

UE20EC303 EMF THEORY UNIT -3

Dr. T. S. Chandar

Department of ECE, PESU.

EMF THEORY TEXT BOOK AND REFERENCES

PES UNIVERSIT

Textbook:

1. "Principles of Electromagnetics", Matthew N. O. Sadiku, 4th / 6th Edition, Oxford University Press, 2007 / 2018.

Reference Books:

- 1. "Electromagnetic Field Theory Fundamentals", Bagh Singh Guru, Huseyin R Hiziroglu, Cambridge University Press, 2nd Edition, 2002.
- 2. "Engineering Electromagnetics", William H Hayt Jr, J.A. Buck, 7th Edition, Tata McGraw Hill, 2007.
- 3. "Microwave Devices and Circuits", Samuel. Y. Liao, Third Edition, Pearson, 2006.
- 4. "Engineering Electromagnetics Essentials", B. N. Basu, Universities Press (India), 2015.

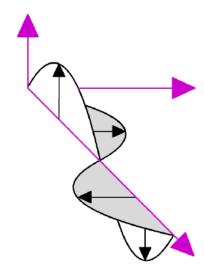






UNIT - 3

Maxwell's Equations for Time – Varying Fields



Dr. T. S. Chandar Department of ECE

EMF Theory – Unit – 3 {Text Book Sec. 9.1 - 9.5, 9.7, 5.9, 8.7, 10.1 – 10.7} CONTENTS

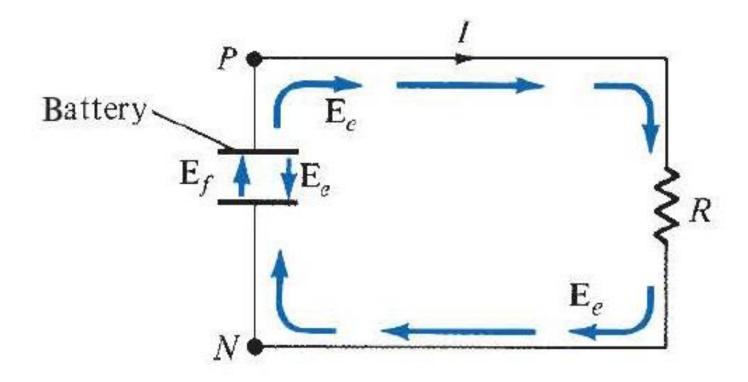


- ***** Faraday's Law.
- Transformer & Motional Electromotive Forces.
- Displacement Current.
- Maxwell's Equations in their final forms.
- Time Harmonic Fields.
- Electric & Magnetic Boundary conditions.
- **Waves, propagation of waves in different media.**
- Wave polarisation.



