistent estimate of E[Y|X=x].
- If E[Y|X=x] is nonlinear, then OLS no longer represents the conditional expectation.
- Still, OLS is the *best linear predictor* for the conditional expectation function.
- Why? Take:

$$\beta_{CEF} = \arg\min_{b} E[(E(Y|X) - X'b)^{2}]$$

 $\beta_{OLS} = \arg\min_{b} E[(Y - X'b)^{2}]$

• Here, $\beta_{\it CEF}$ is the best linear predictor for E(Y|X) under square loss.



OLS as best linear predictor of E(Y|X)

But:

$$E(Y - X'b)^{2} = E[Y - E(Y|X) + E(Y|X) - X'b]^{2}$$

$$= E[Y - E(Y|X)]^{2} + E[E(Y|X) - X'b]^{2} + 2E[Y - E(Y|X)][E(Y|X) - X'b]$$

$$= const + E[E(Y|X) - X'b]^{2}$$

so β_{CEF} and β_{OLS} are maximizing the same thing (plus a constant)

Review of Asymptotic Theory

- In most econometric analyses, we treat our data as the result of a random sampling process
- For example, survey data is of the form $(y_i, X_i, i = 1, ..., N)$ where the outcome variable and covariates for respondent i is drawn from the joint distribution of (y, X) according to a sampling process
- Given the data, we form *statistics* of the data; i.e. *functions* of $(y_i, X_i, i = 1, ..., N)$.
- Ex 1: $\bar{y}_N = \frac{1}{N} \sum_{i=1}^N y_i$, sample average of the outcome variable
- Ex 2: $\hat{\beta}_{OLS} = (X'X)^{-1}X'y$, the OLS coefficients
- These are both functions of the underlying random variables y and X.

- If we know (or assume) something about the distribution of y
 and X, we can also say something about the distribution of
 such statistics.
- Ex: if y_i are iid $N(0, \sigma^2)$, we know that $\sqrt{N}\bar{y}_N$ has the exact finite sample distribution $N(0, \sigma^2)$.
- Many times, however, statistics are complicated function of underlying random variables.
- This makes it difficult to derive exact *finite sample* distributions of the statistics
- However, under certain conditions, we can approximate the distribution of complicated statistics by using laws of large numbers and central limit theorems from probability theory.
- Ex: if y_i are iid with mean zero and finite variance σ^2 , but not necessarily normal, as N grows large, the distribution of $\sqrt{N}\bar{y}_N$ is well-approximated by $N(0, \sigma^2)$.

Probability Limit

- Let θ_N be a statistic (function) of $(y_i, X_i, i = 1, ..., N)$.
- We are interested in the behavior of the sequence θ_N , as N grows large.
- ullet The first thing we look at is the *probability limit* of $heta_N$
- Definition: A sequence of random variables $\{\theta_N\}$ converges in probability to θ if, for any $\varepsilon>0$ and $\delta>0$, there exists $N^*=N^*(\varepsilon,\delta)$ such that for all $N>N^*$,

$$\Pr(|\theta_{\textit{N}} - \theta| < \varepsilon) > 1 - \delta$$

• If such a limit exists, we write that $\operatorname{plim}_{N\to\infty}\theta_N=\theta$, or $\theta_N\stackrel{\mathrm{P}}{\to}\theta$.



Slutsky Theorem

- A really useful feature of plim's is that they are preserved under continuous transformations.
- Slutsky Theorem: Let θ_N be a finite dimensional vector of random variables and let g() be a real valued function continuous at θ .
- Then: $\operatorname{plim} \theta_{N} = \theta$ implies $\operatorname{plim} g(\theta_{N}) = g(\theta)$
- Ex: $\hat{\beta}_{OLS} = \frac{N^{-1} \sum_{i=1}^{N} x_i y_i}{N^{-1} \sum_{i=1}^{N} x_i^2}$
- If we can calculate the plim's of the numerator and denominator, we can get the plim of the ratio.

