

# **Algebraic Topology**

Lectures by: Professor Cameron Gordon

Notes by: Jackson Van Dyke; All errors introduced are my own.

## Contents

Introduction	4
1. Introduction	4
2. A bit more specific	5
Chapter 1. Homotopy	8
Chapter 2. The fundamental group	14
1. Fundamental group of $S^1$	16
2. Induced homomorphisms	19
3. Dependence of $\pi_1$ on the basepoint	20
4. Fundamental theorem of algebra	22
5. Cartesian products	23
6. Retractions	24
Chapter 3. Van Kampen's theorem	25
1. Basic combinatorial group theory	25
2. Statement of the theorem	30
3. Cell complexes	31
4. Knot groups	36

# Introduction

We won't follow the book line by line, but it will be the reference for the course. Read the first three pages of chapter 0, talking about homotopy. We will really get started on chapter 1, section 1.1, about the fundamental group.

Lecture 1; August 29, 2019

## 1. Introduction

Today will be an introductory account of what algebraic topology actually is. In topology the objects of interest are topological spaces where the natural equivalence relation is a homeomorphism, i.e. a bijection  $f : X \rightarrow Y$  such that  $f$  and  $f^{-1}$  are continuous. Somehow the goal is classifying topological spaces up to homeomorphism, so the basic question is somehow:

QUESTION 1. Given topological spaces  $X$  and  $Y$ , is  $X \cong Y$ .

In these terms, algebraic topology is somehow a way of translating this into an algebraic question. More specifically, *algebraic topology* is the construction and study of functors from **Top** to some categories of algebraic objects (e.g. groups<sup>0.1</sup>, abelian groups, vector spaces, rings, modules, ...). Recall this means we have a map from topological spaces  $X \rightarrow A(X)$  for some algebraic object  $A(X)$ . In addition, for every  $f : X \rightarrow Y$  we get a morphism  $f_* : A(X) \rightarrow A(Y)$ . Then these have to satisfy the conditions that

$$(gf)_* = g_*f_* \text{ , } \qquad (\text{id})_* = \text{id} \text{ .}$$

EXERCISE 1.1. Show that  $X \cong Y$  implies that  $A(X) \cong A(Y)$ .

EXAMPLE 0.1 (Fundamental group). Let  $X$  be a topological space. We will construct a group  $\pi_1(X)$ .

EXAMPLE 0.2 (Higher homotopy groups). There is also something,  $\pi_n(X)$ , called the  $n$ th homotopy group. As it turns out for  $n \geq 2$  this is abelian.

EXAMPLE 0.3 (Singular homology). We will define abelian groups  $H_n(X)$  (for  $n \geq 0$ ) called the  $n$ th singular homology group.

We will also define real vector spaces  $H_n(X; \mathbb{R})$  for  $n \geq 0$  which are the  $n$ th singular homology with coefficients in  $\mathbb{R}$ .

EXAMPLE 0.4 (Cohomology). We will also have the  $n$ th (singular) cohomology rings  $H^*(X)$ . These is actually a graded ring.

---

<sup>0.1</sup>Once Professor Gordon was giving a job talk about knot cobordisms. As it turns out these form a semigroup rather than a group. But if you add some sort of 4 dimensional equiv relation you get an honest group. So he was going on about how semigroups aren't so useful. After the talk he found out the chairman of the department worked on semigroups.

WARNING 0.1. Above we actually should have said we're dealing with what are *covariant* functors, but in this case we are actually dealing with a *contravariant* functor. This just means we have:

$$f : X \rightarrow Y \rightsquigarrow f^* : H^*(Y) \rightarrow H^*(X) .$$

REMARK 0.1. The point here is that problems about topological spaces and maps are “continuous” and “hard”. But on the algebraic side these problems become somehow “discrete” and “easy”.

## 2. A bit more specific

Recall in  $\mathbb{R}^n$  we define:

$$D^n = \{x \in \mathbb{R}^n \mid \|x\| \leq 1\} \quad S^{n-1} = \{x \in \mathbb{R}^n \mid \|x\| = 1\} .$$

EXAMPLE 0.5. Two examples of surfaces are  $S^2$  and  $T^2 = S^1 \times S^1$ . They clearly aren't homeomorphic, but how are we supposed to prove such a fact? We will see that  $\pi_1(S^2) = 1$  whereas  $\pi_1(T^2) = \mathbb{Z} \times \mathbb{Z}$ . Since these are not isomorphic, the spaces cannot be homeomorphic.

**2.1. Retraction.** Let  $A \subset X$  be a space and a subspace.

DEFINITION 0.1. A *retraction* from  $X$  to  $A$  is a map  $r : X \rightarrow A$  such that  $r|_A = \text{id}_A$ , i.e. the following diagram commutes:

$$\begin{array}{ccc} & X & \\ i \nearrow & & \searrow r \\ A & \xrightarrow{\text{id}} & A \end{array} .$$

Note that  $r$  is certainly surjective since  $\text{id}$  is.

EXAMPLE 0.6. If  $X$  is any nonempty space,  $x_0 \in X$ , define  $r : X \rightarrow \{x_0\}$  as  $r(x) = x_0$ . So every nonempty space always retract onto a point.

EXAMPLE 0.7. Think of  $A \subset A \times B$  by fixing some  $b_0 \in B$  and sending

$$\begin{aligned} A &\hookrightarrow B \\ & \\ a &\longmapsto (a, b_0) \end{aligned} .$$

Then  $r : A \rightarrow B$  defined by  $r(a, b) = a$  is a retraction.

Recall that for  $f : X \rightarrow Y$  for  $X$  path connected, then  $f(X)$  is also path connected. Recall that  $D^1 = [-1, 1] \subset \mathbb{R}$  is path connected, whereas  $S^0 = \{\pm 1\}$  is not. Therefore there cannot be a retraction  $D^1 \rightarrow S^0$ . This is a basic fact, but it motivates a more general statement which is not so clear.

Suppose there exists a retraction  $r : D^1 \rightarrow S^0$ . Then this means the following diagram commutes:

$$\begin{array}{ccc} & D^1 & \\ \nearrow & & \searrow r \\ S^0 & \xrightarrow{\text{id}} & S^0 \end{array} .$$

If we apply the functor  $H_0$ , we will see that

$$H_0(X) \cong \bigoplus_{\text{path components of } X} \mathbb{Z} .$$

So if we apply  $H_0$  to the diagram we get:

$$\begin{array}{ccc} & H_0(D^1) & \\ i_* \nearrow & & \searrow r_* \\ H_0(S^0) & \xrightarrow{\text{id}} & H_0(S^0) \end{array} = \begin{array}{ccc} & \mathbb{Z} & \\ i_* \nearrow & & \searrow r_* \\ \mathbb{Z} \oplus \mathbb{Z} & \xrightarrow{\text{id}} & \mathbb{Z} \oplus \mathbb{Z} \end{array}$$

but this is clearly impossible.

In the same way we will see the much harder fact:

FACT 1 (Brouwer). *There does not exist a retraction  $D^n \rightarrow S^{n-1}$  (for  $n \geq 2$ ).*

We will see this by applying  $H_{n-1}$ . The idea is that

$$H_{n-1}(D^n) = 0 \qquad H_{n-1}(S^{n-1}) = \mathbb{Z}$$

which means we would have the diagram:

$$\begin{array}{ccc} & 0 & \\ \nearrow & & \searrow \\ \mathbb{Z} & \xrightarrow{\text{id}} & \mathbb{Z} \end{array}$$

which is a contradiction.

This turns out to imply the famous:

THEOREM 0.1 (Brouwer fixed point theorem). *Every map  $f : D^n \rightarrow D^n$  ( $n \geq 1$ ) has a fixed point (i.e. a point  $x \in D^n$  such that  $f(x) = x$ ). In this case one says that  $D^n$  has the fixed point property (FPP).*

PROOF. Suppose there exists an  $f : D^n \rightarrow D^n$  such that  $\forall x \in D^n$   $f(x) \neq x$ . Now draw a straight line from  $x$  to  $f(x)$  and continue it to the boundary  $S^{n-1}$ . Call this point  $g(x)$ . Then this defines a map  $g : D^n \rightarrow S^{n-1}$ .  $g$  is continuous and  $g|_{S^{n-1}} = \text{id}$ . Therefore  $g$  is a retraction  $D^n \rightarrow S^{n-1}$  which we saw cannot exist.  $\square$

**2.2. Dimension.** We know  $\mathbb{R}^n$  somehow has dimension  $n$ . But what does this really mean? The intuition is that  $\mathbb{R}^2$  somehow has more points than  $\mathbb{R}$ . But then in 1877 Cantor proved that there is in fact a bijection  $\mathbb{R} \rightarrow \mathbb{R}^2$ . But this is highly non-continuous, so this tells us continuity should have something to do with it. But then in 1890 Peano showed that there exists a continuous surjection  $\mathbb{R} \rightarrow \mathbb{R}^2$  as well. In 1910, using homology, Brouwer proved:<sup>0.2</sup>

THEOREM 0.2. *For  $m < n$   $\nexists$  continuous injection  $\mathbb{R}^n \rightarrow \mathbb{R}^m$ .*

We will prove this. A corollary of this is the famous invariance of dimension. I.e.  $\mathbb{R}^m \cong \mathbb{R}^n$  iff  $m = n$ . The proof uses separation properties of  $n - 1$ -sphere in  $\mathbb{R}^n$ , thus in turn uses  $H_*$ .

EXERCISE 2.1. Find an easy proof for  $m = 1$ .

THEOREM 0.3 (Jordan curve theorem). *For a subset  $C \subset \mathbb{R}^2$  such that  $C \simeq S^1$  then  $\mathbb{R}^2 \setminus C$  has exactly 2 components  $A$  and  $B$ . In addition  $C = \text{Fr}(A) = \text{Fr}(B)$ . (Recall the frontier is defined as  $\text{Fr}(X) = \overline{X} \cap (\mathbb{R}^2 \setminus X)$  for any  $X \subset \mathbb{R}^2$ .)*

<sup>0.2</sup> When he proved this Lebesgue contacted him saying that he could prove it too. So he sent him his proof, and Brouwer saw some errors. So over many years he eventually corrected it. In the end Brouwer summarized it by saying that it was really just his own proof.

THEOREM 0.4 (Schönflies). *Let  $A$ ,  $B$ , and  $C$  be as above and assume  $A$  is a bounded component of  $\mathbb{R}^2 \setminus X$ . Then  $\overline{A} \cong D^2$ .*

The higher dimensional analog of JCT is true (Brouwer). The proof will use  $H_*$ . The generalization is that for  $\Sigma \subset \mathbb{R}^n$  then  $\Sigma \cong S^{n-1}$ . As it turns out the higher dimensional analog of the Schönflies theorem is false. The counterexample is the famous Alexander horned space. I.e. there exists  $\Sigma \subset \mathbb{R}^3$ ,  $\Sigma \cong S^2$ ;  $A$  a bounded component of  $\mathbb{R}^3 \setminus \Sigma$  and  $\overline{A} \not\cong D^3$ .

Recall

THEOREM 0.5 (Heine-Borel).  *$X \subset \mathbb{R}^n$  compact is equivalent to  $X$  being closed and bounded.*

So consider  $\emptyset \neq X \subset \mathbb{R}$  compact and connected. This is equivalent to being an interval  $X = [a, b]$  ( $a \leq b$ ). In  $\mathbb{R}^2$  things get much worse. In particular there exists compact, connected subset such that  $\mathbb{R}^2 \setminus X$  has exactly three components  $A$ ,  $B$ , and  $C$ , and in particular every neighborhood of every point in  $X$  meets all three components. This is known as the ‘lakes of Wada’. We start with an island with two lakes, and then start digging canals which somehow get closer and closer to the lakes. In the end every point of what is left is arbitrarily close to all three lakes.

QUESTION 2 (Open question). Let  $X$  be a compact connected subset of  $\mathbb{R}^2$  such that  $\mathbb{R}^2 \setminus X$  is connected. Does  $X$  have the fixed point property?

## CHAPTER 1

# Homotopy

Let  $I = [0, 1]$ .

DEFINITION 1.1. Let  $f, g : X \rightarrow Y$ . Say  $f$  is homotopic to  $g$  (and write  $f \simeq g$ ) iff there exists a map  $F : X \times I \rightarrow Y$  such that for all  $x \in X$

$$F(x, 0) = f(x) \qquad F(x, 1) = g(x) \quad .$$

Define  $F_t : X \rightarrow Y$  by  $F_t(x) = F(x, t)$ . Then  $F_t$  is a continuous 1-parameter family of maps  $X \rightarrow Y$  such that  $F_0 = f$  and  $F_1 = g$ .

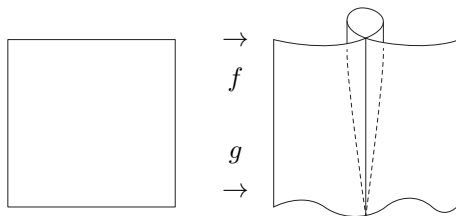


FIGURE 1.

