

# DIGITAL COMMUNICATION

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## **BASEBAND SHAPING**

# Background on Random Processes Power Spectra of Discrete PAM Signals

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#### **RANDOM PROCESSES**

#### **Definition and Basics**



- Recall that a random variable  $X:\Omega \to \mathbb{R}$  such that some constraints are satisfied
- A random process  $X(t, \omega)$  is an indexed set of random variables
- At a high level, it is a collection of continuous-time or discrete-time signals, for every  $\omega$
- For a given  $t, X(t, \omega)$  is a random variable
- Examples: Stock market index, rainfall, weather forecasting
- Examples: Message signal in communications, receiver noise, received signal etc.
- A random process is said to be "deterministic", if future values can be predicted from past samples. Example:  $X(t) = A\cos(\omega t + \phi)$ , where  $\phi \sim U(0, 2\pi)$
- A "non-deterministic" random process is not deterministic

#### **RANDOM PROCESSES**

#### **Statistical Parameters**



- Recall that for a given  $t, X(t, \omega)$  is a random variable
- Therefore, moments on X(t) can be defined for a given value of t
- Let  $\mu_X(t) = \mathbb{E}(X(t))$  -- This is the ensemble average
- Let  $\sigma_X^2(t) = \mathbb{E}([X(t) \mu_X(t)]^2)$  -- These two constitute the first order statistics
- Let  $m_X^2(t) = \mathbb{E}(X^2(t))$  -- This is the mean squared value
- Consider two time instances  $t_1$  and  $t_2$ . Then for all  $t_1, t_2 \in \mathbb{R}$
- $R_{XX}(t_1, t_2) = \mathbb{E}(X(t_1) X(t_2))$  This is called as the autocorrelation function
- $C_{XX}(t_1, t_2) = \mathbb{E}([X(t_1) \mu_X(t_1)][X(t_2) \mu_X(t_2)])$  -- Autocovariance function
- Note that  $R_{XX}(t_1, t_1) = m_X^2(t_1)$
- Note that  $C_{XX}(t_1, t_1) = \sigma_X^2(t_1)$

#### **RANDOM PROCESSES**

## **Strict Sense and Wide Sense Stationarity**



- Recall that for a given  $t, X(t, \omega)$  is a random variable
- A random process  $X(t, \omega)$  is said to be first order stationary, if its PDF at any given time instances t and  $t + \Delta t$  are equal, i.e.,  $f_X(x;t) = f_X(x;t + \Delta t)$
- A random process  $X(t, \omega)$  is said to be stationary in strict sense if  $f(x_1, ..., x_n; t_1, ..., t_n) = f(x_1, ..., x_n; t_1 + \Delta t, ..., t_n + \Delta t)$ , for all  $t_1, ..., t_n, \Delta t \in \mathbb{R}$ ,  $n \in \mathbb{N}$
- A random process  $X(t, \omega)$  is said to be stationary in wide sense (WSS) if
  - $\mu_X(t) = \mu$ , for all  $t \in \mathbb{R}$
  - $R_{XX}(t_1, t_2) = R_{XX}(t_2 t_1) = R_{XX}(\tau)$ , for all  $t_1, t_2 \in \mathbb{R}$
- For continuous-time process,  $R_{XX}(\tau) = R_{XX}(t, t + \tau)$
- For discrete-time process,  $R_{XX}(k) = R_{XX}(n, n + k)$
- The PSD of a WSS process is the FT of its ACF:  $S_X(f) = FT\{R_{XX}(\tau)\}$

## **Power Spectrum of Discrete PAM Signals**



- Let v(t) denote a basic pulse of duration  $T_b$  seconds
- The discrete PAM signal is a random process, defined as

$$X(t) = \sum_{k=-\infty}^{\infty} A_k v(t - kT_b)$$

• Here,  $A_k$  is a discrete random variable, whose value depends on the  $k^{th}$  bit and the chosen format (such as unipolar, polar, bipolar or Manchester)

#### **Power Spectrum of Discrete PAM Signals**

• We can rewrite X(t) as follows

$$X(t) = \sum_{k=-\infty}^{\infty} A_k \left\{ \delta(t - kT_b) * v(t) \right\}$$

$$= \left\{ \sum_{k=-\infty}^{\infty} A_k \delta(t - kT_b) \right\} * v(t)$$

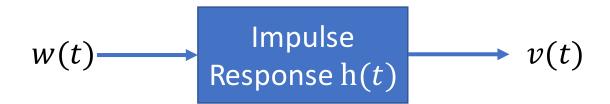
$$= A(t) * v(t)$$

• Therefore, the generation of X(t) can be viewed as an output of an LTI system, with input A(t) and impulse response v(t)

$$A(t) \longrightarrow \begin{array}{c} | \text{Impulse} \\ | \text{Response } v(t) | \end{array} \longrightarrow X(t)$$

## **Power Spectrum of Discrete PAM Signals**

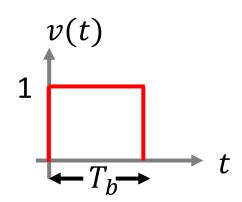




- Assume that v(t) is an output of an LTI system with response h(t) and input w(t)
- When w(t) is a WSS process, v(t) is also WSS and  $S_v(f) = |H(f)|^2 S_w(f)$
- A discrete PAM signal is a cyclo-stationary process (periodic and stationary). Hence,

