



Class-5

Artificial Neural Network

Unit-1

Introduction-ADALINE

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Outline

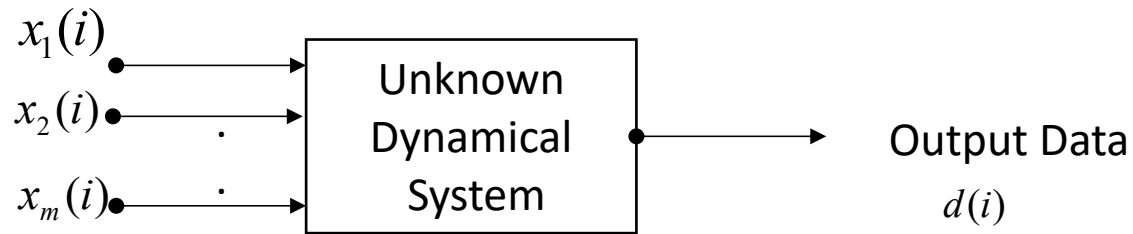


- Adaptive filtering problem
- Unconstrained Optimization Techniques
- Linear least square Solution

Linear Neuron:

Adaptive filtering problem

Unknown dynamical system:



The external behavior of the system is described by the data set

$$\mathfrak{T} : \{X(i), d(i); i = 1, 2, \dots, n, \dots\}$$

where,

$$X(i) = [x_1(i), x_2(i), x_3(i), \dots, x_m(i)]^T$$

the 'm' pertaining to the input vector $x(i)$ is referred to as dimensionality of the input space.

Linear Neuron: Adaptive filtering model



The stimulus $X(i)$ can arise in one of two fundamentally different ways:

1. The m elements of $X(i)$ originate at different points in space: **Spatial**
2. The m element of $X(i)$ represent the set of present and $(m-1)$ past values of some excitation that are uniformly spaced in time: **Temporal**

Linear Neuron: Adaptive filtering model

Objective:

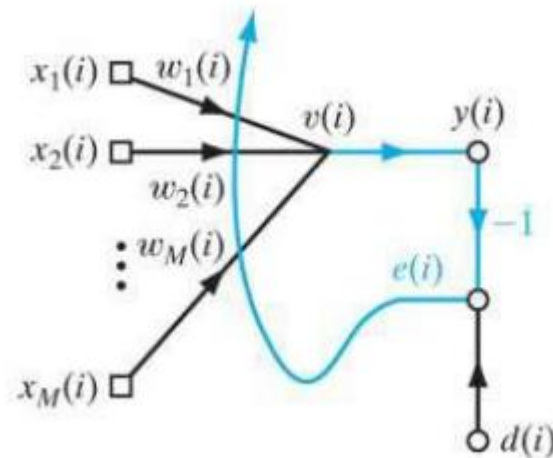
- Design a **multiple input-single output model** of the unknown dynamical system using a **single neuron**.

Linear Neuron: Adaptive filtering model

Objective:

- Design a **multiple input-single output model** of the unknown dynamical system using a **single neuron**.

Signal Flow Graph of linear neuron model:



Linear Neuron: Adaptive filtering model

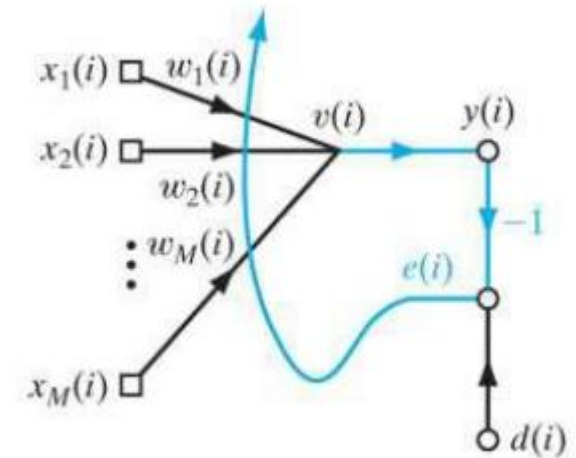


- Develop an **algorithm** that adopt by neuronal model such that it **controls** necessary **adjustment** to the **synaptic weights** of the neuron.
- The **neuronal model** described is referred as **adaptive filter**.

