ECE326 PROGRAMMING LANGUAGES

Lecture 18: Concurrent Programming

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Concurrent Programming

- Multiple tasks execute simultaneously
- Thread
 - Independent sequence of execution
 - Has its own stack, but shares the heap with other threads
- Parallel computing
 - Threads executing at same physical time instant
 - Only possible if each thread runs on its own processor
- Concurrency
 - Threads may interleave on the same processor





Purpose

- Speed up program
 - Usually with more people, a job can get done faster
- Criteria for speed up
 - Threads can work relatively independently
 - Seldom need to wait for other threads
 - E.g. to access shared data
 - E.g. to wait for input produced by another thread
 - Threads are often waiting for IO (e.g. read from disk, network)
 - While one thread waits, other threads can still do work on processor
 - Only important if threads are sharing a processor

Closure

- Anonymous function
- Capture
 - Ability to use variables outside of closure
- Syntax
 - parameters... | { body }

```
fn main() {
    let x = 5;
    let plus_x = |y| { x + y }; // x is captured by closure
    let z = plus_x(8);
    println!("x + y = {}", z); // 13
}
```

Concurrent Programming

- Most programming languages provide library support
 - Creating and managing threads done through function calls
- Go has language support for creating threads

```
go f(x, y, z); // starts a new thread (aka goroutine)
```

Concurrent Programming

- Most programming languages provide library support
 - Creating and managing threads done through function calls
 - E.g. Rust, C++, Python

```
use std::thread;
use std::time::Duration;

for i in 1..10 {
    thread::spawn(move || {
        println!("hi number {} from thread!", i);
        thread::sleep(Duration::from_millis(1));
    });
}
```

Ownership

- A thread can potentially live longer than its creator
 - By default, closures borrow outer variables
- Problem arises if closure references outer variable
 - Therefore, all outer variables must be "moved" into closure
 - If variable implements Copy trait, then it will be copied instead

```
fn main() {
    let v = vec![1, 2, 3];
    let handle = thread::spawn(move || {
            println!("Here's a vector: {:?}", v);
      });
    // you may no longer use 'v' here. main may exit first!
}
```

Basics

- A program always starts with one thread: main
- main creates new threads, and those can create more
- Creator should wait for the threads it created to end

```
fn main()
                                                   Does not need move
    let handle = thread::spawn() {
                                                     if not capturing
        for i in 1..10 {
            println!("hi number {} from thread!", i);
            thread::sleep(Duration::from_millis(1));
    println!("hi from main!");
    handle.join().unwrap(); // wait for thread to finish
```

Challenge

- Sharing data
 - Ownership
 - Threads need to jointly own an object
 - Updates to data can result in race condition
 - Caused by problematic interleaving of threads
 - Race condition can lead to unexpected and often incorrect results
 - Difficult to avoid because we cannot control order of thread execution
- Synchronization
 - Threads may need to communicate with each others
 - One thread may need to wait for another thread to advance

Reference Counting

- A commonly used technique to share an object
- Analogy
 - First person to walk into living room turns on TV
 - Subsequent people entering can sit down immediately
 - Last person to leave will turn off the TV
- Reference Counting
 - Creator of object sets reference count to 1
 - Others will increment count before use
 - Everyone decrements count after use
 - If count is 0, free the object

Smart Pointer

- A wrapper class over a pointer, and acts like a pointer
- C++ Example
 - unique_ptr
 - Automatically frees pointed-to object when it goes out of scope
- shared_ptr
 - A reference counting smart pointer
 - Allows multiple threads to share pointed-to object
 - Last reference holder will delete the object
 - May not be the original creator of the object

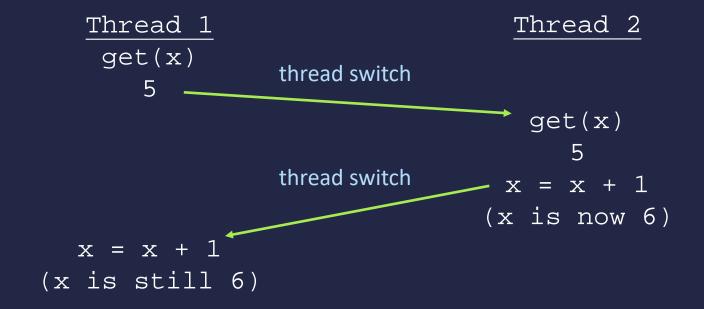
Rc<T>

Allows sharing data in single-threaded setting

```
enum List { Cons(i32, Rc<List>), Nil, }
use List::{Cons, Nil};
use std::rc::Rc;
fn main() {
       let a = Rc::new(Cons(5, Rc::new(Cons(10, Rc::new(Nil))));
       let b = Cons(3, Rc::clone(&a));
       let c = Cons(4, Rc::clone(&a));
                                                          Each time Rc::clone is
                                                         called, reference count
                                                           of a increases by 1.
                a
```

Lost Update

- One potential problem caused by race condition
 - Assume both threads are running on same processor



