

Video Action Recognition任务是理解video中人的行为，其中涉及识别、定位和预测人的行为的任务。具有很多真实场景下的应用：behavior analysis, video retrieval, human-robot interaction, gaming, and entertainment. 该领域的发展也是近几年被大力关注，数据集从11年到15年公布的3个，16年到20年就13个了。就具体的发展趋势而言，有1. 双流网络：光流+RGB流。其中RGB流就是连续帧的图像，用来捕获其中的位置、特征等信息；而光流反应的是连续运动帧中运动物体的运动趋势，是行为识别中的运动信息。这类方法就是结合RGB特征和运动特征的双流网络来进行行为识别。（光流需要预先计算，需要大量的预置存储空间，因此本质上不太实用；另外光流是分析运动情况的，那么如果针对摄像头也是运动的视频场景不知道是不是也有相对改进的方法）2. 3D卷积：既然需要结合图像特征与运动信息，那不如就直接塞到3D卷积黑盒里面去，给个监督标签自己让它学，虽然道理是这么个道理，但是不用细看就知道，肯定有很多需要额外考虑的内容，不过

目前没有看很多这方面的文章。最近一些研究都在将3D卷积进行优化，就是嫌弃它的计算量过大。3. 围绕计算效率上展开，使之在更大size的数据集上训练，适用于真实世界场景。

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关于数据集部分，如今也开源了不少，具体比较常用是Kinetics和Something系列。构建数据集的步骤如下（可能会对后面训练理解标签含义有帮助）：

1. 定义action list，此部分通过组合之前数据集中的定义，以及添加新的action类别定义得到。
2. 通过匹配网上{yzaws, xxnl, chunhliu, mozolf, yuanjx, chongrwu, zhiz, tighej, manmatha, mli}@amazon.com

各种小视频的title和subtitle来爬取相关action list中定义的类别。3. 手动标注一个具体action类别的起始与结束时间，用以后面的训练。4. 数据清洗，删除重复数据以及无关噪音数据

视频动作识别时视频理解任务最具有代表性的任务之二。再过去的十年中，由于深度学习技术的发展，视频动作识别任务也取得了巨大的进步。

然而我们还是遇到了很多的挑战。包括在的视频中存

长时信息，需要的高

量，由于数据集和衡量的第可比

因此，本超过200个现存的在视

频识别领域使度学习的进行了总

目前的这

法可以分为双流网络，以及最近的一些注重计算效率的模型。我们对一些具有代表新的数据集上同一测试了一些流行的方法。最后，我们讨论了一些开放的问题，并且对视频动作分类任务留下了可能。

## 1. Introduction

视频理解任务中最重要的一个任务就是理解人类的动作。

理解人类的动作有非常多的应用，包括行

析，视频动作定位，预测。在

多的视频任务中，中识别别人动作的任务

再过去的十年中，我们对视频动作分类问题的研究导致出现了很多高质量的大规模数



Figure 1. Visual examples of categories in popular video action datasets.

横轴是年份，纵轴是数据集的标注数量(取对数)，大小表示总样本数量

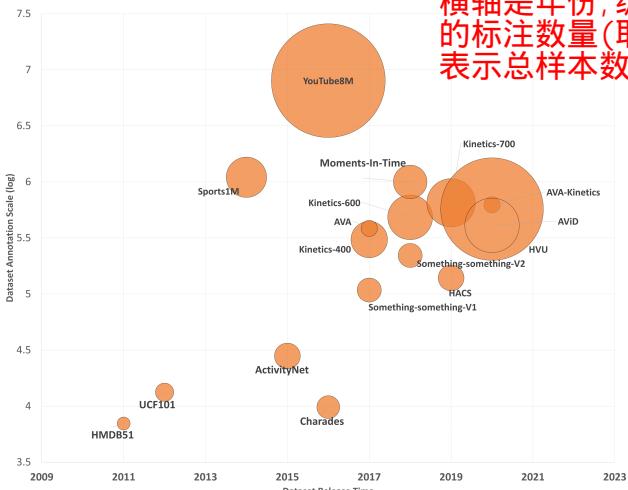


Figure 2. Statistics of most popular video action recognition datasets from past 10 years. The area of an circle represents the scale of each dataset (i.e., number of videos).

过去的十年中，我们不仅见证了数据集规模（视频总数/类别数）的增长，还见证了更多的数据集的开发

datasets in Figure 2. We see that both the number of videos and classes increase rapidly, e.g., from 7K videos over 51 classes in HMDB51 [109] to 8M videos over 3,862 classes in YouTube8M [1]. Also, the rate at which new datasets are released is increasing: 3 datasets were released from 2011 to 2015 compared to 13 released from 2016 to 2020.

Thanks to both the availability of large-scale datasets and the rapid progress in deep learning, there is also a

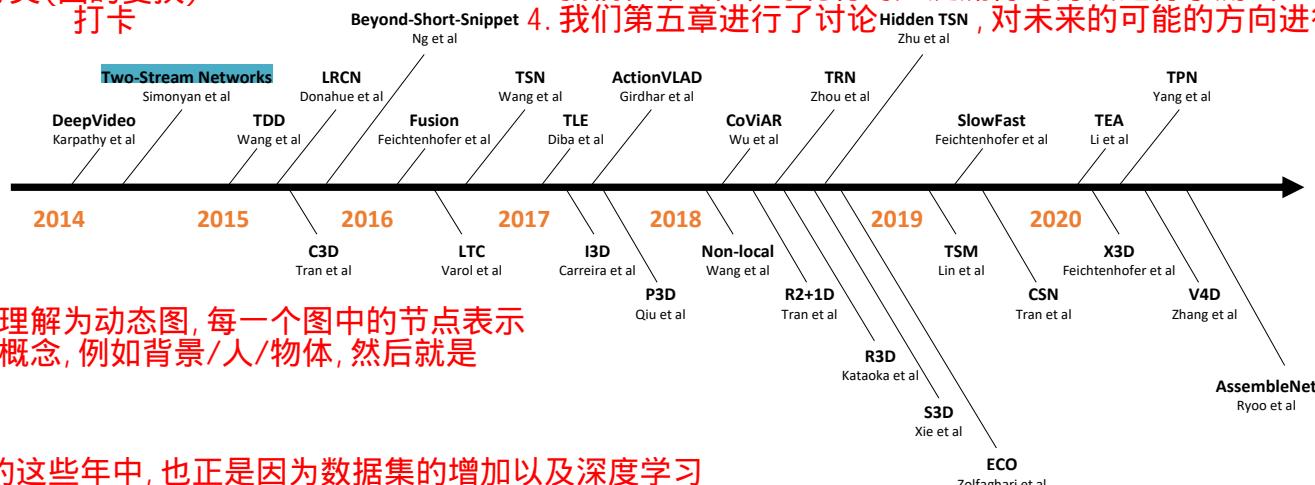
模型学到空间知识和时间知识。  
那么用模型学到的知识-空间知识=时间知识

一张图像里是有不同的概念的. 第一个网络  
抽取概念(图), 第二个网络根据概念间的变  
换进行分类(图的变换)

打卡

本文剩下的部分将按照如下的方式进行组织:

1. 我们在第2章中介绍了用于benchmark的一些常见的数据集以及一些常见的挑战
2. 我们在第3章中详细介绍了最近使用深度学习技术来进行视频识别的进展
3. 我们在第4章中对现有的广泛流行的方法进行了测试
4. 我们第五章进行了讨论 Hidden TSN , 对未来的可能的方向进行了介绍



把视频理解为动态图, 每一个图中的节点表示  
不同的概念, 例如背景/人/物体, 然后就是

再过去的这些年中, 也正是因为数据集的增加以及深度学习  
技术的发展, 有很多方法都被提出来了, 图三中给出了这些年  
具有代表性的方法的 一个编年表

Figure 3. A chronological overview of recent representative work in video action recognition.

14年的Deep learning based models to recognize video actions. In Figure 3, we present a chronological overview of recent representative work. DeepVideo [99] is one of the earliest attempts to apply convolutional neural networks to videos. We observed three trends here. The first trend started by the seminal paper on Two-Stream Networks [187], adds a second path to learn the temporal information in a video by training a convolutional neural network on the optical flow stream. Its great success inspired a large number of follow-up papers, such as TDD [214], LRCN [37], Fusion [50], TSN [218], etc. The second trend was the use of 3D convolutional kernels to model video temporal information, such as I3D [14], R3D [74], S3D [239], Non-local [219], SlowFast [45], etc. Finally, the third trend focused on computational efficiency to scale to even larger datasets so that they could be adopted in real applications. Examples include Hidden TSN [278], TSM [128], X3D [44], TVN [161], etc.

尽管有很多视频识别模型 for video action recognition, there is no comprehensive survey dedicated to these models. Previous survey papers either put more efforts into hand-crafted features [77, 173] or focus on broader topics such as video captioning [236], video prediction [104], video action detection [261] and zero-shot video action recognition [96]. In this paper:对这些方法进行介绍的文章. 早期的一些视频相关的文章要么是关注于视频特征, 要么是关注于视频综合性的特征, 视频预测, 动作检测这类其他的任务

- We comprehensively review over 200 papers on deep learning for video action recognition. We walk the readers through the recent advancements chronologically and systematically, with popular papers explained in detail.

最后, 本文的贡献如下: 1. 我们对超过200篇文章进行了总结, 我们以编年表的顺序系统而又详细的介绍了近年来深度学习技术在视频识别任务上的进展. 对于一些流行的方法进行了详细的介绍. 2. 我们对一些流行的方法在同一的数据集下进行了测试, 以比较不同方法的准确度和效率 3. 我们对现存的一些问题进行了讨论

We also release our implementations for full reproducibility<sup>1</sup>.

- We elaborate on challenges, open problems, and opportunities in this field to facilitate future research.

The rest of the survey is organized as following. We first describe popular datasets used for benchmarking and existing challenges in section 2. Then we present recent advancements using deep learning for video action recognition in section 3, which is the major contribution of this survey. In section 4, we evaluate widely adopted approaches on standard benchmark datasets, and provide discussions and future research opportunities in section 5.

深度学习方法在有大量数据的时候, 性能会有极大的提升  
2. Datasets and Challenges 而对于视频动作理解来说, 这就意味着我们需要大量的标注的数据集来学习到有用的模型  
2.1. Datasets

Deep learning methods usually improve in accuracy when the volume of the training data grows. In the case of video action recognition, this means we need large-scale annotated datasets to learn effective models.

For the task of video action recognition, datasets are often built by the following process: (1) Define an action list, by combining labels from previous action recognition datasets and adding new categories depending on the use case. (2) Obtain videos from various sources, such as YouTube and movies, by matching the video title/subtitle to the action list. (3) Provide temporal annotations manually to indicate the start and end position of the action, and (4) finally clean up the dataset by de-duplication and filtering

<sup>1</sup>Model zoo in both PyTorch and MXNet: [https://cv.gluon.ai/model\\_zoo/action\\_recognition.html](https://cv.gluon.ai/model_zoo/action_recognition.html)

构建视频的数据集包含下面几步: 1. 定义动作列表, 具体可以根据先前的数据集来增加新的动作 2. 从多种渠道获取视频, 包括从youtube的视频中进行配对 3. 提供时间标注信息来说明动作什么时候开始什么时候结束 4. 最后通过去除重复和滤去噪音来清洗数据集

HMDB51数据集在2011年公开.里面的动作主要是从电影,还有一小部分是从Prelinger归档,YouTube和谷歌视频中获取的.数据集一共包含6849个视频,包含51种动作.每个动作至少有101个视频.视频一共提供了三个官方的分割,一般来说,使用这个数据集的人都是提供在split 1上的top 1准确率或者三个split的平均准确率

Dataset	Year	# Samples	Ave. Len	# Actions
UCF101数 据集在201 2年被公开, 是先前UCF 50数据集的 扩展.他从 YouTube中 得到了133 20段视频, 一共包含1 01中动作. 数据集的 测试方法 和HMDB51 是一样的	2011	7K	~5s	51
HMDB51 [109]	2012	13.3K	~6s	101
Sports1M [99]	2014	1.1M	~5.5m	487
ActivityNet [40]	2015	28K	[5, 10]m	200
YouTube8M [1]	2016	8M	229.6s	3862
Charades [186]	2016	9.8K	30.1s	157
Kinetics400 [100]	2017	306K	10s	400
Kinetics600 [12]	2018	482K	10s	600
Kinetics700 [13]	2019	650K	10s	700
Sth-Sth V1 [69]	2017	108.5K	[2, 6]s	174
Sth-Sth V2 [69]	2017	220.8K	[2, 6]s	174
AVA [70]	2017	385K	15m	80
AVA-kinetics [117]	2020	624K	15m, 10s	80
MIT [142]	2018	1M	3s	339
HACS Clips [267]	2019	1.55M	2s	200
HVU [34]	2020	572K	10s	739
AVid [165]	2020	450K	[3, 15]s	887

**Sports1M** Table 1. A list of popular datasets for video action recognition 是第一个大规模的数据集,在2014年发布.包含从YouTube上获取到的超过一千万和视频,分为487类.每一类动作划分的都非常细致,因此类内的差异就会很小.他的官方提供了10折验证划分

**HMDB51** [109] was introduced in 2011. It was collected mainly from movies, and a small proportion from public databases such as the Prelinger archive, YouTube and Google videos. The dataset contains 6,849 clips divided into 51 action categories, each containing a minimum of 101 clips. The dataset has three official splits. Most previous papers either report the top-1 classification accuracy on split 1 or the average accuracy over three splits.

