



Digital Signal Processing

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Linear Filtering methods based on the DFT

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Signals, Linear Filtering methods based on the DFT

Overlap-Add Method



Deals with the following signal processing principles:

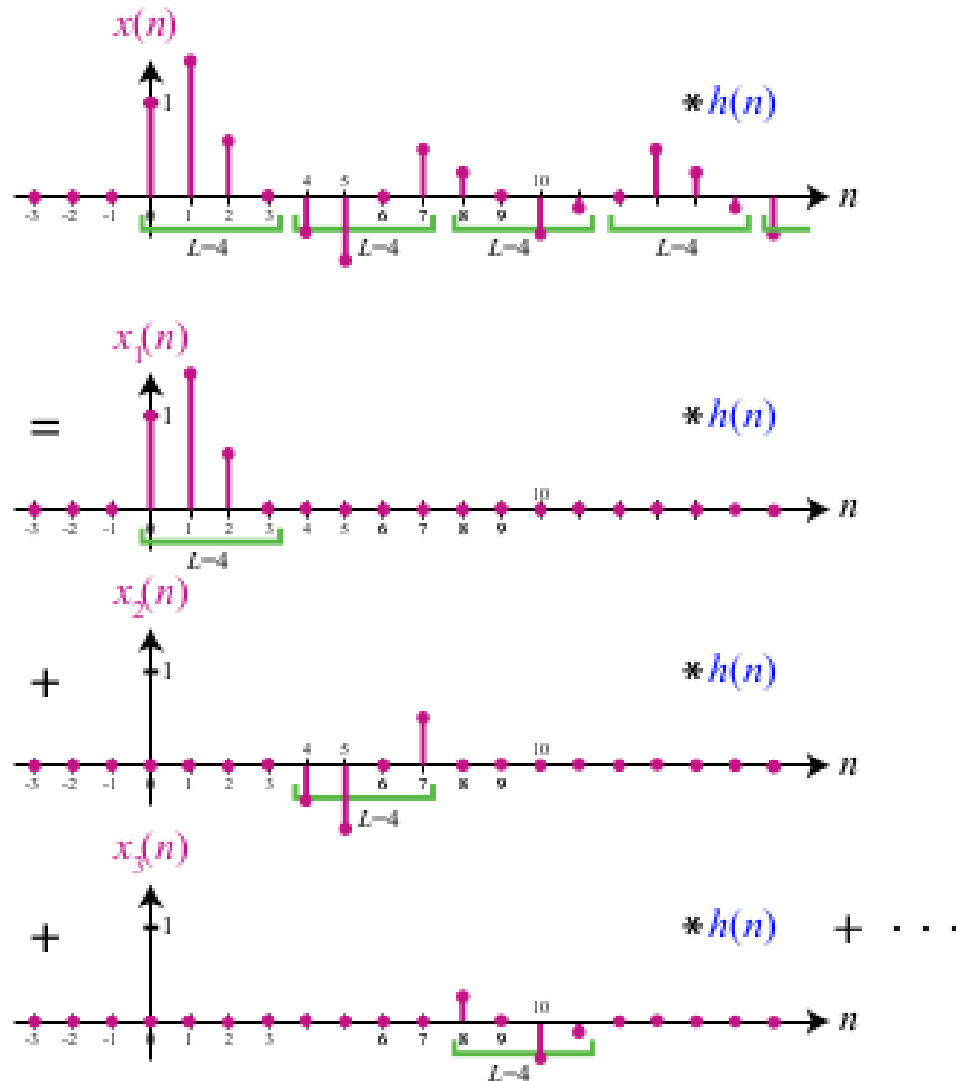
- ▶ The linear convolution of a discrete-time signal of length L and a discrete-time signal of length M produces a discrete-time convolved result of length $L + M - 1$.

- ▶ Additivity:

$$(x_1(n) + x_2(n)) * h(n) = x_1(n) * h(n) + x_2(n) * h(n)$$

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Overlap-Add Method



Input $x(n]$ is divided into **non-overlapping** blocks $x_m(n)$ each of length L .