Solution: atomic instructions

Arc<T>

- Allows sharing data across different threads
 - A in Arc stands for atomic
- Atomic instruction
 - A single, uninterruptible instruction on processor
 - Can complete without interference from other threads
 - Generally not used because it is more expensive (time-wise)
 - E.g. fetch-and-add

```
function FetchAndAdd(address location, int inc) {
    int value := *location
    *location := value + inc
    return value
}
```

Arc<T>

- Arc<T> uses atomic instructions to update counter
 - Unlike regular Rc<T>, which is not thread safe
- Thread safety
 - Function using shared data behaves correctly during simultaneous execution by multiple threads
 - E.g. freedom from race condition

```
use std::sync::Arc;
let foo = Arc::new(vec![1.0, 2.0, 3.0]);
// The two syntaxes below are equivalent.
let a = foo.clone();
let b = Arc::clone(&foo);
// a, b, and foo all point to the same shared memory location
```

Arc<T>

Limitations

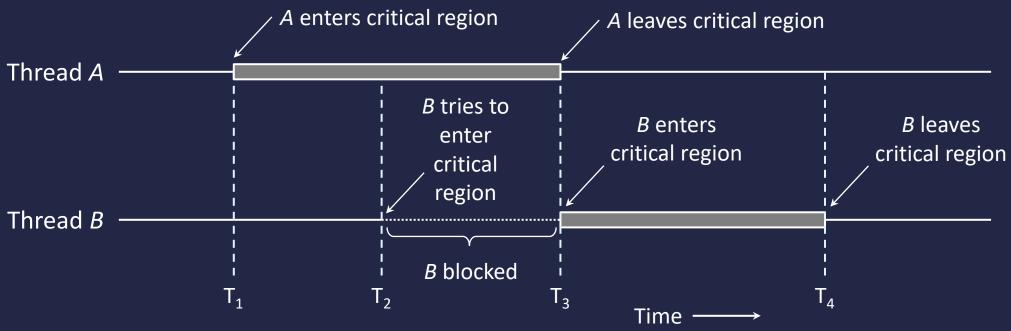
- Arc<T> makes sharing objects thread safe
- However, it does not make using the objects thread safe
 - E.g. methods of the object may be thread unsafe
- Object within Arc<T> is immutable

Need

- A construct that allows shared mutable object
- A construct that makes using objects thread safe

Mutual Exclusion

- Ensures only one thread can access shared data at once
- Critical region
 - Time that a thread uses to update shared data



Mutex<T>

- Provides mutual exclusion
- When mutex is locked, no other threads can use object
 - Locking mutex creates a MutexGuard

Mutex<T>

- Caveat
 - Mutex is not sharable (ownership rule)
- Must be combined with Arc<T>
- Provides interior mutability
 - The mutex is immutable, but the data it contains is mutable

```
let counter = Arc::new(Mutex::new(0));
for _ in 0..10 {
    let counter = Arc::clone(&counter);
    let handle = thread::spawn(move || {
        let mut num = counter.lock().unwrap();
        *num += 1;
    });
}
```

synchronized

Language support in Java for mutual exclusion

```
class ThreadedSend extends Thread {
     private String msg;
     Sender sender; // shared among different threads
     ThreadedSend(String m, Sender obj) {
           msg = m; sender = obj;
     public void run() {
            // Only one thread can send message at a time.
            synchronized(sender) {
                  // synchronizing the send object
                  sender.send(msg);
```

synchronized

Alternatively, can make an entire method critical region

```
class Sender {
    // Same effect as previous slide, only one thread can send
   public synchronized void send(String msg) {
        System.out.println("Sending\t" + msg );
        try {
            Thread.sleep(1000);
        catch (Exception e) {
            System.out.println("Thread interrupted.");
        System.out.println("\n" + msg + "Sent");
```

Polling

- Also known as busy looping
 - Continuously lock shared data to check on condition in a loop
 - OK on multiple processors if wait time is short
 - On uniprocessor, reduces performance of entire system
- Example: bounded buffer problem

```
mutex 1; char buf[n]; // circular buffer

void send(char msg) {
    lock(l);
    /* buffer is full, keep checking if space becomes available */
    while ((in-out+n)%n == n - 1) { unlock(l); lock(l); }
    buf[in] = msg;
    in = (in + 1) % n;
    unlock(l);
}
```

Message Passing

- Threads communicate by sending message with data
- Allows threads to synchronize
 - i.e. thread waits for condition to satisfy before continuing
- Thread sleeps while waiting for message
 - Sleeping thread will not be scheduled to run by OS
- Another thread can wake it up by sending a message
 - Once woken up, thread can check the message

channel<T>

- Creates a sender and a receiver end, thread safe
- Must send/receive same data type

```
use std::thread;
use std::sync::mpsc;
fn main() {
      let (tx, rx) = mpsc::channel();
      thread::spawn(move | {
            let val = String::from("hi");
            tx.send(val).unwrap(); // val moves into send()
      let received = rx.recv().unwrap();
      println!("Got: {}", received);
```

mpsc::channel

- Multiple producers, single consumer
- iteration on rx finishes when channel is closed
 - i.e. when all senders close their end

```
let (tx, rx) = mpsc::channel();
for i in 1..10 {
    let tx = mpsc::Sender::clone(&tx);
    thread::spawn(move || {
        tx.send(String::from("hello")).unwrap();
    });
}
for received in rx {
    println!("Got: {}", received);
}
```