**UCF101** [190] was introduced in 2012 and is an extension of the previous UCF50 dataset. It contains 13,320 videos from YouTube spreading over 101 categories of human actions. The dataset has three official splits similar to HMDB51, and is also evaluated in the same manner.

**Sports1M** [99] was introduced in 2014 as the first large-scale video action dataset which consisted of more than 1 million YouTube videos annotated with 487 sports classes. The categories are fine-grained which leads to low inter-class variations. It has an official 10-fold cross-validation split for evaluation.

**ActivityNet** [40] was originally introduced in 2015 and the ActivityNet family has several versions since its initial launch. The most recent ActivityNet 200 (V1.3) contains 200 human daily living actions. It has 10,024 training, 4,926 validation, and 5,044 testing videos. On average there are 137 untrimmed videos per class and 1.41 activity instances per video.

**YouTube8M** [1] was introduced in 2016 and is by far the largest-scale video dataset that contains 8 million YouTube videos (500K hours of video in total) and annotated with 3,862 action classes. Each video is annotated with one or multiple labels by a YouTube video annotation system. This dataset is split into training, validation and test in the ratio

YouTube8M是2016年被公开的,所有视频由一个或者多个YouTube标注系统标注的.所有的视频按照7:2:1的比例划分的

Charades在2016年公开,主要为了真实生活中的动作理解.它包含9848个长度在30秒左右的视频.数据集包括157个多个标注的日常室内活动,有267个不同的人扮演.他官方提供的训练/验证集有7985个example用于训练,1863个用于验证

**Kinect系列**是目前使用最广泛的数  
据集.  
**Kinect400**在2017年被公开,包含240k个训练example和20k个验证example.每个视频都被修剪成10秒,一共包含400中人类动作.**Kinect系列的数据量还在增加**

70:20:10. The validation set of this dataset is also extended with human-verified segment annotations to provide temporal localization information.

**Charades** [186] was introduced in 2016 as a dataset for real-life concurrent action understanding. It contains 9,848 videos with an average length of 30 seconds. This dataset includes 157 multi-label daily indoor activities, performed by 267 different people. It has an official train-validation split that has 7,985 videos for training and the remaining 1,863 for validation.

**Kinetics Family** is now the most widely adopted benchmark. Kinetics400 [100] was introduced in 2017 and it consists of approximately 240k training and 20k validation videos trimmed to 10 seconds from 400 human action categories. The Kinetics family continues to expand, with Kinetics-600 [12] released in 2018 with 480K videos and Kinetics700[13] in 2019 with 650K videos.

**20BN-Something-Something** [69] V1 was introduced in 2017 and V2 was introduced in 2018. This family is another popular benchmark that consists of 174 action classes that describe humans performing basic actions with everyday objects. There are 108,499 videos in V1 and 220,847 videos in V2. Note that the Something-Something dataset requires strong temporal modeling because most activities cannot be inferred based on spatial features alone (e.g. opening something, covering something with something).

**AVA** [70] was introduced in 2017 as the first large-scale spatio-temporal action detection dataset. It contains 430 15-minute video clips with 80 atomic actions labels (only 60 labels were used for evaluation). The annotations were provided at each key-frame which lead to 214,622 training, 57,472 validation and 120,322 testing samples. The AVA dataset was recently expanded to AVA-Kinetics with 352,091 training, 89,882 validation and 182,457 testing samples [117].

**Moments in Time** [142] was introduced in 2018 and it is a large-scale dataset designed for event understanding. It contains one million 3 second video clips, annotated with a dictionary of 339 classes. Different from other datasets designed for human action understanding, Moments in Time dataset involves people, animals, objects and natural phenomena. The dataset was extended to **Multi-Moments in Time (M-MiT)** [143] in 2019 by increasing the number of videos to 1.02 million, pruning vague classes, and increasing the number of labels per video.

**HACS** [267] was introduced in 2019 as a new large-scale dataset for recognition and localization of human actions collected from Web videos. It consists of two kinds of manual annotations. HACS Clips contains 1.55M 2-second clip annotations on 504K videos, and HACS Segments has 140K complete action segments (from action start to end) on 50K videos. The videos are annotated with the same 200 human action classes used in ActivityNet (V1.3) [40].

**MiT**是在2018年发布的用于时间理解的数据集.其中包含一百万个超过3秒的视频片段,标注为339类.和其他只包含人类动作数据集不一样,MiT包含了人类,动物,物体和自然现象的视频.在2019年这个数据集通过增加视频总量,删去配了标注模糊的类别以及增加label的方式升级到了M-MiT

HVU是2020年为了多任务/标签而发表的新数据集。HVU一共包含3142个标签。官方提供的划分中训练/验证/测试集分别有481K/31K/65K个视频。HVU数据集一共有六个任务目录，分别是：场景，物体，动作，时间，属性以及概念。

AViD则是在2020年发布的用于匿名动作识别的数据集。里面包含410K HVU [34] dataset was released in 2020 for multi-label training data and multi-task video understanding. This dataset has 572K videos and 3,142 labels. The official split has 481K, 31K and 65K videos for train, validation, and test respectively.

This dataset has six task categories: scene, object, action, event, attribute, and concept. On average, there are about 2,112 samples for each label. The duration of the videos varies with a maximum length of 10 seconds.

作者考虑AViD [165] was introduced in 2020 as a dataset for anonymized action recognition. It contains 410K videos for training and 40K videos for testing. Each video clip duration is between 3-15 seconds and in total it has 887 action classes. During data collection, the authors tried to collect data from various countries to deal with data bias. They also remove face identities to protect privacy of video makers. Therefore, AViD dataset might not be a proper choice for recognizing face-related actions.

年史之前，Before we dive into the chronological review of methods, we present several visual examples from the above datasets in Figure 4 to show their different characteristics.

In the top two rows, we pick action classes from UCF101 [190] and Kinetics400 [100] datasets. Interestingly, we find

that these actions can sometimes be determined by the context or scene alone.

For example, the model can predict the action riding a bike as long as it recognizes a bike in the video frame. The model may also predict the action cricket bowling if it recognizes the cricket pitch. Hence for these classes, video action recognition may become an object/scene classification problem without the need of reasoning motion/temporal information. In the middle two rows, we pick action classes from Something-Something dataset [69]. This dataset focuses on human-object interaction, thus it is more fine-grained and requires strong temporal modeling. For example, if we only look at the first frame of dropping something and picking something up without looking at other video frames, it is impossible to tell these two actions apart.

In the bottom row, we pick action classes from Moments in Time dataset [142]. This dataset is different from most video action recognition datasets, and is de-

signed to have large inter-class and intra-class variation that represent dynamical events at different levels of abstraction.

For example, the action climbing can have different actors (person or animal) in different environments (stairs or tree).

Non-trivial 就是具有一定复杂度，  
2.2. Challenges 需要一定脑力活动、加工过程才能  
而且需要很 得到的（结果、结论、实现...）

There are several major challenges in developing effective video action recognition algorithms.

In terms of dataset, first, defining the label space for training action recognition models is non-trivial. It's because human actions are usually composite concepts and the hierarchy of these concepts are not well-defined. Second, annotating videos for action recognition are laborious (e.g., need to watch all the video frames) and ambiguous

第三类数据例 因为里面的动力学  
如MiT这类是 运动时间是高级别  
具有很大的类 的抽象  
内和类间差异

对于建模来说，也存在很多的问题，例如：1. 人类动作之间存在很多的类内和类间差异。2. 是别人累动作需要同步理解长短期动作信息 3. 计算开销很大

HACS是在2019年发布的用于识别和定位的大型数据集。视频来源于网络，分类和ActivityNet一样，包含200个类别。标注有两种方式，一种是对504k个视频中得到的1.55M个2秒视频的标注，还有从50k个视频中得到140k个完整的动作片段（从开始到结束）

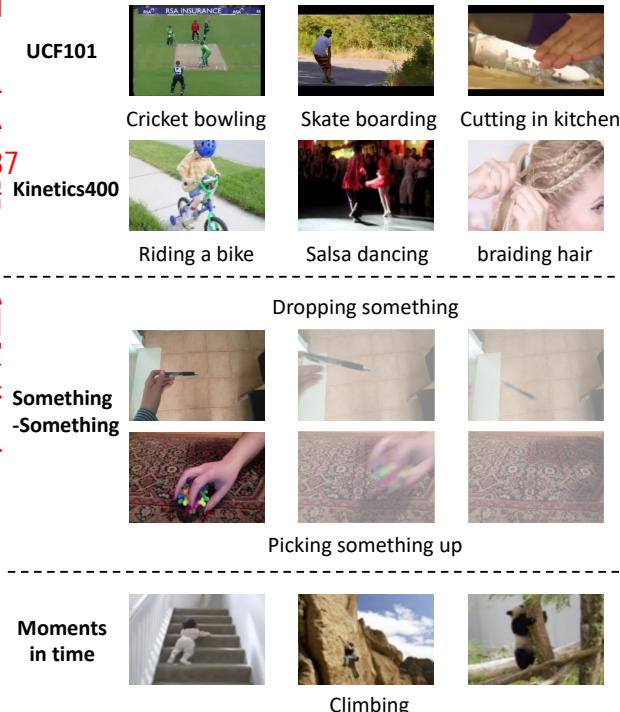


Figure 4. Visual examples from popular video action datasets. Top: individual video frames from action classes in UCF101 and Kinetics400. A single frame from these scene-focused datasets often contains enough information to correctly guess the category. Middle: consecutive video frames from classes in Something-Something. The 2nd and 3rd frames are made transparent to indicate the importance of temporal reasoning that we cannot tell these two actions apart by looking at the 1st frame alone. Bottom: individual video frames from classes in Moment in Time. Same action could have different actors in different environments.

(e.g., hard to determine the exact start and end of an action). Third, some popular benchmark datasets (e.g., Kinetics family) only release the video links for users to download and not the actual video, which leads to a situation that methods are evaluated on different data. It is impossible to do fair comparisons between methods and gain insights.

In terms of modeling, first, videos capturing human actions have both strong intra- and inter-class variations. People can perform the same action in different speeds under various viewpoints. Besides, some actions share similar movement patterns that are hard to distinguish. Second, recognizing human actions requires simultaneous understanding of both short-term action-specific motion information and long-range temporal information. We might need a sophisticated model to handle different perspectives rather than using a single convolutional neural network. Third, the computational cost is high for both training and inference, hindering both the development and deployment of action recognition models. In the next section, we will demonstrate how video action recognition methods developed over the last decade to address the aforementioned challenges.

现在的数据集存在的问题：  
1. 类别的划分是非平凡的，因为人类的动作通常是由多个概念的，并且这些概念以不同的层次组合。  
2. 对视频进行标注是费时费力的。  
3. 一些数据集只提供了下载链接，因此不同的人可能在不同的数据上进行的测试，因此在不同的数据下训练得到的模型是不具有可比性的。

在英文及其他很多语言中，单词“奥德赛”(odyssey)现在用来指代一段史诗般的征程。

<https://zh.wikipediac.org/wiki/%E5%A5%A5%E5%BE%B7%E8%B5%9B>

尽管有的方法试着在视频动作识别使用卷积神经网络，但是在2015年以前，手工设计的特征，尤其是IDT这类特征，它们的高准确率导致了他们是占主导的方法。然而，手工设计的特征需要很大的计算量，并且非常难以部署到大型的3. An Odyssey of Using Deep Learning for Video Action Recognition

数据集上  
随着深度学  
习技术的发  
展，越来  
越多的研  
究源开始  
把卷积网  
络运用到视  
频识别问  
题。最早  
的DeepVi  
deo对每  
一帧图像  
使用2D卷  
积网络，  
are hard to scale and deploy.

然后探究了  
不同的时间  
模式的来  
让我们学  
习到用于  
视频识别  
的时空特  
征。虽然  
他提出了  
一些被后  
来的文章  
证明了非  
常好的模  
型。但是  
在UCF101  
上迁移学  
习的性能  
降低了20  
%. 不仅如此，  
他还发现以单帧图像作为输入的模型的表现和  
以视频(堆叠起来的帧)作为输入的  
模型的性能  
是差不多的。  
这就意味着这  
个模型学到的特征无法捕捉到人的运动

Since there being some papers using Convolutional Neural Networks (CNNs) for video action recognition, [200, 5, 91], hand-crafted features [209, 210, 158, 112], particularly Improved Dense Trajectories (IDT) [210], dominated the video understanding literature before 2015, due to their high accuracy and good robustness. However, hand-crafted features have heavy computational cost [244], and are hard to scale and deploy.

With the rise of deep learning [107], researchers started to adapt CNNs for video problems. The seminal work DeepVideo [99] proposed to use a single 2D CNN model on each video frame independently and investigated several temporal connectivity patterns to learn spatio-temporal features for video action recognition, such as late fusion, early fusion and slow fusion. Though this model made early progress with ideas that would prove to be useful later such as a multi-resolution network, its transfer learning performance on UCF101 [190] was 20% less than hand-crafted IDT features (65.4% vs 87.9%). Furthermore, DeepVideo [99] found that a network fed by individual video frames, performs equally well when the input is changed to a stack of frames. This observation might indicate that the learned spatio-temporal features did not capture the motion well. It also encouraged people to think about why CNN models did not outperform traditional hand-crafted features in the video domain unlike in other computer vision tasks [107, 171].

3.2. Two-stream networks  
Since video understanding intuitively needs motion information, finding an appropriate way to describe the temporal relationship between frames is essential to improving the performance of CNN-based video action recognition.

