

## CS211 – Hash Tables

### Open Addressing – Methods:

- **Linear Probing:**
  - Move linearly looking for the next available space
    - Start by modding the key value by the hash table size
    - If that slot is full – then move to the next one
    - Repeat until a free slot is found
- **Quadratic Probing:**
  - Systematic jumps to look for a free space, step sizes get bigger and bigger to avoid clustering
    - Start by modding the key value by the hash table size
    - Jump to this slot  $x$
    - If this slot is full, then jump to the slot  $(x + step^2)$ , where step is the step size (1, 2, 3, ... etc)
      - Example: First we probe  $x$ , then  $x + 1$ , then  $x + 4$ , then  $x + 9$
      - $x, x + 1^2, x + 2^2, x + 3^2, etc.$
    - Do this until a free slot is found
- **Double Hashing:**
  - Using a different hash function to generate a unique jump size for items that generated the same hash index
    - Start by modding the key value by the hash table size – **primary hash function**
    - Then use the secondary hash function to generate the step size
      - The step size is given by:  $MAX - (x \% MAX)$  where  $x$  is the given unique key

**Load Factor:** The ratio between the size of the hash table and the number of items in it:

- Load Factor of 1 = as many items as there are slots
- Load Factor of 0 = hash table is empty
- With *Open Addressing* the max Load Factor is 1 – each slot can only hold one item
- With separate chaining the load factor can be higher because each slot holds a linked list