Each input block $x_m(n)$ is **individually** filtered **as it is received** to produce the output block $y_m(n)$.

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- ▶ makes use of the N -DFT and N -IDFT where: $N = L + M - 1$
 - ▶ Thus, zero-padding of $x(n)$ and $h(n)$ that are of length $L, M < N$ is required.
 - ▶ The actual implementation of the DFT/IDFT will use the FFT/IFFT for computational simplicity.

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Overlap-Add Method



Let $x_m(n)$ have support $n = 0, 1, \dots, L - 1$.

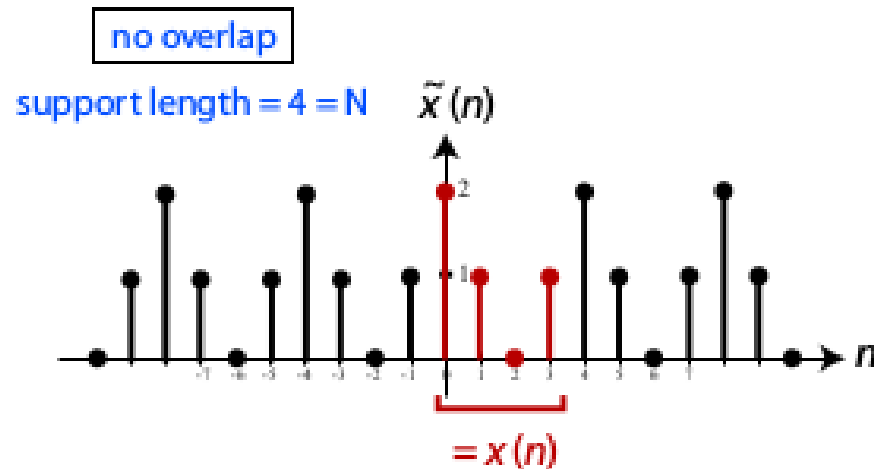
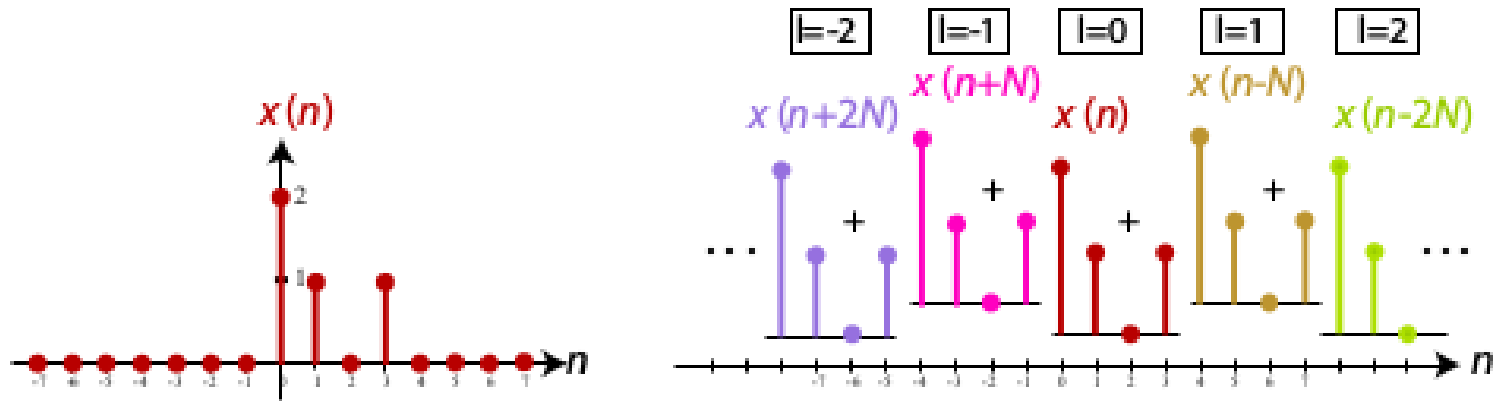
Let $h(n)$ have support $n = 0, 1, \dots, M - 1$.

