Spherical varieties

Jackson Van Dyke

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But first... ©

Our building will officially be renamed "PMA"! ©

See here for the full announcement.

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Notation

- k is a field.
- *G* is an algebraic group over *k* (an algebraic variety which is also a group).
- X is an algebraic variety over k equipped with an action of G.



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What are they?

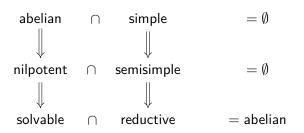
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Why define such a thing?

Where do they show up?

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Map of the zoo



Definition (solvable)

An algebraic group G is solvable if and only if it admits a subnormal series

$$G = G_0 \supset G_1 \supset \cdots \supset G_k = \{1\}$$
 (1)

such that each G_i/G_{i+1} is abelian. In other words it is built out of abelian groups by extensions.

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Simple, semisimple, and reductive

The radical of G, written R(G), is the maximal normal subgroup which is connected, and solvable.

(Such a subgroup exists because extensions and quotients of solvable algebraic groups are solvable.)

Definition 1 (simple)

G is simple if and only if it does not contain any (proper, nontrivial, and connected) normal subgroups.

Definition 2 (semisimple)

G is semisimple if and only if $R(G) = \{1\}$.

Definition 3 (reductive)

G is *reductive* if and only if $R(G) \cong (\mathbb{C}^{\times})^n$ for some *n*.

TI;dr:

Simple = no normal subgroups;	(2)
semisimple = no <u>solvable</u> <u>normal</u> subgroups;	(3)

reductive = solvable normal subgroups are <u>abelian</u>. (4

First observations

- ullet Simple \Longrightarrow semisimple \Longrightarrow reductive.
- G/R(G) is always semisimple.
- If G is abelian then G is reductive.
- If G is solvable and nonabelian then G is not reductive.
- If *G* is unipotent then *G* is not reductive.

Unipotent characterization

Recall an operator T is called *unipotent* if and only if there is some $N \in \mathbb{Z}_+$ such that

$$(T-1)^N=0. (5)$$

An algebraic group is called *unipotent* if it acts by unipotent operators in any rational representation.

Fact 1

G is reductive if and only if it does not contain any normal subgroups which are (proper, connected, and) unipotent.

Just as G/R(G) was semisimple, the quotient of any algebraic group by its maximal normal subgroup which is (connected and) unipotent is reductive.

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Examples of reductive algebraic groups

Example 1

 $(\mathbb{C}^{\times})^n$ is reductive.

Example 2

The algebraic groups

- SL_n (for $n \ge 2$),
- \bullet Sp_{2n}, and
- SO_n (for $k = \overline{k}$)

are all simple, so reductive.

Example 3

 GL_n and O_n are reductive.

Examples which are not reductive

Example 4

The additive group, and product of it, are not reductive. This is because we can view $a \in \mathbb{G}_a$ as

$$\begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix} . (6)$$

So this is actually an unipotent group, and therefore cannot be reductive.

Example 5

The Borel subgroup B of GL_n is not reductive. This consists of upper triangular matrices, and has nontrivial unipotent normal subgroup consisting of upper-triangular matrices with 1 on the diagonal.

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Example of semisimple quotient

The following is from [Mil]. Consider the algebraic group GL_{m+n} . This is given by block matrices

$$\begin{bmatrix} A & B \\ 0 & C \end{bmatrix} \tag{7}$$

where A is $m \times m$ and C is $n \times n$.

The radical consists of matrices of the form:

$$\begin{bmatrix} al_m & B \\ 0 & cl_n \end{bmatrix}$$
 (8)

and the semisimple quotient is:

$$G/R(G) = PGL_m \times PGL_n . (9)$$

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Semi-simple representations

A semisimple (or completely reducible) representation is a direct sum of simple (or irreducible) representations.

link wikipedia



Rep. theoretic characteristic of being reductive

Theorem

Assume char k = 0. G is reductive iff every representation is semisimple.

The direction(\iff) is easy to show. Normal unipotent subgroups of G act trivially on semisimple representations of G. So if G admits a faithful semisimple representation then G is reductive.

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Usual definition of spherical varieties

Definition (spherical variety)

X is a spherical variety if and only if it contains an open dense B orbit.

Now we will identify some equivalent characterizations of spherical varieties. The punchline will be that this is fundamentally some kind of finiteness condition.

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Complexity

Definition (complexity)

The complexity of X, written c(X), is the minimal codimension of a B orbit.

Theorem 1

X is spherical if and only if c(X) = 0.

Proof.

Open dense orbits are the proper codimension 0 orbits.



Finitely many B orbits

Theorem 2

X is spherical if and only if it has finitely many B orbits.

Lemma 2 (Theorem 4.5.5 [Par])

If $Y \subset X$ is a closed B-stable subvariety then $c(Y) \leq c(X)$.

Proof.

 (\Longrightarrow) : Let $Y\subseteq X$ be some minimal subvariety containing infinitely many orbits. Lemma 2 implies c(Y)=0. The complement of this orbit is a closed G-stable subvariety which must have infinitely many B-orbits, contradicting minimality of Y.

 (\Leftarrow) : Nonzero complexity implies infinitely many G orbits (and hence B orbits) since any maximal orbit has nonzero codimension, and orbits are disjoint.

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Borel invariant rational functions

Theorem 3

X is spherical if and only if the only B invariant rational functions are constant: $k(X)^B = 0$.

This follows from Rosenlicht's theorem [Ros63] Theorem 2.3.

Theorem (Rosenlicht)

The transcendence degree of $k(X)^B$ over k is c(X).

The idea is that

$$c(X) = \dim("X/B") \tag{10}$$

= transcendence degree
$$(k("X/B"))$$
 (11)

= transcendence degree
$$(k(X)^B)$$
. (12)

So
$$c(X) = 0$$
 if and only if $k(X)^B = k$.

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TI;dr (equivalent definitions of spherical varieties)

Theorem

The following are equivalent:

- X is spherical (i.e. X contains an open dense B orbit),
- c(X) = 0 (i.e. the maximal B orbit is codimension 0),
- X has finitely many B orbits,
- $k(X)^B = k$.

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Good features of spherical varieties

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