EXAMPLE 1.1. Let  $F : S^{n-1} \times I \rightarrow \mathbb{R}^n$  be defined by  $F(x, t) = (1 - t)x$ . Then  $F_0$  is the inclusion  $S^{n-1} \hookrightarrow \mathbb{R}^n$  and  $F_1$  is the constant map  $S^{n-1} \rightarrow \text{origin}$ .

Lecture 2;  
September 3, 2019

LEMMA 1.1. *Homotopy is an equivalence relation on the set of all maps  $X \rightarrow Y$ .*

PROOF. (i)  $f \simeq f$ : Let  $F$  be the constant homotopy, i.e.  $F(x, t) = f(x)$  for all  $t \in I$  and for all  $x \in X$ .  
(ii)  $f \simeq g \implies g \simeq f$ : Suppose  $f \simeq_F g$ . Let  $\bar{F}$  be the reverse homotopy  $\bar{F}(x, t) = F(x, 1 - t)$ . Then  $g \simeq_{\bar{F}} f$ .  
(iii)  $f \simeq g, g \simeq h \implies f \simeq h$ : Define  $H : X \times I \rightarrow Y$  by

$$H(x, t) = \begin{cases} F(x, 2t) & 0 \leq t \leq 1/2 \\ G(x, 2t - 1) & 1/2 \leq t \leq 1 \end{cases} .$$

Then by exercise 2 on homework 1  $H$  is continuous and therefore  $f \simeq_H h$ . □

LEMMA 1.2 (compositions of homotopic maps are homotopic). *If  $f \simeq f' : X \rightarrow Y$ ,  $g \simeq g' : Y \rightarrow Z$ , then  $gf \simeq g'f' : X \rightarrow Z$ .*



PROOF. Suppose  $f \simeq_F f'$ ,  $g \simeq_G g'$ . Then the composition

$$X \times I \xrightarrow{F} Y \xrightarrow{g} Z$$

is a homotopy from  $gf$  to  $gf'$ . Then the composition

$$X \times I \xrightarrow{f' \times \text{id}} Y \times I \xrightarrow{G} Z$$

is a homotopy from  $gf'$  to  $g'f'$ . By transitivity of equivalence relations from lemma 1.1.  $\square$

Let  $[X, Y]$  be the set of homotopy classes of maps from  $X \rightarrow Y$ .

REMARK 1.1. We should probably assume  $X \neq \emptyset \neq Y$ .

Lemma 1.2 then tells us that composition defines a function

$$[X, Y] \times [Y, Z] \rightarrow [X, Z] .$$

### 0.1. Homotopy equivalence.

DEFINITION 1.2.  $X$  is *homotopy equivalent* to  $Y$  (or *of the same homotopy type* as  $Y$ ) written  $X \simeq Y$  if there exist maps  $f : X \rightarrow Y$  and  $g : Y \rightarrow X$  such that  $gf \simeq \text{id}_X$  and  $fg \simeq \text{id}_Y$ . Then we say  $f$  is a homotopy equivalence and  $g$  is a homotopy inverse of  $f$ .

EXAMPLE 1.2. A homeomorphism is a homotopy equivalence, but in general this is much weaker.

LEMMA 1.3. *Homotopy equivalence is an equivalence relation.*

- PROOF. (i)  $X \simeq X$ :  $f = g = \text{id}_X$ , lemma 1.1.  
(ii)  $X \simeq Y \implies Y \simeq X$ : by definition.  
(iii)  $X \simeq Y, Y \simeq Z \implies X \simeq Z$ : So we have

$$X \begin{array}{c} \xrightarrow{f} \\ \xleftarrow{f'} \end{array} Y$$

where  $f'f \simeq \text{id}_X$ ,  $ff' \simeq \text{id}_Y$  and similarly

$$Y \begin{array}{c} \xrightarrow{g} \\ \xleftarrow{g'} \end{array} Z$$

where  $g'g \simeq \text{id}_Y$ ,  $gg' \simeq \text{id}_Z$ . Then we compose:

$$X \begin{array}{c} \xrightarrow{gf} \\ \xleftarrow{f'g'} \end{array} Y$$

and we have that

$$(f'g')gf = f'(g'g)f \simeq f'\text{id}_Y f = f'f \simeq \text{id}_X$$

(from lemma 1.2) and similarly

$$(gf)(f'g') \simeq \text{id}_Y$$

so  $gf : X \rightarrow Y$  is a homotopy equivalence.  $\square$

LEMMA 1.4.  $X \simeq X', Y \simeq Y' \implies X \times Y \simeq X' \times Y'$ .

PROOF. (exercise) □

REMARK 1.2. Many functors in algebraic topology (e.g.  $\pi_1$ ,  $H_n$ , ...) have the property that  $f \simeq g \implies f_* = g_*$ . In other words they factor through the homotopy category where the objects are topological spaces and morphisms are just homotopy classes of maps:

$$\begin{array}{ccc} & \mathbf{Top}/\simeq & \\ \nearrow & & \searrow \\ \mathbf{Top} & \xrightarrow{\quad\quad\quad} & \{\text{Algebraic objects, morphisms}\} \end{array} \quad .$$

$$f : X \rightarrow Y \xrightarrow{\quad\quad\quad} f_* : A(X) \rightarrow A(Y)$$

DEFINITION 1.3. Let  $A \subset X$ ,  $f, g : X \rightarrow Y$  such that  $f|_A = g|_A$ . Then  $f \simeq g$  (rel.  $A$ ) iff there exists  $f \simeq_F g$  such that

$$F_t|_A = f|_A (= g|_A)$$

for all  $t \in I$ .

Homotopy equivalence rel.  $A$  is an equivalence relation on the set

$$\{f : X \rightarrow Y \mid f|_A \text{ is a fixed map}\}$$

Let  $i : A \rightarrow X$  be the inclusion. Then  $i$  being a homotopy equivalence means there exists some  $f : X \rightarrow A$  such that

- (i)  $if \simeq \text{id}_X$ , and
- (ii)  $fi \simeq \text{id}_A$ .

Now we can strengthen this in multiple ways.

DEFINITION 1.4. If we strengthen (ii) to say  $fi = \text{id}_A$  (i.e.  $f$  is a retraction) then  $\text{id}_X \simeq_F if$  is a *deformation retraction of  $X$  onto  $A$* . In other words we have

$$F : X \times I \rightarrow X$$

such that  $F_0 = \text{id}_X$ ,  $F_1(x) \in A$  for all  $x \in X$ , and  $F_1|_A = \text{id}_A$  (since  $F_1 = if$ ).

DEFINITION 1.5. If in addition we strengthen (i) to say that  $\text{id}_X \simeq_F if$  (rel  $A$ ) then  $F$  is a *strong deformation retraction* (of  $X$  onto  $A$ ). In other words we have  $F : X \times I \rightarrow X$  such that

$$F_0 = \text{id}_X \quad \forall x \in X, F_1(x) \in A \quad \forall t \in I, \forall a \in A, F_t(a) = a.$$

The idea here is that  $X$  strong deformation retracts to  $A$  implies  $X$  deformation retracts to  $A$  which implies  $i : A \hookrightarrow X$  is a homotopy equivalence. As it will turn out, both of these implications are strict.

EXAMPLE 1.3.  $X \times \{0\}$  is a strong deformation retract of  $X \times I$ :

$$F : (X \times I) \times I \rightarrow X \times I$$

where  $F((x, s), t) = (x, (1-t)s)$ .

EXAMPLE 1.4.  $\mathbb{R}^n \setminus \{0\}$  strong deformation retracts to  $S^{n-1}$ .

EXAMPLE 1.5.  $A = S^1 \times [-1, 1]$  strong deformation retracts to  $S^1 \times \{0\}$ . A Möbius band  $B$  also strong deformation retracts to  $S^1$ . Therefore  $A \simeq B$ .

EXAMPLE 1.6. Let  $X$  be a twice punctured disk. Then it is sort of clear that this strong deformation retracts to

- (i) the boundary along with one arc passing between the punctures,
- (ii) the wedge of two circles, and
- (iii) two circles connected by an interval.

This means these three are all homotopy equivalent.

EXAMPLE 1.7. Consider a once-punctured torus  $X = T^2 \setminus \text{int}(D^2)$ . This strong deformation retracts to the wedge of two circles. This tells us that the once punctured torus is actually homotopy equivalent to the disk with two punctures.

These examples show that homotopy equivalence does not imply homeomorphism, even for surfaces with boundary. We can immediately see these examples are homeomorphic because there's no way for the boundaries to be mapped to one another.

**0.2. Manifolds.** Topological spaces can be very wild, but manifolds are usually quite nice.

DEFINITION 1.6. An  $n$ -dimensional manifold is a Hausdorff, second countable space  $M$  such that every  $x \in M$  has a neighborhood homeomorphic to  $\mathbb{R}^n$ .

EXAMPLE 1.8.  $\mathbb{R}^n, S^n, T^n = \underbrace{S^1 \times \dots \times S^1}_n$ .

DEFINITION 1.7. A manifold is *closed* iff it is compact.

DEFINITION 1.8. A surface is a closed 2-manifold.

EXAMPLE 1.9. We have all of the two-sided or orientable surfaces ( $S^2, T^2, \dots$ ) and then non orientable ones like  $\mathbb{P}^2$  and the Klein bottle. As it turns out this is a complete list up to homeomorphism.

For any two spaces  $X \cong Y$  implies  $X \simeq Y$ . As we have seen, the converse isn't even true for surfaces with boundary. But for closed manifolds, there are many interesting cases where it is true:

- (1) For  $M, M'$  closed surfaces,  $M \simeq M' \implies M \cong M'$ .
- (2) For  $M$  an  $n$ -manifold,  $M \simeq S^n \implies M \cong S^n$ . (Generalized Poincaré conjecture)

For  $n = 0, 1, 2$  this is not so bad. For  $n \geq 5$ , Connell and Newman independently proved it. The next step was proving this for  $n = 4$ . This was proved by Freedman. Finally for  $n = 3$  Perelman proved this. The smooth 4-dimensional version is still open. I.e. the statement for diffeomorphism.

REMARK 1.3. Poincaré originally posed this conjecture as saying that having the same homology as  $S^n$  was sufficient. But he discovered a counterexample, now called the Poincaré homology sphere. This shares homology with  $S^3$  but has different fundamental group. This is in fact why he invented the fundamental group.

DEFINITION 1.9.  $f : X \rightarrow Y$  is a *constant map* if there is some  $y_0 \in Y$  such that for all  $x \in X$   $f(x) = y_0$ . We write  $f = c_{y_0}$ .

DEFINITION 1.10. A map  $f : X \rightarrow Y$  is *null-homotopic* iff  $f \simeq$  a constant map.

DEFINITION 1.11.  $X$  is *contractible* if  $\text{id}_X$  is null-homotopic. I.e. there exists some  $x_0 \in X$  such that  $X$  deformation retracts to  $x_0$ .

EXAMPLE 1.10. (1) Any nonempty convex<sup>1.1</sup> subspace of  $\mathbb{R}^n$  is contractible. Choose an arbitrary point  $x_0 \in X$ . Define  $F : X \times I \rightarrow X$  by

$$F(x, t) = (1 - t)x + tx_0.$$

Then  $\text{id}_X \simeq_F c_{x_0}$ . In fact this is a strong deformation retraction. Sometimes you can do this for some point but not all, and for some you can't do it for any points.

(2)  $S^1$  is not contractible.

Lecture 3;  
September 5, 2019

LEMMA 1.5. For a topological space  $X$  TFAE:

- (1)  $X$  is contractible,
- (2)  $\forall x_0 \in X$ ,  $X$  deformation retracts to  $\{x_0\}$ ,
- (3)  $X \simeq \{\text{pt}\}$ ,
- (4)  $\forall Y$ , any two maps  $Y \rightarrow X$  are homotopic.
- (5)  $\forall Y$ , any map  $X \rightarrow Y$  is null-homotopic.

PROOF. (1)  $\implies$  (3): (1) is equivalent to saying that  $X$  deformation retracts to a point, so the inclusion map is certainly a homotopy equivalence.

(3)  $\implies$  (4): Let  $f : X \rightarrow \{z\}$  be a homotopy equivalence. By homework 1 exercise 3, we get an induced function:

$$f_* : [Y, X] \rightarrow [Y, \{z\}]$$

but there is only one map in the target set, so clearly there is only one homotopy class of maps  $Y \rightarrow \{z\}$ .

(4)  $\implies$  (2): Take  $Y = X$ , and take any  $x_0 \in X$ . This means  $\text{id}_X \simeq c_{x_0}$ , but this is exactly saying that  $X$  deformation retracts to  $x_0$ .

