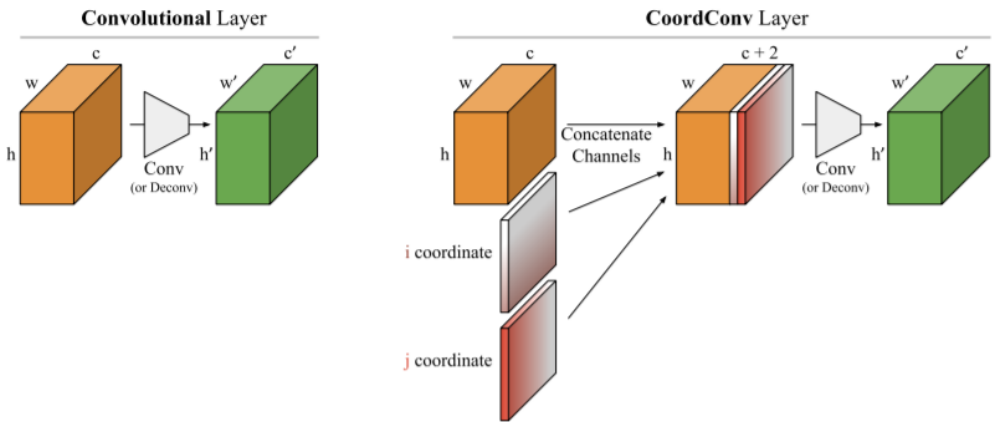
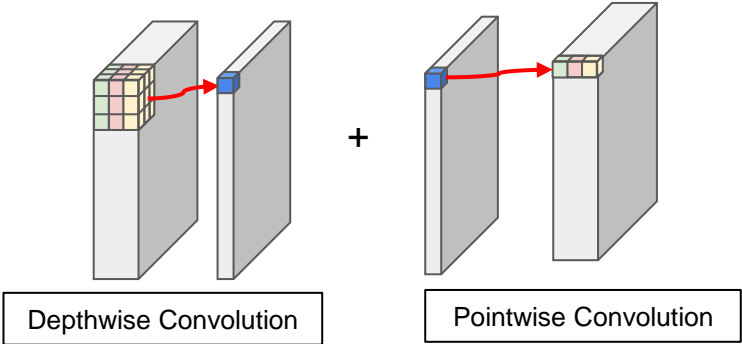


# Convolutional Layer Variations

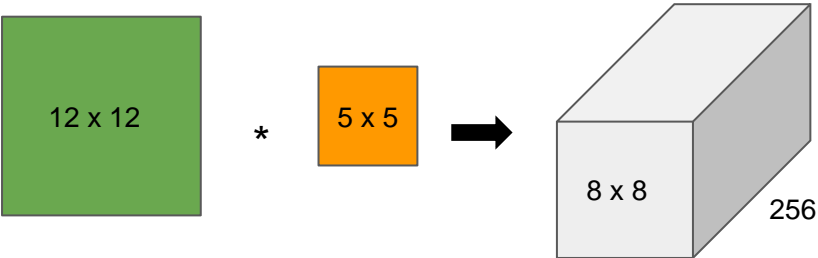
CoordConv.



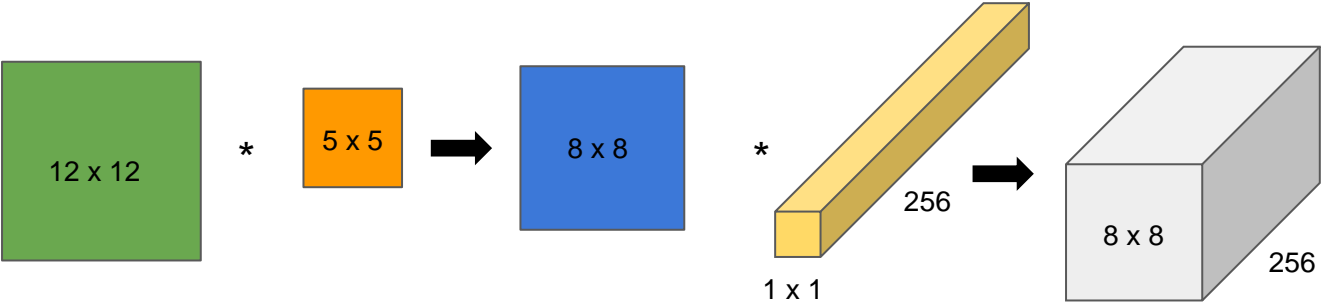
Seperable Conv.