Laws of Large Numbers

- Kolmogorov LLN: Let $\{X_i\}$ be iid.
- If and only if $E[X_i] = \mu$ and $E[|X_i|] < \infty$:

plim
$$\frac{1}{N} \sum_{i=1}^{N} X_i = \frac{1}{N} \sum_{i=1}^{N} E[X_i] = \mu.$$

- Markov LLN: Let $\{X_i\}$ be independent, but not necessarily identical, with $E[X_i] = \mu_i$ and $Var(X_i) = \sigma_i^2$.
- If $\sum_{i=1}^{\infty} \frac{\sigma_i^2}{i^2} < \infty$,

$$p\lim\left(\frac{1}{N}\sum_{i=1}^{N}X_{i}-\frac{1}{N}\sum_{i=1}^{N}E[X_{i}]\right)=0$$

• I.e. in the non-identical iid case, variance can grow with *i*, but not too fast.



Convergence in Distribution

- Since *N* is finite in applications, specifying the probability limit of an estimator is not enough.
- We also need the distribution of θ_N . However, this might be difficult to derive exactly in most cases.
- We thus resort to central limit theorems to approximate the distribution of θ_N , as N grows large.
- A sequence of random variables, $\{\theta_N\}$ converges in distribution to a random variable θ , if

$$\lim_{N \to \infty} \Pr(\theta_N < x) = \Pr(\theta < x)$$

for every x. (Here, the limit is in the deterministic sense.)

• Note that convergence in probability implies converges in distribution (but not the other way around).



• Convergence in distribution is also preserved under continuous transformations (*continuous mapping theorem*):

$$\theta_N \xrightarrow{D} \theta \implies g(\theta_N) \xrightarrow{D} g(\theta)$$

Central Limit Theorems

- Now we can state the most useful limit results for convergence in distribution
- Let

$$Z_N = \frac{\bar{X}_N - E[\bar{X}_N]}{\sqrt{Var(\bar{X}_N)}}$$

where $\bar{X}_N = N^{-1} \sum_{i=1}^N X_i$, the sample mean.

- Central Limit Theorem I: Let X_i be iid with $E[X_i] = \mu$ and $Var(X_i) = \sigma^2$, then $Z_N \xrightarrow{D} N(0, 1)$.
- Central Limit Theorem II: Let X_i be independent with $E[X_i] = \mu_i$ and $Var(X_i) = \sigma_i^2$. If:

$$\lim_{N\to\infty}\frac{\sum_{i=1}^N E[|X_i-\mu_i|^{2+\delta}]}{\left(\sum_{i=1}^N \sigma_i^2\right)^{(2+\delta)/2}}=0$$

for some $\delta > 0$, then $Z_N \stackrel{\mathrm{D}}{\to} N(0,1)$.



Asymptotic Theory for OLS

• Given random variables $\{X_i\}$ and $\{u_i\}$, let y_i be generated as:

$$y = X\beta + u$$

- where y is the $(N \times 1)$ vector of y_i , u is $(N \times 1)$ vector of u_i , X is $(N \times K)$ matrix of X_i , β is $(K \times 1)$.
- We observe only (y, X), but not u.
- We form the OLS estimator of β , $\hat{\beta}_N$:

$$\begin{split} \hat{\beta}_N &= (X'X)^{-1}X'(X\beta + u) \\ &= \beta + (X'X)^{-1}X'u \\ &= \beta + (\frac{1}{N}X'X)^{-1}\left(\frac{1}{N}X'u\right) \end{split}$$

Consistency of OLS

- When is $\hat{\beta}_N \stackrel{P}{\rightarrow} \beta$?
- Need:

$$\frac{1}{N}X'u \stackrel{\mathrm{P}}{\to} 0$$

- This is a $(K \times 1)$ vector, each element k of the form $\frac{1}{N} \sum_{i=1}^{N} X_i^{(k)} u_i$. Need each of these to have plim zero.
- If $E[X_i^{(k)}u_i] = E[w_i^{(k)}] = 0$, $w_i^{(k)}$ are independent draws, and $Var(w_i^{(k)})$ is not increasing too fast in i, we can use the Markov LLN to get the plim equal zero.
- Note: $E[X_i^{(k)}u_i] = Cov(X_i^{(k)}, u_i)$. $E[u_i|X_i^{(k)}] = 0$, $E[u_i] = 0$ sufficient for $Cov(X_i^{(k)}, u_i) = 0$.
- Practical question: What kinds of heteroskedasticity does this allow for?
- Also need $M_{XX} = \text{plim } \frac{1}{N}X'X$ to exist, and to be invertible.
- To use the Markov LLN for this, need restrictions on the variance of $X^{(i)}X^{(j)}$ (products of covariates) not growing too