We set $N \geq L + M - 1$ (the length of the linear convolution result) and zero pad $x_m(n)$ and $h(n)$ to have support $n = 0, 1, \dots, N - 1$.

1. Take N -DFT of $x_m(n)$ to give $X_m(k)$, $k = 0, 1, \dots, N - 1$.
2. Take N -DFT of $h(n)$ to give $H(k)$, $k = 0, 1, \dots, N - 1$.
3. Multiply: $Y_m(k) = X_m(k) \cdot H(k)$, $k = 0, 1, \dots, N - 1$.
4. Take N -IDFT of $Y_m(k)$ to give $y_m(n)$, $n = 0, 1, \dots, N - 1$.

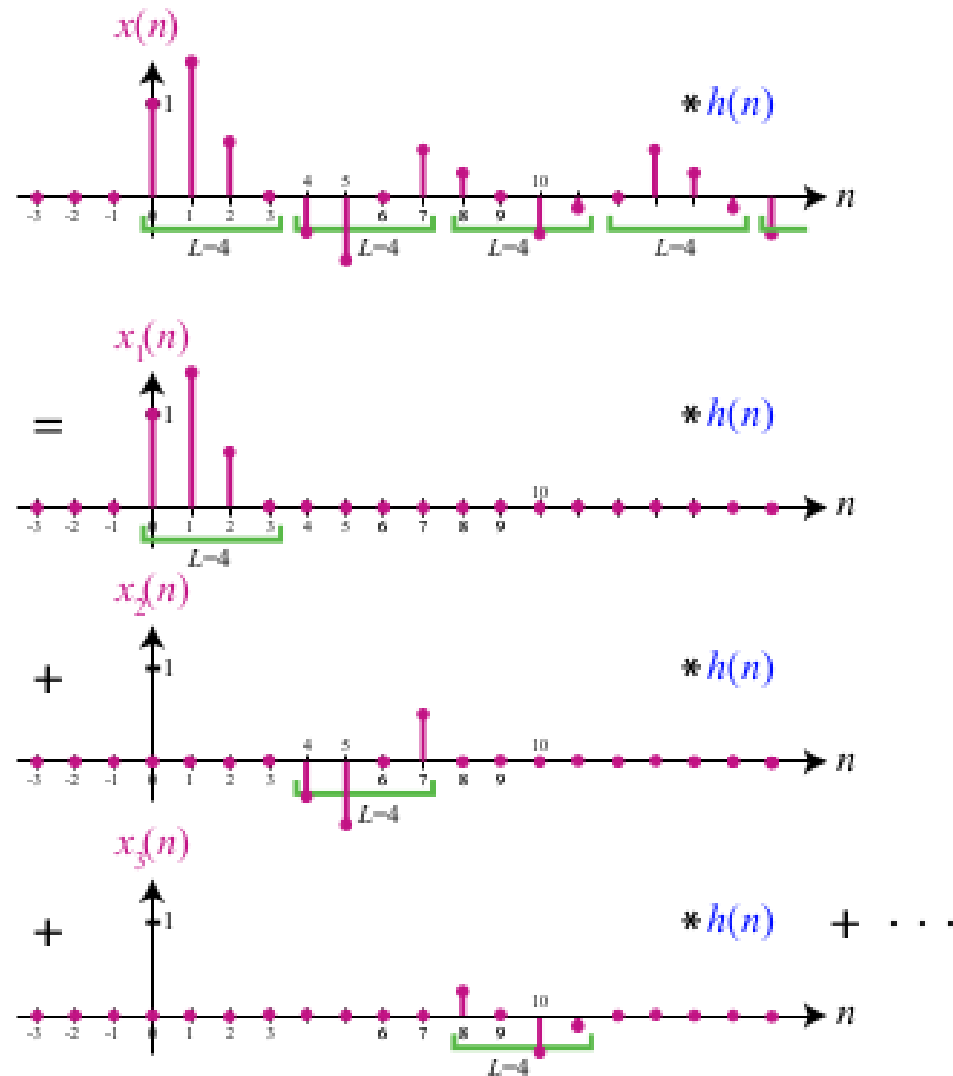
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Length of linear convolution result = Length of DFT



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Overlap-Add Method



Input $x(n)$ is divided into **non-overlapping** blocks $x_m(n)$ each of length L .