(2)  $\implies$  (5): Let  $f : X \rightarrow Y$  and  $x_0 \in X$ . Then (2) implies  $\text{id}_X \simeq_F c_{x_0}$ . Then

$$f \circ \text{id}_X \simeq_{f \circ F} f \circ c_{x_0}$$

i.e.  $f$  is nullhomotopic.

(5)  $\implies$  (1): Take  $Y = X$ . □

COROLLARY 1.1. For  $X, Y$  contractible, then

- (1)  $X \simeq Y$ ,
- (2) any map  $X \rightarrow Y$  is a homotopy equivalence.

PROOF. (1) If  $X, Y \simeq \{\text{pt}\}$  then  $X \simeq Y$ .

(2) Given  $f : X \rightarrow Y$ , let  $g : Y \rightarrow X$  be any map.  $gf : X \rightarrow X$ , but  $X$  is contractible, so  $gf \simeq \text{id}_X$  by lemma 1.5. □

Now we will give an example of a deformation retraction which is not a strong deformation retraction. Recall  $X$  strong deformation retracts to  $A$  implies  $X$  deformation retracts to  $A$  which implies  $i : A \hookrightarrow X$  is a homotopy equivalence, but none of these implications are reversible.

<sup>1.1</sup> Recall  $X \subset \mathbb{R}^n$  is convex if  $x, y \in X$  implies  $tx + (1 - t)y \in X$  for all  $t \in I$ .

EXAMPLE 1.11 (Comb space). Define the comb space  $C \subset I \times I \subset \mathbb{R}^2$  to be:

$$C = \{(x, y) \in \mathbb{R}^2 \mid y = 0, 0 \leq x \leq 1; 0 \leq y \leq 1, x = 0, 1/n (n = 1, 2, \dots)\} .$$

This should be pictured as a bunch of vertical intervals.<sup>1,2</sup> The first thing to note is that  $C$  strong deformation retracts to  $(0, 0)$ . Therefore  $C$  is contractible.  $C$  also deformation retracts to  $(0, 1)$ . [More generally: if  $X$  deformation retracts to some  $x_0 \in X$  and  $X$  is path connected, then  $X$  deformation retracts to any  $x \in X$ ].

CLAIM 1.1. But it does not strong deformation retract to  $(0, 1)$ .

PROOF. Let  $F : C \times I \rightarrow C$  be such a strong deformation retraction. Let  $U$  be some open disc of radius  $1/2$  centered at  $(0, 1)$ .  $F^{-1}(U) \subset X \times I$  contains  $(0, 1) \times I$ . Therefore for all  $t \in I$  there exists some neighborhood  $V_t$  of  $(0, 1) \times \{t\}$  such that  $V_t \subset F^{-1}(U)$ . But  $V_t = W_t \times Z_t$  for  $W_t$  some neighborhood of  $(0, 1)$  in  $C$  and  $Z_t$  some neighborhood of  $t$  in  $I$ .  $I$  is compact which means  $\exists t_1, \dots, t_m$  such that

$$\bigcup_{i=1}^m Z_{t_i} = I .$$

Let

$$W = \bigcap_{i=1}^m W_{t_i} .$$

This is a neighborhood of  $(0, 1)$  in  $C$ , and  $W \times I \subset F^{-1}(U)$ . (This is sometimes called the tube lemma). Pick  $n$  such that  $(1/n, 1) \in W$ . Then  $F((1/n, 1), t)$ ,  $0 \leq t \leq 1$ , is a path in  $U$  from  $(1/n, 1)$  to  $(0, 1)$  but there clearly isn't such a path since these two points are in different path components.  $\square$

COROLLARY 1.2. Let  $X \subset I^2 \subset \mathbb{R}^2$  where  $C, I^2$  are both contractible. Then the inclusion  $i : C \rightarrow I^2$  is a homotopy equivalence. But there does not exist a deformation retraction  $I^2 \rightarrow C$ . In fact there is no retraction at all.

REMARK 1.4. There exists a space  $X$  such that  $X$  is contractible (therefore  $\{x\} \hookrightarrow X$  is a homotopy equivalence for all  $x \in X$ ) but there does not exist a deformation retraction from  $X$  to any  $x \in X$ . (e.g. Hatcher chapter 0, 6(b)).

**0.3. Fixed point property.** A space  $X$  has the fixed point property (FPP) iff  $\forall f : X \rightarrow X, \exists x \in X$  such that  $f(x) = x$ .  $X$  being contractible does not imply  $X$  has the FPP (e.g.  $\mathbb{R}^1$ ).

QUESTION 3 (Borsuk). If  $X$  is compact and contractible does contractible imply FPP?

---

<sup>1,2</sup>Which is supposed to look like a comb.

## CHAPTER 2

### The fundamental group

DEFINITION 2.1. A *path* from  $x_0$  to  $x$  is a map  $\sigma : I \rightarrow X$  such that  $\sigma(0) = x_0$  and  $\sigma(1) = x$ .

DEFINITION 2.2. Let  $\sigma$  be a path in  $X$  from  $x_0$  to  $x_1$ , and  $\tau$  a path in  $X$  from  $x_1$  to  $x_2$ . Their *concatenation*  $\sigma * \tau$  is a path from  $x_0$  to  $x_2$  given by:

$$(\sigma * \tau)(s) = \begin{cases} \sigma(2s) & 0 \leq s \leq 1/2 \\ \tau(2s - 1) & 1/2 \leq s \leq 1 \end{cases} .$$

DEFINITION 2.3. The *homotopy class* of  $\sigma$  is

$$[\sigma] = \{\sigma' \mid \sigma' \simeq \sigma \text{ (rel } \partial I)\} .$$

LEMMA 2.1. If  $[\sigma] = [\sigma']$  and  $[\tau] = [\tau']$  where  $\sigma(1) = \tau(0)$  then  $[\sigma * \tau] = [\sigma' * \tau']$ .

PROOF. If  $\sigma \simeq_{F_t} \sigma'$  and  $\tau \simeq_{G_t} \tau'$  then  $\sigma * \tau \simeq_{F_t * G_t} \sigma' * \tau' \text{ (rel } \partial I)$ .  $\square$

This means we can define the product of two homotopy classes to be the homotopy class of the concatenation. This is well defined by the lemma.

LEMMA 2.2 (Reparameterization). Let  $u : I \rightarrow I$  be a map such that  $u|_{\partial I} = \text{id}$ . Then  $u \simeq \text{id}_I \text{ (rel } \partial I)$ .

PROOF. Define  $F : I \times I \rightarrow I$  by  $F(s, t) = ts + (1 - t)u(s)$ .  $F_0 = u$ ,  $F_1 = \text{id}_I$ ,  $F_t|_{\partial I} = \text{id}$  for all  $t \in I$ .  $\square$

LEMMA 2.3 (Associativity). Let  $\rho, \sigma, \tau$  be paths in  $X$  such that  $\rho(1) = \sigma(0)$ ,  $\sigma(1) = \tau(0)$ . Then

$$([\rho][\sigma])[\tau] = [\rho]([\sigma][\tau]) .$$

PROOF. Define  $u : I \rightarrow I$  by

$$u(s) = \begin{cases} 2s & 0 \leq s \leq 1/4 \\ s + 1/4 & 1/4 \leq s \leq 1/2 \\ (s + 1)/2 & 1/2 \leq s \leq 1 \end{cases} .$$

Then

$$(\rho * (\sigma * \tau))u = (\rho * \sigma) * \tau .$$

but  $u \simeq \text{id}_I \text{ (rel } \partial I)$  so  $(\rho * (\sigma * \tau)) = (\rho * \sigma) * \tau \text{ (rel } \partial I)$   $\square$

Let  $c_{x_0} : I \rightarrow X$  be the constant path given by  $c_{x_0} = x_0$  for all  $s \in I$ .

LEMMA 2.4. For  $\sigma$  a path in  $X$  from  $x_0$  to  $x_1$  then

$$[\sigma] = [\sigma][c_{x_1}] = [c_{x_0}][\sigma] .$$

PROOF. Let  $u : I \rightarrow I$  be

$$u(s) = \begin{cases} 2s & 0 \leq s \leq 1/2 \\ 1 & 1/2 \leq s \leq 1 \end{cases} .$$

Then  $\sigma * c_{x_1} = \sigma * u$

$$[\sigma] = [\sigma][c_{x_1}]$$

by lemma 2.2. The proof is the same for the other part.  $\square$

If  $\sigma$  is a path from  $x_0$  to  $x_1$ , the reverse of  $\sigma$  is the path  $\bar{\sigma}$  from  $x_1$  to  $x_0$  given by

$$\bar{\sigma}(s) = \sigma(1 - s) .$$

Note that immediately we have  $\overline{(\bar{\sigma})} = \sigma$ .

LEMMA 2.5.  $[\sigma][\bar{\sigma}] = [c_{x_0}]$  .

PROOF. Define  $F : I \times I \rightarrow X$  by

$$F(s, t) = \begin{cases} \sigma(2st) & 0 \leq s \leq 1/2 \\ \sigma(2(1-s)t) & 1/2 \leq s \leq 1 \end{cases} .$$

Note that  $F_0 = c_{x_0}$  and  $F_1 = \sigma * \bar{\sigma}$  so we are done.  $\square$

A *loop* in a space  $X$  based at a point  $x_0 \in X$  is a path in  $X$  from  $x_0$  to  $x_0$ . If  $\sigma$  and  $\tau$  are loops at  $x_0$  then this implies  $\sigma * \tau$  is a loop at  $x_0$ . Let

$$\pi_1(X, x_0) = \{[\sigma] \mid \sigma \text{ loop in } X \text{ based at } x_0\} .$$

THEOREM 2.1.  $\pi_1(X, x_0)$  is a group with respect to the operation  $[\sigma][\tau]$ ; the fundamental group of  $X$  with basepoint  $x_0$ .

PROOF. We proved associativity last time in lemma 2.3 the identity is the constant map  $[c_{x_0}]$  as shown in lemma 2.4, and inverses are given by  $[\sigma]^{-1} = [\bar{\sigma}]$  as shown in lemma 2.5.  $\square$

EXAMPLE 2.1. Suppose  $X$  strong deformation retracts to some point  $x_0$ . This means there exists some homotopy  $F : X \times I \rightarrow X$  such that  $F_0 = \text{id}_X$  and  $F_1(x) = x_0$  for all  $x \in X$ . Since it is a strong deformation retraction for all  $t \in I$  we have  $F_t(x_0) = x_0$ . Now let  $\sigma : I \rightarrow X$  be a loop based at  $x_0$ . Then  $\sigma \simeq_{F_t \sigma} c_{x_0} \text{ (rel } \partial I)$ . Therefore  $[\sigma] = 1$  and  $\pi_1(X, x_0) = 1$ .

REMARK 2.1. We will actually prove a more general fact later, when we discuss change of basepoint.

Now we will finally have an example with nontrivial fundamental group. For all we know every space is contractible.<sup>2.1</sup>

---

<sup>2.1</sup>Professor Gordon says our ignorance is extensive.



FIGURE 1.  $p$  mapping  $\mathbb{R}$  to  $S^1$ . Note the preimage of a  $1 \in S^1$  looks like  $\mathbb{Z}$ .

### 1. Fundamental group of $S^1$

A key example is  $S^1 = \{z \in \mathbb{C} \mid |z| = 1\}$ .

THEOREM 2.2.  $\pi_1(S^1, 1) \simeq \mathbb{Z}$ .

REMARK 2.2. The idea of the proof is to somehow unwrap the circle. This proof led to the idea of a covering space.

Let  $p : \mathbb{R} \rightarrow S^1$  be the map defined by  $p(x) = e^{2\pi i x}$ . The picture is as in fig. 1. Note that  $p^{-1}(1) = \mathbb{Z} \subset \mathbb{R}$ .

LEMMA 2.6 (path-lifting). *Let  $\sigma : I \rightarrow S^1$  be a path with  $\sigma(0) = 1$ . Then there exists a unique path  $\tilde{\sigma} : I \rightarrow \mathbb{R}$  such that  $\tilde{\sigma}(0) = 0$  and  $p\tilde{\sigma} = \sigma$ , i.e.  $\tilde{\sigma}$  is a lift of  $\sigma$  so the following diagram commutes:*

$$\begin{array}{ccc} & & \mathbb{R} \\ & \nearrow \tilde{\sigma} & \downarrow p \\ I & \xrightarrow{\sigma} & S^1 \end{array} .$$

PROOF. Let

$$U = \left\{ e^{i\theta} \mid -\frac{3\pi}{4} < \theta < \frac{3\pi}{4} \right\}$$

$$V = \left\{ e^{i\theta} \mid \frac{\pi}{4} < \theta < \frac{7\pi}{4} \right\} .$$

This looks as in fig. 2. Then  $\{U, V\}$  is an open cover of  $S^1$ . First notice that the distance between the points  $\pi/4$  and  $3\pi/4$  is  $\sqrt{2}$ . This means that for any  $z, z' \in S^1$  we have that  $d(z, z') < \sqrt{2}$  implies either  $z, z' \in U$  and  $z, z' \in V$ .