EMF Theory – Unit - 3 FARADAY'S LAW

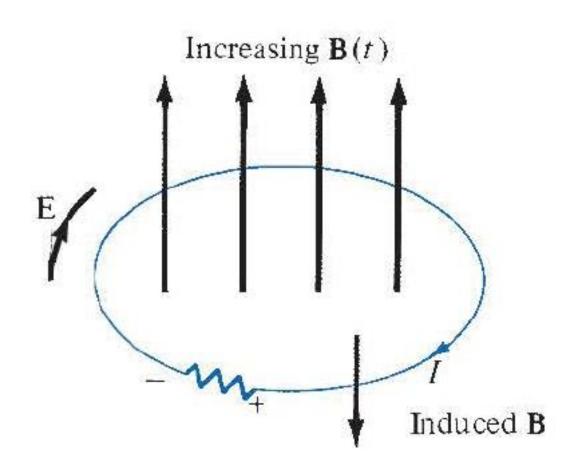






EMF Theory – Unit - 3 TRANSFORMER EMF



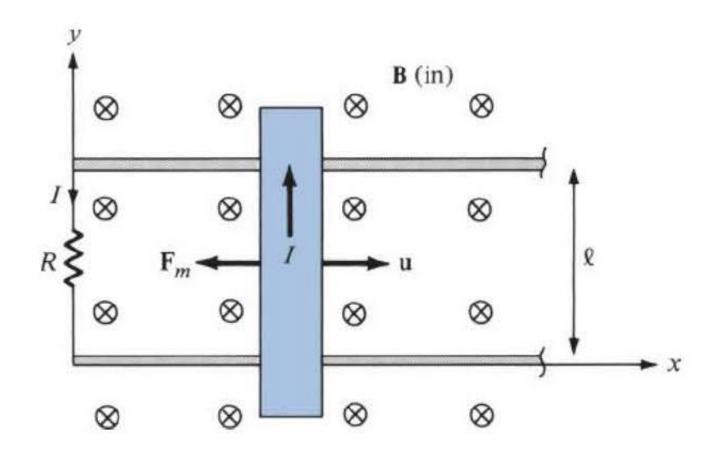


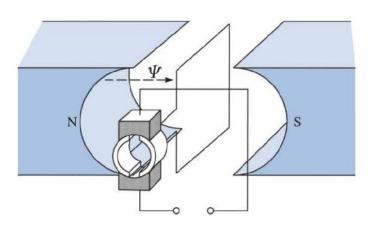


EMF Theory – Unit - 3 MOTIONAL EMF



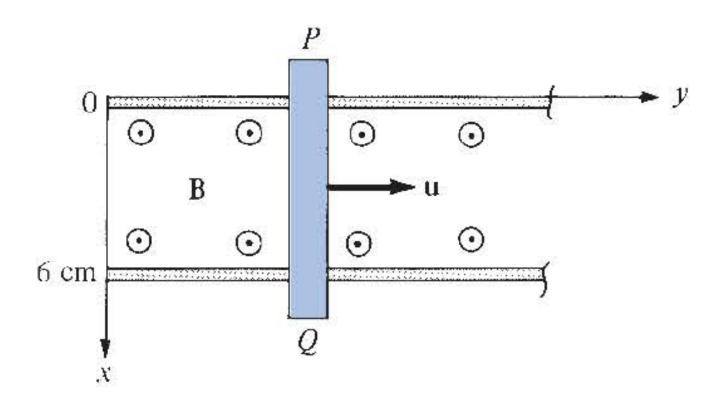






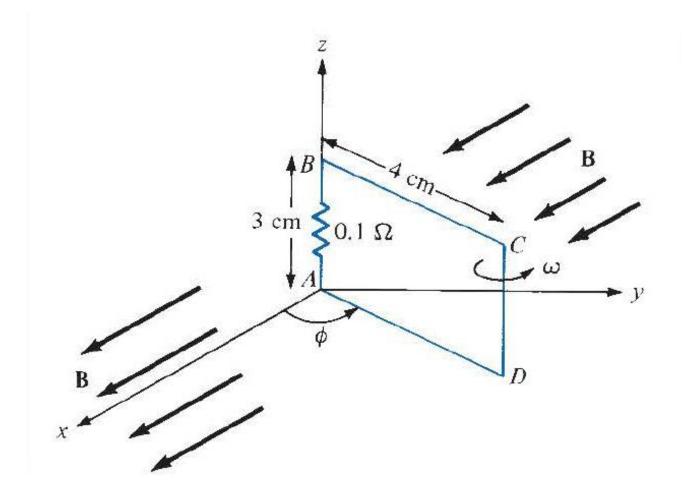
EMF Theory – Unit - 3 NUMERICALS







EMF Theory – Unit - 3 NUMERICALS



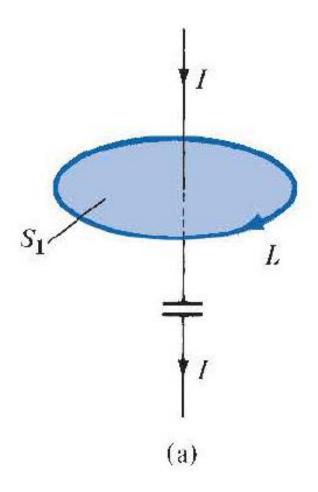


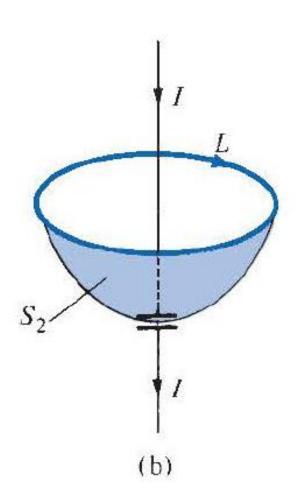


EMF Theory – Unit - 3 DISPLACEMENT CURRENT









Self Study from Text Book

GENERALISED MAXWELL'S EQUATIONS



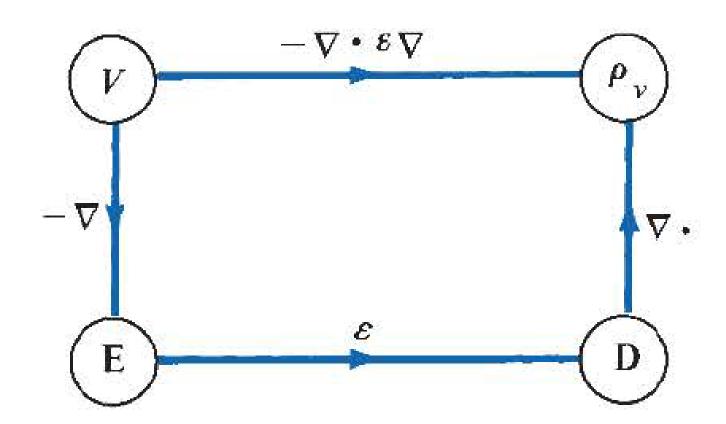
TABLE 9.1 Generalized Forms of Maxwell's Equations

Differential Form	Integral Form	Remarks
$\nabla \cdot \mathbf{p} = \rho_{\nu}$	$\oint_{S} \mathbf{D} \cdot d\mathbf{S} = \int_{v} \rho_{v} dv$	Gauss's law
$\nabla \cdot \mathbf{B} = 0$	$\oint_{S} \mathbf{B} \cdot d\mathbf{S} = 0$	Nonexistence of isolated magnetic charge*
$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$	$\oint_{L} \mathbf{E} \cdot d1 = -\frac{\partial}{\partial t} \int_{S} \mathbf{B} \cdot d\mathbf{S}$	Faraday's law
$\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$	$\oint_{L} \mathbf{H} \cdot d1 = \int_{S} \left(\mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} \right) \cdot d\mathbf{S}$	Ampère's circuit law

^{*}This is also referred to as Gauss's law for magnetic fields.