# Separable Convolutional Layer (Computation Example)

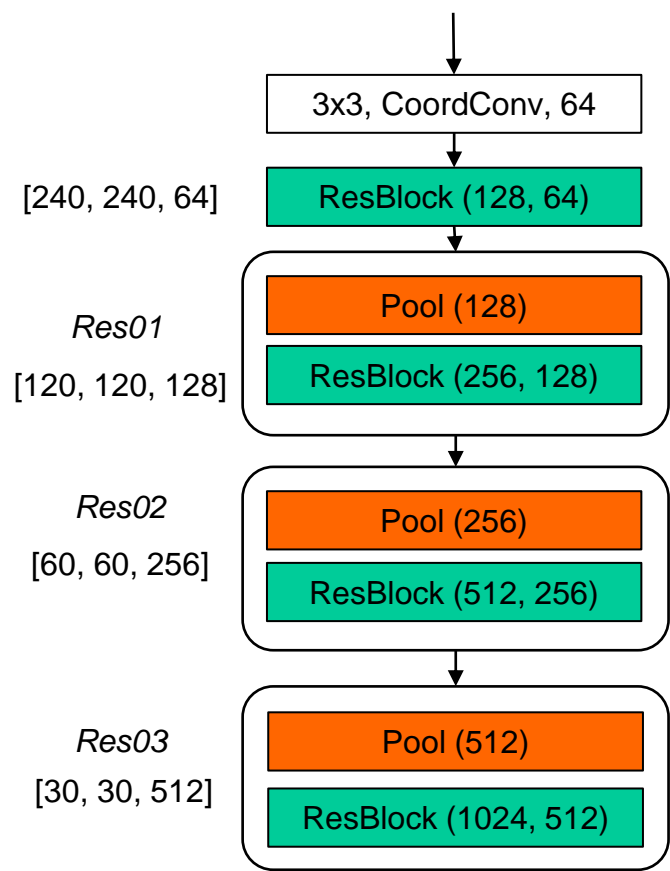


(Normal) Multiplication:  $5 \times 5 \times 8 \times 8 \times 256 = 409,600$



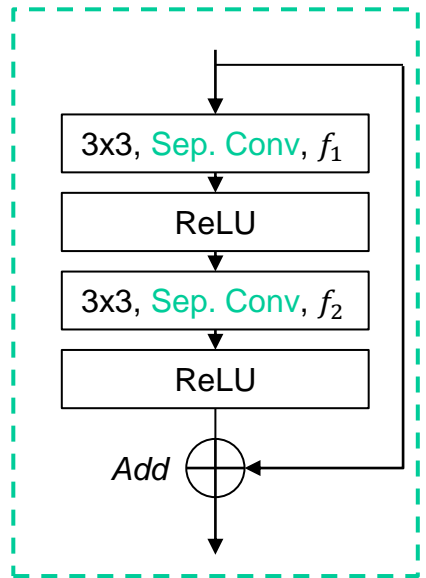
(Separable) Multiplication:  $5 \times 5 \times 8 \times 8 + 8 \times 8 \times 1 \times 1 \times 256 = 17,984$

# ResNet

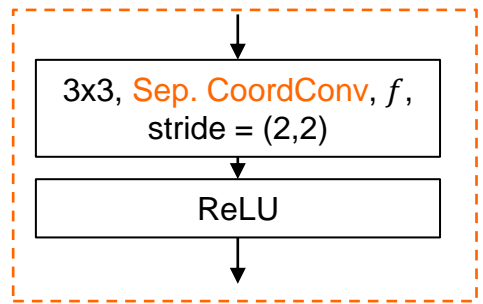


\*Dim: [w, h, c]