Optical flow [79] is an effective motion representation to describe object/scene movement. To be precise, it is the pattern of apparent motion of objects, surfaces, and edges in a visual scene caused by the relative motion between an observer and a scene. We show several visualizations of optical flow in Figure 5. As we can see, optical flow is able to describe the motion pattern of each action accurately. The advantage of using optical flow is it provides orthogonal information compared to the the RGB image. For example, the two images on the bottom of Figure 5 have cluttered backgrounds. Optical flow can effectively remove the non-moving background and result in a simpler learning problem compared to using the original RGB images as input.

光流可以  
准确的描  
述物体的  
运动。使  
用光流的  
优点就在  
于相比与  
RGB图像，  
光流提供  
了正交的  
信息  
例如在图5中，光流可以有效地去除非运动的  
背景，因此相比于RGB图像来说是一种更加简  
单并且易于学习的问题

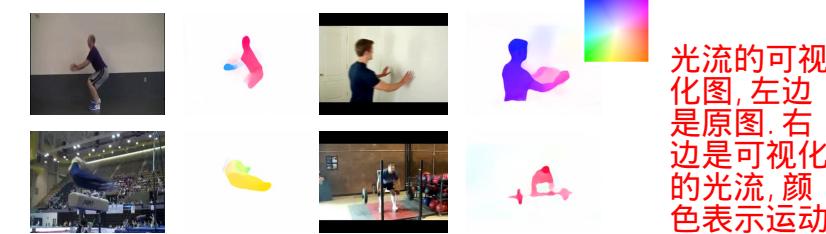


Figure 5. Visualizations of optical flow. We show four image-flow pairs, left is original RGB image and right is the estimated optical flow by FlowNet2 [85]. Color of optical flow indicates the directions of motion, and we follow the color coding scheme of FlowNet2 [85] as shown in top right.

除了光流能够提供额外的信息以外，光流也已经被证明在视频处理任务上可以工作的很好。传统的手工设计的特征 In addition, optical flow has been shown to work well on video problems. Traditional hand-crafted features such as IDT [210] also contain optical-flow-like features, such as Histogram of Optical Flow (HOF) and Motion Boundary Histogram (MBH).

Hence, Simonyan *et al.* [187] proposed two-stream networks, which included a spatial stream and a temporal stream as shown in Figure 6. This method is related to the two-streams hypothesis [65], according to which the human visual cortex contains two pathways: the ventral stream (which performs object recognition) and the dorsal stream (which recognizes motion). The spatial stream takes raw video frame(s) as input to capture visual appearance information. The temporal stream takes a stack of optical flow images as input to capture motion information between video frames. To be specific, [187] linearly rescaled the horizontal and vertical components of the estimated flow (i.e., motion in the x-direction and y-direction) to a [0, 255] range and compressed using JPEG. The output corresponds to the two optical flow images shown in Figure 6. The compressed optical flow images will then be concatenated as the input to the temporal stream with a dimension of  $H \times W \times 2L$ , where H, W and L indicates the height, width and the length of the video frames. In the end, the final prediction is obtained by averaging the prediction scores from both streams.

By adding the extra temporal stream, for the first time, a CNN-based approach achieved performance similar to the previous best hand-crafted feature IDT on UCF101 (88.0% vs 87.9%) and on HMDB51 [109] (59.4% vs 61.1%). [187] makes two important observations. First, motion information is important for video action recognition. Second, it is still challenging for CNNs to learn temporal information directly from raw video frames. Pre-computing optical flow as the motion representation is an effective way for deep learning to reveal its power. Since [187] managed to close the gap between deep learning approaches and traditional hand-crafted features, many follow-up papers on two-stream networks emerged and greatly advanced the development.

187提出的双流网络提供了两个重要的理解：1. 对于视频动作识别来说，运动信息是非常重要的。2. 对于CNN来说，直接从视频帧中学习得到时间信息是很困难的。从提前计算得到的光流中进行学习对于深度学习来说是有效地

双流网络中的空间流用于识别物体，其原始视频帧作为输入，而时间流用于识别物体的运动，其输入是输入视频的光流。具体来说是提取了原始视频x和y方向上的光流，然后把值压缩到0-255之后编码成JPEG格式，和原始输入格式对齐。接下来各自截取一半，融合之后作为输入。最终的结果是时间流和空间流的预测分数平均之后进行分类

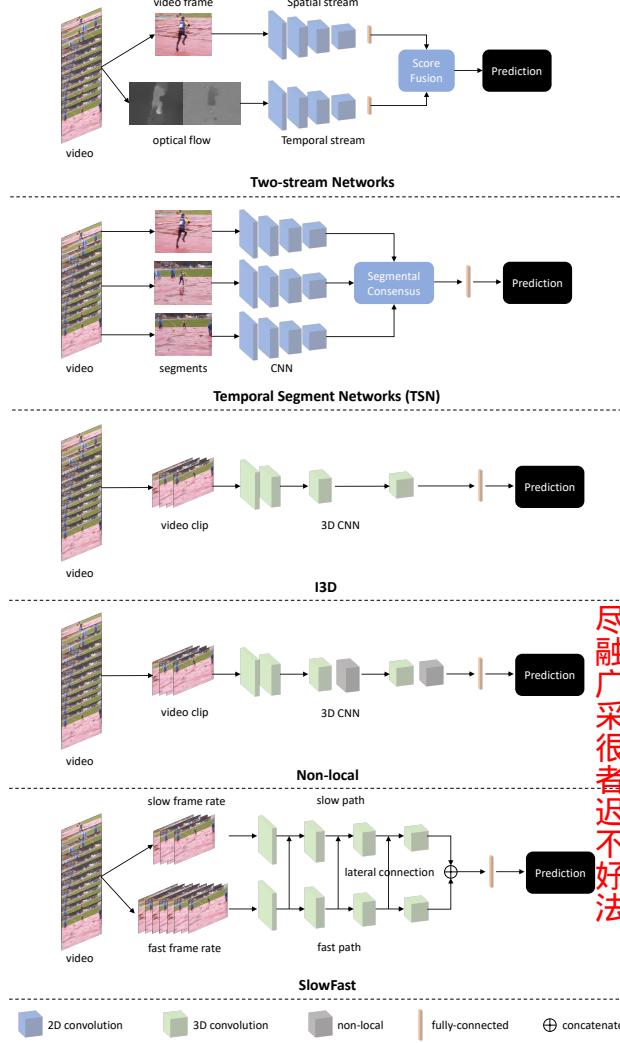


Figure 6. Workflow of five important papers: two-stream networks [187], temporal segment networks [218], I3D [14], Non-local [219] and SlowFast [45]. Best viewed in color.

因为187中提出的双流网络第一次弥补了深度学习方法和传统方法之间的差距，因此再之后出现了很多双流系列的网络来改进。这些方法极大地推动了视频动作识别的发展。因此我们下面将会分解介绍这些方法。

### 3.2.1 Using deeper network architectures

因为187中提出的双流网络使用的是比较浅的网络，因此一个非常自然的扩展就是使用深层网络。Two-stream networks [187] used a relatively shallow network architecture [107]. Thus a natural extension to the two-stream networks involves using deeper networks. However, Wang *et al.* [215] finds that simply using deeper networks does not yield better results, possibly due to overfitting on the small-sized video datasets [190, 109]. Recall from section 2.1, UCF101 and HMDB51 datasets only have thousands of training videos. Hence, Wang *et al.* [217] introduce a series of good practices, including cross-modality initialization, synchronized batch normalization,

但是Wang等人却发现简单的使用更深层的网络并不会带来性能上的提升。这很有可能是由于overfitted小数据集。因此，Wang等人在217中提出了一系列非常好用的训练技巧，包括跨模态初始化，同步batch normalization，角落切割，多尺度切割，大dropout率等等方式。最终成功使用VGG16作为backbone，并且在UCF101数据集上极大地超越了原始的双流网络

corner cropping and multi-scale cropping data augmentation, large dropout ratio, etc. to prevent deeper networks from overfitting. With these good practices, [217] was able to train a two-stream network with the VGG16 model [188] that outperforms [187] by a large margin on UCF101. These good practices have been widely adopted and are still being used. Later, Temporal Segment Networks (TSN) [218] performed a thorough investigation of network architectures, such as VGG16, ResNet [76], Inception [198], and demonstrated that deeper networks usually achieve higher recognition accuracy for video action recognition. We will describe more details about TSN in section 3.2.4.

因为双流网络中存在两条通路，因此就一定会

### 3.2.2 Two-stream fusion 存在两条通路信息融合的阶段。这个阶段通常称为时空融合阶段。

Since there are two streams in a two-stream network, there will be a stage that needs to merge the results from both networks to obtain the final prediction. This stage is usually referred to as the spatial-temporal fusion step.

The easiest and most straightforward way is late fusion, which performs a weighted average of predictions from both streams. Despite late fusion being widely adopted [187, 217], many researchers claim that this may not be the optimal way to fuse the information between the spatial appearance stream and temporal motion stream. They believe that earlier interactions between the two networks could benefit both streams during model learning and this is termed as early fusion.

Fusion [50] is one of the first of several papers investigating the early fusion paradigm, including how to perform spatial fusion (e.g., using operators such as sum, max, bilinear, convolution and concatenation), where to fuse the network (e.g., the network layer where early interactions happen), and how to perform temporal fusion (e.g., using 2D or 3D convolutional fusion in later stages of the network). [50] shows that early fusion is beneficial for both streams to learn richer features and leads to improved performance over late fusion. Following this line of research, Feichtenhofer *et al.* [46] generalizes ResNet [76] to the spatio-temporal domain by introducing residual connections between the two streams. Based on [46], Feichtenhofer *et al.* [47] further propose a multiplicative gating function for residual networks to learn better spatio-temporal features. Concurrently, [225] adopts a spatio-temporal pyramid to perform hierarchical early fusion between the two streams.

Feichtenhofer等人把残差网络泛化到了两条路的时空领域，并且在47中更仅有一步提出了更好的函数

Since a video is essentially a temporal sequence, researchers have explored Recurrent Neural Networks (RNNs) for temporal modeling inside a video, particularly the usage of Long Short-Term Memory (LSTM) [78].

LRCN [37] and Beyond-Short-Snippets [253] are the first of several papers that use LSTM for video action recog-

说到底，视频还是一个时序数据，因此用一些研究者尝试如何把RNN(尤其是LSTM)运用到视频动作识别领域。LRCN和BSS是最早的几篇把LSTM作为双流网络中一路从而把LSTM运用到视频动作识别任务上的文章

直到现在，Wang等人提出的技巧仍然在被广泛的使用

接下来TSN中对不同的网络结构进行了详细的比较，例如VGG16，最后发现更深的网络往往能得到更好的性能

实现时空融合最简单的一步就是迟融合，即对两个通路的网络最后的结果进行加权平均

诸多学者相信在特征提取的初期进行特征融合是更加有益的

Fusion是最早研究早融合范式的文章，包括如何进行空间融合(即探究不同的运算方法，sum, max, 卷积或者拼接)，在那里进行融合以及如何进行时间融合。50中的结果最终表明早融合对于两条路来说都是有益的，并且相比于晚融合会提升性能

说到底，视频还是一个时序数据，因此用一些研究者尝试如何把RNN(尤其是LSTM)运用到视频动作识别领域。LRCN和BSS是最早的几篇把LSTM作为双流网络中一路从而把LSTM运用到视频动作识别任务上的文章

LRCN和BSS把CNN得到的feature map作为LSTM的输入，然后通过聚合帧级别的CNN特征来得到最后的视频级别的预测。需要注意的是，他们都是在两条路中分别使用的LSTM，然后进行的迟融合。但是，使用LSTM相比于原始的双流网络来说并没有非常多的提升。

跟随者CNN under the two-stream networks setting. They take the NN-LSTM的范式，有很多变体被提出了，包括双向LSTM, CNN-LSTM融合, 分层LSTM融合。[125]中介绍的VideoLSTM使用了基于相关性的空间注意力机制，以及一个轻量的基于动作的注意力机制。V-LSTM的结果不仅提高了视频动作识别的精度上限，并且说明了学习到的注意力可以帮助进行动作定位。Ma等人首先建立了一个强大

的baseline作为比较的基准，然后使用相同的LSTM作为Backbone来研究不同的LSTM的性能。最后他们发现LSTM需要预段的数据

3.2.4 Segment-based methods 来完全获取时间信息

通过光流进行学习使得模型可以学习到短时的时空信息，但是却无法学习到长时信息。因此Wang等人提出了TSN来进行视频级别的动作识别。虽然TSN最早被提出来是用于2D的卷积，但是其思想却非常简单并且易于泛化。因此最近的许多文章2D或者3D的卷积网络都是建立在TSN的框架的基础上的。

TSN首先把整个视频分成几个在时间上均匀分布视频段，然后在每一段中抽出来单独的一帧，让网络进行推理。最后会进行段间共识来聚合不同采样的帧之间的信息。段间共识的计算方法可以是平均池化，最大池化，线性插值等等。TSN可以建模长期的时间结构，因为模型看完了视频的

randomly selects a single video frame within each segment and forwards them through the network. Here, the network shares weights for input frames from all the segments. In the end, a segmental consensus is performed to aggregate information from the sampled video frames. The segmental consensus could be operators like average pooling, max pooling, bilinear encoding, etc. In this sense, TSN is capable of modeling long-range temporal structure because the model sees the content from the entire video. In addition, this sparse sampling strategy lowers the training cost over long video sequences but preserves relevant information.