So we have some  $\sigma : I \rightarrow S^1$ ,  $\sigma(0) = 1$ . Since  $I$  is compact this implies  $\exists \delta > 0$  such that  $d(s, s') < \delta$  implies  $d(\sigma(s), \sigma(s')) < \sqrt{2}$ .

Now we decompose the interval. Let  $0 = s_0 < s_1 < \dots < s_m = 1$  such that  $|s_i - s_{i-1}| < \delta$  for all  $i$ . Then  $\sigma([s_{i-1}, s_i]) \subset U$  or  $V$  for all  $i$ .

Now we look at the inverse image in  $\mathbb{R}$  and we get these overlapping intervals covering  $\mathbb{R}$  as in fig. 3.



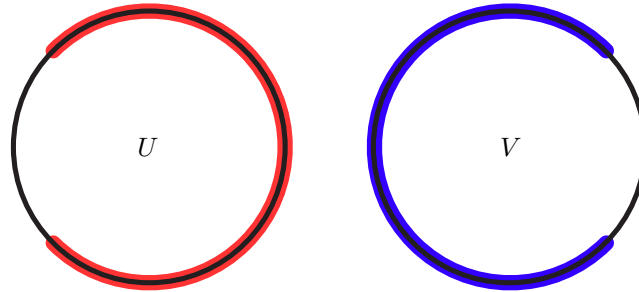


FIGURE 2. An open cover for the circle is given by the two sets  $U$  and  $V$ .

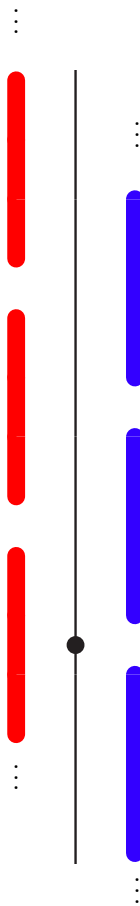


FIGURE 3. The preimage of the cover  $U$  and  $V$  in  $\mathbb{R}$  under the map  $p$ .

In particular

$$\begin{aligned} p^{-1}(U) &= \bigcup_{n \in \mathbb{Z}} \tilde{U}_n & \tilde{U}_n &= \left(n - \frac{3}{8}, n + \frac{3}{8}\right) \\ p^{-1}(V) &= \bigcup_{n \in \mathbb{Z}} \tilde{V}_n & \tilde{V}_n &= \left(n + \frac{1}{8}, n + \frac{7}{8}\right). \end{aligned}$$

The restrictions

$$p|_{\tilde{U}_n} : \tilde{U}_n \rightarrow U \qquad p|_{\tilde{V}_n} : \tilde{V}_n \rightarrow V$$

are homeomorphisms for all  $n$ . This means if we try to lift the path from  $s_0$  to  $s_1$  we have no choice in the lift since it stays in  $U$  in  $S^1$ . So we get a unique lift. In detail, we define  $\tilde{\sigma}$  inductively on  $[0, s_k]$ ,  $0 \leq k \leq m$ . For  $k = 0$ ,  $\sigma(0) = 0$ . So now suppose  $\tilde{\sigma}$  is defined on  $[0, s_{k-1}]$  for some  $k$  such that  $1 \leq k \leq m$ . Then WLOG

$$\sigma([s_{k-1}, s_k]) \subset U$$

(rather than  $V$ ). This means  $\tilde{\sigma}(s_{k-1}) \in \tilde{U}_r$  for some  $r \in \mathbb{Z}$ . Since  $p|_{\tilde{U}_r}$  is a homeomorphism let  $q_r : U \rightarrow \tilde{U}_r$  be  $(p|_{\tilde{U}_r})^{-1}$ . Define

$$\tilde{\sigma}|_{[s_{k-1}, s_k]} = q_r \sigma|_{[s_{k-1}, s_k]}$$

and note this is the only choice. Therefore by induction  $\tilde{\sigma}$  exists and is unique.  $\square$

LEMMA 2.7 (Homotopy lifting). *Let  $\sigma, \tau : I \rightarrow S^1$  be paths with  $\sigma(0) = \tau(0) = 1$  and let  $F : I \times I \rightarrow S^1$  be a homotopy from  $\sigma$  to  $\tau$  (rel  $\partial I$ ). (So  $\sigma(1) = \tau(1)$ ). Then there exists a unique  $\tilde{F} : I \times I \rightarrow \mathbb{R}$ , a homotopy from  $\tilde{\sigma}$  to  $\tilde{\tau}$  (rel  $\partial I$ ), i.e. the following diagram commutes:*

$$\begin{array}{ccc} & & \mathbb{R} \\ & \nearrow \tilde{F} & \downarrow p \\ I \times I & \xrightarrow{F} & S^1 \end{array} .$$

PROOF. This proof is very similar to the proof of lemma 2.6.  $I \times I$  is compact so there exists some  $0 < s_0 < s_1 < \dots < s_m = 1$  and  $0 = t_0 < t_1 < \dots < t_n = 1$  such that if

$$R_{i,j} = [s_{i-1}, s_i] \times [t_{j-1}, t_j]$$

(for  $1 \leq i \leq m$ ,  $1 \leq j \leq n$ ) then  $F(R_{i,j}) \subset U$  or  $V$ . Order the  $R_{i,j}$  and relabel them as  $R_k$ . Then let

$$S_k = \bigcup_{i \leq k} R_i .$$

Now we define  $\tilde{F}$  inductively on  $S_k$ . First  $\tilde{F}(S_0) = \tilde{F}(0,0) = 0$ . Now suppose  $\tilde{F}$  is defined on  $S_{k-1}$ . Then  $S_k = S_{k-1} \cup R_k$  and  $F(R_k) \subset U$  or  $V$ ; say  $U$ . Then  $S_{k-1} \cap R_k$  is nonempty and connected and in  $U$ , and therefore

$$\tilde{F}(S_{k-1} \cap R_k) \subset \tilde{U}_r$$

for some  $r \in \mathbb{Z}$ . So we can (and must) define

$$\tilde{F}|_{R_k} = q_r F|_{R_k} .$$

Therefore  $\tilde{F}$  exists and is unique.  $\tilde{F}_0$  is a lift of  $F_0 = \sigma$ , starting at 0,  $\tilde{F}_1$  is a lift of  $F_1 = \tau$ , starting at 0, therefore by the uniqueness of lemma 2.6,  $\tilde{F}_0 = \tilde{\sigma}$  and  $\tilde{F}_1 = \tilde{\tau}$ . Finally  $p^{-1}(1) = \mathbb{Z}$  is discrete in  $\mathbb{R}$ , so  $\tilde{F}_t(0) = \tilde{\sigma}(0) = 0$  and  $\tilde{F}_t(1) = \tilde{\sigma}(1)$  for all  $t \in I$ , so indeed  $\tilde{\sigma} \simeq_{F_t} \tilde{\tau} \text{ (rel } \partial I)$ .  $\square$

PROOF OF THEOREM 2.1. Let  $\sigma$  be a loop in  $S^1$  at 1. Define  $\varphi : \pi_1(S^1, 1) \rightarrow \mathbb{Z}$  by  $\varphi([\sigma]) = \tilde{\sigma}(1)$ . Then we claim:

- (1)  $\varphi$  is well defined: This follows from lemmata 2.6 and 2.7.
- (2)  $\varphi$  is onto: Let  $n \in \mathbb{Z}$ ; define  $\tilde{\sigma} : I \rightarrow \mathbb{R}$  by  $\tilde{\sigma}(s) = ns$ . Let  $\sigma = p\tilde{\sigma}$ . Then  $\varphi([\sigma]) = \tilde{\sigma}(1) = n$ .
- (3)  $\varphi$  is a homomorphism: Let  $[\sigma], [\tau] \in \pi_1(S^1, 1)$  with  $\varphi([\sigma]) = m$ ,  $\varphi([\tau]) = n$  and

$$[\sigma][\tau] = [\sigma * \tau] .$$

Then

$$\widetilde{\sigma * \tau} = \tilde{\sigma} * \hat{\tau}$$

where  $\hat{\tau}(s) = \tilde{s} + m$  and therefore

$$\varphi([\sigma][\tau]) = \varphi([\sigma * \tau]) = (\widetilde{\sigma * \tau})(1) = (\tilde{\sigma} * \hat{\tau})(1) = m + n = \varphi([\sigma]) + \varphi([\tau])$$

as desired.

- (4)  $\varphi$  is one-to-one: Suppose  $\varphi([\sigma]) = 0$ , i.e.  $\tilde{\sigma}$  is a loop in  $\mathbb{R}$  at 0.  $\mathbb{R}$  strong deformation retracts to 0, so  $\tilde{\sigma} \simeq_{x_0} \text{rel } \partial I$ . Therefore  $[\sigma] = 1$ .

$\square$

## 2. Induced homomorphisms

So consider some map  $f : (X, x_0) \rightarrow (Y, y_0)$ . Then the claim is that we can define a group homomorphism

$$f_* : \pi(X, x_0) \rightarrow \pi_1(Y, y_0)$$

by  $f_*([\sigma]) = [f\sigma]$ .

- THEOREM 2.3. (1)  $f_*$  is a well-defined homomorphism.  
 (2)  $(gf)_* = g_*f_*$ ,  $\text{id}_* = \text{id}$ .  
 (3)  $f \simeq g \text{ (rel } x_0)$  implies  $f_* = g_*$ .

PROOF. (1) Suppose we have two loops  $\sigma \simeq_{F_t} \sigma' \text{ (rel } \partial I)$ . Then this means

$$f\sigma \simeq_{fF_t} f\sigma' \text{ (rel } \partial I)$$

which means  $f_*$  is well-defined.

(2)

$$\begin{aligned} f_*([\sigma][\tau]) &= f_*([\sigma * \tau]) = [f(\sigma * \tau)] \\ &= [f(\sigma) * f(\tau)] = [f\sigma][f\tau] \\ &= f_*([\sigma])f_*([\tau]) . \end{aligned}$$

$\square$

EXAMPLE 2.2. Let  $\mu_n(z) = z^n$  for  $n \in \mathbb{Z}$ . Then

$$\mu_{n*} : \pi_1(S^1, 1) \rightarrow \pi_1(S^1, 1)$$

is multiplication by  $n$ , i.e.

$$\begin{array}{ccc} \pi_1(S^1, 1) & \xrightarrow{\mu_{n*}} & \pi_1(S^1, 1) \\ \downarrow \varphi & & \downarrow \varphi \\ \mathbb{Z} & \xrightarrow{\times n} & \mathbb{Z} \end{array}$$

PROOF. The loop  $\sigma : I \rightarrow S^1$  with  $\sigma(s) = e^{2\pi i s}$  represents  $1 \in \mathbb{Z} \simeq \pi_1(S^1, 1)$ , i.e.  $\varphi([\sigma]) = 1$ . Then

$$\mu_{n*}([\sigma]) = [\mu_n \sigma]$$

where  $(\mu_n \sigma)(s) = e^{2\pi i n s}$ . Therefore  $\varphi([\mu_n \sigma]) = n$ .  $\square$

The following is an application of Theorem 2.1.

THEOREM 2.4. *There is no retraction  $D^2 \rightarrow S^1$ .*

PROOF. Let  $r : D^2 \rightarrow S^1$  be a retraction. Then

$$\begin{array}{ccc} & D^2 & \\ i \nearrow & & \searrow r \\ S^1 & \xrightarrow{\text{id}} & S^1 \end{array}$$

commutes. Then we apply the functor  $\pi_1$  to get:

$$\begin{array}{ccc} & \pi_1(D^2, 1) & \\ i_* \nearrow & & \searrow r_* \\ \pi_1(S^1, 1) & \xrightarrow{\text{id}_*} & \pi_1(S^1, 1) \end{array} = \begin{array}{ccc} & 0 & \\ & \searrow & \\ \mathbb{Z} & \xrightarrow{\quad} & \mathbb{Z} \end{array}$$

which is a contradiction.  $\square$

COROLLARY 2.1. *Every map  $D^2 \rightarrow D^2$  has a fixed point.*

### 3. Dependence of $\pi_1$ on the basepoint

Let  $\alpha : I \rightarrow X$  be a path from  $x_0$  to  $x_1$ . Define  $\alpha_{\#} : \pi_1(X, x_0) \rightarrow \pi_1(X, x_1)$  by

$$\alpha_{\#}[\sigma] = [\bar{\alpha}][\sigma][\alpha] = [\bar{\alpha} * \sigma * \alpha] .$$

The point is that we take a loop at one basepoint and attach this path on both ends (with one reversed) to get a loop at the other basepoint.

THEOREM 2.5. (1)  $\alpha_{\#}$  is an isomorphism.