ResBlock ( $f_1, f_2$ ):

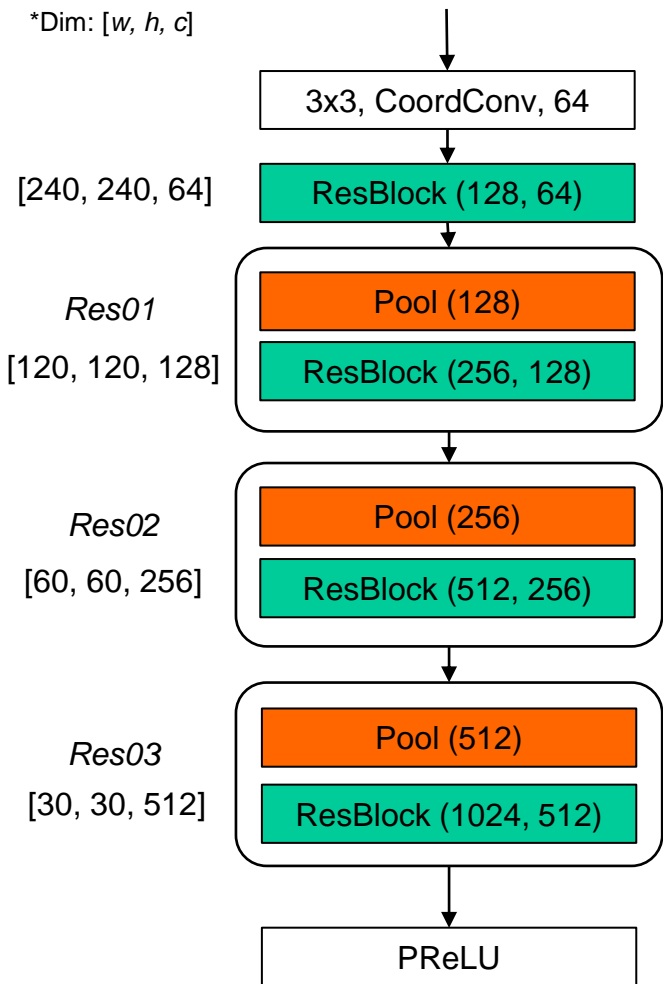


Learnable Pooling Layer( $f$ ):

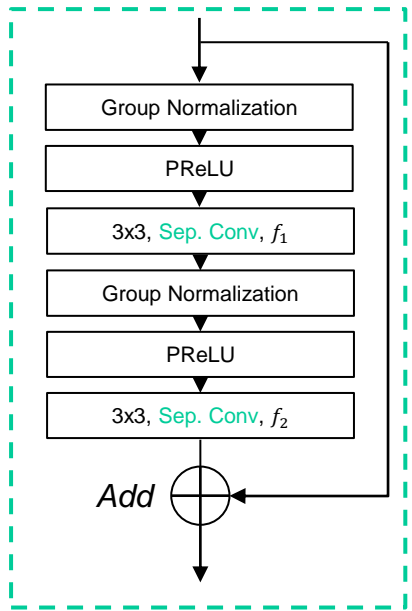


# ResNet v02

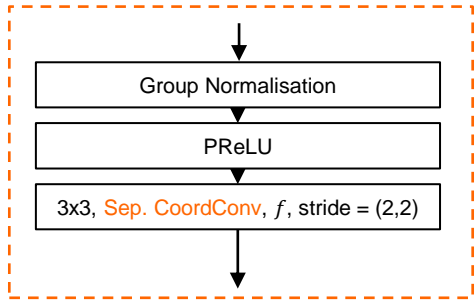
\*Dim: [w, h, c]