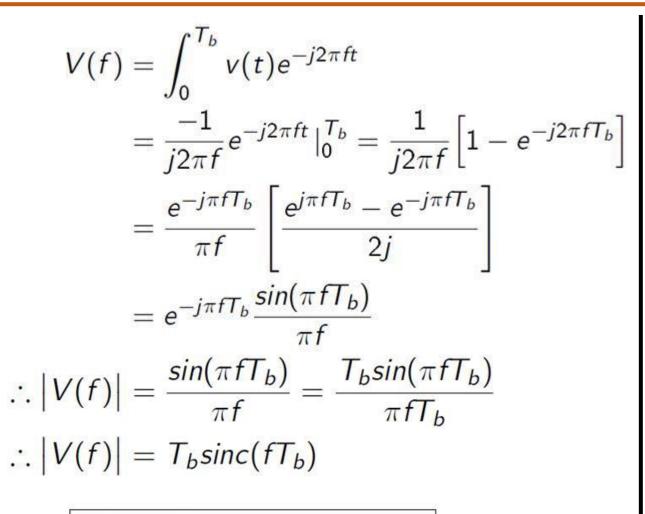
$$S_X(f) = \frac{|V(f)|^2}{T_b} S_A(f)$$

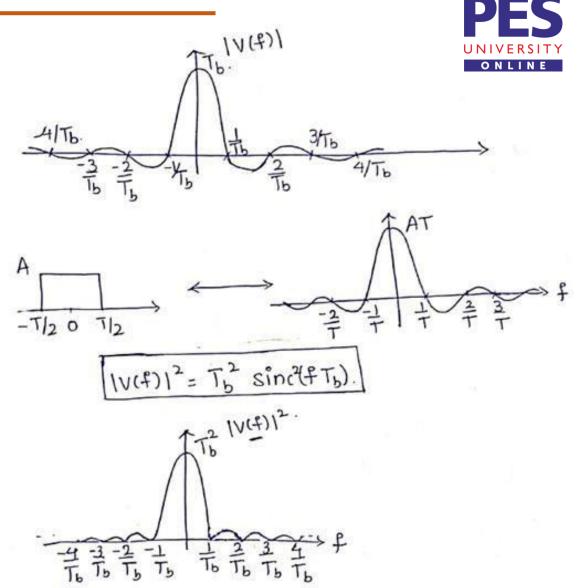
- Therefore, to evaluate  $S_X(f)$ , we need  $|V(f)|^2$
- Assume that v(t) is a rectangular function with unit amplitude



 $| \cdot \cdot |V(f)|^2 = T_b^2 \operatorname{sinc}^2(fT_b)$ 

#### **Power Spectrum of Discrete PAM Signals**





## **Power Spectrum of Discrete PAM Signals**



- Now that we have evaluated V(f), we next need to evaluate  $S_A(f)$
- Recall that the power spectrum is the Fourier transform of the autocorrelation
- A sequence of samples  $x_k$  can be represented either as a discrete-time sequence x(n) or a continuous-time signal x(t)

$$x(n) = \sum_{k=-\infty}^{\infty} x_k \delta(n-k)$$

$$x(t) = \sum_{k=-\infty}^{\infty} x_k \delta(t - kT)$$

Now, in the Fourier representation

$$x(n) \stackrel{\mathsf{F.T}}{\longleftrightarrow} X(e^{j\omega}) = \sum_{k=-\infty}^{\infty} x_k e^{-j\omega k}$$
$$x(t) \stackrel{\mathsf{F.T}}{\longleftrightarrow} X(f) = \int_{t=-\infty}^{\infty} x(t) e^{-j2\pi f t} dt$$

$$X(f) = \int_{t=-\infty}^{\infty} \sum_{k} x_{k} \delta(t - KT) e^{-j2\pi f t} dt$$
$$= \sum_{k} x_{k} \left\{ \int_{t=-\infty}^{\infty} \delta(t - KT) e^{-j2\pi f t} dt \right\}$$

## **Power Spectrum of Discrete PAM Signals**



- Recall that the power spectrum is the Fourier transform of the autocorrelation
- Therefore for us, the sequence of interest  $x_k = R_A(k)$
- From the previously shown development, we can write

$$X(f) = \int_{t=-\infty}^{\infty} \sum_{k} x_{k} \delta(t - KT) e^{-j2\pi f t} dt$$
$$= \sum_{k} x_{k} \left\{ \int_{t=-\infty}^{\infty} \delta(t - KT) e^{-j2\pi f t} dt \right\}$$

$$X(f) = \sum_{k} x_k e^{-j2\pi fKT}$$

$$S_A(f) = \sum_{n=-\infty}^{\infty} R_A(n)e^{-j2\pi f nT_b}$$

where 
$$R_A(n) = E[A_k A_{k-n}]$$

#### **POWER SPECTRUM OF PAM SIGNALS**

## **Power Spectrum of Discrete PAM Signals**



- Next, we intend to calculate the power spectra for the following cases
  - Unipolar NRZ
  - Bipolar NRZ
  - Polar NRZ
  - Manchester coding
- In each case, we first evaluate  $S_A(f)$  from  $R_A(n)$  and then evaluate  $S_X(f)$  using

$$S_X(f) = \frac{|V(f)|^2}{T_h} S_A(f)$$

Note that we have shown

$$|V(f)|^2 = T_b^2 \operatorname{sinc}^2(fT_b)$$



## **THANK YOU**

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