Given TSN's good performance and simplicity, most two-stream methods afterwards become segment-based two-stream networks. Since the segmental consensus is simply doing a max or average pooling operation, a feature encoding step might generate a global video feature and lead to improved performance as suggested in traditional approaches [179, 97, 157]. Deep Local Video Feature (DVOF) [114] proposed to treat the deep networks that trained on local inputs as feature extractors and train another encoding function to map the global features into global labels. Temporal Linear Encoding (TLE) network [36] appeared concurrently with DVOF, but the encoding layer was embedded in the network so that the whole pipeline could be trained end-to-end. VLAD3 and ActionVLAD [123, 63] also appeared concurrently. They extended the NetVLAD layer [4] to the video domain to perform video-level encoding, instead of using compact bilinear encoding as in [36]. To improve the temporal reasoning ability of TSN, Temporal Relation Network (TRN) [269] was proposed to learn and reason about temporal dependencies between video frames at multiple time scales. The recent state-of-the-art efficient model TSM [128] is also segment-based. We will discuss it in more detail in section 3.4.2.

类似的，VLAD3和ActionVLAD把NetVLAD扩展到了视频领域来获得视频级别的编码。此外为了提高TSN的

### 3.2.5 Multi-stream networks 时间推理能力，研究者提出了能够学习到不同帧之间的时间相关性的TRN

Two-stream networks are successful because appearance and motion information are two of the most important properties of a video. However, there are other factors that can help video action recognition as well, such as pose, object, audio and depth, etc.

Pose information is closely related to human action. We can recognize most actions by just looking at a pose (skeleton) image without scene context. Although there is previous work on using pose for action recognition [150, 246], P-CNN [23] was one of the first deep learning methods that successfully used pose to improve video action recognition. P-CNN proposed to aggregates motion and appearance information along tracks of human body parts, in a similar spirit to trajectory pooling [214]. [282] extended this pipeline to a chained multi-stream framework, that computed and integrated appearance, motion and pose. They 等等姿态信息和人的动作有紧密的关系。对于我们人来说，我们能够通过姿态(骨架)就可以识别出来绝大多数人的动作。尽管先前有一些工作使用姿态来识别动作，但是P-CNN是第一个成功使用深度学习的方法来提升视频动作识别的准确率。P-CNN中提出了通过人体部分的追踪来聚合运动和外观信息。282中的多流网络来获取出现，运动和姿态信息

282中引入了马尔科夫链来把出现,运动和姿态连续的加入进行推测,并且最终在动作分类和动作识别上获取到不错的效果. 25中提出的PoTi on是P-CNN的后续作品,但是引入了更加强大的特征表示,即人体语义关键点的运动. PoTi on中首先通过一个人体姿态估计器来抽取到人体关节点的热力图. 然后在时空上不断聚合获取到的关节点的概率图最终得到分类的结果 introduced a Markov chain model that added these cues successively and obtained promising results on both action recognition and action localization. PoTion [25] was a follow-up work to P-CNN, but introduced a more powerful feature representation that encoded the movement of human semantic keypoints. They first ran a decent human pose estimator and extracted heatmaps for the human joints in each frame. They then obtained the PoTion representation by temporally aggregating these probability maps. PoTion is lightweight and outperforms previous pose representations [23, 282]. In addition, it was shown to be complementary to standard appearance and motion streams, e.g. combining PoTion with I3D [14] achieved state-of-the-art result on UCF101 (98.2%). 除了姿势以外, 物体信息也是非常重要的. Object information is another important cue because most human actions involve human-object interaction. Wu [232] proposed to leverage both object features and scene features to help video action recognition. The object and scene features were extracted from state-of-the-art pre-trained object and scene detectors. Wang *et al.* [252] took a step further to make the network end-to-end trainable. They introduced a two-stream semantic region based method, by replacing a standard spatial stream with a Faster RCNN network [171], to extract semantic information about the object, person and scene. 自来都对特征和场景信息进行识别.

音频信号也存在于视频中，而且视觉信息是互补的。Audio signals usually come with video, and are complementary to the visual information. Wu *et al.* [233] introduced a multi-stream framework that integrates spatial, short-term motion, long-term temporal and audio in videos to digest complementary clues. Recently, Xiao *et al.* [237] introduced AudioSlowFast following [45], by adding another audio pathway to model vision and sound in an unified representation.

**在RGBD动作识别领域，使用深度信息是标准的做法。但是对于单目相机** In RGB-D video action recognition field, using depth information is standard practice [59]. However, for vision-based video action recognition (e.g., only given monocular videos), we do not have access to ground truth depth information as in the RGB-D domain. An early attempt Depth2Action [280] uses off-the-shelf depth estimators to extract depth information from videos and use it for action

本质上，多流网络是一种多模态学习的方式，使用不同的线索作为输入信号来帮助视频动作识别。我们将会在第5.12节中讨论更多关于多模态学习的内容。

试使用深度估计器来估计深度信息

### 3.3. The rise of 3D CNNs

预计算的光流对计算量的需求非常大，并且需要大量的存储空间。Pre-computing optical flow is computationally intensive and storage demanding, which is not friendly for large-scale training and real-time deployment. A conceptually easy way to understand a video is as a 3D tensor with two spatial and one time dimension. Hence, this leads to the usage of 3D CNNs as a processing unit to model the temporal information.简单来说，就是将视频视为一个3D张量，有两个空间维度和一个时间维度。因此使用3D卷积作为时空信息建模的单元就很自然。

91是最早使用3D卷积网络的文章，虽然非常有启发意义，但是它们的模型并不是很深，因此没有展现出来非常强大的性能。因此，Tran等人在202中将91中的模型扩展为了更深的3D卷积网络，称为C3D。C3D的模型设计遵从了188中的模范结构。188中的结构可以说是VGG网络的翻版。虽然C3D在标准的基准测试集上的表现并不是非常好，但是却展现了强大的泛化能力，因此可以用于多种视频

The seminal work for using 3D CNNs for action recognition is [91]. While inspiring, the network was not deep enough to show its potential. Tran *et al.* [202] extended [91] to a deeper 3D network, termed C3D. C3D follows the modular design of [188], which could be thought of as a 3D version of VGG16 network. Its performance on standard benchmarks is not satisfactory, but shows strong generalization capability and can be used as a generic feature extractor for various video tasks [250].

However, 3D networks are hard to optimize. In order to train a 3D convolutional filter well, people need a large-scale dataset with diverse video content and action categories. Fortunately, there exists a dataset, Sports1M [99] which is large enough to support the training of a deep 3D network. However, the training of C3D takes weeks to converge. Despite the popularity of C3D, most users just adopt it as a feature extractor for different use cases instead of modifying/fine-tuning the network. This is partially the reason why two-stream networks based on 2D CNNs dominated the video action recognition domain from year 2014 to 2017. 因此绝大多数研究者就是把C3D当做了特征提取器.

The situation changed when Carreira *et al.* [14] proposed I3D in year 2017. As shown in Figure 6, I3D takes a video clip as input, and forwards it through stacked 3D convolutional layers. A video clip is a sequence of video frames, usually 16 or 32 frames are used. The major contributions of I3D are: 1) it adapts mature image classification architectures to use for 3D CNN; 2) For model weights, it adopts a method developed for initializing optical flow networks in [217] to inflate the ImageNet pre-trained 2D model weights to their counterparts in the 3D model. Hence, I3D bypasses the dilemma that 3D CNNs have to be trained from scratch. With pre-training on a new large-scale dataset Kinetics400 [100], I3D achieved a 95.6% on UCF101 and 74.8% on HMDB51. I3D ended the era where different methods reported numbers on small-sized datasets such as UCF101 and HMDB51<sup>2</sup>. Publications following I3D needed to report their performance on Kinetics400, or other large-scale benchmark datasets, which pushed video action recognition to the next level. In the next few years, 3D CNNs advanced quickly and became top performers on almost every benchmark dataset. We will review the 3D CNNs based literature in several categories below.

We want to point out that 3D CNNs are not replacing two-stream networks, and they are not mutually exclusive. They just use different ways to model the temporal relationship in a video. Furthermore, the two-stream approach is a generic framework for video understanding, instead of a specific method. As long as there are two networks, one for spatial appearance modeling using RGB frames, the other for temporal motion modeling using optical flow, the

<sup>2</sup> As we can see in Table 2, the model achieved an accuracy of 71.0% on the H36M dataset.

需要说明的是，3D卷积网络并没有取代双流网络，因为两者并不是互斥的，3D卷积网络只不过是另外一种建模视频中的时空信息的方式。其实双流网络是指一类网络，只要模型中有两个网络，一个用于建模空间信息，一个用于建模时间信息就可以被归类为双流网络。

在I3D的原始文章中，其实也构建了一条时间通路，I3D结合时间通路得到的性能甚至更高。因此最终的I3D的模型是3D卷积网络和双流网络的结合。但是这页从某个角度说明I3D本身并不是依赖于时间流，即与双流网络是不同的方法

method may be categorized into the family of two-stream networks. In [14], they also build a temporal stream with I3D architecture and achieved even higher performance, 98.0% on UCF101 and 80.9% on HMDB51. Hence, the final I3D model is a combination of 3D CNNs and two-stream networks. However, the contribution of I3D does not lie in the usage of optical flow.

2D卷积网络从大规模的图像数据集(Places205)中受益。  
3.3.1 Mapping from 2D to 3D CNNs 而且图像领域的数据远远不是视频数据集可比的。因此就有很多的研究者致力于把2D CNNs enjoy the benefit of pre-training brought by the 2D图像的领 large-scale of image datasets such as ImageNet [30] and 先运用到3D Places205 [270], which cannot be matched even with the领域 largest video datasets available today. On these datasets numerous efforts have been devoted to the search for 2D CNN architectures that are more accurate and generalize better. Below we describe the efforts to capitalize on these advances for 3D CNNs.

ResNet直接 ResNet3D [74] directly took 2D ResNet [76] and re-use 2D卷积网络的结构，并且把卷积核更换为3D卷积核受到了ResNext的启发，Chen等人提出了一个由多纤维网络。通过把一个复杂的网络分割为多个轻量级的网络(fiber)的集合

3.3.2 Unifying 2D and 3D CNNs

为了减小3D卷积计算的复杂度，P3D和R2+1D探索了3D卷积核分解。具体来说，一个3D卷积核可以分解为两个独立的卷积操作。To reduce the complexity of 3D network training, P3D [169] and R2+1D [204] explore the idea of 3D factorization. To be specific, a 3D kernel (e.g.,  $3 \times 3 \times 3$ ) can be factorized to two separate operations, a 2D spatial convolution (e.g.,  $1 \times 3 \times 3$ ) and a 1D temporal convolution (e.g.,  $3 \times 1 \times 1$ ). The differences between P3D and R2+1D are how they arrange the two factorized operations and how they formulate each residual block. Trajectory convolution [268] follows this idea but uses deformable convolution for the temporal component to better cope with motion.

另外一种简化3D卷积的方式是在一个网络中混合2D和3D卷积。MiCTNet [271] integrates 2D and 3D CNNs to generate deeper and more informative feature maps, while reducing training complexity in each round of spatio-temporal fusion. ARTNet [213] introduces an appearance-and-relation network by using a new building block. The building block consists of a spatial branch using 2D CNNs and a relation branch using 3D CNNs. S3D [239] combines the merits from approaches mentioned above. It first replaces the 3D convolutions at ARTNet中通过他们提出的模块构建了出现-关系网络。这个木块包含使用2D卷积的空间分支和使用3D卷积的事件分支。实现了更深的网络，并且得到的特征更加具有意义。

S3D中首先发现把网络底端的3D卷积核更换为2D卷积核能够提高篇网络的准确率，因此S3D中就把所有剩余的卷积核(类似P3D和R2+1D一样的)进行了分解。同时期的工作ECO也采用了类似的头重脚轻的网络来实现在线级别的视频理解

the bottom of the network with 2D kernels, and find that this kind of top-heavy network has higher recognition accuracy. Then S3D factorizes the remaining 3D kernels as P3D and R2+1D do, to further reduce the model size and training complexity. A concurrent work named ECO [283] also adopts such a top-heavy network to achieve online video understanding. 在3D卷积网络中，长期时间练习可以通过堆叠多个短时卷积网络。但是有用时间信息可能在

### 3.3.3 Long-range temporal modeling 网络的后半部分丢失，尤其是在很后面的阶段

In 3D CNNs, long-range temporal connection may be achieved by stacking multiple short temporal convolutions, e.g.,  $3 \times 3 \times 3$  filters. However, useful temporal information may be lost in the later stages of a deep network, especially for frames far apart. 为了能够实现长时时间建模，LTC引入并且评价了在多个视频帧之间的长期卷积。然而由于GPU显存的限制，LTC的作者牺牲了输入的分辨率。在这之后T3D使

In order to perform long-range temporal modeling, LTC [206] introduces and evaluates long-term temporal convolutions over a large number of video frames. However, limited by GPU memory, they have to sacrifice input resolution to use more frames. After that, T3D [32] adopted a densely connected structure [83] to keep the original temporal information as complete as possible to make the final prediction. Later, Wang *et al.* [219] introduced a new building block, termed non-local. Non-local is a generic operation similar to self-attention [207], which can be used for many computer vision tasks in a plug-and-play manner. As shown in Figure 6, they used a spacetime non-local module after later residual blocks to capture the long-range dependence in both space and temporal domain, and achieved improved performance over baselines without bells and whistles. Wu *et al.* [229] proposed a feature bank representation, which embeds information of the entire video into a memory cell, to make context-aware prediction. Recently, V4D [264] proposed video-level 4D CNNs, to model the evolution of long-range spatio-temporal representation with 4D convolutions.