(2)  $\alpha \simeq \beta \text{ (rel } \partial I)$  implies  $\alpha_{\#} = \beta_{\#}$ .

(3)  $(\alpha * \beta)_{\#} = \beta_{\#} \alpha_{\#}$ .

(4) If  $f : X \rightarrow Y$  is a map then

$$\begin{array}{ccc} \pi_1(X, x_0) & \xrightarrow{f_*} & \pi_1(Y, f(x_0)) \\ \downarrow \alpha_{\#} & & \downarrow (f\alpha)_{\#} \\ \pi_1(X, x_1) & \xrightarrow{f_*} & \pi_1(Y, f(x_1)) \end{array}$$

commutes.

REMARK 2.3. Professor Cameron learned algebraic topology from Hilton and Wylie. He is surprised he learned anything at all because they decided that since homology is a covariant functor and cohomology is a contravariant functor homology should be cohomology and cohomology should be “contrahomology”. They also wrote all of the maps on the right.

PROOF. (1) We can directly verify  $\alpha_{\#}$  is a homomorphism:

$$\begin{aligned}\alpha_{\#}([\sigma][\tau]) &= [\bar{\alpha}][\sigma][\tau][\alpha] = [\bar{\alpha}][\sigma][c_{x_0}][\tau][\alpha] \\ &= [\bar{\alpha}][\sigma]([\alpha][\bar{\alpha}])[\tau][\alpha] \\ &= \alpha_{\#}([\sigma])\alpha_{\#}([\tau]) .\end{aligned}$$

$\alpha_{\#}$  is a bijection because  $(\bar{\alpha})_{\#}$  is an inverse of  $\alpha_{\#}$ .

(2) Obvious.

(3) Exercise.

(4) Exercise.

□

REMARK 2.4. If  $x_1 = x_0$  then  $\alpha$  is a loop at  $x_0$  so

$$\alpha_{\#}([\sigma]) = [\bar{\alpha}][\sigma][\alpha] = [\alpha]^{-1}[\sigma][\alpha]$$

i.e.  $\alpha_{\#}$  is conjugation by  $\alpha$ .

COROLLARY 2.2. *If  $X$  is path-connected then  $\pi_1(X, x_0)$  is independent of  $x_0$  (up to isomorphism).*

DEFINITION 2.4.  $X$  is *simply connected* if  $X$  is path-connected and  $\pi_1(X) = 1$ .

LEMMA 2.8. *Let  $f, g : X \rightarrow Y$ . Let  $F$  be a homotopy from  $f$  to  $g$ . Let  $\alpha$  be the path  $\alpha(t) = F(x_0, t)$  in  $Y$  from  $f(x_0)$  to  $g(x_0)$ . Then the diagram*

$$\begin{array}{ccc}\pi_1(X, x_0) & \begin{array}{c} \xrightarrow{f_*} \\ \searrow g_* \end{array} & \begin{array}{c} \pi_1(Y, f(x_0)) \\ \cong \downarrow \alpha_{\#} \\ \pi_1(Y, g(x_0)) \end{array}\end{array}$$

*commutes.*

PROOF. Let  $\sigma$  be a loop in  $X$  at  $x_0$ . Let  $H = F(\sigma \times \text{id}) : I \times I \rightarrow Y$ . Pictorially we have:  $H|_{\partial(I \times I)}$  (suitably reparameterized) is a loop in  $Y$  at  $g(x_0)$ . Reading fig. 4 counterclockwise we get

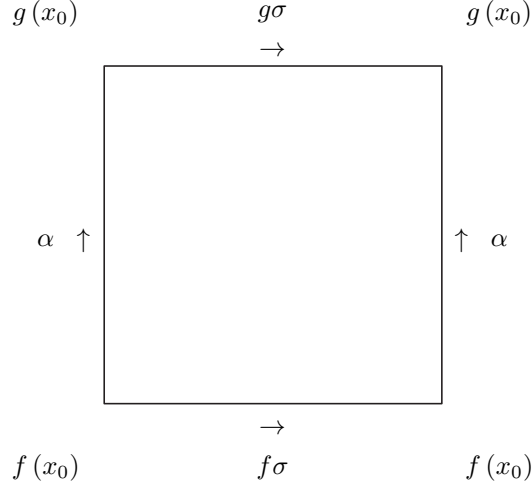
$$[H|_{\partial(I \times I)}] = [\bar{\alpha}][f\sigma][\alpha][g\sigma]^{-1} .$$

But this extends over  $I \times I$  so it is just  $1 \in \pi_1(Y, g(x_0))$ , i.e.  $\alpha_{\#}f_*([\sigma]) = g_*([\sigma])$  which implies  $\alpha_{\#}f_* = g_*$ . □

THEOREM 2.6. *Let  $f : X \rightarrow Y$  be a homotopy equivalence. Then  $f_* : \pi_1(X, x_0) \rightarrow \pi_1(Y, f(x_0))$  is an isomorphism for all  $x_0 \in X$ .*

PROOF. Let  $g : Y \rightarrow X$  be a homotopy inverse of  $f$ . So we get maps

$$\pi_1(X, x_0) \xrightarrow{f_*} \pi_1(Y, f(x_0)) \xrightarrow{g_*} \pi_1(X, gf(x_0))$$

FIGURE 4.  $I \times I$  labelled as in lemma 2.8.

but we have  $gf \simeq \text{id}_X$  which means  $(gf)_* = g_*f_*$  is an isomorphism. by lemma 2.8 and theorem 2.5 (1) so  $g_*$  is onto.

Then we have

$$\pi_1(Y, f(x_0)) \xrightarrow{g_*} \pi_1(X, gf(x_0)) \xrightarrow{f_*} \pi_1(Y, fgf(x_0))$$

and  $fg \simeq \text{id}_Y$  so  $f_*g_*$  is an isomorphism so  $g_*$  is one-to-one. Therefore  $g_*$  is an isomorphism and  $g_*f_*$  is an isomorphism which implies  $f_*$  is an isomorphism.  $\square$

**COROLLARY 2.3.** *IF  $X$  is contractible then  $\pi_1(X, x_0) = 1$  for all  $x_0 \in X$ .*

**PROOF.**  $X$  being contractible is equivalent to  $i : \{x_0\} \hookrightarrow X$  being a homotopy equivalence.  $\square$

#### 4. Fundamental theorem of algebra

**THEOREM 2.7** (Fundamental theorem of algebra). *Every non-constant polynomial with coefficients in  $\mathbb{C}$  has a root in  $\mathbb{C}$ .*

**REMARK 2.5.** Professor Cameron says this topological proof of an algebraic statement should provide topologists some comfort in light of the Poincaré conjecture receiving some sort of proof via PDEs.

**PROOF.** Let  $f(z) = z^n + a_{n-1}z^{n-1} + \dots + a_0$  for all  $a_i \in \mathbb{C}$  for  $n \geq 1$ . Suppose  $f(z) \neq 0$  for all  $z \in \mathbb{C}$ ; so  $a_0 \neq 0$ . So  $f$  is a map  $\mathbb{C} \rightarrow \mathbb{C} \setminus \{0\}$ .

The idea of the proof is as follows. As  $|z| \rightarrow \infty$  somehow  $f \simeq z^n$ , i.e.  $f \simeq \mu_n$  and similarly as  $|z| \rightarrow 0$  somehow  $f \simeq a_0$ , i.e.  $f \simeq c_{a_0}$  but this implies  $\mu_n \simeq c_{a_0}$  which is a contradiction. Now we make this precise.

Let  $R \in \mathbb{R}$ ,  $R \geq 0$ . Define  $F : S^1 \times I \rightarrow S^1$  by

$$F(z, t) = F_t(z) = \frac{f(tRz)}{|f(tRz)|}.$$

Note that  $F_0(z) = 1$  so  $F_0 = c_1$ .

Let

$$g(z) = a_{n-1}z^{n-1} + \dots + a_0$$

so  $f(z) = z^n + g(z)$ . Choose

$$R > \max \left\{ 1, \sum_{k=0}^{n-1} |a_k| \right\} .$$

Then if  $|z| = R$

$$|g(z)| \leq \sum_{k=0}^{n-1} |a_k z^k| = \sum_{k=0}^{n-1} |a_k| R^k \leq {}^{2.2} \left( \sum_{k=0}^{n-1} |a_k| \right) R^{n-1} < R^n = |z|^n .$$

Therefore for all  $t \in I$

$$|z^m + tg(z)| \geq |z|^n - t|g(z)| \geq |z|^n - |g(z)| > 0 .$$

Let  $h_t(z) = z^n + tg(z)$ . So  $h_0(z) = z^n$  and  $h_1(z) = f(z)$ .

So define  $H : S^1 \times I \rightarrow S^1$  by

$$H(z, t) = \frac{h_t(Rz)}{h_t(Rz)}$$

and

$$H_1(z) = \frac{f(Rz)}{|f(Rz)|} = F_1(z) \qquad H_0(z) = \frac{(Rz)^n}{|Rz|^n} = z^n$$

and therefore  $H_0 = \mu_n$ .

Now we can put it all together. We have

$$c_1 = F_0 \simeq F_1 = H_1 \simeq H_0 = \mu_n$$

so  $c_1 \simeq \mu_n$ . Therefore by lemma 2.8

$$\begin{array}{ccc} & \pi_1(S^1, 1) & \\ \mu_{n*} \nearrow & \downarrow \alpha_{\#} & \nearrow \times n \\ \pi_1(S^1, 1) & & \mathbb{Z} \\ c_{1*} \searrow & & \downarrow 0 \\ & \pi_1(S^1, 1) & \mathbb{Z} \end{array} = \begin{array}{ccc} & \mathbb{Z} & \\ \times n \nearrow & & \downarrow \simeq \\ \mathbb{Z} & & \mathbb{Z} \\ 0 \searrow & & \downarrow \end{array}$$

which is a contradiction. Note  $\alpha_{\#}$  is conjugation by  $[\alpha]$ , but  $\mathbb{Z}$  is abelian so this is just the identity.  $\square$

## 5. Cartesian products

If  $f : Z \rightarrow X$  and  $g : Z \rightarrow Y$  are maps, let  $(f, g) : Z \rightarrow X \times Y$  be the map given by

$$(f, g)(z) = (f(z), g(z)) .$$

We will use the same notation for group homomorphisms. Let  $p : X \times Y \rightarrow X$  and  $q : X \times Y \rightarrow Y$  be the projections.

**THEOREM 2.8.**  $(p_*, q_*) : \pi_1(X \times Y, (x_0, y_0)) = \pi_1(X, x_0) \times \pi_1(Y, y_0)$ .

**PROOF.** Exercise.  $\square$

**EXAMPLE 2.3.**  $\pi_1(T^n) \simeq \mathbb{Z}^n$ .

---

<sup>2.2</sup>Since  $R > 1$

**6. Retractions**

Consider some  $i : A \hookrightarrow X$  and some  $a_0 \in A$ . Suppose there exists a retraction  $r : X \rightarrow A$ . Then we get a commutative diagram

$$\begin{array}{ccc} & \pi_1(X, a_0) & \\ i_* \nearrow & & \searrow r_* \\ \pi_1(A, a_0) & \xrightarrow{\text{id}} & \pi_1(A, a_0) \end{array}$$

i.e.  $r_* i_* = \text{id}$  so therefore  $i_*$  is one-to-one and  $r_*$  is onto.



## CHAPTER 3

### Van Kampen's theorem

The idea is to calculate the fundamental group of  $X = X_1 \cup X_2$  from the data of the groups  $\pi_1(X_1)$ ,  $\pi_1(X_2)$ ,  $\pi_1(X_1 \cap X_2)$  and the associated inclusion maps. These always fit into the diagram:

$$\begin{array}{ccc} \pi_1(X_1 \cap X_2) & \xrightarrow{i_{1*}} & \pi_1(X_1) \\ \downarrow i_{2*} & & \downarrow j_{1*} \\ \pi_1(X_2) & \xrightarrow{j_{2*}} & \pi_1(X) \end{array} \quad .$$

Lecture 6;  
September 24, 2019

#### 1. Basic combinatorial group theory

**1.1. Free products.** Let  $A$  and  $B$  be groups. The free product is a group  $D$  and homomorphisms  $i_A : A \rightarrow D$  and  $i_B : B \rightarrow D$  such that given a group  $G$  and homomorphisms  $\alpha : A \rightarrow G$  and  $\beta : B \rightarrow G$ , there exists a unique homomorphism  $\varphi : D \rightarrow G$  such that  $\varphi i_A = \alpha$  and  $\varphi i_B = \beta$ ; i.e. the following push-out diagram commutes:

$$\begin{array}{ccc} A & & \\ \downarrow i_A & \searrow \varphi & \\ B \xrightarrow{i_B} D & \xrightarrow{\quad} & G \end{array} \quad .$$

REMARK 3.1. This is the coproduct in the category **Grp**.