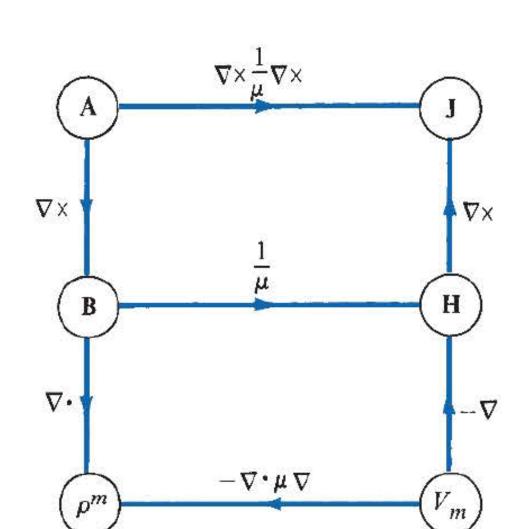
FLOW DIAGRAM – ELECTROSTATIC SYSTEM







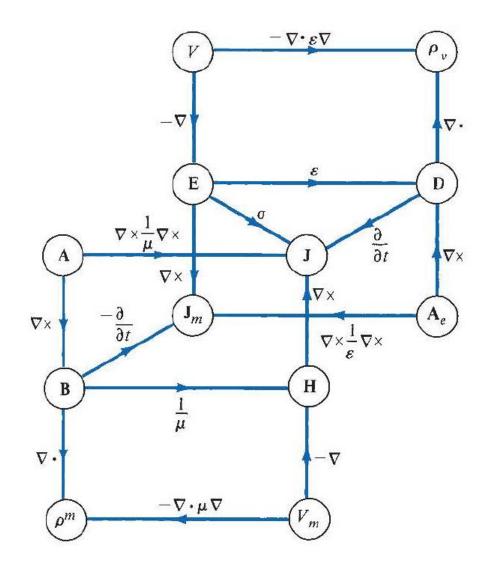
FLOW DIAGRAM – MAGNETOSTATIC SYSTEM







FLOW DIAGRAM – ELECTROMAGNETIC SYSTEM







TIME-HARMONIC MAXWELL'S EQUATIONS – PHASOR FORM

Point Form

Integral Form

$$\nabla \cdot \mathbf{D}_{s} = \rho_{vs}$$

$$\oint \mathbf{D}_s \cdot d\mathbf{S} = \int \rho_{vs} \, dv$$

$$\nabla \cdot \mathbf{B}_s = 0$$

$$\oint \mathbf{B}_{s} \cdot d\mathbf{S} = 0$$

$$\nabla \times \mathbf{E}_{s} = -j\omega \mathbf{B}_{s}$$

$$\oint \mathbf{E}_s \cdot d\mathbf{1} = -j\omega \int \mathbf{B}_s \cdot d\mathbf{S}$$

$$\nabla \times \mathbf{H}_{s} = \mathbf{J}_{s} + j\omega \mathbf{D}_{s}$$

$$\oint \mathbf{H}_s \cdot d\mathbf{1} = \int (\mathbf{J}_s + j\omega \mathbf{D}_s) \cdot d\mathbf{S}$$





ELECTRIC FIELDS IN MATERIAL SPACE – BOUNDARY CONDITIONS





Boundary Conditions.

- of electric of eld in a homogeneous medium.
- -> If the field exists in a region consisting of two different media. The conditions Kat the field must satisfy at the interface Reparating to media are called Boundary and kons.
- -> There conditions are helpful in determining the field on one side of the boundary of the fill on the other side is known.
- -s subsequent discussione would be for the following: interfaces lefarating;
 - (a) Didedric (Er.) a Didedric (Erz)
 - (b) Condudor of dichebric
 - cer conductor of free I face.

ELECTRIC FIELDS IN MATERIAL SPACE – BOUNDARY CONDITIONS





-> To determine the boundary conditions, we use the following maxwell's equations;

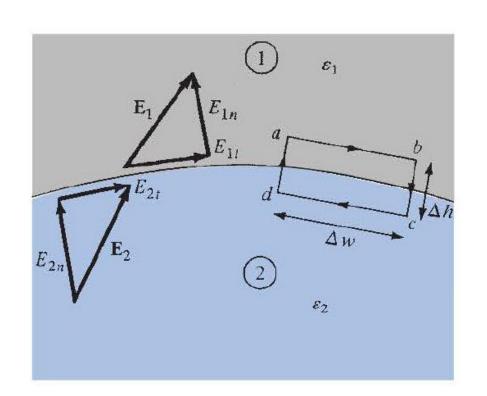
-> The electric field Entensity & is de computed into

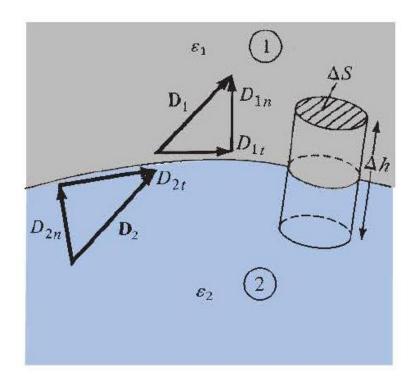
- A Rimilar decomposition can be done for the Electric fluxe deneit D.

ELECTRIC FIELDS IN MATERIAL SPACE – BOUNDARY CONDITIONS







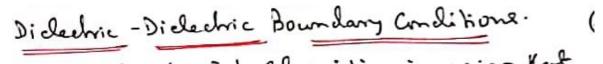


Dielectric – Dielectric Boundary Conditions

ELECTRIC FIELDS IN MATERIAL SPACE – BOUNDARY CONDITIONS







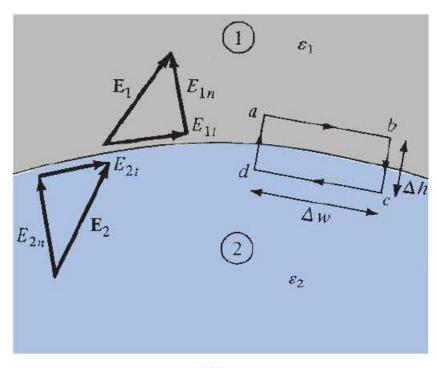
-> consider Na F. field excising in a region Kert consists of a different dielectrice characterised by E. = ED Es, of Ez = Eo Erz.

com be le composed in to.