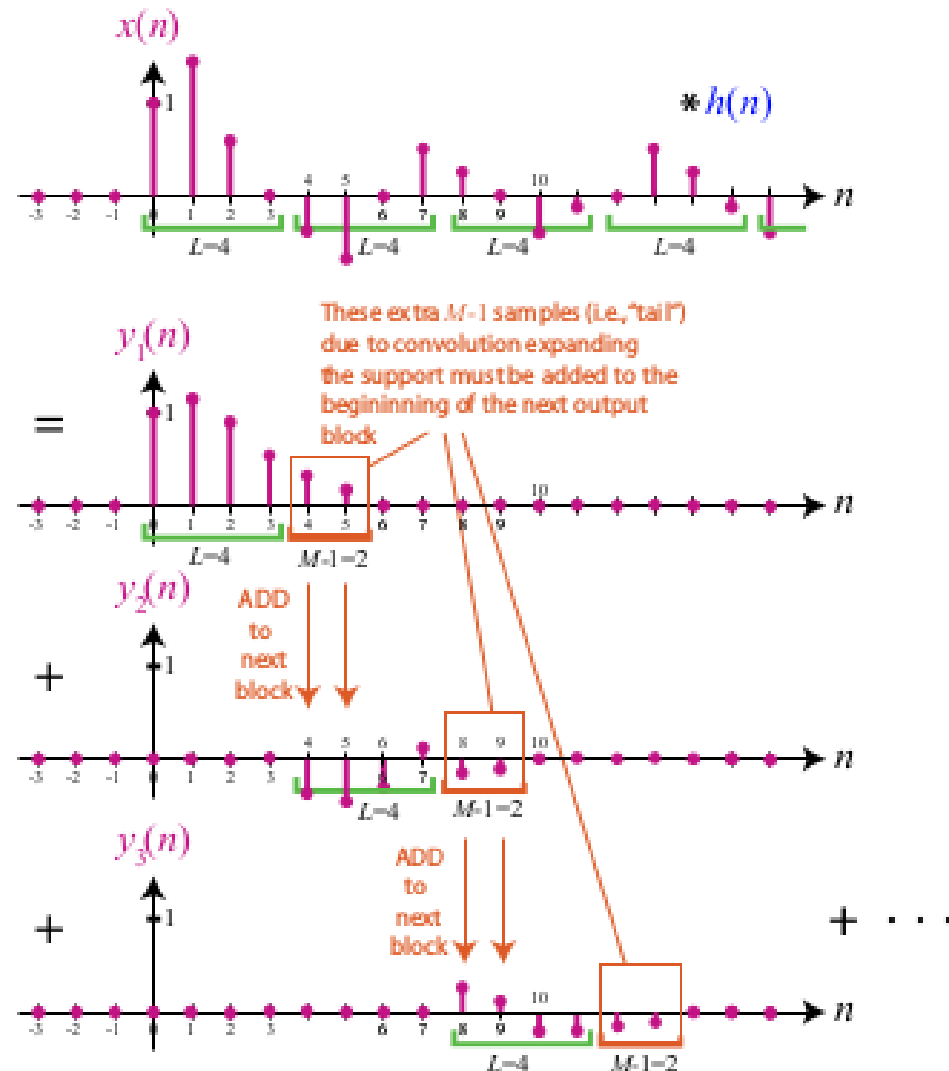
Each input block $x_m(n)$ is **individually** filtered **as it is received** to produce the output block $y_m(n)$.