Asymptotic distribution of OLS estimator

• Scale $\hat{\beta}_N$ by \sqrt{N} .

$$\sqrt{N} \left(\hat{\beta}_N - \beta \right) = \left(\frac{1}{N} X' X \right)^{-1} \frac{1}{\sqrt{N}} X' u$$

$$(Why?) \stackrel{D}{\rightarrow} M_{XX}^{-1} \frac{1}{\sqrt{N}} X' u$$

- But $\frac{1}{\sqrt{N}}X'u = \frac{1}{\sqrt{N}}\sum_{i=1}^{N}X_iu_i = \frac{1}{\sqrt{N}}\sum_{i=1}^{N}q_i$.
- If $E[q_i] = 0$ and variance does not grow too fast, we can apply CLT II here.

$$\frac{1}{\sqrt{N}} \sum_{i=1}^{N} X_i u_i \stackrel{\mathcal{D}}{\to} N(0, M_{X\Omega X})$$



where

$$M_{X\Omega X} = \frac{1}{N} \sum_{i=1}^{N} Var(X_i u_i)$$

$$(u_i \text{ is scalar}) = \frac{1}{N} \sum_{i=1}^{N} E(u_i^2 X_i X_i')$$

$$(\text{When?}) = \text{plim } \frac{1}{N} \sum_{i=1}^{N} u_i^2 X_i X_i'$$

So:

$$\sqrt{N}\left(\hat{\beta}_{N}-\beta\right)\stackrel{\mathrm{D}}{
ightarrow}N(0,M_{XX}^{-1}M_{X\Omega X}M_{XX}^{-1})$$

where

$$M_{XX} = \operatorname{plim} \frac{1}{N} X' X$$

 $M_{X\Omega X} = \operatorname{plim} \frac{1}{N} \sum_{i=1}^{N} u_i^2 X_i X_i'$

Heteroskedasticity robust (White) standard errors

- Since we do not see M_{XX} and $M_{X\Omega X}$, we need to estimate them.
- White (1980) suggested:

$$\hat{M}_{XX} = \frac{1}{N} X' X$$

$$\hat{M}_{X\Omega X} = \frac{1}{N} \sum_{i=1}^{N} \hat{u}_i^2 X_i X_i'$$

and showed the restrictions under which

$$\sqrt{N} \left(\hat{\beta}_N - \beta \right) \stackrel{\mathrm{D}}{\to} N(0, \hat{M}_{XX}^{-1} \hat{M}_{X\Omega X} \hat{M}_{XX}^{-1})$$



• Basic idea of the proof is showing that

$$\begin{aligned} \text{plim } \hat{M}_{X\Omega X} &\stackrel{?}{=} & M_{X\Omega X} \\ &= & \text{plim } \frac{1}{N} \sum_{i=1}^{N} \left(y_i - X_i \hat{\beta} \right)^2 X_i X_i' \\ &= & \text{plim } \frac{1}{N} \sum_{i=1}^{N} \left(u_i + X_i (\beta - \hat{\beta}) \right)^2 X_i X_i' \\ &= & \text{plim } \frac{1}{N} \sum_{i=1}^{N} u_i^2 X_i X_i' + \text{extra terms} \end{aligned}$$

White showed that the plim of extra terms is zero.

- Asymptotic theory can be used to show the consistency and derive limit distribution of the OLS estimator under quite general assumptions on u_i .
- Key statistical assumptions:

$$Cov(X_i, u_i) = 0$$

plim $\frac{1}{N}X'X = M_{XX}$ exists and invertible

- White standard errors account for quite general forms of heteroskedasticity.
- You can use standard OLS to get consistent estimates of β , then use White standard error formula to do (asymptotically) correct inference.