-> While afflying he com. DE. LI=O to he closed fall aboda as elwan, assuming that he fall is very small with fall a variations, we have be

$$0 = \underbrace{E_{1} + \Delta \omega}_{ab} - \underbrace{E_{1} \times \Delta b}_{2} - \underbrace{E_{2} \times \Delta b}_{2} - \underbrace{E_{3}}_{2}$$

$$+ \underbrace{E_{2} \times \Delta b}_{2} + \underbrace{E_{1} \times \Delta b}_{2}$$



(a)

ELECTRIC FIELDS IN MATERIAL SPACE – BOUNDARY CONDITIONS



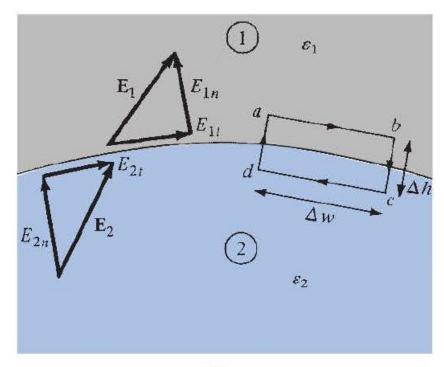


of havel along aboda at the direction of the component vectors.

- Also Et = | Et | + En = | En | . The Ah forms Concel resulting in

Donke hos sides of he boundary.

- s In other words. Et undergever no change on he Aboundary & it is Raid to be Continuous across Ke boundary.



(a)

ELECTRIC FIELDS IN MATERIAL SPACE – BOUNDARY CONDITIONS

(19)



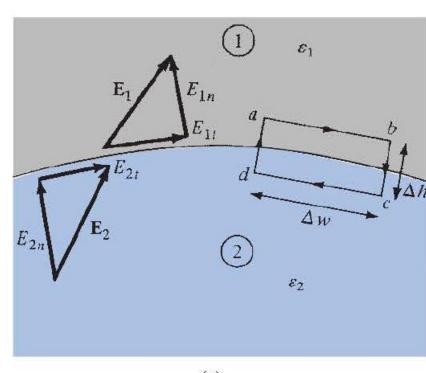


$$\frac{D_1 t}{\epsilon_1} = E_{1t} = E_{2t} = \frac{D_2 t}{\epsilon_2}$$

σv

$$\frac{D_{1+}}{\varepsilon_{1}} = \frac{D_{2+}}{\varepsilon_{2}}$$

Henre Di is said to be "discontinuous" across He interface.



ELECTRIC FIELDS IN MATERIAL SPACE – BOUNDARY CONDITIONS





→ Similarly, when apply the Equation. \$ J. ds = Denc ble cylindrical Cauxian Surface in Keoker figure, -> The contribution due to the lider vanishes. Allowing Sh -> O fives

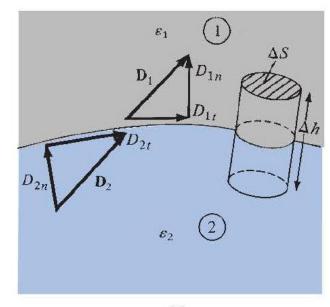
DQ = Ps Ds = Dan DS - Dan DS

[-versign due to officeik direction
at Ke bollom]

0~ Din - Dan = Ps

where Ps is the free change density placed deliberately at the boundary.

-> It is to be noted that the equ. Din-Dan = Ps is based on the alternation Kent D is lineated from Pryion 2 to Region 1 + is about be applied a coordingly.



(b)

ELECTRIC FIELDS IN MATERIAL SPACE – BOUNDARY CONDITIONS

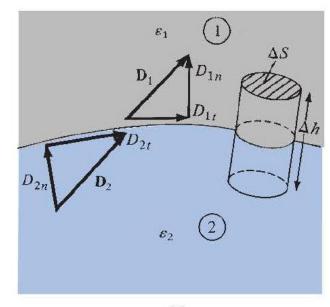




3 H no free changes escirt at the interface Gre changes are not deliberately placed), Pe = 0. Nem

Din = Dan With Pi = 0

across le normal component of Discontinuous across le insterface (on) Dr undergoes no change at le boundary.



(b)

ELECTRIC FIELDS IN MATERIAL SPACE — BOUNDARY CONDITIONS

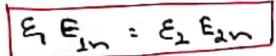
ssince D= EE, we have







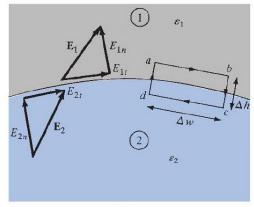


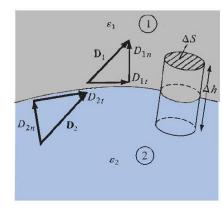


meaning the normal comforment of E is discontinuous at le boundary.