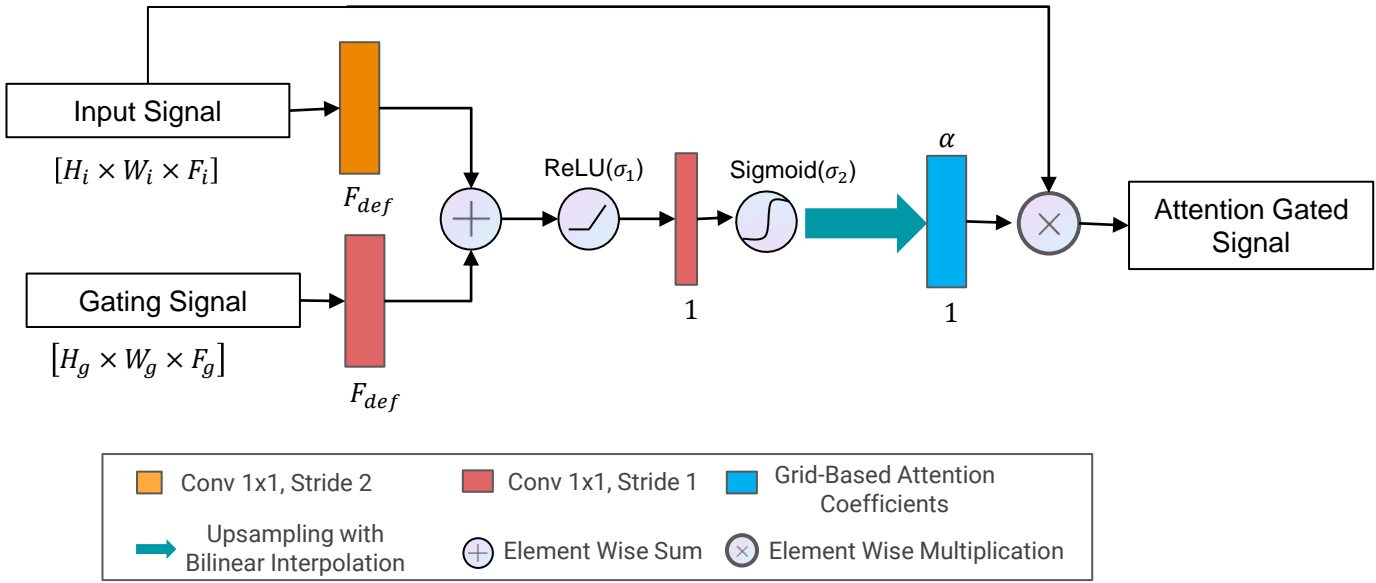
## ResBlock ( $f_1, f_2$ ):