From the Additivity property, since:

$$\begin{aligned}x(n) &= x_1(n) + x_2(n) + x_3(n) + \cdots = \sum_{m=1}^{\infty} x_m(n) \\x(n) * h(n) &= (x_1(n) + x_2(n) + x_3(n) + \cdots) * h(n) \\&= x_1(n) * h(n) + x_2(n) * h(n) + x_3(n) * h(n) + \cdots \\&= \sum_{m=1}^{\infty} x_m(n) * h(n) = \sum_{m=1}^{\infty} y_m(n)\end{aligned}$$

Signals, Linear Filtering methods based on the DFT

Overlap-Add Method



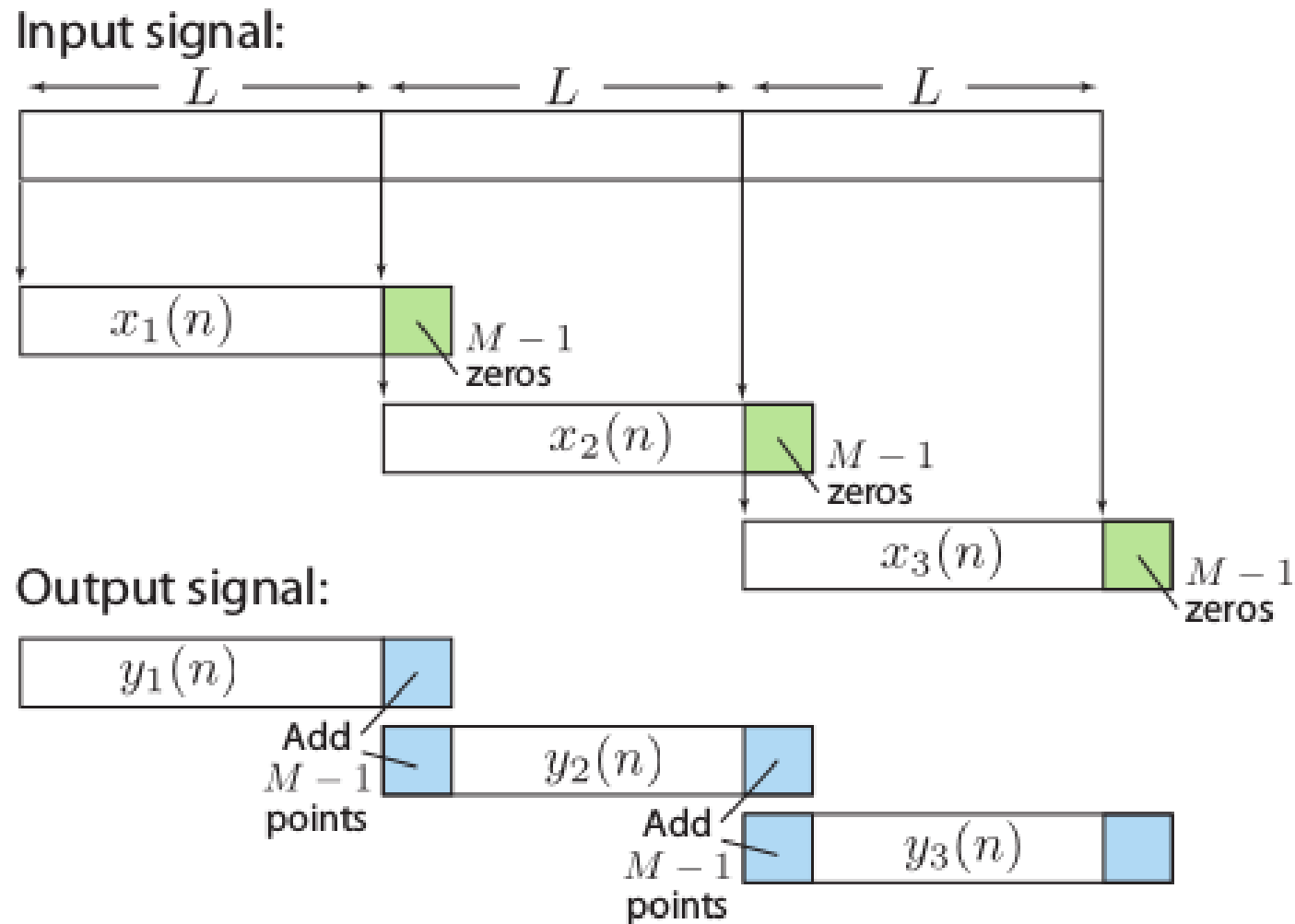
Output blocks $y_m(n)$ must be fitted together **appropriately** to generate:

$$y(n) = x(n) * h(n)$$

The support **overlap** amongst the $y_m(n)$ blocks must be accounted for.