-s Summarising he Boundary Conditions Kut need to be Rahi efical by an somelectric fieldat he boundary reparating two different didutics,

$$\frac{D_{1}-}{\varepsilon_{1}}=\frac{D_{2}+}{\varepsilon_{2}}$$

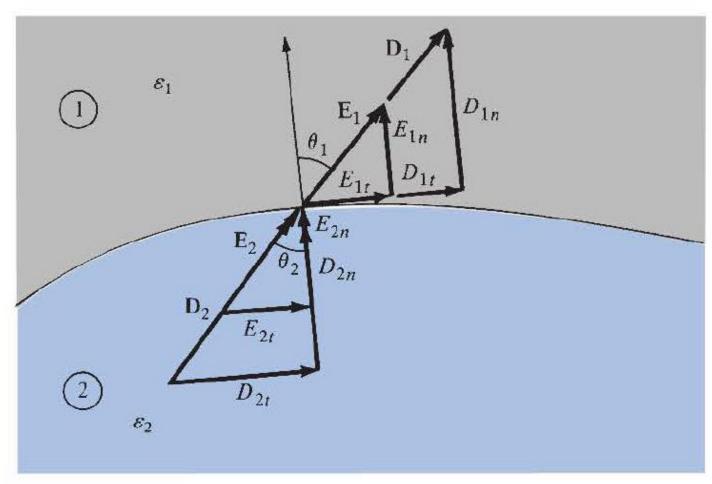




ELECTRIC FIELDS IN MATERIAL SPACE – BOUNDARY CONDITIONS





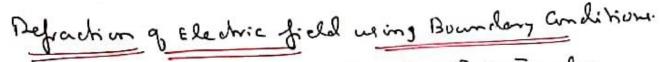


Refraction in Dielectric – Dielectric Boundary

ELECTRIC FIELDS IN MATERIAL SPACE – BOUNDARY CONDITIONS



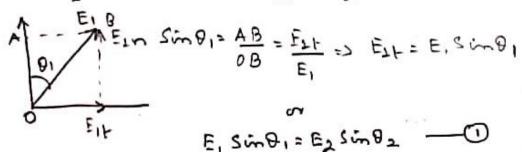


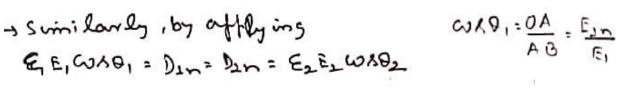


- Refor the figure. Comider Di or E, 4 Dz tor Ez maling angles 0, + 02 with the normal to the inter face as shown.

-> icsing Ke Egn. Ezt = Edt, we have.

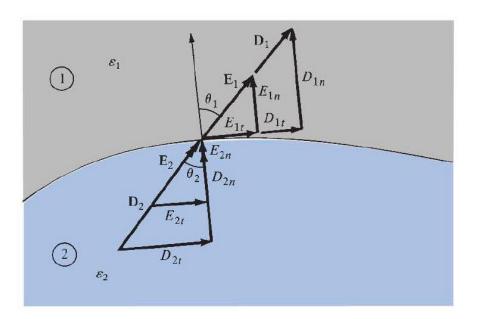
EI Sind, = EIF = EX = EZ: Sinda (in magnitude from)





(e^r)

E, E, WAD, = E2 E2 62 82 - @



ELECTRIC FIELDS IN MATERIAL SPACE – BOUNDARY CONDITIONS

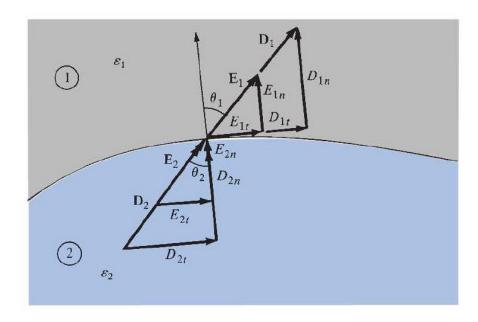




-> Sin 10 E, = E0 Ex, 4 E2 2 E0 Ex2, we have

-s This is law of repraction of electric field at the boundary, free of change (Pe= o assumed)

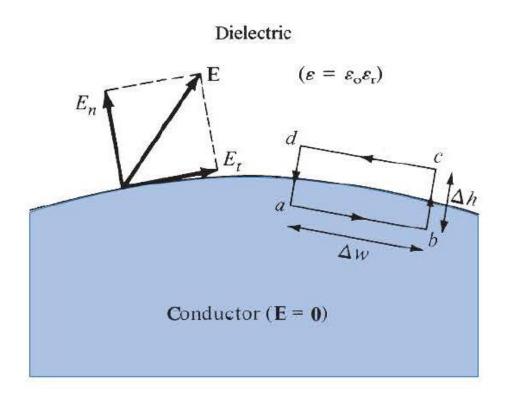
-> In former al, our interface between 2 dichebrics produce - bending of flux lines.

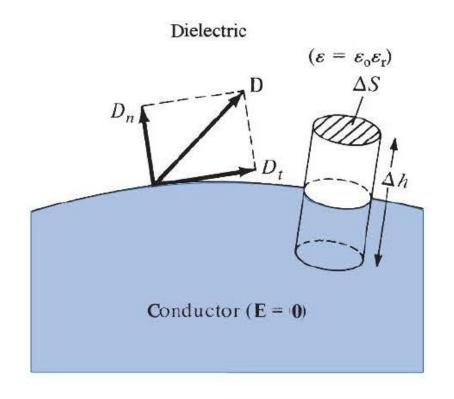


ELECTRIC FIELDS IN MATERIAL SPACE – BOUNDARY CONDITIONS









Conductor – Dielectric Boundary Conditions

ELECTRIC FIELDS IN MATERIAL SPACE – BOUNDARY CONDITIONS

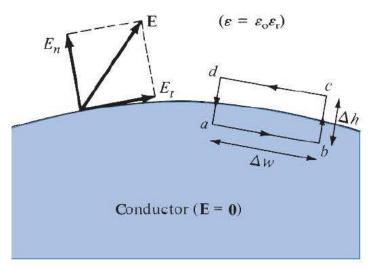




Worductur- Didectric Boundary unditions.