为了进一步提升3D卷及网络的运算效率(即每秒进行的浮点计算次数，模型参数，计算延迟)，很多3D卷积网络的变体3.3.4 Enhancing 3D efficiency 被提出来了

In order to further improve the efficiency of 3D CNNs (i.e., in terms of GFLOPs, model parameters and latency), many variants of 3D CNNs begin to emerge. 收到了2D卷积网高效性的

Motivated by the development in efficient 2D networks, researchers started to adopt channel-wise separable convolution and extend it for video classification [111, 203]. CSN [203] reveals that it is a good practice to factorize 3D convolutions by separating channel interactions and spatio-temporal interactions, and is able to obtain state-of-the-art performance while being 2 to 3 times faster than the previous best approaches. These methods are also related to multi-fiber networks [20] as they are all inspired by group convolution.

Recently, Feichtenhofer *et al.* [45] proposed SlowFast, an efficient network with a slow pathway and a fast path-

way. The network design is partially inspired by the biological Parvo- and Magnocellular cells in the primate visual systems. As shown in Figure 6, the slow pathway operates at low frame rates to capture detailed semantic information, while the fast pathway operates at high temporal resolution to capture rapidly changing motion. In order to incorporate motion information such as in two-stream networks, SlowFast adopts a lateral connection to fuse the representation learned by each pathway. Since the fast pathway can be made very lightweight by reducing its channel capacity, the overall efficiency of SlowFast is largely improved. Although SlowFast has two pathways, it is different from the two-stream networks [187], because the two pathways are designed to model different temporal speeds, not spatial and temporal modeling. There are several concurrent papers using multiple pathways to balance the accuracy and efficiency [43].

Following this line, Feichtenhofer [44] introduced X3D that progressively expand a 2D image classification architecture along multiple network axes, such as temporal duration, frame rate, spatial resolution, width, bottleneck width, and depth. X3D pushes the 3D model modification/factorization to an extreme, and is a family of efficient video networks to meet different requirements of target complexity. With similar spirit, A3D [276] also leverages multiple network configurations. However, A3D trains these configurations jointly and during inference deploys only one model. This makes the model at the end more efficient. In the next section, we will continue to talk about efficient video modeling, but not based on 3D convolutions.

### 3.4. Efficient Video Modeling

With the increase of dataset size and the need for deployment, efficiency becomes an important concern.

If we use methods based on two-stream networks, we need to pre-compute optical flow and store them on local disk. Taking Kinetics400 dataset as an illustrative example, storing all the optical flow images requires 4.5TB disk space. Such a huge amount of data would make I/O become the tightest bottleneck during training, leading to a waste of GPU resources and longer experiment cycle. In addition, pre-computing optical flow is not cheap, which means all the two-stream networks methods are not real-time.

If we use methods based on 3D CNNs, people still find that 3D CNNs are hard to train and challenging to deploy. In terms of training, a standard SlowFast network trained on Kinetics400 dataset using a high-end 8-GPU machine takes 10 days to complete. Such a long experimental cycle and huge computing cost makes video understanding research only accessible to big companies/labs with abundant computing resources. There are several recent attempts to speed up the training of deep video models [230], but these are still expensive compared to most image-based computer vi-

sion tasks. In terms of deployment, 3D convolution is not as well supported as 2D convolution for different platforms. Furthermore, 3D CNNs require more video frames as input which adds additional IO cost.

Hence, starting from year 2018, researchers started to investigate other alternatives to see how they could improve accuracy and efficiency at the same time for video action recognition. We will review recent efficient video modeling methods in several categories below.

#### 3.4.1 Flow-mimic approaches

One of the major drawback of two-stream networks is its need for optical flow. Pre-computing optical flow is computationally expensive, storage demanding, and not end-to-end trainable for video action recognition. It is appealing if we can find a way to encode motion information without using optical flow, at least during inference time.

[146] and [35] are early attempts for learning to estimate optical flow inside a network for video action recognition. Although these two approaches do not need optical flow during inference, they require optical flow during training in order to train the flow estimation network. Hidden two-stream networks [278] proposed MotionNet to replace the traditional optical flow computation. MotionNet is a lightweight network to learn motion information in an unsupervised manner, and when concatenated with the temporal stream, is end-to-end trainable. Thus, hidden two-stream CNNs [278] only take raw video frames as input and directly predict action classes without explicitly computing optical flow, regardless of whether its the training or inference stage. PAN [257] mimics the optical flow features by computing the difference between consecutive feature maps. Following this direction, [197, 42, 116, 164] continue to investigate end-to-end trainable CNNs to learn optical-flow-like features from data. They derive such features directly from the definition of optical flow [255]. MARS [26] and D3D [191] used knowledge distillation to combine two-stream networks into a single stream, e.g., by tuning the spatial stream to predict the outputs of the temporal stream. Recently, Kwon *et al.* [110] introduced MotionSqueeze module to estimate the motion features. The proposed module is end-to-end trainable and can be plugged into any network, similar to [278].

#### 3.4.2 Temporal modeling without 3D convolution

A simple and natural choice to model temporal relationship between frames is using 3D convolution. However, there are many alternatives to achieve this goal. Here, we will review some recent work that performs temporal modeling without 3D convolution.

Lin *et al.* [128] introduce a new method, termed temporal shift module (TSM). TSM extends the shift operation

[228] to video understanding. It shifts part of the channels along the temporal dimension, thus facilitating information exchanged among neighboring frames. In order to keep spatial feature learning capacity, they put temporal shift module inside the residual branch in a residual block. Thus all the information in the original activation is still accessible after temporal shift through identity mapping. The biggest advantage of TSM is that it can be inserted into a 2D CNN to achieve temporal modeling at zero computation and zero parameters. Similar to TSM, TIN [182] introduces a temporal interlacing module to model the temporal convolution.

There are several recent 2D CNNs approaches using attention to perform long-term temporal modeling [92, 122, 132, 133]. STM [92] proposes a channel-wise spatio-temporal module to present the spatio-temporal features and a channel-wise motion module to efficiently encode motion features. TEA [122] is similar to STM, but inspired by SENet [81], TEA uses motion features to recalibrate the spatio-temporal features to enhance the motion pattern. Specifically, TEA has two components: motion excitation and multiple temporal aggregation, while the first one handles short-range motion modeling and the second one efficiently enlarge the temporal receptive field for long-range temporal modeling. They are complementary and both light-weight, thus TEA is able to achieve competitive results with previous best approaches while keeping FLOPs as low as many 2D CNNs. Recently, TEINet [132] also adopts attention to enhance temporal modeling. Note that, the above attention-based methods are different from non-local [219], because they use channel attention while non-local uses spatial attention.

### 3.5. Miscellaneous

In this section, we are going to show several other directions that are popular for video action recognition in the last decade.

#### 3.5.1 Trajectory-based methods

While CNN-based approaches have demonstrated their superiority and gradually replaced the traditional hand-crafted methods, the traditional local feature pipeline still has its merits which should not be ignored, such as the usage of trajectory.

Inspired by the good performance of trajectory-based methods [210], Wang *et al.* [214] proposed to conduct trajectory-constrained pooling to aggregate deep convolutional features into effective descriptors, which they term as TDD. Here, a trajectory is defined as a path tracking down pixels in the temporal dimension. This new video representation shares the merits of both hand-crafted features and deep-learned features, and became one of the top performers on both UCF101 and HMDB51 datasets in the year

2015. Concurrently, Lan *et al.* [113] incorporated both Independent Subspace Analysis (ISA) and dense trajectories into the standard two-stream networks, and show the complementarity between data-independent and data-driven approaches. Instead of treating CNNs as a fixed feature extractor, Zhao *et al.* [268] proposed trajectory convolution to learn features along the temporal dimension with the help of trajectories.

#### 3.5.2 Rank pooling

There is another way to model temporal information inside a video, termed rank pooling (a.k.a learning-to-rank). The seminal work in this line starts from VideoDarwin [53], that uses a ranking machine to learn the evolution of the appearance over time and returns a ranking function. The ranking function should be able to order the frames of a video temporally, thus they use the parameters of this ranking function as a new video representation. VideoDarwin [53] is not a deep learning based method, but achieves comparable performance and efficiency.

To adapt rank pooling to deep learning, Fernando [54] introduces a differentiable rank pooling layer to achieve end-to-end feature learning. Following this direction, Bilen *et al.* [9] apply rank pooling on the raw image pixels of a video producing a single RGB image per video, termed dynamic images. Another concurrent work by Fernando [51] extends rank pooling to hierarchical rank pooling by stacking multiple levels of temporal encoding. Finally, [22] propose a generalization of the original ranking formulation [53] using subspace representations and show that it leads to significantly better representation of the dynamic evolution of actions, while being computationally cheap.

#### 3.5.3 Compressed video action recognition

Most video action recognition approaches use raw videos (or decoded video frames) as input. However, there are several drawbacks of using raw videos, such as the huge amount of data and high temporal redundancy. Video compression methods usually store one frame by reusing contents from another frame (i.e., I-frame) and only store the difference (i.e., P-frames and B-frames) due to the fact that adjacent frames are similar. Here, the I-frame is the original RGB video frame, and P-frames and B-frames include the motion vector and residual, which are used to store the difference. Motivated by the developments in the video compression domain, researchers started to adopt compressed video representations as input to train effective video models.

Since the motion vector has coarse structure and may contain inaccurate movements, Zhang *et al.* [256] adopted knowledge distillation to help the motion-vector-based temporal stream mimic the optical-flow-based temporal stream.

双流网络的结果表明: 1. 没有动作/时间建模, 纯卷积(DeepVideo)的表现非常烂. 2. 传统方法中得到的知识(TDD的Trajectory Pooling, TLE的Global Feature Encoding)对于深度网络来说非常有助

3D卷积的结果表明: 1. 优化3D卷积核其实很难(C3D在大型的视频数据集上进行了训练, 但是性能上却表现得比同时期的一些工作(主要是双流网络)要差), 因此最近有一些工作, 例如I3D, P3D, R2+1D和S3D把3D卷积核分解为2D空间卷积核和1D的时间卷积核来简化训练

Method	Pre-train	Flow	Backbone	Venue	UCF101	HMDB51	Kinetics400
DeepVideo [99]	I	-	AlexNet	CVPR 2014	65.4	-	-
Two-stream [187]	I	✓	CNN-M	NeurIPS 2014	88.0	59.4	-
LRCN [37]	I	✓	CNN-M	CVPR 2015	82.3	-	-
TDD [214]	I	✓	CNN-M	CVPR 2015	90.3	63.2	-
Fusion [50]	I	✓	VGG16	CVPR 2016	92.5	65.4	-
TSN [218]	I	✓	BN-Inception	ECCV 2016	94.0	68.5	<b>73.9</b>
TLE [36]	I	✓	BN-Inception	CVPR 2017	<b>95.6</b>	<b>71.1</b>	-
3D卷积(或者把3D卷积分解为2D空间卷积和1D时间卷积). 关注与训练效率的方法	C3D [202]	S	VGG16-like	ICCV 2015	82.3	56.8	59.5
	I3D [14]	I,K	BN-Inception-like	CVPR 2017	95.6	74.8	71.1
	P3D [169]	S	ResNet50-like	ICCV 2017	88.6	-	71.6
	ResNet3D [74]	K	ResNeXt101-like	CVPR 2018	94.5	70.2	65.1
	R2+1D [204]	K	ResNet34-like	CVPR 2018	96.8	74.5	72.0
	NL I3D [219]	I	ResNet101-like	CVPR 2018	-	-	77.7
	S3D [239]	I,K	BN-Inception-like	ECCV 2018	96.8	<b>75.9</b>	74.7
	SlowFast [45]	-	ResNet101-NL-like	ICCV 2019	-	-	79.8
	X3D-XXL [44]	-	ResNet-like	CVPR 2020	-	-	<b>80.4</b>
	TPN [248]	-	ResNet101-like	CVPR 2020	-	-	78.9
	CIDC [121]	-	ResNet50-like	ECCV 2020	<b>97.9</b>	75.2	75.5
Hidden TSN [278] OFF [197] TSM [128] STM [92] TEINet [132] TEA [122] MSNet [110]	I	-	BN-Inception	ACCV 2018	93.2	66.8	72.8
	I	-	BN-Inception	CVPR 2018	96.0	74.2	-
	I	-	ResNet50	ICCV 2019	95.9	73.5	74.1
	I,K	-	ResNet50-like	ICCV 2019	96.2	72.2	73.7
	I,K	-	ResNet50-like	AAAI 2020	96.7	72.1	76.2
	I,K	-	ResNet50-like	CVPR 2020	<b>96.9</b>	73.3	76.1
	I,K	-	ResNet50-like	ECCV 2020	-	<b>77.4</b>	<b>76.4</b>

Table 2. Results of widely adopted methods on three scene-focused datasets. Pre-train indicates which dataset the model is pre-trained on. I: ImageNet, S: Sports1M and K: Kinetics400. NL represents non local.

However, their approach required extracting and processing each frame. They obtained comparable recognition accuracy with standard two-stream networks, but were 27 times faster. Wu *et al.* [231] used a heavyweight CNN for the I frame and lightweight CNN's for the P frames. This required that the motion vectors and residuals for each P frame be referred back to the I frame by accumulation. DMC-Net [185] is a follow-up work to [231] using adversarial loss. It adopts a lightweight generator network to help the motion vector capturing fine motion details, instead of knowledge distillation as in [256]. A recent paper SCSampler [106], also adopts compressed video representation for sampling salient clips and we will discuss it in the next section 3.5.4. As yet none of the compressed approaches can deal with B-frames due to the added complexity.