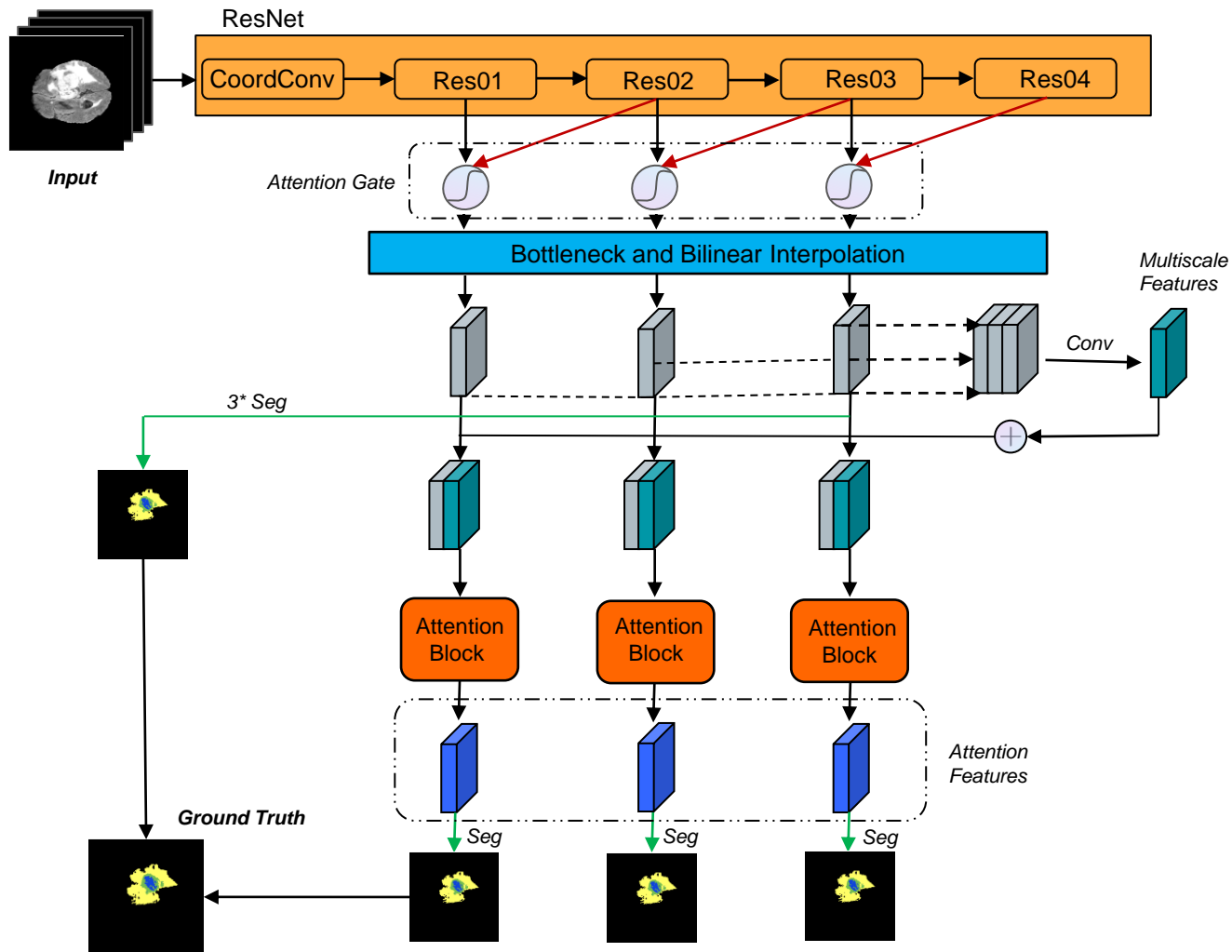


## Learnable Pooling Layer( $f$ ):

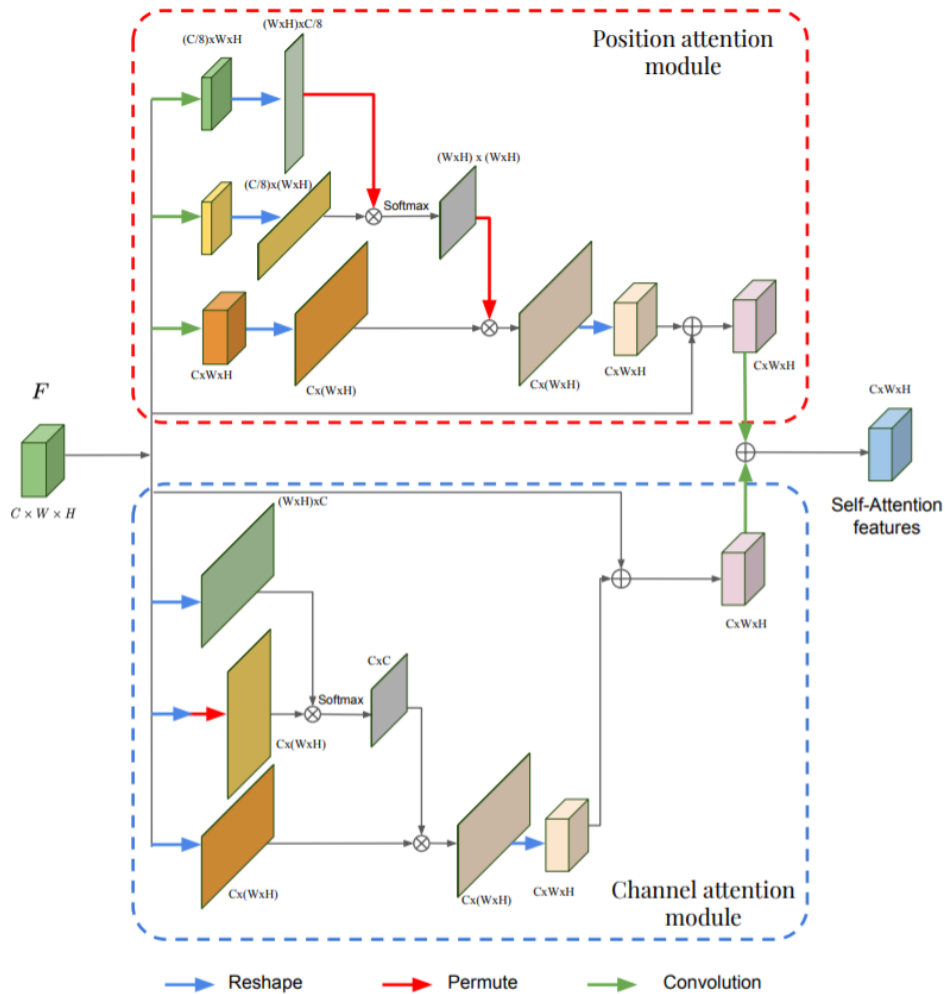


# Attention Gate



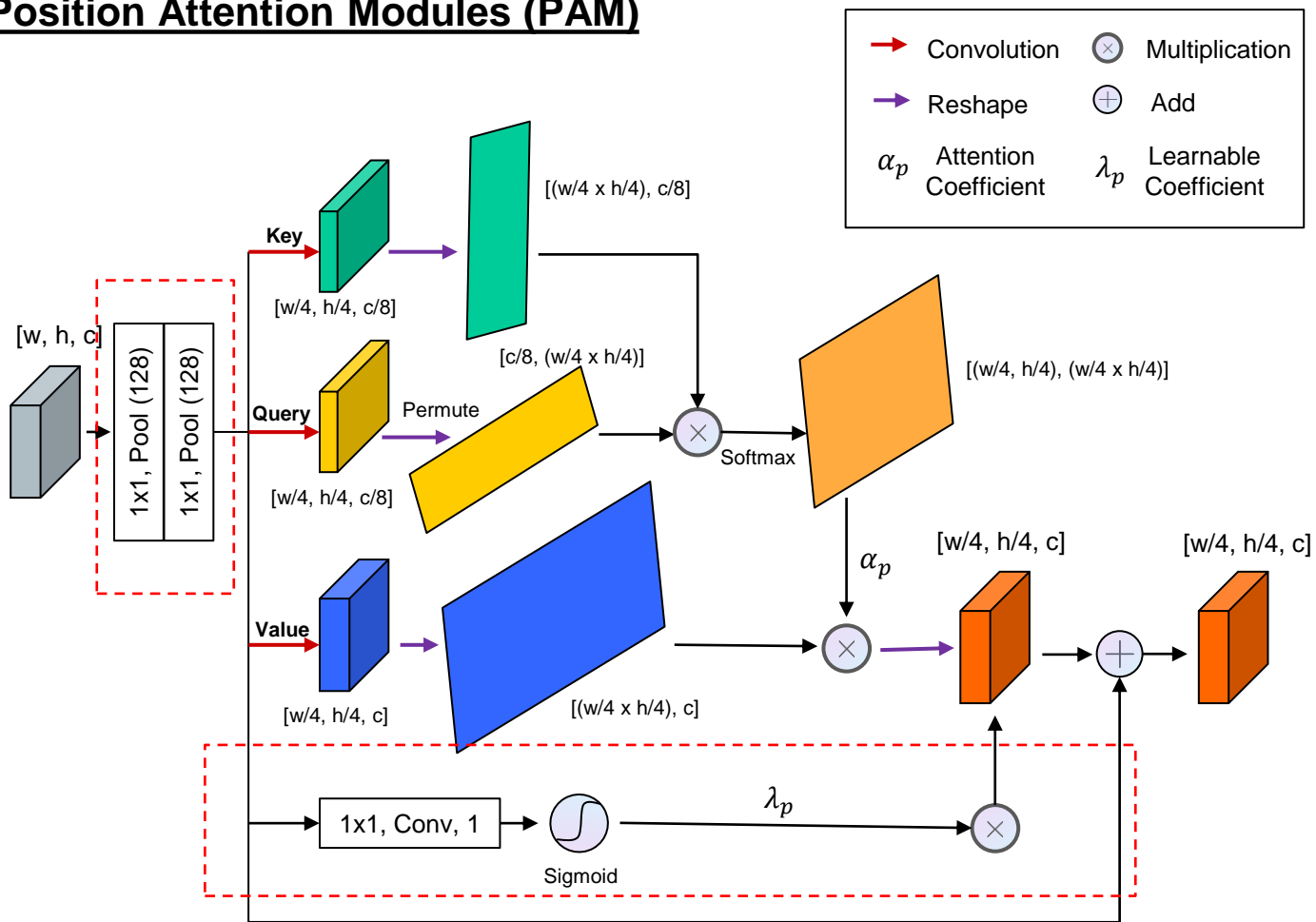


# PAM and CAM

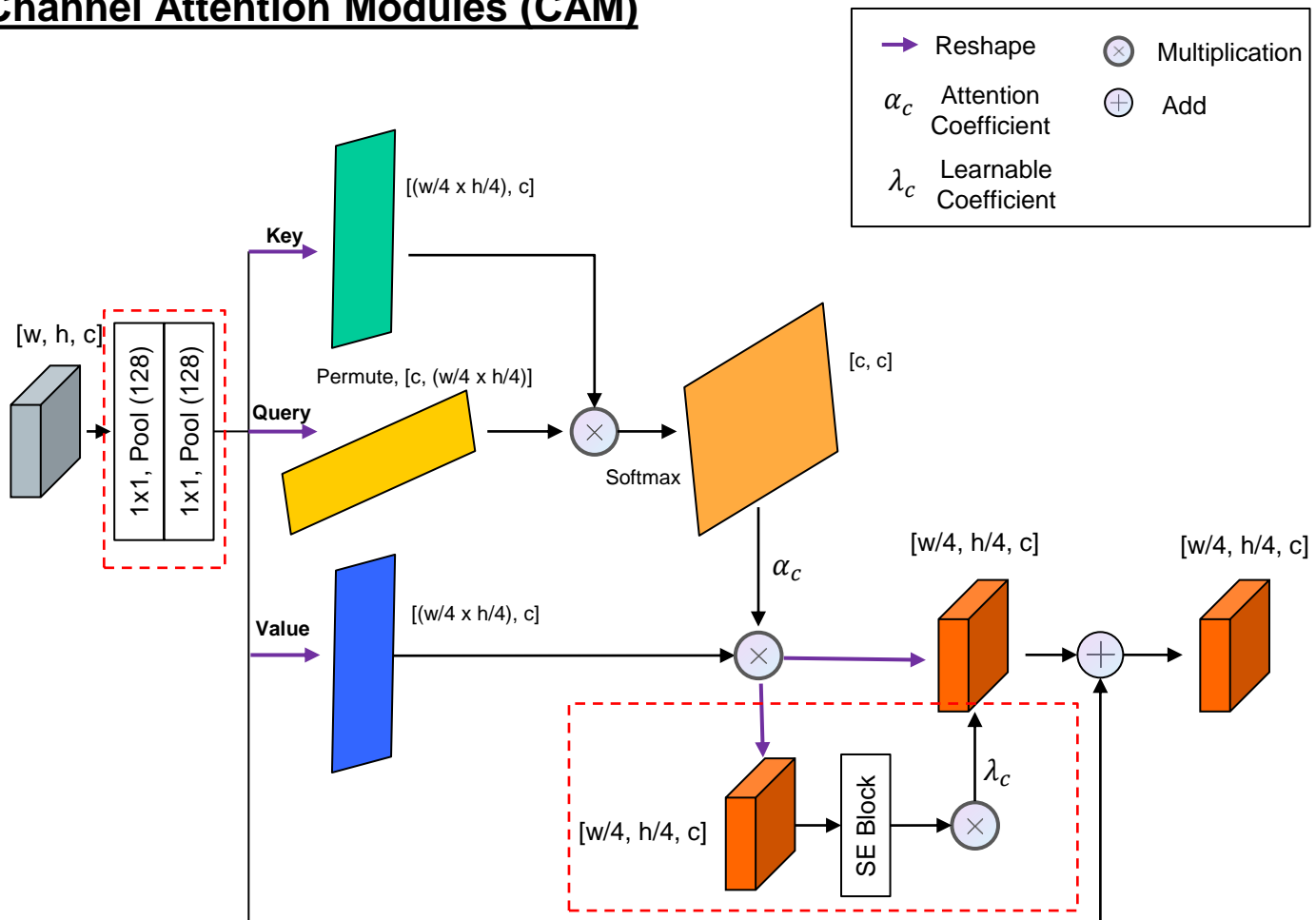