- -> The conductor is assumed to be jurged (5-)ar).
- -> To determine the boundary conditions, we follow the lame procedure, except that E = 0 incide the conductor:
- -> Vering ke equation & E. li= D to ke clusted pathiabeda' es in the fisure, sives





(a)

OGAC RAC-

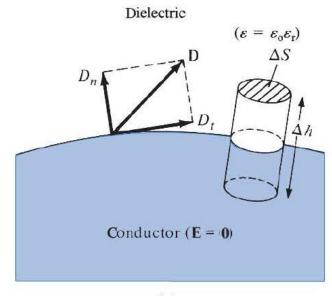
Er = 0

ELECTRIC FIELDS IN MATERIAL SPACE – BOUNDARY CONDITIONS





-> Similarly, wing $\int \overline{D} \cdot d\tilde{s} = \Omega_{enc}$. When while Courtier Surface of Lething $\Delta h \rightarrow 0$, we have $\Delta \theta = D_n \cdot \Delta s - 0 \cdot \Delta s = P_s \Delta s$ -> Similarly, wing $\overline{D} = E E = 0$ intide the conductor, we have



(b)

ELECTRIC FIELDS IN MATERIAL SPACE – BOUNDARY CONDITIONS

conclusions: under static conditions, following 22) can be in forred/anduded for a for fed-conductor:

-> NO electric field many esuit within the conductor. | Pu=0; \(\hat{E}=0 \)

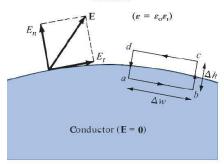
-> Since E= VV= D. Mere can be no potential difference between any 2 joints in the conductor i.e a conductor is an equipotential body.

-s An cleatric field E must be external to the conductor & must be mormal to it & Surface.

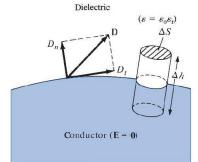








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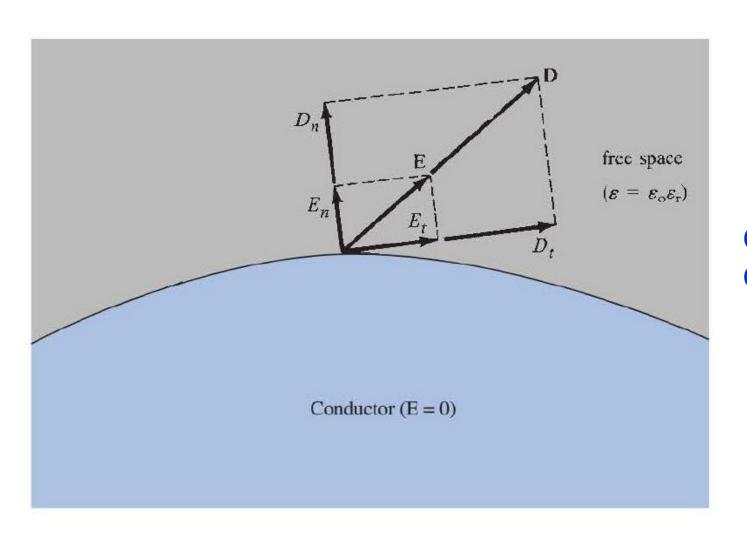


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ELECTRIC FIELDS IN MATERIAL SPACE – BOUNDARY CONDITIONS







Conductor – Free Space Boundary Conditions

ELECTRIC FIELDS IN MATERIAL SPACE — BOUNDARY CONDITIONS

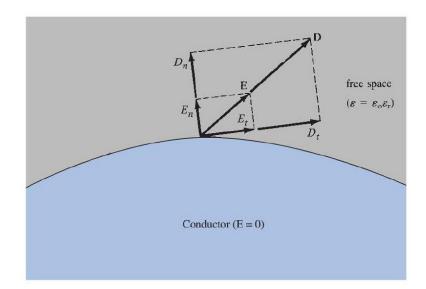




Conductor - Free Space Boundary Conditions.

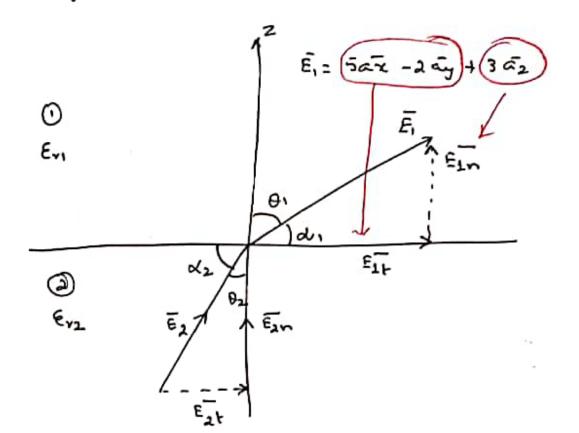
- -> Refor the figure.
- -> Boundary anditions can be obtained from Dr = & E. Et = 0 + Dr = & Et En= Ps
- by replacing E, by 1 (: free Stace man he regarded as a special dideshic for which E = 1).
- -> The electric field & must be external to the conductor & normal to its Runface.

-s The above relation implies Kert the Efield must affroach the conducting lumpace normally.