LEMMA 3.1. *If  $D$  exists then it is unique (up to unique isomorphism).*

PROOF. If  $D, D'$  are free products of  $A$  and  $B$  there exist unique  $\varphi, \psi$  as shown:

$$\begin{array}{ccc} D' & \xleftarrow{i'_A} & A \\ \uparrow i'_B & \swarrow \psi & \downarrow i_A \\ B & \xrightarrow{i_B} & D \end{array}$$

□

Now we can write *the* free product of  $A$  and  $B$  as  $A * B$ , and say  $A$  and  $B$  are the *factors* of  $A * B$ .

THEOREM 3.1. *Free products exist.*

PROOF. Define  $A * B$  to be the set of all sequences  $x = (x_1 x_2 \dots x_m)$  for  $m \geq 0$  where  $x_i \in A$  or  $B$ ;  $x_i \neq 1$ ; and  $x_i$  and  $x_{i+1}$  are in different factors.  $m$  is the *length* of  $x$ , 1 is the empty sequence.

Define the product of two sequence by

$$(x_1 \dots x_m)(y_1 \dots y_n) = \begin{cases} (x_1 \dots x_m y_1 \dots y_n) & x_m, y_1 \in \text{different fac.} \\ (x_1 \dots x_{m-1} (x_m y_1) y_2 \dots y_n) & x_m, y_1 \in \text{same fac., } x_m y_1 \neq 1 \\ (x_1 \dots x_{m-1}) (y_2 \dots y_n) & x_m, y_1 \in \text{same fac., } x_m y_1 = 1 \end{cases} .$$

Then  $x1 = 1x = x$  for all  $x \in A * B$ . Define the inverse  $x^{-1} = (x_m^{-1} \dots x_1^{-1})$ , then  $xx^{-1} = 1 = x^{-1}x$  for all  $x \in A * B$ .

So we just have to check associativity.  $x(yz) = (xy)z$ . We induct on  $n$  (where  $n$  is the length of  $y$ ).  $n = 0$  is trivial. For  $n = 1$ , WLOG  $y = (a)$  for  $a \in A$ ,  $a \neq 1$ . Then there are several cases, e.g.

- $x_m \in B$ ,  $z_1 \in B$ ;
- $x_m \in B$ ,  $z_1 \in A$ ;
- ...

For  $n > 1$ ,  $y = y'y''$  where the length of  $y'$  and  $y''$  are less than  $n$ . Then by induction

$$(xy)z = (x(y'y''))z = ((xy')y'')z = (xy')(y''z) .$$

On the other hand

$$x(yz) = x((y'y'')z) = x(y'(y''z)) = (xy')(y''z)$$

so  $A * B$  is a group.

Now we see it has the universal properties. Define  $i_A : A \rightarrow A * B$  by  $i_A(a) = (a)$  and similarly for  $B$ . Given  $\alpha : A \rightarrow G$  and  $\beta : B \rightarrow G$  then define  $\varphi : A * B \rightarrow G$  by

$$\varphi(x_1 \dots x_m) = \gamma(x_1) \dots \gamma(x_m)$$

where  $\gamma_i = \alpha$  if  $x_i \in A$  and  $\gamma_i = \beta$  if  $x_i \in B$ . Therefore  $\varphi$  is unique as a homomorphism and it has the desired properties:

$$\varphi i_A = \alpha \qquad \varphi i_B = \beta .$$

□

REMARK 3.2.  $i_A$  and  $i_B$  are actually injective in this case. For general pushouts they won't be. This means we can identify  $A$  and  $B$  with their images in  $A * B$ . In other words we can drop the parentheses. Each element in  $A * B$  has a unique expression as  $x_1 \dots x_m$  for  $x_i \in A$  or  $B$ ;  $x_i \neq 1$ ;  $x_i, x_{i+1}$  in different factors. This is called a *reduced word* in  $A$  and  $B$ . We say  $A * B$  is a non-trivial free product if  $A \neq \text{id} \neq B$ .

EXAMPLE 3.1.  $\mathbb{Z}/2\mathbb{Z} * \mathbb{Z}/2\mathbb{Z} = \{1, a, b, ab, ba, aba, bab, abab, \dots\}$ .

REMARK 3.3. A non-trivial free product is infinite:  $a \in A \setminus \{1\}$ ,  $b \in B \setminus \{1\}$ , then  $ab$  has infinite order in  $A * B$ .

REMARK 3.4. We can define free product  $* A_\lambda$  for any collection  $\{A_\lambda\}$  of groups. As a special case we can take  $A_\lambda = \mathbb{Z}$  for all  $\lambda$ , then write  $x_\lambda$  for the generator of  $A_\lambda$ . Then  $* A_\lambda$  is the *free group on the set*  $X = \{x_\lambda\}$ , written  $F(X)$ .

Any function  $\{x_{\lambda_0}\} \rightarrow G$  extends to a unique homomorphism  $\mathbb{Z} = \mathbb{Z}(x_{\lambda_0}) \rightarrow G$ . So  $F(X)$  is characterized by the following. For any group  $G$  and any function  $f : X \rightarrow G$ , there exists unique homomorphism  $\varphi : F(X) \rightarrow G$  such that

$$\begin{array}{ccc} X & \xrightarrow{f} & G \\ \downarrow i & \nearrow \varphi & \\ F(X) & & \end{array}$$

commutes.

Note that every element of  $F(X)$  has a unique expression as a reduced word

$$x_{\lambda_1}^{n_1} x_{\lambda_2}^{n_2} \dots x_{\lambda_m}^{n_m}$$

where  $\lambda_i \neq \lambda_{i+1}$  and  $n_i \in \mathbb{Z}$ ,  $n_i \neq 0$ .

DEFINITION 3.1.  $(X : R)$  is a *presentation* of the group  $G$  if  $R \subset F(X)$  and there exists an epimorphism  $\varphi : F(X) \rightarrow G$  such that  $\ker \varphi = N(R)$  is the normal closure of  $R$  in  $F(X)$ , the smallest normal subgroup of  $F(X)$  that contains  $R$ , i.e. the set of all products of conjugates of elements in  $R$  and their inverses:

$$\left\{ \prod_{i=1}^k u_i^{-1} r_i^{\epsilon_i} u_i \mid u_i \in F(X), r_i \in R, \epsilon_i = \pm 1 \right\}.$$

THEOREM 3.2. *Every group has a presentation.*

PROOF. Let  $Y = \{y_\lambda\}$  be any set of generators of  $G$ . (Worst case we could take  $Y = G$ .) Let  $X = \{x_\lambda\}$  and define a function  $f : X \rightarrow G$  by mapping  $f(x_\lambda) = y_\lambda$ .  $f$  extends to a homomorphism  $\varphi : F(X) \rightarrow G$  which is onto (since  $Y$  generates  $G$ ). (Worst case take  $R = \ker \varphi$ .)  $\square$

DEFINITION 3.2.  $G$  is *finitely generated* iff there exists a finite set of generators for  $G$ , iff  $G$  has a presentation  $(X : R)$  with  $X$  finite.

$G$  is *finitely presentable* iff there exists a presentation  $(X : R)$  of  $G$  with  $X$  and  $R$  finite.

If  $(X : R)$  is a presentation of  $G$  we say  $R$  is the set of relators, and  $X$  is the set of generators. We often suppress  $\varphi$ , i.e. we regard  $X \subset G$ , and write  $r = 1$  ( $r \in R$ ) to indicate that  $\varphi(r) = 1 \in G$ . We also write  $G = \langle X : R \rangle$ . Write  $(\{x_1, \dots\} : \{r_1, \dots\})$  as  $(x_1, \dots : r_1, \dots)$ .

- EXAMPLE 3.2. (1)  $\langle X : \emptyset \rangle \cong F(X)$ ,  
 (2)  $\langle \{x\} \mid x^n = 1 \rangle \cong \mathbb{Z}_{|n|}$ ,  
 (3)  $\langle \{x, y\} \mid xy = yx \rangle \cong \mathbb{Z} \times \mathbb{Z}$ ,  
 (4)  $\langle a, b \mid a^n = 1, b^2 = 1, b^{-1}ab = a^{-1} \rangle$

THEOREM 3.3. *If  $X \cap Y = \emptyset$  then  $\langle X \mid R \rangle * \langle Y \mid S \rangle \cong \langle X \cup Y \mid R \cup S \rangle$ .*

EXAMPLE 3.3.  $\mathbb{Z}/2\mathbb{Z} * \mathbb{Z}/2\mathbb{Z} \cong \langle a, b \mid a^2 = b^2 = 1 \rangle$ .

- EXERCISE 1.1. (1) Show  $\langle x, y \mid x^{-1}yx = y^2, y^{-1}xy = x^2 \rangle$  is trivial.  
 (2) Is  $\langle x, y, z \mid x^{-1}yx = y^2, y^{-1}zy = z^2, z^{-1}xz = x^2 \rangle$  trivial?  
 (3) Is  $\langle x, y, z, w \mid x^{-1}yx = y^2, y^{-1}zy = z^2, z^{-1}wz = w^2, w^{-1}xw = x^2 \rangle$  trivial?  
 (4) Show  $\langle x, y \mid xyx = yxy, x^n = y^{n+1} \rangle$  is trivial for  $n \geq 0$ .

These are called balanced presentations of the trivial group because the set of relators is the same size as the set of generators.

CONJECTURE 1. *Every balanced presentation can be taken to the trivial balanced presentation under some particular “moves”.*

REMARK 3.5. Dealing with groups via their finite presentations is notoriously difficult. It is an unsolvable problem to find whether a group is trivial based only on a presentation. There is not algorithm which determines whether a group is trivial from its finite presentation.

REMARK 3.6. Novikov and Boone proved this unsolvability independently. Boone was at UIUC at the time. He had only one copy of his manuscript and when he biked home in the snow, he lost it. So he summoned his graduate students to find it.

**1.2. Push-outs.** Let  $A$ ,  $B$ , and  $C$  be groups with homomorphisms  $j_A : C \rightarrow A$ ,  $j_B : C \rightarrow B$ . Then a push-out of this diagram is a group  $D$  and homomorphisms  $i_A : A \rightarrow D$  and  $i_B : B \rightarrow D$  such that  $i_A j_A = i_B j_B$ , and given a group  $G$  and homomorphisms  $\alpha : A \rightarrow G$ ,  $\beta : B \rightarrow G$  such that  $\alpha j_A = \beta j_B$  there exists a unique homomorphism  $\varphi : D \rightarrow G$  such that  $\varphi i_A = \alpha$  and  $\varphi i_B = \beta$ . In other words, the following diagram commutes:

$$\begin{array}{ccc} C & \xrightarrow{j_A} & A \\ \downarrow j_B & & \downarrow i_A \\ B & \xrightarrow{i_B} & D \end{array} \quad \begin{array}{c} \searrow \alpha \\ \nearrow \beta \\ \downarrow \varphi \end{array} \quad \begin{array}{c} \\ \\ G \end{array} .$$

THEOREM 3.4. *Push-outs exist.*

PROOF. Consider  $A * B$  (regard  $A, B \subset A * B$ ). Let

$$N = N \left( \left\{ j_A(c) j_B(c)^{-1} \mid c \in C \right\} \right) \triangleleft A * B .$$

Let  $q : A * B \rightarrow A * B / N$  be quotient homomorphisms. Define  $i_A = q|_A$ ,  $i_B = q|_B$ . Then  $A * B / N$  is the pushout.  $\square$

REMARK 3.7. In the case  $A * B$  (i.e.  $C = 1$ ),  $i_A$  and  $i_B$  are injective. This is not true in an arbitrary pushout.

COUNTEREXAMPLE 1. Consider  $\mathbb{Z}(y) \xleftarrow{0} \mathbb{Z} \xrightarrow{\text{id}} \mathbb{Z}(x)$ . Then the pushout is  $\langle x, y \mid x = 1 \rangle \simeq \mathbb{Z}$ :

$$\begin{array}{ccc} \mathbb{Z} & \xrightarrow{\text{id}} & \mathbb{Z}(x) \\ \downarrow 0 & & \downarrow 0 \\ \mathbb{Z}(y) & \xrightarrow{\text{id}} & \mathbb{Z} \end{array}$$

so  $i_A$  is not injective.

If  $j_A$  and  $j_B$  are injective, then  $i_A$  and  $i_B$  are injective. The pushout is called the free product of  $A$  and  $B$  amalgamated along  $C$ ,  $A *_C B$ .

EXAMPLE 3.4. Take  $\mathbb{Z} \xleftarrow{q} \mathbb{Z} \xrightarrow{p} \mathbb{Z}$  for  $p, q \geq 2$ . Then the pushout is:

$$\begin{array}{ccc} \mathbb{Z} & \xrightarrow{\times p} & \mathbb{Z}(x) \\ \downarrow \times q & & \downarrow \\ \mathbb{Z}(y) & \longrightarrow & \mathbb{Z} *_\mathbb{Z} \mathbb{Z} \end{array}$$

where  $\mathbb{Z} *_\mathbb{Z} \mathbb{Z} = \langle x, y \mid x^p = y^q \rangle$ .