# Position Attention Modules (PAM)



# Channel Attention Modules (CAM)





# Attention Mechanism

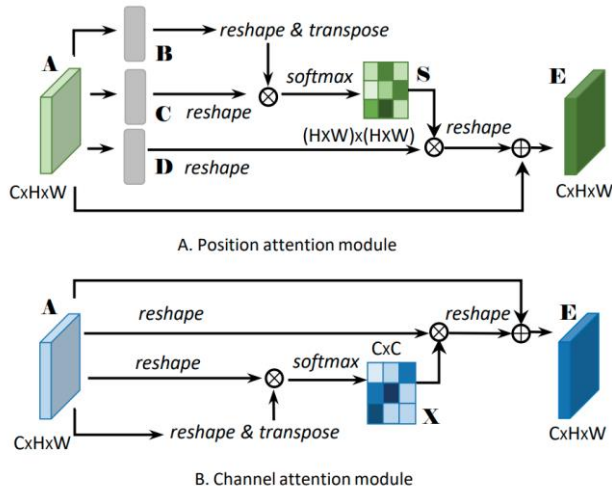


Fig.1A. Spatial self attention (A) Position attention module (PAM) and channel self attention (B) Channel attention module (CAM). Figure from [1]

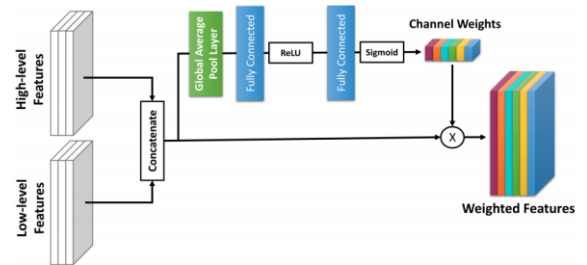


Fig.2A. Channel attention block(CAB) with squeeze and attention block. Figure from [2]

[1] Image source: Fu.J., Liu.J., Tian.H., Li.Yong., Bao. Y., Fang.Z., Lu.H., Dual Attention Network for Scene Segmentation, Computer Vision and Pattern Recognition 2019.

[2] Image source: Noori, M., Bahri, A., Mohammadi, K.: Attention-guided version of 2d unet for automatic brain tumor segmentation. In: 2019 9th International Conference on Computer and Knowledge Engineering (ICCKE). pp. 269–275.