Can clone tx to allow

Monitor

- Allows for both mutual exclusion and synchronization
- Allows for multiple producers and multiple consumers
- Mutual exclusion
 - Provided by a mutex object
- Synchronization
 - Provided by one or more condition variables
 - Allows arbitrary condition for synchronization
 - Thread wait on a condition variable to be signalled
 - Thread sleeps while waiting

Condition Variable

- Allows thread to relinquish lock and go to sleep
- Automatically re-acquires lock prior to wake up

Condvar

- wait(&self, val: MutexGuard)
 - Thread waits until condvar is notified
 - Re-acquire lock on val before waking up
- notify_one(&self)
 - Wakes up exactly one thread waiting on the condvar
 - Equivalent to signal() in other literature
- notify_all(&self)
 - Wakes up all threads waiting on the condvar
 - Equivalent to broadcast() in other literature

Condition Variable

```
use std::sync::{Arc, Mutex, Condvar};
let pair = Arc::new((Mutex::new(false), Condvar::new()));
let pair2 = pair.clone();
thread::spawn(move) {
      let (lock, cvar) = &*pair2;
      let mut started = lock.lock().unwrap();
      *started = true;
      cvar.notify one(); // notify that the value has changed.
let (lock, cvar) = &*pair;
let mut started = lock.lock().unwrap();
while !*started
      // wait for started to become true
      started = cvar.wait(started).unwrap();
```

Multiple producers, multiple consumers problem

```
const MAXLEN: usize = 8;
struct Bounded { buffer: [i32; MAXLEN], top: usize, bottom: usize, }
impl Bounded {
      fn push(& mut self, val: i32) {
             self.buffer[self.top] = val;
             self.top = (self.top + 1) % MAXLEN;
      fn pop(& mut self) -> i32 {
             let val = self.buffer[self.bottom];
             self.bottom = (self.bottom + 1) % MAXLEN;
             val
      fn is_empty(& self) -> bool { self.bottom == self.top }
      fn is_full(& self) -> bool {
             (self.bottom + 1) % MAXLEN == self.top
```

Create a monitor around the bounded buffer

```
use std::sync::{Arc, Mutex, Condvar};
struct Monitor<T> {
                                                         Stores all the handles
       mutex: Mutex<T>,
       empty: Condvar,
                                                          for each thread so we
       full: Condvar,
                                                         can call join() on them.
fn main() {
       let mut threads = vec![];
       let monitor = Arc::new(Monitor {
              mutex: Mutex::new(Bounded {
                     buffer: [0; MAXLEN], top: 0, bottom: 0
              empty: Condvar::new(),
              full: Condvar::new(),
```

Producer threads

```
const NPRODUCER: i32 = 3;
                                        const NPRODUCT: i32 = 10;
for i in 1..=NPRODUCER {
    let monitor = monitor.clone();
    threads.push(thread::spawn(move | {
        for j in 0..NPRODUCT {
            let val = i * 10 + j;
            let Monitor {mutex, empty, full} = &*monitor;
            let mut circ = mutex.lock().unwrap();
            while circ.is_full() {
                                                      Wait for the bounded
                 circ = full.wait(circ).unwrap();__
                                                      buffer to have space.
            circ.push(val);
            empty.notify_all();
                                     Notify consumer
                                    that data is available
```

Consumer threads

```
for i in 1..=NCONSUMER {
                                                     Collect up to 15 pieces
    let monitor = monitor.clone();
                                                        of data and exit.
    threads.push(thread::spawn(move
        let mut v = vec![];
        while v.len() < NCONSUMED</pre>
            let Monitor {mutex, empty, full} = &*monitor;
            let mut circ = mutex.lock().unwrap();
            while circ.is_empty() {
                 circ = empty.wait(circ).unwrap();
            v.push(circ.pop());
            full.notify_all();
        println!("thread {} consumed: {:?}", i, v);
```

Wait for all threads to finish before main exits

```
fn main() {
    let mut threads = vec![];

    /* creating producer and consumer threads */
    for child in threads {
        child.join().unwrap();
    }
}
```

Output

```
thread 1 consumed: [10, 20, 11, 12, 21, 34, 13, 22, 14, 36, 15, 38, 23, 39, 16] thread 2 consumed: [30, 31, 32, 33, 35, 37, 24, 17, 18, 25, 19, 26, 27, 28, 29]
```

Deadlock

- Circular waiting
- Each thread is holding a resource that the other needs to be able to continue (e.g., two pieces of shared data)
- Rust cannot prevent deadlocks
- Possible solutions
 - Lock ordering
 - Always acquire a set of locks in same order
 - Try lock
 - If one of the locks already taken, release all locks you own and restart