Lecture 7;  
September 26, 2019

THEOREM 3.5. *Push-outs exist.*

PROOF. So we need to show that given  $B \leftarrow C \rightarrow A$  we have:

$$\begin{array}{ccc} C & \xrightarrow{j_A} & A \\ \downarrow j_B & & \downarrow i_A \\ B & \xrightarrow{i_B} & D \end{array} \quad \begin{array}{c} \searrow \alpha \\ \nearrow \beta \\ \searrow \varphi \end{array} \quad \begin{array}{c} \\ \\ G \end{array} .$$

Define

$$N = N \left( \left\{ j_A(c) j_B(c)^{-1} \mid c \in C \right\} \right) \triangleleft A * B .$$

where we regard  $A, B < A * B$ . Let  $q : A * B \rightarrow A * B / N$  be the quotient homomorphism and let  $i_A = q|_A$  and  $i_B = q|_B$ . Then the diagram certainly commutes.

CLAIM 3.1. This is the push-out.

PROOF. Given  $\alpha : A \rightarrow G$  and  $\beta : B \rightarrow G$  such that  $\alpha j_A = \beta j_B : C \rightarrow G$  there exists  $\psi : A * B \rightarrow G$  such that  $\psi|_A = \alpha$  and  $\psi|_B = \beta$  by theorem 3.1.

Now  $\alpha j_A = \beta j_B$  implies that  $\psi j_A = \psi j_B$ , which means  $\psi(j_A(c) j_B(c)^{-1}) = 1$  for all  $c \in C$ , which means  $\psi(N) = 1$ . This means  $\psi$  induces  $\varphi : A * B / N \rightarrow G$ , i.e.

$$\begin{array}{ccc} A * B & \xrightarrow{q} & A * B / N \\ & \searrow \psi & \swarrow \varphi \\ & G & \end{array}$$

commutes. I.e.  $\varphi q|_A = \alpha$  and  $\varphi q|_B = \beta$ , i.e.  $\varphi i_A = \alpha$  and  $\varphi i_B = \beta$ . Then  $A \cup B$  generates  $A * B$ , and therefore  $q(A) \cup q(B)$  generates  $A * B / N$ . Then  $\varphi$  is determined by  $\varphi|_{q(A)}$  and  $\varphi|_{q(B)}$ . But we have to define  $\varphi q|_A = \alpha$  and  $\varphi q|_B = \beta$  and therefore  $\varphi$  is unique.  $\square$

■

REMARK 3.8. It follows from theorem 3.3 that if  $A = \langle X \mid R \rangle$  and  $B = \langle Y \mid S \rangle$  then the pushout is

$$\langle X \cup Y \mid R \cup S, j_A(c) = j_B(c), \forall c \in C \rangle .$$

We could also replace  $C$  by any set generating  $C$ .

REMARK 3.9. Push-outs are defined and exist for  $\{A_\lambda, j_\lambda : C \rightarrow A_\lambda\}$ .

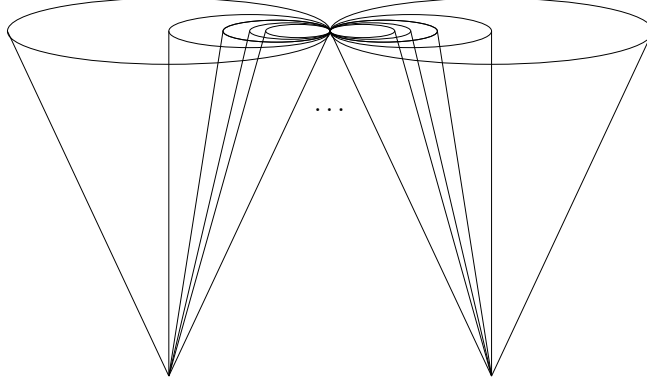


FIGURE 1. The cone of two Hawaiian earrings joined at a point. This has nontrivial fundamental group even though it is the union of two things with trivial fundamental group.

## 2. Statement of the theorem

THEOREM 3.6 (van Kampen's theorem). *Suppose  $X = X_1 \cup X_2$ , with  $X_1, X_2, X_1 \cap X_2$  open and path-connected. Let  $x_0 \in X_1 \cap X_2$ . Then  $\pi_1(X, x_0)$  is the push-out:*

$$\begin{array}{ccc} \pi_1(X_1 \cap X_2, x_0) & \longrightarrow & \pi_1(X_1, x_0) \\ \downarrow & & \downarrow \\ \pi_1(X_2, x_0) & \longrightarrow & \pi_1(X, x_0) \end{array}$$

where all homomorphisms are induced by inclusions.

REMARK 3.10. (1) There exists an analogous statement when  $X = \cup_\lambda X_\lambda$ .

(2) In practice, one often applies theorem 3.6 when  $X_1$  and  $X_2$  are closed in  $X$  but where  $X_i$  has an open subsets  $U_i \subset X$  such that there exists a strong deformation retractions of pairs:

$$(U_1, U_1 \cap X_2) \rightarrow (X_1, X_1 \cap X_2) \quad (U_2, U_2 \cap X_1) \rightarrow (X_2, X_1 \cap X_2) .$$

(3) Theorem 3.6 is false without the openness assumption. The counterexample is the double cone of the wedge of two Hawaiian earrings as in fig. 1. If we take each cone of an earring to be one of the  $X_i$  then the intersection is a point, so it satisfies all of the assumptions except the openness. But notice that each of the  $X_i$  is contractible since cones are always contractible. However  $\pi_1(X_1 \cup X_2) \neq 1$  because the two earrings themselves form a nontrivial loop.

COROLLARY 3.1. *Let  $X_1, X_2$  be as in theorem 3.6. Then  $\pi_1(X_1) = \pi_1(X_2) = 1$  which implies  $\pi_1(X) = 1$ .*

COROLLARY 3.2. *If  $n \geq 2$  then  $\pi_1(S^n) = 1$ .*

PROOF. We can write  $S^n = D_+^n \cup D_-^n$  where  $D_+ \cap D_- \cong S^{n-1}$ . For  $n \geq 2$   $S^{n-1}$  is path-connected and  $D^n$  is contractible, so  $\pi_1(D_+) = \pi_1(D_-) = 1$ .  $\square$

COROLLARY 3.3. *If  $\pi_1(X_1 \cap X_2) = 1$  then  $\pi_1(X) = \pi_1(X_1) * \pi_1(X_2)$ .*

### 3. Cell complexes

Let  $Y$  be a topological space and  $f : S^{n-1} \rightarrow Y$  a map. Then the quotient space

$$X = (D^n \amalg Y) / (x \sim f(x), \forall x \in S^{n-1})$$

is obtained from  $Y$  by attaching an  $n$  cell, and  $f$  is the attaching map.

Note that  $X$  has the quotient topology, i.e. if  $q : D^n \amalg Y \rightarrow X$  is the quotient map, then  $U \subset X$  is open iff  $q^{-1}(U) \subset D^n \amalg Y$  is open. Also note that one can similarly add multiple  $n$ -cells to  $Y$  via maps  $f_\lambda : S_\lambda^{n-1} \rightarrow Y$ .

An  $n$ -complex (or  $n$ -dimensional CW complex) is defined inductively by:

- a  $-1$ -complex is  $\emptyset$ ,
- an  $n$ -complex is a space obtained by attached a collection of  $n$ -cells to an  $n-1$ -complex so a  $0$ -complex is a discrete set of points.

An  $n$ -complex is finite if there exists only finitely many cells. Note that we can define an inf-dimensional CW-complex by setting

$$X = \bigcup_{n=0}^{\infty} X_n$$

for  $X_n$  an  $n$ -complex such that  $X_i \subset X_{i+1}$  for all  $i$ . Note that  $U \subset X$  is open iff  $U \cap X_n$  is open for all  $n$ .

For  $X$  a cell-complex define the  $n$ -skeleton of  $X$ ,  $X^{(n)}$ , to be the union of all cells of dimension  $\leq n$ .

EXAMPLE 3.5. The same space might have multiple cell decompositions. Consider  $S^2$ . We can think of this as a cell-complex as being one  $0$ -cell, one  $1$ -cell, and two  $2$ -cells (hemispheres). A more simple way of seeing this is one  $0$ -cell and a  $2$ -cell with the entire boundary mapping to the point.

#### 3.1. Effect of adding a cell on the fundamental group.

EXAMPLE 3.6. Consider  $X = Y \cup$  some  $2$ -cell, i.e.  $X = Y \cup_f D^2$  where  $f$  is the attaching map. Let  $u \in D^2$ . Then define  $X_1 = Y \cup_f (D^2 \setminus \{0\})$  and  $X_2 = \text{int}(D^2) \subset X$ . This means  $X_1$  and  $X_2$  are open in  $X$ ,  $X = X_1 \cup X_2$ , and

$$X_1 \cap X_2 = \text{int}(D^2) \setminus \{0\} \simeq S^1 \times \mathbb{R} \simeq S^1.$$

By van Kampen  $\pi_1(X)$  is the push-out of

$$\mathbb{Z} \simeq \pi_1(X_1 \cap X_2) \xrightarrow{j_{2*}} \pi_1(X_1)$$

$$\pi_1(X_2) = 1$$

Let  $w \in \pi_1(Y) = \pi_1(Y, f(1))$  be the element represented by  $f : S^1 \rightarrow Y$ . We have a strong deformation retraction  $D^2 \setminus \{0\} \rightarrow S^1$ , which induces a strong deformation retraction  $X_1 \rightarrow Y$  so  $j_{1*}(z) = w$  and

$$\boxed{\pi_1(X) / N(w)}.$$

Similarly, if we attach a collection of  $2$ -cells we get  $\pi_1(X) / N(\{w_\lambda\})$ .

REMARK 3.11. The same argument shows, using the fact that  $\pi_1(S^{n-1}) = 1$  ( $n \geq 3$ ) that if  $X = Y \cup$  some  $n$ -cells then the inclusion map  $\pi_1(Y) \rightarrow \pi_1(X)$  is an isomorphism.

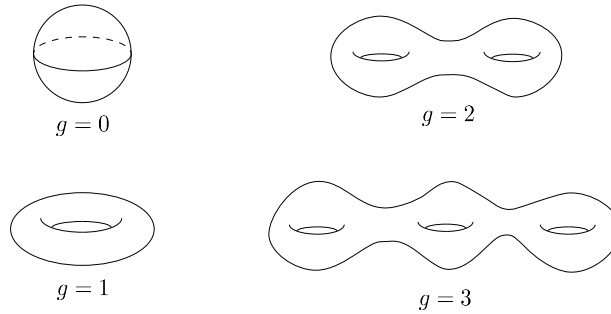


FIGURE 2. The first few closed orientable surfaces.

EXAMPLE 3.7. Let

$$X = \bigvee_{\lambda} S_{\lambda} .$$

We can consider the open set around the common point:

$$U = \bigcup_{\lambda} I_{\lambda} \subset X$$

where each  $I_{\lambda}$  is an open interval in the  $S_{\lambda}$  around the common point. So attach this  $U$  to each circle:

$$X_{\lambda} = S_{\lambda}^1 \cup U$$

and then apply van Kampen's theorem to get:

$$\pi_1(X) = *_{\lambda} \pi_1(X_{\lambda}) = *_{\lambda} \mathbb{Z} = F(\{x_{\lambda}\}) .$$

Recall a closed  $n$ -dimensional manifold  $M$  is a compact metric space such that every  $x \in M$  has a neighborhood homeomorphic to  $\mathbb{R}^n$ . Then a *surface* is a connected, closed 2-manifold.

Lecture 8; October 1, 2019

If  $S_1$  and  $S_2$  are two surfaces, let  $D_i \subset S_i$  be a disk, define  $S_1 \# S_2$  (the *connect sum* of  $S_1$  and  $S_2$ ) to be

$$\text{Cl}((S_1 \setminus D_1)) \cup_f \text{Cl}((S_2 \setminus D_2))$$

where  $f$  is any homeomorphism  $f : \partial D_1 \rightarrow \partial D_2$ . One can show that this is well-defined, i.e. the homeomorphism type of  $S_1 \# S_2$  is independent of all choices.

EXAMPLE 3.8.  $S^2$  and  $T^2$  are surfaces. Then we can take connect sums to get the closed orientable genus 2 surface  $T^2 \# T^2$ , and similarly we get the closed orientable genus 3 surface by taking  $T^2 \# T^2 \# T^2$ . These look as in fig. 2.

The projective plane is given by:

$$\mathbb{P}^2 = S^2 / \{x \sim -x \forall x \in S^2\} .$$

This can be viewed as a Möbius band  $M$  with a disk  $D$  attached. We could also connect some these together to get what are called the *non-orientable surfaces* (or one-sided surfaces).