### 3.5.4 Frame/Clip sampling

Most of the aforementioned deep learning methods treat every video frame/clip equally for the final prediction. However, discriminative actions only happen in a few moments, and most of the other video content is irrelevant or weakly related to the labeled action category. There are several

drawbacks of this paradigm. First, training with a large proportion of irrelevant video frames may hurt performance. Second, such uniform sampling is not efficient during inference.

Partially inspired by how human understand a video using just a few glimpses over the entire video [251], many methods were proposed to sample the most informative video frames/clips for both improving the performance and making the model more efficient during inference.

KVM [277] is one of the first attempts to propose an end-to-end framework to simultaneously identify key volumes and do action classification. Later, [98] introduce AdaScan that predicts the importance score of each video frame in an online fashion, which they term as adaptive temporal pooling. Both of these methods achieve improved performance, but they still adopt the standard evaluation scheme which does not show efficiency during inference. Recent approaches focus more on the efficiency [41, 234, 8, 106]. AdaFrame [234] follows [251, 98] but uses a reinforcement learning based approach to search more informative video clips. Concurrently, [8] uses a teacher-student framework, i.e., a see-it-all teacher can be used to train a compute ef-

ficient see-very-little student. They demonstrate that the efficient student network can reduce the inference time by 30% and the number of FLOPs by approximately 90% with negligible performance drop. Recently, SCSampler [106] trains a lightweight network to sample the most salient video clips based on compressed video representations, and achieve state-of-the-art performance on both Kinetics400 and Sports1M dataset. They also empirically show that such saliency-based sampling is not only efficient, but also enjoys higher accuracy than using all the video frames.

### 3.5.5 Visual tempo

Visual tempo is a concept to describe how fast an action goes. Many action classes have different visual tempos. In most cases, the key to distinguish them is their visual tempos, as they might share high similarities in visual appearance, such as walking, jogging and running [248]. There are several papers exploring different temporal rates (tempos) for improved temporal modeling [273, 147, 82, 281, 45, 248]. Initial attempts usually capture the video tempo through sampling raw videos at multiple rates and constructing an input-level frame pyramid [273, 147, 281]. Recently, SlowFast [45], as we discussed in section 3.3.4, utilizes the characteristics of visual tempo to design a two-pathway network for better accuracy and efficiency trade-off. CIDC [121] proposed directional temporal modeling along with a local backbone for video temporal modeling. TPN [248] extends the tempo modeling to the feature-level and shows consistent improvement over previous approaches.

We would like to point out that visual tempo is also widely used in self-supervised video representation learning [6, 247, 16] since it can naturally provide supervision signals to train a deep network. We will discuss more details on self-supervised video representation learning in section 5.13.

**本节我们在几个基准数据集上比较了流行的方法. 更明确的说, 4. Evaluation and Benchmarking 我们首先介绍了几个标准的评价方法. 然后我们把现有的数据集分成了三种:** In this section, we compare popular approaches on benchmark datasets. To be specific, we first introduce standard evaluation schemes in section 4.1. Then we divide common benchmarks into three categories, scene-focused (UCF101, HMDB51 and Kinetics400 in section 4.2), motion-focused (Sth-Sth V1 and V2 in section 4.3) and multi-label (Charades in section 4.4). In the end, we present a fair comparison among popular methods in terms of both recognition accuracy and efficiency in section 4.5.

### 4.1. Evaluation scheme 方法的效率和精度进行了比较

During model training, we usually randomly pick a video frame/clip to form mini-batch samples. However, for evaluation, we need a standardized pipeline in order to perform

在模型训练阶段, 我们通常会随机选取视频帧或者视频的片段来形成mini-batch的example. 但是在测试阶段, 我们需要标准的pipeline来得到公平的比较

对于卷积网络而言, 一个广泛采用的评价方案就是从每个视频中均匀抽取出来25帧形成测试样本. 对于抽出来的每一帧, 都会进行ten-crop数据增强, 具体来说就是把一张图像的中心和四个角切出来, 然后再进行水平反转. 这样一个测试样本就由250帧图像组成.

对于3D卷积网络, 一种广泛采用的评价方法就是从每个视频fair comparisons. 里面抽取得到10帧图像, 然后短边放缩到256个像素, 然后用三段来包

括整个空间信息

For 2D CNNs, a widely adopted evaluation scheme is to evenly sample 25 frames from each video following [187, 217]. For each frame, we perform ten-crop data augmentation by cropping the 4 corners and 1 center, flipping them horizontally and averaging the prediction scores (before softmax operation) over all crops of the samples, i.e., this means we use 250 frames per video for inference.

For 3D CNNs, a widely adopted evaluation scheme termed 30-view strategy is to evenly sample 10 clips from each video following [219]. For each video clip, we perform three-crop data augmentation. To be specific, we scale the shorter spatial side to 256 pixels and take three crops of  $256 \times 256$  to cover the spatial dimensions and average the prediction scores.

However, the evaluation schemes are not fixed. They are evolving and adapting to new network architectures and different datasets. For example, TSM [128] only uses two clips per video for small-sized datasets [190, 109], and perform three-crop data augmentation for each clip despite its being a 2D CNN. We will mention any deviations from the standard evaluation pipeline. 对于评价的指标, 对于单标签动作识别

In terms of evaluation metric, we report accuracy for single-label action recognition, and mAP (mean average precision) for multi-label action recognition. 作识别使用mAP作为指

### 4.2. Scene-focused datasets

这部分我们在关注于场景的三个数据集: UCF101, HMDB51和

Here, we compare recent state-of-the-art approaches on Kinect400 scene-focused datasets: UCF101, HMDB51 and Kinetics400. The reason we call them scene-focused is because most action videos in these datasets are short, and can be recognized by static scene appearance alone as shown in Figure 4. 是场景数据集, 是因为这些数据集中的视频是非常

Following the chronology, we first present results for early attempts of using deep learning and the two-stream networks at the top of Table 2. We make several observations. First, without motion/temporal modeling, the performance of DeepVideo [99] is inferior to all other approaches. Second, it is helpful to transfer knowledge from traditional methods (non-CNN-based) to deep learning. For example, TDD [214] uses trajectory pooling to extract motion-aware CNN features. TLE [36] embeds global feature encoding, which is an important step in traditional video action recognition pipeline, into a deep network.

We then compare 3D CNNs based approaches in the middle of Table 2. Despite training on a large corpus of videos, C3D [202] performs inferior to concurrent work [187, 214, 217], possibly due to difficulties in optimization of 3D kernels. Motivated by this, several papers - I3D [14], P3D [169], R2+1D [204] and S3D [239] factorize 3D convolution filters to 2D spatial kernels and 1D temporal kernels to ease the training. In addition, I3D introduces an inflation strategy to avoid training from scratch by bootstrap-

我们接下来比较了3D卷积的方法. 虽然C3D在大型的视频数据集上进行了训练, 但是性能上却表现得比同时期的一些工作(主要是双流网络)要差, 这就表明了优化3D卷积核其实很难. 因此最近有一些工作, 例如I3D, P3D, R2+1D和S3D把3D卷积核分解为2D空间卷积核和1D的时间卷积核来简化训练

Method	Pre-train	Backbone	Frames×Views	Venue	V1 Top1	V2 Top1
TSN [218]	I	BN-Inception	8×1	ECCV 2016	19.7	-
I3D [14]	I,K	ResNet50-like	32×6	CVPR 2017	41.6	-
NL I3D [219]	I,K	ResNet50-like	32×6	CVPR 2018	44.4	-
NL I3D + GCN [220]	I,K	ResNet50-like	32×6	ECCV 2018	46.1	-
ECO [283]	K	BNIncep+ResNet18	16×1	ECCV 2018	41.4	-
TRN [269]	I	BN-Inception	8×1	ECCV 2018	42.0	48.8
STM [92]	I	ResNet50-like	8×30	ICCV 2019	49.2	-
STM [92]	I	ResNet50-like	16×30	ICCV 2019	50.7	-
TSM [128]	K	ResNet50	8×1	ICCV 2019	45.6	59.1
TSM [128]	K	ResNet50	16×1	ICCV 2019	47.2	63.4
bLVNet-TAM [43]	I	BLNet-like	8×2	NeurIPS 2019	46.4	59.1
bLVNet-TAM [43]	I	BLNet-like	16×2	NeurIPS 2019	48.4	61.7
TEA [122]	I	ResNet50-like	8×1	CVPR 2020	48.9	-
TEA [122]	I	ResNet50-like	16×1	CVPR 2020	51.9	-
TSM + TPN [248]	K	ResNet50-like	8×1	CVPR 2020	49.0	62.0
MSNet [110]	I	ResNet50-like	8×1	ECCV 2020	50.9	63.0
MSNet [110]	I	ResNet50-like	16×1	ECCV 2020	<b>52.1</b>	<b>64.7</b>
TIN [182]	K	ResNet50-like	16×1	AAAI 2020	47.0	60.1
TEINet [132]	I	ResNet50-like	8×1	AAAI 2020	47.4	61.3
TEINet [132]	I	ResNet50-like	16×1	AAAI 2020	49.9	62.1

通过这些技巧，这些3D网络在没有使用光流网的前提下超越了双流网络的性能。此外，通过此使用更多参数来简化3D模型的训练，避免了从头训练一个网络的训练样

本，额外 By using these techniques, they achieve comparable performance to the best two-stream network methods [36] without the need for optical flow. Furthermore, recent 3D models obtain even higher accuracy, by using more training samples [203], additional pathways [45], or architecture search [44].

最后，我们展示了最近的模型 Finally, we show recent efficient models in the bottom of Table 2. We can see that these methods are able to achieve higher recognition accuracy than two-stream networks (top), and comparable performance to 3D CNNs (middle). Since they are 2D CNNs and do not use optical flow, these methods are efficient in terms of both training and inference. Most of them are real-time approaches, and some can do online video action recognition [128]. We believe 2D CNN plus temporal modeling is a promising direction due to the need of efficiency. Here, temporal modeling can be attention based, flow based or 3D kernel based.

**4.3. Motion-focused datasets** 有前景的方向，因为它非常高效。此外，时间建模的方法可以是注意力机制或光流的方法，或者3D卷积的方法。 In this section, we compare the recent state-of-the-art approaches on the 20BN-Something-Something (Sth-Sth) dataset. We report top1 accuracy on both V1 and V2. Sth-Sth datasets focus on humans performing basic actions with daily objects. Different from scene-focused datasets, background scene in Sth-Sth datasets contributes little to the final action class prediction. In addition, there are classes

在本节，我们比较了最近的SOTA在SSV1和SSV2上的表现。我们报告了V1和V2上的top1准确率。和场景数据集不一样，动作数据集中的背景对动作识别的贡献非常的小。此外，数据集中还存在把东西从左移到右和从右移到左这两类动作，因此动作数据集要求模型有很强的动作理解能力

such as “Pushing something from left to right” and “Pushing something from right to left”, and which require strong motion reasoning. 通过比较先前的工作在SSV2上的表现，我们发现：1. 相同的网络使用更长的输入得到的性能更好。2. 使用时间卷积的模型比简单的3D模型更好。

#### 4.4. Multi-label datasets

In this section, we first compare the recent state-of-the-art approaches on Charades dataset [186] and then we list some recent work that use assemble model or additional object information on Charades.

Comparing the previous work in Table 4, we make the following observations. First, 3D models [229, 45] generally perform better than 2D models [186, 231] and 2D models with optical flow input. This indicates that the spatio-temporal reasoning is critical for long-term complex concurrent action understanding. Second, longer input helps with the recognition [229] probably because some actions require long-term feature to recognize. Third, models with strong backbones that are pre-trained on larger datasets gen-

通过对先前文章的比较，我们得到如下的观察：1. 3D模型通常表现的比2D模型要好，即便2D模型以光流作为输入。2. 使用更长的输入更有利动作的辨识，可能是因为有一些动作本身就需要长的输入。3. 在大型数据及上预训练的强大的模型作为backbone的方法通常表现的要好。

Method	Extra-information	Backbone	Pre-train	Venue	mAP
2D CNN [186]	-	AlexNet	I	ECCV 2016	11.2
Two-stream [186]	flow	VGG16	I	ECCV 2016	22.4
ActionVLAD [63]	-	VGG16	I	CVPR 2017	21.0
CoViAR [231]	-	ResNet50-like	-	CVPR 2018	21.9
MultiScale TRN [269]	-	BN-Inception-like	I	ECCV 2018	<b>25.2</b>
I3D [14]	-	BN-Inception-like	K400	CVPR 2017	32.9
STRG [220]	-	ResNet101-NL-like	K400	ECCV 2018	39.7
LFB [229]	-	ResNet101-NL-like	K400	CVPR 2019	42.5
TC [84]		ResNet101-NL-like	K400	ICCV 2019	41.1
HAF [212]	IDT + flow	BN-Inception-like	K400	ICCV 2019	43.1
SlowFast [45]	-	ResNet-like	K400	ICCV 2019	42.5
SlowFast [45]	-	ResNet-like	K600	ICCV 2019	<b>45.2</b>
Action-Genome [90]	person + object	ResNet-like	-	CVPR 2020	<b>60.1</b>
AssembleNet++ [177]	flow + object	ResNet-like	-	ECCV 2020	59.9

Table 4. **Charades evaluation using mAP**, calculated using the officially provided script. NL: non-local network. Pre-train indicates which dataset the model is pre-trained on. I: ImageNet, K400: Kinetics400 and K600: Kinetics600.