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Overlap-Add Method



Signals, Linear Filtering methods based on the DFT

Overlap-Add Method



1. Break the input signal $x(n)$ into **non-overlapping** blocks $x_m(n)$ of length L .
2. Zero pad $h(n)$ to be of length $N = L + M - 1$.
3. Take N -DFT of $h(n)$ to give $H(k)$, $k = 0, 1, \dots, N - 1$.
4. For each block m :
 - 4.1 Zero pad $x_m(n)$ to be of length $N = L + M - 1$.
 - 4.2 Take N -DFT of $x_m(n)$ to give $X_m(k)$, $k = 0, 1, \dots, N - 1$.
 - 4.3 Multiply: $Y_m(k) = X_m(k) \cdot H(k)$, $k = 0, 1, \dots, N - 1$.
 - 4.4 Take N -IDFT of $Y_m(k)$ to give $y_m(n)$, $n = 0, 1, \dots, N - 1$.
5. Form $y(n)$ by overlapping the **last** $M - 1$ samples of $y_m(n)$ with the **first** $M - 1$ samples of $y_{m+1}(n)$ and adding the result.

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Overlap-Add Method



If you **DO NOT overlap and add**, but only **append** the output blocks $y_m(n)$ for $m = 1, 2, \dots$, then you will not get the **true** $y(n)$ sequence.

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Overlap-Add Method



Signal $x[n]$ (time domain): [3, -1, 0, 3, 2, 0, 1, 2, 1]

Filter $h[n]$ (time domain): [1, -1, 1] $M=3$

If $N=5$

$N = L + M - 1 = L + 3 - 1 = 5$ Thus $L=3$

n	0	1	2	3	4	5	6	7	8	9	10
$x[n]$	3	-1	0	3	2	0	1	2	1	0	0
$x_0[n]$	3	-1	0	0	0	0	0	0	0	0	0
$x_1[n-3]$	0	0	0	3	2	0	0	0	0	0	0
$x_2[n-6]$	0	0	0	0	0	0	1	2	1	0	0

Signals, Linear Filtering methods based on the DFT

Overlap-Add Method

Computing $y_0[n]$ Using Method 1: Fourier Transform

$$x_0[n] = [3, -1, 0, 0, 0]$$

$$h[n] = [1, -1, 1, 0, 0]$$

$$y_0[n] = \text{IDFT}(\text{DFT}(x_0[n]) \cdot \text{DFT}(h[n]))$$

$$X_0[n] = \text{DFT}(x_0[n]) = [2, 2.691 + 0.951i, 3.809 + 0.588i, 3.809 - 0.588i, 2.691 - 0.951i]$$

$$H[n] = \text{DFT}(h[n]) = [1, -0.118 + 0.363i, 2.118 + 1.539i, 2.118 - 1.539i, -0.118 - 0.363i]$$

$$H[n] \cdot X_0[n] = [2, -0.663 + 0.865i, 7.163 + 7.106i, 7.163 - 7.106i, -0.663 - 0.865i]$$

$$y_0[n] = [3, -4, 4, -1, 0]$$

Computing $y_0[n]$ Using Method 2: Standard Convolution

$$x_0[n] = [3, -1, 0, 0, 0]$$

$$h[n] = [1, -1, 1, 0, 0]$$

$$y_0[n] = \begin{array}{c|ccccc|c|c|c} & 1 & 0 & 0 & 1 & -1 & | & 3 & | & 3 & | \\ & -1 & 1 & 0 & 0 & 1 & | & -1 & | & -4 & | \\ \hline & 1 & -1 & 1 & 0 & 0 & | & 0 & | & 4 & | \\ & 0 & 1 & -1 & 1 & 0 & | & 0 & | & -1 & | \\ & 0 & 0 & 1 & -1 & 1 & | & 0 & | & 0 & | \end{array}$$