THEOREM 3.7. *Any surface is homeomorphic to be exactly one of the above.*



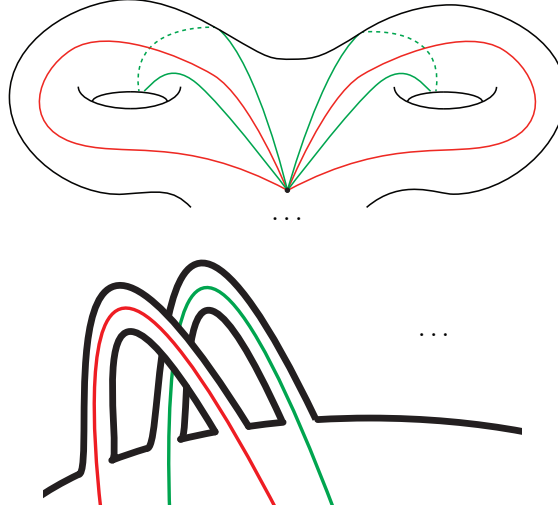


FIGURE 3. Top: Two “handles” of a closed surface. If we take a neighborhood of the two loops in each handle, the complement is just a disk. Bottom: A better picture of the neighborhood of these loops. Note this space strong deformation retracts to the wedge of  $2g$  copies of  $S^1$ .

EXAMPLE 3.9 (Surfaces). Recall  $\pi_1(S^2) = 1$  and  $\pi_1(T^2) = \mathbb{Z}^2$ .

If we consider the wedge of two circles ( $a$  and  $b$ ) we can also build a Torus by attaching a disk, so we get

$$\pi_1(T^2) = \langle a, b \mid aba^{-1}b^{-1} = 1 \rangle \cong \mathbb{Z}^2.$$

For the Klein bottle<sup>3.1</sup> we get  $\langle a, b \mid aba^{-1}b = 1 \rangle$ .

Now we want to calculate the fundamental group of a closed orientable surface of any genus. First consider the  $2g$  curves in fig. 3. Call a neighborhood of these loops  $N$ .  $N$  itself is shown in the bottom of fig. 3. Notice that  $N$  strong deformation retracts to the wedge of  $2g$  circles, so we get:

$$\pi_1(N) = F_{2g} = F(a_1, b_1, \dots, a_g, b_g).$$

For  $f : S^1 \rightarrow \partial N \subset N$  the attaching map we have

$$f_*(\text{gen.}) = \prod_{i=1}^g [a_i, b_i] \in \pi_1(N) = F(a_1, b_1, \dots, a_g, b_g)$$

where  $[g, h] = ghg^{-1}h^{-1}$ . So by van Kampen we get:

$$\pi_1(\#_g T^2) = \left\langle a_1, b_1, \dots, a_g, b_g \mid \prod_{i=1}^g [a_i, b_i] = 1 \right\rangle.$$

Note also that  $\#_g T^2$  can also be viewed as in fig. 4.

This tells us that it is a cell complex with one 0-cell,  $2g$  1-cells, and one 2-cell.

<sup>3.1</sup> The name of the Klein bottle is actually a joke in German based on the German words for surfaces and bottles.

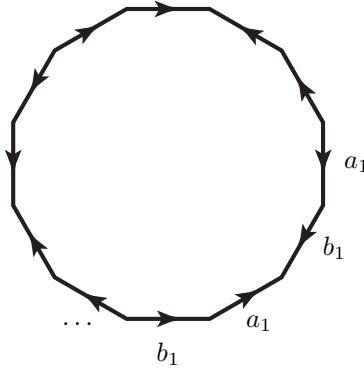


FIGURE 4. We can quotient this polygon to get a closed orientable genus  $g$  surface.

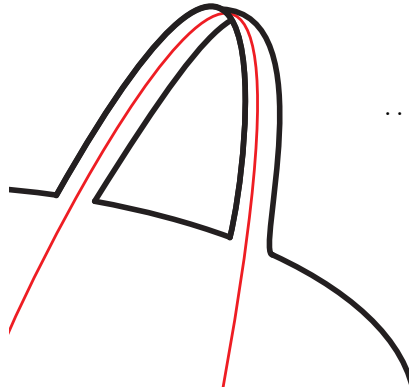


FIGURE 5. We can view the connect sum of  $k$  copies of  $\mathbb{P}^2$  as being a disk glued to this space  $N$ .

EXAMPLE 3.10. Recall  $\mathbb{P}^2 = S^2 / (x \sim -x)$ . We can view  $S^2$  as being two disks glued together along  $S^1 \times I$ . Then we can view  $\mathbb{P}^2$  as a Möbius band  $B$  with a disk glued in. Recall  $\pi_1(B) \simeq \mathbb{Z}$  so this disk kills certain classes and we get

$$\pi_1(\mathbb{P}^2) = \langle x \mid x^2 = 1 \rangle \simeq \mathbb{Z}/2\mathbb{Z}.$$

Now we can connect sum these together to get:

$$\#_k \mathbb{P}^2 \cong N \cup D^2$$

where  $N$  is pictured in fig. 5.

Then by van Kampen we get:

$$\pi_1(\#_k \mathbb{P}^2) = \left\langle a_1, \dots, a_k \mid \prod_{i=1}^k a_i^2 = 1 \right\rangle.$$

We can also view this as a quotient space as in fig. 6.

This tells us this has a cell-composition with one 0-cell,  $k$  1-cells, and one 2-cell.

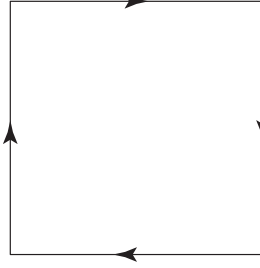


FIGURE 6. We can quotient this square as indicated to get the projective plane. In fact we can view all connect sums of copies of  $\mathbb{P}^2$  as quotients of polygons. This is the non-orientable analogue to fig. 4.

Let  $G$  be a group. Then the *commutator subgroup*,  $[G, G]$ , is the subgroup generated by  $\{[g, h] \mid g, h \in G\}$ . Note that  $[G, G] \triangleleft G$  and  $G/[G, G] = G_{\text{ab}}$  is abelian. Call this the *abelianization* of  $G$ . Let  $A$  be an abelian group and  $\alpha$  be a group homomorphism. Then clearly  $G_{\text{ab}}$  satisfies

$$\begin{array}{ccc} & G_{\text{ab}} & \\ \pi \nearrow & & \searrow \varphi \\ G & \xrightarrow{\alpha} & A \end{array},$$

i.e. there exists a unique  $\varphi : G_{\text{ab}} \rightarrow A$  such that  $\alpha = \varphi\pi$ .

Note that  $[G, G]$  is also a characteristic subgroup, which means  $G \simeq H$  implies  $G_{\text{ab}} \simeq H_{\text{ab}}$ .

**THEOREM 3.8.** *The surfaces listed are pairwise non-homeomorphic.*

**PROOF.**  $(\pi_1(\#_g T^2))_{\text{ab}}$  is the free abelian group on  $2g$  generators, i.e.  $\bigoplus_{2g} \mathbb{Z}$ .

On the other hand,  $(\pi_1(\#_k \mathbb{P}^2))_{\text{ab}}$  is an abelian group with generators  $a_1, \dots, a_k$  with the relation

$$2(a_1 + a_2 + \dots + a_k) = 0.$$

Then  $\{a_1, a_2, \dots, a_1 + a_2 + \dots + a_k\}$  is a  $\mathbb{Z}$  basis for the free abelian group on  $\{a_1, \dots, a_k\}$  which means

$$\boxed{(\pi_1(\#_k \mathbb{P}^2))_{\text{ab}} \cong \mathbb{Z}^{k-1} \oplus \mathbb{Z}_2}$$

therefore the surfaces listed are pairwise non-isomorphic abelianized fundamental group and are therefore not homeomorphic.  $\square$

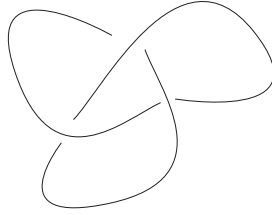


FIGURE 7. (Left) The trefoil knot.

#### 4. Knot groups

A *knot*<sup>3.2</sup> is a smooth subset  $K \subset S^3$  such that  $K \cong S^1$ . See fig. 7 for the example of the trefoil knot. We say  $K_1 \simeq K_2$  if there exists a homeomorphism  $h : S^3 \rightarrow S^3$  such that  $h(K_1) = K_2$ .

The *group of  $K$* ,  $\pi(K) = \pi_1(S^3 \setminus K)$ . Then  $K_1 \sim K_2$  implies  $S^3 \setminus K_1 \cong S^3 \setminus K_2$ , which implies  $\pi(K_1) \cong \pi(K_2)$ .

EXAMPLE 3.11. For  $K$  the unknot, we have  $\pi(K) \cong \mathbb{Z}$ . Essentially using van Kampen's theorem one can then show that the group of the trefoil is

$$\langle a, b \mid aba = bab \rangle$$

which is not  $\mathbb{Z}$ , so it is not the unknot.

In fact we also have:

LEMMA 3.2 (Dehn).  $K$  is trivial iff  $\pi(K) \cong \mathbb{Z}$ .

One might wonder if  $\pi(K) \cong \pi(K')$  implies  $K \sim K'$ . This is not true.

COUNTEREXAMPLE 2. Consider the square knot and granny knot in fig. 8. These have the same group but  $K \not\sim K'$ .

We can also connect sum knots. The idea is to cut out a small piece out of each and then past the gaps together as in fig. 9.

We say  $K$  is prime if  $K = K_1 \# K_2$  implies either  $K_1$  or  $K_2$  is trivial.

THEOREM 3.9. Let  $K$  be prime. Then  $\pi(K) \cong \pi(K')$  implies  $K \sim K'$ .

EXAMPLE 3.12 (Torus knots). Let  $p, q \geq 1$  relatively prime. Then identify the ends of a solid cylinder  $I \times D^2$  by  $2\pi p/q$ . This gives a solid torus for any  $p, q$ . Now take  $q$  arcs in  $S^1 \times I \hookrightarrow D^2 \times I$  given by

$$\left\{ \frac{2\pi k}{q} \right\} \times I$$

for  $k = 0, 1, \dots, q-1$ . In the quotient space  $D^2 \times S^1$ , this gives a circle  $K_{p,q} \subset \partial(D^2 \times S^1)$ . This is called the  $p, q$  torus knot  $T_{p,q} \subset S^3$ . For example the trefoil is  $T_{2,3}$ . another example is in fig. 10.

---

<sup>3.2</sup>Once Professor Gordon was giving a big important talk at a conference about knots. He prepared a joke for the beginning of his talk, which was that it's hard not to give knot puns in your talk. So a nice woman comes up to introduce him and says something along the lines of: "He's talking about knots, not talking about not knots". So he gets up and says the line anyway, for it was just too late. And as he was saying it, he was thinking to himself how bad of an idea it was.

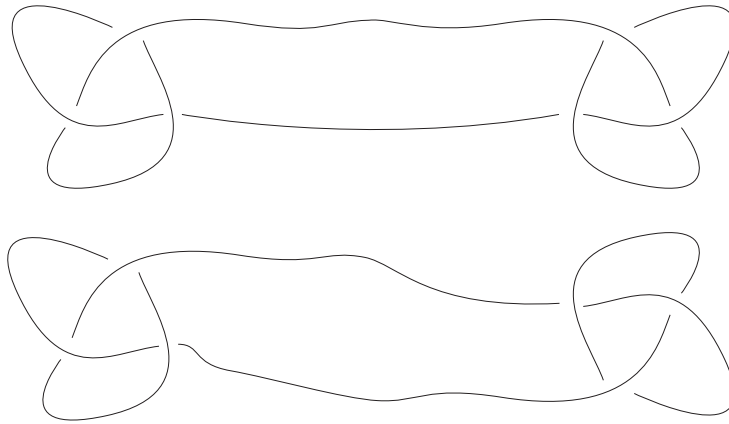


FIGURE 8. The square knot (top) and the granny knot (bottom). They are both connect sums of the trefoil.

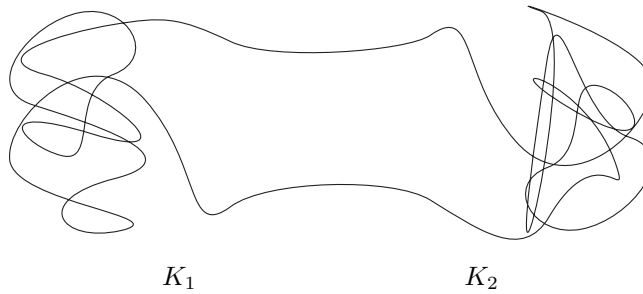


FIGURE 9. The connect sum of two knots  $K_1$  and  $K_2$ .



FIGURE 10. The 5,2 torus knot. (Photo from [the knot atlas](#).)