ELECTRIC FIELDS IN MATERIAL SPACE – BOUNDARY CONDITIONS

Two extensive homogeneous, saphopic dielectrice (23)
meet on plane 2=0 for 2>0; En= 4, 4 for 220
Erz=3. Auniform clectric field E,= 5ax-2ay +3az ky/m
eruits for 2>0.







ELECTRIC FIELDS IN MATERIAL SPACE – BOUNDARY CONDITIONS



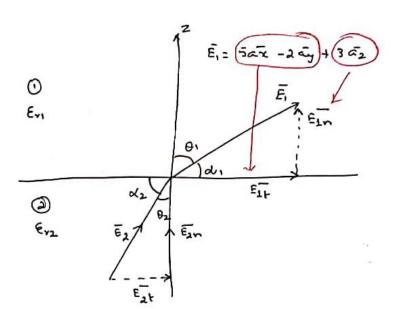


(a) Find Ez for 26

Since az (unitrector in 2-direction) is normal to the boundary plane, we can obtain the normal components as

Now
$$\vec{E} = \vec{E}_{\downarrow} + \vec{E}_{n} = 3$$
 $\vec{E}_{1} + \vec{E}_{1} - \vec{E}_{1n} = 5 \vec{a}_{x} - 2 \vec{a}_{y} + 3 \vec{a}_{z}$

Now wing the boundary andition of D.D, we have







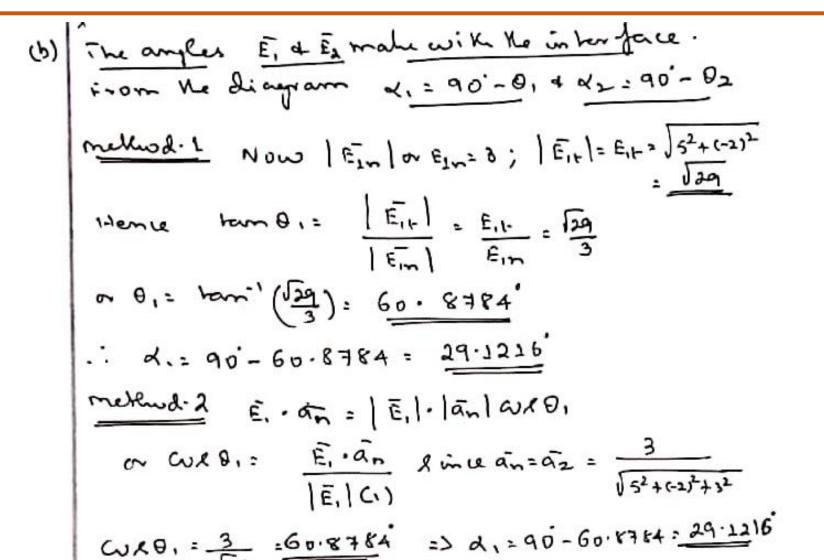
Sumilarly
$$D_{1n} = D_{2n}$$
 or $E_{v_1} E_{n_1} = E_{v_2} E_{2n}$

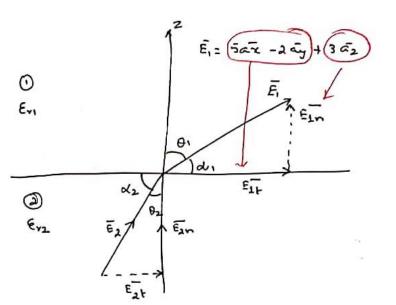
or $E_{2n} = \frac{E_{v_1}}{E_{v_2}} E_{2n} = \frac{A}{3} (3 \overline{a_2}) = \frac{A \overline{a_2}}{4 \overline{a_2}}$

Thus $E_{3} = E_{2l} + E_{2n} = 5\overline{a_x} - 2\overline{a_y} + 4\overline{a_2}$ E_{v_2}
 $E_{v_2} = E_{2l} + E_{2n} = 5\overline{a_x} - 2\overline{a_y} + 4\overline{a_2}$ $E_{v_2} = E_{2l} + E_{2n} = 5\overline{a_x} - 2\overline{a_y} + 4\overline{a_2}$