Linear Neuron: Adaptive filtering problem

- **Adaptive filter** operation consists of two continuous processes:
 1. Filtering process
 2. Adaptive Process
- Combination of this 2 processes working together constitutes a **feedback loop** acting around the neuron.
- Since the neuron is **linear**, the output $y(i)$ is exactly the same as the induced local field $v(i)$;

$$y(i) = v(i) = \sum_{k=1}^m w_k(i) x_k(i)$$



Linear Neuron: Adaptive filtering problem

$$y(i) = v(i) = \sum_{k=1}^m w_k(i) x_k(i)$$

where

$w_1(i), w_2(i), \dots, w_m(i)$ are the **m synaptic weight** of the neuron

In matrix form we may express $y(i)$ as an inner product of the vector $x(i)$ and $w(i)$ as follows:

$$y(i) = X^T(i)W(i) = W^T(i)X(i)$$

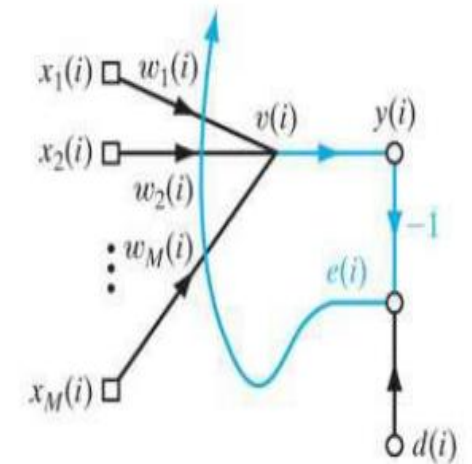
where $W(i) = [w_1(i), w_2(i), \dots, w_m(i)]^T$

Linear Neuron: Adaptive filtering problem

- The **neuron's output** is **compared** with the corresponding **output $d(i)$** received from the unknown system at time i .

$$e(i) = d(i) - y(i)$$

- This **error signal** is used to control the **adjustment** of the **neuron's synaptic weight**.
- The manner in which **error signal** is to be used is determine by the **cost function** and used to **derive** the **adaptive filtering algorithm of interest**.



Adaptive filtering problem: Unconstrained Optimization Techniques

- **Adaptive filtering problem** is close to **optimization problem**.
- Optimization techniques: it is a mathematical technique for finding a **maximum or minimum** value of a **function of several variables** subject to a **set of constraints**.
- if it is not subjected to a **set of constraints then**, the technique is referred as Unconstrained optimization.

Adaptive filtering problem: Unconstrained Optimization Techniques

- Consider a **cost function** that is **continuously differentiable** function of some **unknown weight vector** W .
- The **cost function** is a measure of how to choose the weight vector W of an adaptive filtering algorithm so that it behaves in an **optimum manner**.
- Find the optimum solution W^* that satisfies the condition

$$\xi(W^*) \leq \xi(W)$$

This is referred as an **Unconstrained Optimization Techniques**

Adaptive filtering problem: Unconstrained Optimization Techniques

- **Unconstrained Optimization Techniques:**

Minimize the cost function w.r.t the weight vector W , and the necessary condition for optimality is

$$\nabla \xi(W^*) = 0$$

where the gradient operator:

$$\nabla = \left[\frac{\partial}{\partial w_1}, \frac{\partial}{\partial w_2}, \dots, \frac{\partial}{\partial w_m} \right]^T$$

$$\nabla \xi(W) = \left[\frac{\partial \xi}{\partial w_1}, \frac{\partial \xi}{\partial w_2}, \dots, \frac{\partial \xi}{\partial w_m} \right]^T$$

Adaptive filtering problem: Unconstrained Optimization Techniques

- **Unconstrained Optimization Techniques:**

It is well suited to local iterative method and the statement as follows:

Starting with an initial guess denoted by $W(0)$, generate a sequence of weight $W(1), W(2), \dots$, such that the cost function is reduced at each iteration of the algorithm as shown by

$$\xi(W^*(n+1)) \leq \xi(W(n))$$

Adaptive filtering problem: Unconstrained Optimization Techniques



- Linear Least Square filter
- Wiener filter
- Gauss-Netwon Method
- Steepest Descent Method
- Newton's Method
- LMS Method

Adaptive filtering problem: Unconstrained Optimization Techniques



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THANK YOU

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