此外,一些研究者最近研究了不同的方法来处理并发的动作识别,例如集成模型或者使用额外的人物交互信息。这些方法极大地超过了原有方法,通常有更好的表现 [45]。这是因为 Charades 是一个中等规模的数据集,其中并不包含足够的多样性来训练一个深度模型。

Recently, researchers explored the alternative direction for complex concurrent action recognition by assembling models [177] or providing additional human-object interaction information [90]. These papers significantly outperformed previous literature that only finetune a single model on Charades. It demonstrates that exploring spatio-temporal human-object interactions and finding a way to avoid overfitting are the keys for concurrent action understanding.

#### 4.5. Speed comparison

To deploy a model in real-life applications, we usually need to know whether it meets the speed requirement before we can proceed. In this section, we evaluate the approaches mentioned above to perform a thorough comparison in terms of (1) number of parameters, (2) FLOPS, (3) latency and (4) frame per second.

We present the results in Table 5. Here, we use the models in the GluonCV video action recognition model zoo<sup>3</sup> since all these models are trained using the same data, same data augmentation strategy and under same 30-view evaluation scheme, thus fair comparison. All the timings are done on a single Tesla V100 GPU with 105 repeated runs, while the first 5 runs are ignored for warming up. We always use a batch size of 1. In terms of model input, we use the suggested settings in the original paper.

As we can see in Table 5, if we compare latency, 2D models are much faster than all other 3D variants. This is

<sup>3</sup>To reproduce the numbers in Table 5, please visit <https://github.com/dmlc/gluon-cv/blob/master/scripts/action-recognition/README.md>

其次, FLOPS与真实的处理延迟之间并不是强相关的

probably why most real-world video applications still adopt frame-wise methods. Secondly, as mentioned in [170, 259], FLOPS is not strongly correlated with the actual inference time (i.e., latency). Third, if comparing performance, most 3D models give similar accuracy around 75%, but pre-training with a larger dataset can significantly boost the performance<sup>4</sup>. This indicates the importance of training data and partially suggests that self-supervised pre-training might be a promising way to further improve existing methods.

大多数3D模型的性能都在75%左右，但是在大型数据集上通过预训练可以极大地提升准确度

## 5. Discussion and Future Work

We have surveyed more than 200 deep learning based methods for video action recognition since year 2014. Despite the performance on benchmark datasets plateauing, there are many active and promising directions in this task worth exploring.

### **5.1. Analysis and insights**

More and more methods have been developed to improve video action recognition, at the same time, there are some papers summarizing these methods and providing analysis and insights. Huang *et al.* [82] perform an explicit analysis of the effect of temporal information for video understanding. They try to answer the question “how important is the motion in the video for recognizing the action”. Feichtenhofer *et al.* [48, 49] provide an amazing visualization of what two-stream models have learned in order to understand how these deep representations work and what they are capturing. Li *et al.* [124] introduce a concept, representation bias of a dataset, and find that current datasets

<sup>4</sup>Note that, R2+1D-ResNet152\* and CSN-ResNet152\* in Table 5 are pretrained on a large-scale IJG65M dataset [60].

从延迟的角度来说, 2D模型相比于3D模型可以更快的获得输出

Model	Input	FLOPS (G)	# of params (M)	FPS	Latency (s)	Acc (%)
TSN-ResNet18 [218]	$3 \times 224 \times 224$	3.671	21.49	151.96	0.0066	69.85
TSN-ResNet34 [218]	$3 \times 224 \times 224$	1.819	11.382	264.01	0.0038	66.73
TSN-ResNet50 [218]	$3 \times 224 \times 224$	4.110	24.328	114.05	0.0088	70.88
TSN-ResNet101 [218]	$3 \times 224 \times 224$	7.833	43.320	59.56	0.0167	72.25
TSN-ResNet152 [218]	$3 \times 224 \times 224$	11.558	58.963	36.93	0.0271	72.45
I3D-ResNet50 [14]	$3 \times 32 \times 224 \times 224$	33.275	28.863	1719.50	0.0372	74.87
I3D-ResNet101 [14]	$3 \times 32 \times 224 \times 224$	51.864	52.574	1137.74	0.0563	75.10
I3D-ResNet50-NL [219]	$3 \times 32 \times 224 \times 224$	47.737	38.069	1403.16	0.0456	75.17
I3D-ResNet101-NL [219]	$3 \times 32 \times 224 \times 224$	66.326	61.780	999.94	0.0640	75.81
R2+1D-ResNet18 [204]	$3 \times 16 \times 112 \times 112$	40.645	31.505	804.31	0.0398	71.72
R2+1D-ResNet34 [204]	$3 \times 16 \times 112 \times 112$	75.400	61.832	503.17	0.0636	72.63
R2+1D-ResNet50 [204]	$3 \times 16 \times 112 \times 112$	65.543	53.950	667.06	0.0480	74.92
R2+1D-ResNet152* [204]	$3 \times 32 \times 112 \times 112$	252.900	118.227	546.19	0.1172	81.34
CSN-ResNet152* [203]	$3 \times 32 \times 224 \times 224$	74.758	29.704	435.77	0.1469	83.18
I3D-Slow-ResNet50 [45]	$3 \times 8 \times 224 \times 224$	41.919	32.454	1702.60	0.0376	74.41
I3D-Slow-ResNet50 [45]	$3 \times 16 \times 224 \times 224$	83.838	32.454	1406.00	0.0455	76.36
I3D-Slow-ResNet50 [45]	$3 \times 32 \times 224 \times 224$	167.675	32.454	860.74	0.0744	77.89
I3D-Slow-ResNet101 [45]	$3 \times 8 \times 224 \times 224$	85.675	60.359	1114.22	0.0574	76.15
I3D-Slow-ResNet101 [45]	$3 \times 16 \times 224 \times 224$	171.348	60.359	876.20	0.0730	77.11
I3D-Slow-ResNet101 [45]	$3 \times 32 \times 224 \times 224$	342.696	60.359	541.16	0.1183	78.57
SlowFast-ResNet50-4x16 [45]	$3 \times 32 \times 224 \times 224$	27.820	34.480	1396.45	0.0458	75.25
SlowFast-ResNet50-8x8 [45]	$3 \times 32 \times 224 \times 224$	50.583	34.566	1297.24	0.0493	76.66
SlowFast-ResNet101-8x8 [45]	$3 \times 32 \times 224 \times 224$	96.794	62.827	889.62	0.0719	76.95
TPN-ResNet50 [248]	$3 \times 8 \times 224 \times 224$	50.457	71.800	1350.39	0.0474	77.04
TPN-ResNet50 [248]	$3 \times 16 \times 224 \times 224$	99.929	71.800	1128.39	0.0567	77.33
TPN-ResNet50 [248]	$3 \times 32 \times 224 \times 224$	198.874	71.800	716.89	0.0893	78.90
TPN-ResNet101 [248]	$3 \times 8 \times 224 \times 224$	94.366	99.705	942.61	0.0679	78.10
TPN-ResNet101[248]	$3 \times 16 \times 224 \times 224$	187.594	99.705	754.00	0.0849	79.39
TPN-ResNet101[248]	$3 \times 32 \times 224 \times 224$	374.048	99.705	479.77	0.1334	79.70

带\*的是在大型的IG65M上预训练的模型

Table 5. Comparison on both efficiency and accuracy. Top: 2D models and bottom: 3D models. FLOPS means floating point operations per second. FPS indicates how many video frames can the model process per second. Latency is the actual running time to complete one network forward given the input. Acc is the top-1 accuracy on Kinetics400 dataset. TSN, I3D, I3D-slow families are pretrained on ImageNet. R2+1D, SlowFast and TPN families are trained from scratch.

are biased towards static representations. Experiments on such biased datasets may lead to erroneous conclusions, which is indeed a big problem that limits the development of video action recognition. Recently, Piergiovanni *et al.* introduced the AVID [165] dataset to cope with data bias by collecting data from diverse groups of people. These papers provide great insights to help fellow researchers to understand the challenges, open problems and where the next breakthrough might reside.

## 5.2. Data augmentation

Numerous data augmentation methods have been proposed in image recognition domain, such as mixup [258], cutout [31], CutMix [254], AutoAugment [27], FastAutoAug [126], etc. However, video action recognition still adopts basic data augmentation techniques introduced before year 2015 [217, 188], including random resizing, random cropping and random horizontal flipping. Recently,

SimCLR [17] and other papers have shown that color jittering and random rotation greatly help representation learning. Hence, an investigation of using different data augmentation techniques for video action recognition is particularly useful. This may change the data pre-processing pipeline for all existing methods.

## 5.3. Video domain adaptation

Domain adaptation (DA) has been studied extensively in recent years to address the domain shift problem. Despite the accuracy on standard datasets getting higher and higher, the generalization capability of current video models across datasets or domains is less explored.

There is early work on video domain adaptation [193, 241, 89, 159]. However, these literature focus on small-scale video DA with only a few overlapping categories, which may not reflect the actual domain discrepancy and may lead to biased conclusions. Chen *et al.* [15] intro-

duce two larger-scale datasets to investigate video DA and find that aligning temporal dynamics is particularly useful. Pan *et al.* [152] adopts co-attention to solve the temporal misalignment problem. Very recently, Munro *et al.* [145] explore a multi-modal self-supervision method for fine-grained video action recognition and show the effectiveness of multi-modality learning in video DA. Shuffle and Attend [95] argues that aligning features of all sampled clips results in a sub-optimal solution due to the fact that all clips do not include relevant semantics. Therefore, they propose to use an attention mechanism to focus more on informative clips and discard the non-informative ones. In conclusion, video DA is a promising direction, especially for researchers with less computing resources.

#### 5.4. Neural architecture search

Neural architecture search (NAS) has attracted great interest in recent years and is a promising research direction. However, given its greedy need for computing resources, only a few papers have been published in this area [156, 163, 161, 178]. The TVN family [161], which jointly optimize parameters and runtime, can achieve competitive accuracy with human-designed contemporary models, and run much faster (within 37 to 100 ms on a CPU and 10 ms on a GPU per 1 second video clip). AssembleNet [178] and AssembleNet++ [177] provide a generic approach to learn the connectivity among feature representations across input modalities, and show surprisingly good performance on Charades and other benchmarks. AttentionNAS [222] proposed a solution for spatio-temporal attention cell search. The found cell can be plugged into any network to improve the spatio-temporal features. All previous papers do show their potential for video understanding.

Recently, some efficient ways of searching architectures have been proposed in the image recognition domain, such as DARTS [130], Proxyless NAS [11], ENAS [160], one-shot NAS [7], etc. It would be interesting to combine efficient 2D CNNs and efficient searching algorithms to perform video NAS for a reasonable cost.

#### 5.5. Efficient model development

Despite their accuracy, it is difficult to deploy deep learning based methods for video understanding problems in terms of real-world applications. There are several major challenges: (1) most methods are developed in offline settings, which means the input is a short video clip, not a video stream in an online setting; (2) most methods do not meet the real-time requirement; (3) incompatibility of 3D convolutions or other non-standard operators on non-GPU devices (e.g., edge devices).

Hence, the development of efficient network architecture based on 2D convolutions is a promising direction. The approaches proposed in the image classification do-

main can be easily adapted to video action recognition, e.g. model compression, model quantization, model pruning, distributed training [68, 127], mobile networks [80, 265], mixed precision training, etc. However, more effort is needed for the online setting since the input to most action recognition applications is a video stream, such as surveillance monitoring. We may need a new and more comprehensive dataset for benchmarking online video action recognition methods. Lastly, using compressed videos might be desirable because most videos are already compressed, and we have free access to motion information.

#### 5.6. New datasets

Data is more or at least as important as model development for machine learning. For video action recognition, most datasets are biased towards spatial representations [124], i.e., most actions can be recognized by a single frame inside the video without considering the temporal movement. Hence, a new dataset in terms of long-term temporal modeling is required to advance video understanding. Furthermore, most current datasets are collected from YouTube. Due to copyright/privacy issues, the dataset organizer often only releases the YouTube id or video link for users to download and not the actual video. The first problem is that downloading the large-scale datasets might be slow for some regions. In particular, YouTube recently started to block massive downloading from a single IP. Thus, many researchers may not even get the dataset to start working in this field. The second problem is, due to region limitation and privacy issues, some videos are not accessible anymore. For example, the original Kinetics400 dataset has over 300K videos, but at this moment, we can only crawl about 280K videos. On average, we lose 5% of the videos every year. It is impossible to do fair comparisons between methods when they are trained and evaluated on different data.

#### 5.7. Video adversarial attack

Adversarial examples have been well studied on image models. [199] first shows that an adversarial sample, computed by inserting a small amount of noise on the original image, may lead to a wrong prediction. However, limited work has been done on attacking video models.

This task usually considers two settings, a white-box attack [86, 119, 66, 21] where the adversary can always get the full access to the model including exact gradients of a given input, or a black-box one [93, 245, 226], in which the structure and parameters of the model are blocked so that the attacker can only access the (input, output) pair through queries. Recent work ME-Sampler [260] leverages the motion information directly in generating adversarial videos, and is shown to successfully attack a number of video classification models using many fewer queries. In summary,

this direction is useful since many companies provide APIs for services such as video classification, anomaly detection, shot detection, face detection, etc. In addition, this topic is also related to detecting DeepFake videos. Hence, investigating both attacking and defending methods is crucial to keeping these video services safe.