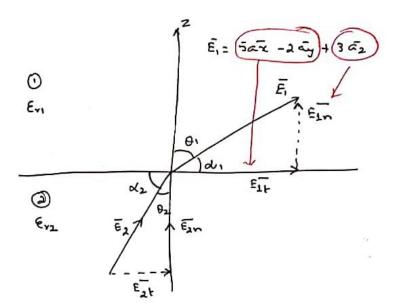


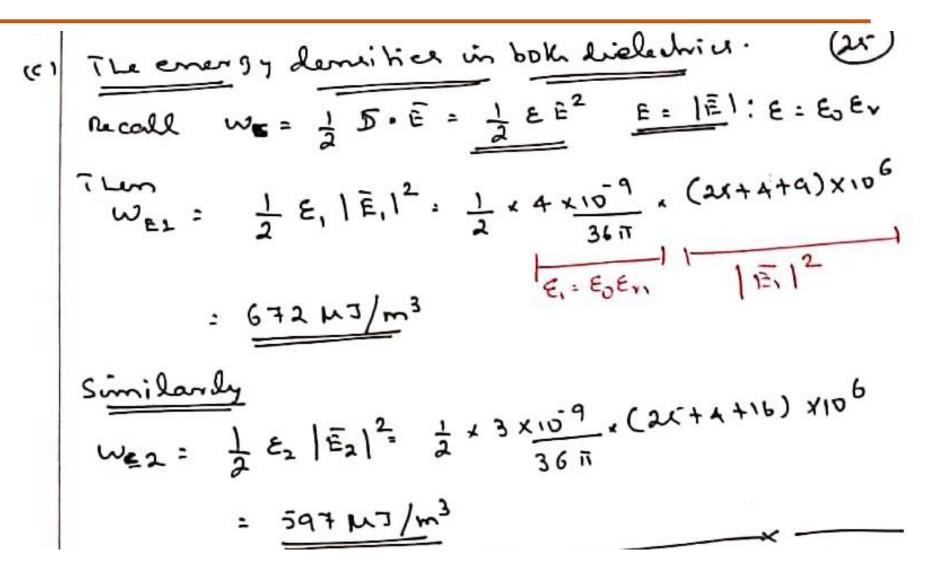






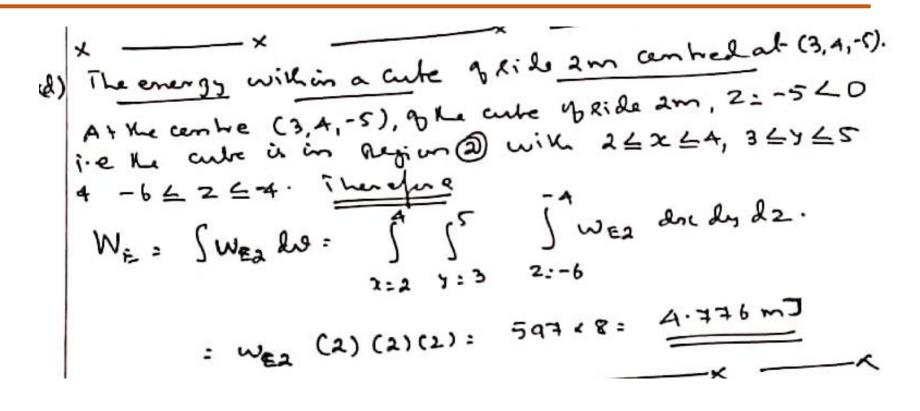
Similarly
$$|E_{2n}| = |4\bar{a}_{2}| = 4$$
; $E_{2r} = E_{1r} = \sqrt{29}$
 $|E_{2n}| = |4\bar{a}_{2}| = 4$; $|E_{2r}| = |E_{2r}| = |E_{2r}| = 1.346 = 20$ $|E_{2r}| = |E_{2r}| = |E_{2r}|$







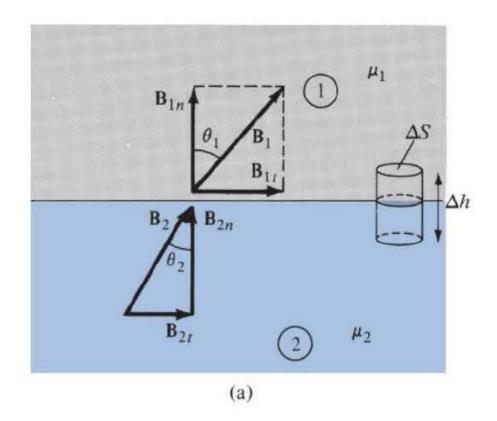


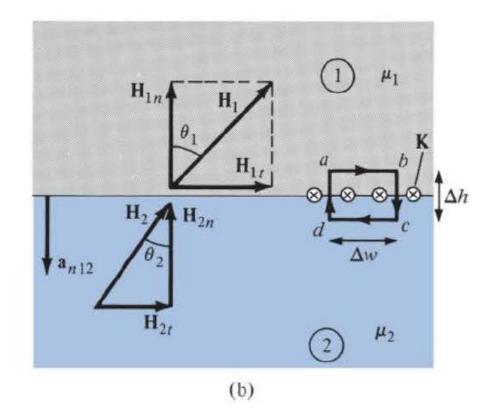














MAGNETIC FIELDS IN MATERIAL SPACE – BOUNDARY CONDITIONS



Summary:

$$B_{1n} = B_{2n}$$
 or $\mu_1 H_{1n} = \mu_2 H_{2n}$

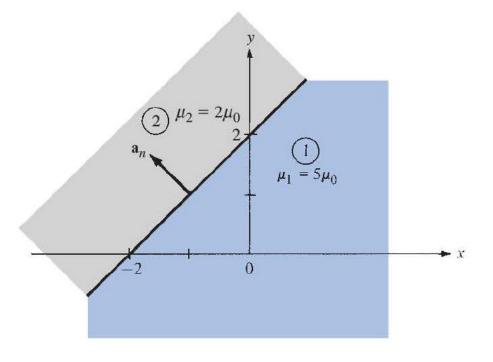
$$(H_{1n} - H_{2n}) \times a_{n12} = K$$

$$H_{1t} = H_{2t}$$
 or $\frac{B_{1t}}{\mu_1} = \frac{B_{2t}}{\mu_2}$ with the boundary free of current.

$$\frac{\tan\theta_1}{\tan\theta_2} = \frac{\mu_1}{\mu_2}$$

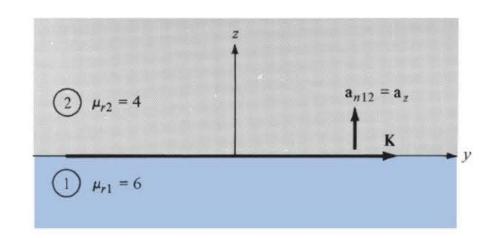






Ex. 1

Ex. 2







THANK YOU

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