Signals, Linear Filtering methods based on the DFT

Overlap-Add Method

Computing $y_1[n]$ Using Method 1: Fourier Transform

$$x_1[n] = [3, 2, 0, 0, 0]$$

$$h[n] = [1, -1, 1, 0, 0]$$

$$y_1[n] = \text{IDFT}(\text{DFT}(x_1[n]) \cdot \text{DFT}(h[n]))$$

$$X_1[n] = \text{DFT}(x_1[n]) = [5, 3.618 - 1.902i, 1.382 - 1.176i, 1.382 + 1.176i, 3.618 + 1.902i]$$

$$H[n] = \text{DFT}(h[n]) = [1, -0.118 + 0.363i, 2.118 + 1.539i, 2.118 - 1.539i, -0.118 - 0.363i]$$

$$H[n] \cdot X_1[n] = [5, 0.264 + 1.539i, 4.736 - 0.363i, 4.736 + 0.363i, 0.264 - 1.539i]$$

$$y_1[n] = [3, -1, 1, 2, 0]$$

Computing $y_1[n]$ Using Method 2: Standard Convolution

$$x_1[n] = [3, 2, 0, 0, 0]$$

$$h[n] = [1, -1, 1, 0, 0]$$

$$y_1[n] = \begin{array}{c|c|c|c|c|c|c|c|c|c|} | & 1 & 0 & 0 & 1 & -1 & | & | & 3 & | & | & 3 & | \\ | & -1 & 1 & 0 & 0 & 1 & | & | & 2 & | & | & -1 & | \\ y_1[n] = & | & 1 & -1 & 1 & 0 & 0 & | & \cdot & | & 0 & | & = & | & 1 & | \\ | & 0 & 1 & -1 & 1 & 0 & | & | & 0 & | & | & 2 & | \\ | & 0 & 0 & 1 & -1 & 1 & | & | & 0 & | & | & 0 & | \end{array}$$

Signals, Linear Filtering methods based on the DFT

Overlap-Add Method

Computing $y_2[n]$ Using Method 1: Fourier Transform

$$x_2[n] = [1, 2, 1, 0, 0]$$

$$h[n] = [1, -1, 1, 0, 0]$$

$$y_2[n] = \text{IDFT}(\text{DFT}(x_2[n]) \cdot \text{DFT}(h[n]))$$

$$X_2[n] = \text{DFT}(x_2[n]) = [4, 0.809 - 2.49i, -0.309 - 0.225i, -0.309 + 0.225i, 0.809 + 2.49i]$$

$$H[n] = \text{DFT}(h[n]) = [1, -0.118 + 0.363i, 2.118 + 1.539i, 2.118 - 1.539i, -0.118 - 0.363i]$$

$$H[n] \cdot X_2[n] = [4, 0.809 + 0.588i, -0.309 - 0.951i, -0.309 + 0.951i, 0.809 - 0.588i]$$

$$y_2[n] = [1, 1, 0, 1, 1]$$

Computing $y_2[n]$ Using Method 2: Standard Convolution

$$x_2[n] = [1, 2, 1, 0, 0]$$

$$h[n] = [1, -1, 1, 0, 0]$$

$$y_2[n] = \begin{array}{c|ccccc|c|c|c} & 1 & 0 & 0 & 1 & -1 & | & 1 & | & 1 & | \\ & -1 & 1 & 0 & 0 & 1 & | & 2 & | & 1 & | \\ y_2[n] = & 1 & -1 & 1 & 0 & 0 & | & 1 & | = & 0 & | \\ & 0 & 1 & -1 & 1 & 0 & | & 0 & | & 1 & | \\ & 0 & 0 & 1 & -1 & 1 & | & 0 & | & 1 & | \end{array}$$

Signals, Linear Filtering methods based on the DFT

Overlap-Add Method

n	0	1	2	3	4	5	6	7	8	9	10
y_0[n]	3	-4	4	-1	0	0	0	0	0	0	0
y_1[n]	0	0	0	3	-1	1	2	0	0	0	0
y_2[n]	0	0	0	0	0	0	1	1	0	1	1
y[n]	3	-4	4	2	-1	1	3	1	0	1	1



THANK YOU

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