## 5.8. Zero-shot action recognition

Zero-shot learning (ZSL) has been trending in the image understanding domain, and has recently been adapted to video action recognition. Its goal is to transfer the learned knowledge to classify previously unseen categories. Due to (1) the expensive data sourcing and annotation and (2) the set of possible human actions is huge, zero-shot action recognition is a very useful task for real-world applications.

There are many early attempts [242, 88, 243, 137, 168, 57] in this direction. Most of them follow a standard framework, which is to first extract visual features from videos using a pretrained network, and then train a joint model that maps the visual embedding to a semantic embedding space. In this manner, the model can be applied to new classes by finding the test class whose embedding is the nearest-neighbor of the model’s output. A recent work URL [279] proposes to learn a universal representation that generalizes across datasets. Following URL [279], [10] present the first end-to-end ZSL action recognition model. They also establish a new ZSL training and evaluation protocol, and provide an in-depth analysis to further advance this field. Inspired by the success of pre-training and then zero-shot in NLP domain, we believe ZSL action recognition is a promising research topic.

## 5.9. Weakly-supervised video action recognition

Building a high-quality video action recognition dataset [190, 100] usually requires multiple laborious steps: 1) first sourcing a large amount of raw videos, typically from the internet; 2) removing videos irrelevant to the categories in the dataset; 3) manually trimming the video segments that have actions of interest; 4) refining the categorical labels. Weakly-supervised action recognition explores how to reduce the cost for curating training data.

The first direction of research [19, 60, 58] aims to reduce the cost of sourcing videos and accurate categorical labeling. They design training methods that use training data such as action-related images or partially annotated videos, gathered from publicly available sources such as Internet. Thus this paradigm is also referred to as webly-supervised learning [19, 58]. Recent work on omni-supervised learning [60, 64, 38] also follows this paradigm but features bootstrapping on unlabelled videos by distilling the models’ own inference results.

The second direction aims at removing trimming, the most time consuming part in annotation. Untrimmed-

Net [216] proposed a method to learn action recognition model on untrimmed videos with only categorical labels [149, 172]. This task is also related to weakly-supervised temporal action localization which aims to automatically generate the temporal span of the actions. Several papers propose to simultaneously [155] or iteratively [184] learn models for these two tasks.

## 5.10. Fine-grained video action recognition

Popular action recognition datasets, such as UCF101 [190] or Kinetics400 [100], mostly comprise actions happening in various scenes. However, models learned on these datasets could overfit to contextual information irrelevant to the actions [224, 227, 24]. Several datasets have been proposed to study the problem of fine-grained action recognition, which could examine the models’ capacities in modeling action specific information. These datasets comprise fine-grained actions in human activities such as cooking [28, 108, 174], working [103] and sports [181, 124]. For example, FineGym [181] is a recent large dataset annotated with different moves and sub-actions in gymnastic videos.

## 5.11. Egocentric action recognition

Recently, large-scale egocentric action recognition [29, 28] has attracted increasing interest with the emerging of wearable cameras devices. Egocentric action recognition requires a fine understanding of hand motion and the interacting objects in the complex environment. A few papers leverage object detection features to offer fine object context to improve egocentric video recognition [136, 223, 229, 180]. Others incorporate spatio-temporal attention [192] or gaze annotations [131] to localize the interacting object to facilitate action recognition. Similar to third-person action recognition, multi-modal inputs (e.g., optical flow and audio) have been demonstrated to be effective in egocentric action recognition [101].

## 5.12. Multi-modality

Multi-modal video understanding has attracted increasing attention in recent years [55, 3, 129, 167, 154, 2, 105]. There are two main categories for multi-modal video understanding. The first group of approaches use multi-modalities such as scene, object, motion, and audio to enrich the video representations. In the second group, the goal is to design a model which utilizes modality information as a supervision signal for pre-training models [195, 138, 249, 62, 2].

**Multi-modality for comprehensive video understanding** Learning a robust and comprehensive representation of video is extremely challenging due to the complexity

Method	Dataset	Video	Audio	Text	Size	Backbone	Venue	UCF101		HMDB51	
								Linear	FT	Linear	FT
AVTS [105]	K400	✓	✓	—	224	R(2+1)D-18	NeurIPS 2018	—	86.2	—	52.3
AVTS [105]	AS	✓	✓	—	224	R(2+1)D-18	NeurIPS 2018	—	89.1	—	58.1
CBT [194]	K600+	✓	—	✓	112	S3D	arXiv 2019	54.0	79.5	29.5	44.6
MIL-NCE [138]	HTM	✓	—	✓	224	S3D	CVPR 2020	82.7	91.3	53.1	61.0
ELO [162]	YT8M	✓	✓	—	224	R(2+1)D-50	CVPR 2020	—	93.8	64.5	67.4
XDC [3]	K400	✓	✓	—	224	R(2+1)D-18	NeurIPS 2020	—	86.8	—	52.6
XDC [3]	AS	✓	✓	—	224	R(2+1)D-18	NeurIPS 2020	—	93.0	—	63.7
XDC [3]	IG65M	✓	✓	—	224	R(2+1)D-18	NeurIPS 2020	—	94.6	—	66.5
XDC [3]	IG-K	✓	✓	—	224	R(2+1)D-18	NeurIPS 2020	—	<b>95.5</b>	—	68.9
AVID [144]	AS	✓	✓	—	224	R(2+1)D-50	arXiv 2020	—	91.5	—	64.7
GDT [154]	K400	✓	✓	—	112	R(2+1)D-18	arXiv 2020	—	89.3	—	60.0
GDT [154]	AS	✓	✓	—	112	R(2+1)D-18	arXiv 2020	—	92.5	—	66.1
GDT [154]	IG65M	✓	✓	—	112	R(2+1)D-18	arXiv 2020	—	95.2	—	72.8
MMV [2]	AS+ HTM	✓	✓	✓	200	S3D	NeurIPS 2020	89.6	92.5	62.6	69.6
MMV [2]	AS+ HTM	✓	✓	✓	200	TSM-50x2	NeurIPS 2020	<b>91.8</b>	95.2	<b>67.1</b>	<b>75.0</b>
OPN [115]	UCF101	✓	—	—	227	VGG	ICCV 2017	—	59.6	—	23.8
3D-RotNet [94]	K400	✓	—	—	112	R3D	arXiv 2018	—	62.9	—	33.7
ST-Puzzle [102]	K400	✓	—	—	224	R3D	AAAI 2019	—	63.9	—	33.7
VCOP [240]	UCF101	✓	—	—	112	R(2+1)D	CVPR 2019	—	72.4	—	30.9
DPC [71]	K400	✓	—	—	128	R-2D3D	ICCVW 2019	—	75.7	—	35.7
SpeedNet [6]	K400	✓	—	—	224	S3D-G	CVPR 2020	—	81.1	—	48.8
MemDPC [72]	K400	✓	—	—	224	R-2D3D	ECCV 2020	54.1	86.1	30.5	54.5
CoCLR [73]	K400	✓	—	—	128	S3D	NeurIPS 2020	<b>74.5</b>	87.9	<b>46.1</b>	54.6
CVRL [167]	K400	✓	—	—	224	R3D-50	arXiv 2020	—	92.2	—	66.7
CVRL [167]	K600	✓	—	—	224	R3D-50	arXiv 2020	—	<b>93.4</b>	—	<b>68.0</b>

Table 6. **Comparison of self-supervised video representation learning methods.** Top section shows the multi-modal video representation learning approaches and bottom section shows the video-only representation learning methods. From left to right, we show the self-supervised training setting, e.g. dataset, modalities, resolution, and architecture. Two last right columns show the action recognition results on two datasets UCF101 and HMDB51 to measure the quality of self-supervised pre-trained model. HTM: HowTo100M, YT8M: YouTube8M, AS: AudioSet, IG-K: IG-Kinetics, K400: Kinetics400 and K600: Kinetics600.

of semantics in videos. Video data often includes variations in different forms including appearance, motion, audio, text or scene [55, 129, 166]. Therefore, utilizing these multi-modal representations is a critical step in understanding video content more efficiently. The multi-modal representations of video can be approximated by gathering representations of various modalities such as scene, object, audio, motion, appearance and text. Ngiam *et al.* [148] was an early attempt to suggest using multiple modalities to obtain better features. They utilized videos of lips and their corresponding speech for multi-modal representation learning. Miech *et al.* [139] proposed a mixture-of embedding-experts model to combine multiple modalities including motion, appearance, audio, and face features and learn the shared embedding space between these modalities and text. Roig *et al.* [175] combines multiple modalities such as action, scene, object and acoustic event features in a pyramidal structure for action recognition. They show that adding each modality improves the final action recognition accuracy. Both CE [129] and MMT [55], follow a

similar research line to [139] where the goal is to combine multiple-modalities to obtain a comprehensive representation of video for joint video-text representation learning. Piergiovanni *et al.* [166] utilized textual data together with video data to learn a joint embedding space. Using this learned joint embedding space, the method is capable of doing zero-shot action recognition. This line of research is promising due to the availability of strong semantic extraction models and also success of transformers on both vision and language tasks.

**Multi-modality for self-supervised video representation learning** Most videos contain multiple modalities such as audio or text/caption. These modalities are great source of supervision for learning video representations [3, 144, 154, 2, 162]. Korbar *et al.* [105] incorporated the natural synchronization between audio and video as a supervision signal in their contrastive learning objective for self-supervised representation learning. In multi-modal self-supervised representation learning, the dataset plays an im-

portant role. VideoBERT [195] collected 310K cooking videos from YouTube. However, this dataset is not publicly available. Similar to BERT, VideoBERT used a “masked language model” training objective and also quantized the visual representations into “visual words”. Miech *et al.* [140] introduced HowTo100M dataset in 2019. This dataset includes 136M clips from 1.22M videos with their corresponding text. They collected the dataset from YouTube with the aim of obtaining instructional videos (how to perform an activity). In total, it covers 23.6K instructional tasks. MIL-NCE [138] used this dataset for self-supervised cross-modal representation learning. They tackled the problem of visually misaligned narrations, by considering multiple positive pairs in the contrastive learning objective. Act-BERT [275], utilized HowTo100M dataset for pre-training of the model in a self-supervised way. They incorporated visual, action, text and object features for cross modal representation learning. Recently AVLnet [176] and MMV [2] considered three modalities visual, audio and language for self-supervised representation learning. This research direction is also increasingly getting more attention due to the success of contrastive learning on many vision and language tasks and the access to the abundance of unlabeled multi-modal video data on platforms such as YouTube, Instagram or Flickr. The top section of Table 6 compares multi-modal self-supervised representation learning methods. We will discuss more work on video-only representation learning in the next section.

### 5.13. Self-supervised video representation learning

Self-supervised learning has attracted more attention recently as it is able to leverage a large amount of unlabeled data by designing a pretext task to obtain free supervisory signals from data itself. It first emerged in image representation learning. On images, the first stream of papers aimed at designing pretext tasks for completing missing information, such as image coloring [262] and image reordering [153, 61, 263]. The second stream of papers uses instance discrimination [235] as the pretext task and contrastive losses [235, 151] for supervision. They learn visual representation by modeling visual similarity of object instances without class labels [235, 75, 201, 18, 17].

Self-supervised learning is also viable for videos. Compared with images, videos has another axis, temporal dimension, which we can use to craft pretext tasks. Information completion tasks for this purpose include predicting the correct order of shuffled frames [141, 52] and video clips [240]. Jing *et al.* [94] focus on the spatial dimension only by predicting the rotation angles of rotated video clips. Combining temporal and spatial information, several tasks have been introduced to solve a space-time cubic puzzle, anticipate future frames [208], forecast long-term motions [134] and predict motion and appearance statis-

tics [211]. RSPNet [16] and visual tempo [247] exploit the relative speed between video clips as a supervision signal.

The added temporal axis can also provide flexibility in designing instance discrimination pretexts [67, 167]. Inspired by the decoupling of 3D convolution to spatial and temporal separable convolutions [239], Zhang *et al.* [266] proposed to decouple the video representation learning into two sub-tasks: spatial contrast and temporal contrast. Recently, Han *et al.* [72] proposed memory augmented dense predictive coding for self-supervised video representation learning. They split each video into several blocks and the embedding of future block is predicted by the combination of condensed representations in memory.

The temporal continuity in videos inspires researchers to design other pretext tasks around correspondence. Wang *et al.* [221] proposed to learn representation by performing cycle-consistency tracking. Specifically, they track the same object backward and then forward in the consecutive video frames, and use the inconsistency between the start and end points as the loss function. TCC [39] is a concurrent paper. Instead of tracking local objects, [39] used cycle-consistency to perform frame-wise temporal alignment as a supervision signal. [120] was a follow-up work of [221], and utilized both object-level and pixel-level correspondence across video frames. Recently, long-range temporal correspondence is modelled as a random walk graph to help learning video representation in [87].

We compare video self-supervised representation learning methods at the bottom section of Table 6. A clear trend can be observed that recent papers have achieved much better linear evaluation accuracy and fine-tuning accuracy comparable to supervised pre-training. This shows that self-supervised learning could be a promising direction towards learning better video representations.

**本文, 我们对200多篇视频动作识别的文章进行了综述.**

## 6. Conclusion

**虽然文章很多, 但是我们希望这篇文章读起来不是很难懂, 并且希望这个综述可以作为一个很容易上手的新手教程(对于刚入门的人), 或者是一个非常有启发的讨论(对于寻找新的研究方向的这个领域的研究者)**

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