

Stability :

1. External Stability : For a bounded input we get a bounded output then system is BIBO stable

Location of the poles

poles in LHS — Stable

poles in RHS — Unstable

poles on jw axis — Marginally stable

$$G(s) = \frac{20(s+1)}{(s-1)(s^2+2s+2)}$$

Unstable $s = +1$

$$G(s) = \frac{20(s-1)}{(s+2)(s^2+4)}$$

Marginally stable $s = \pm j2$

$$G(s) = \frac{20(s-1)}{(s+2)(s^2+4)^2}$$

Stable? Or Unstable?
Marginally stable?

$$Y(s) = G(s) R(s) = G(s) = \frac{1}{(s^2+4)^2}$$

$$Y(s) = \frac{As+B}{s^2+4} + \frac{Cs+D}{(s^2+4)^2}$$

\downarrow ILT \downarrow ILT

$$y(t) = \cos(2t) + t \cos(2t)$$

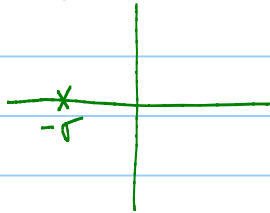
Type of roots

Nature of
Impulse Response

Impulse Response

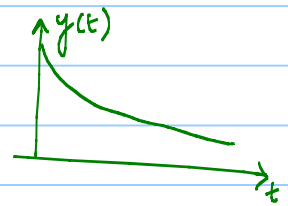
①

Single root at
 $s = -\sigma$

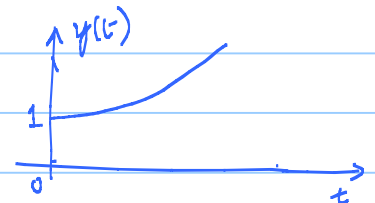


$$G(s) = \frac{1}{s + \sigma}$$

$$y(t) = e^{-\sigma t}, t \geq 0$$



$$y(t) = e^{\sigma t}, t \geq 0$$



2. Multiple roots at σ
(k roots)

$$G(s) = \frac{1}{(s + \sigma)^k}$$

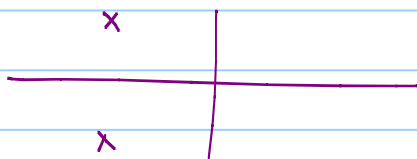


$$y(t) = A_1 e^{-\sigma t} + A_2 t e^{-\sigma t} + \dots + A_k t^{k-1} e^{-\sigma t}, t \geq 0$$

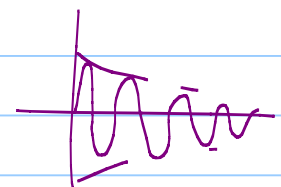
Unstable

3. Complex conjugate poles

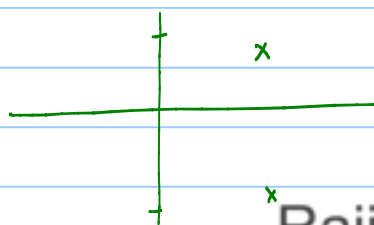
$$s = -\sigma \pm j\omega$$



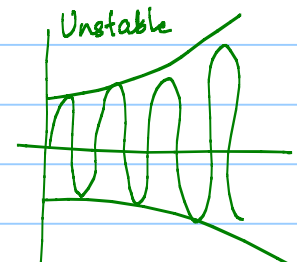
$$y(t) = e^{-\sigma t} \sin(\omega t)$$



Stable



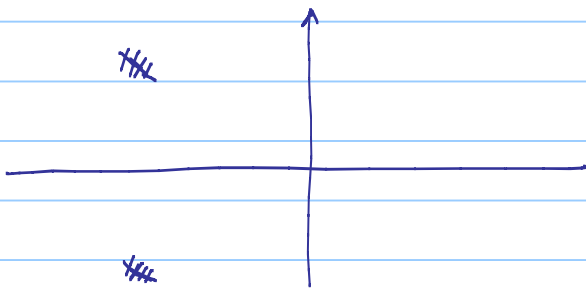
$$y(t) = e^{+\sigma t} \sin \omega t$$



Unstable

4. Multiple conjugate poles
(k roots)

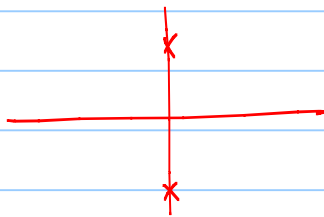
$$s = -\sigma \pm j\omega \quad \text{--- } k \text{ times}$$



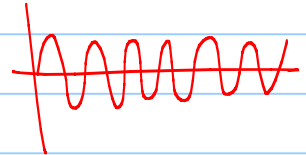
$$y(t) = e^{-\sigma t} \sin \omega t + t e^{-\sigma t} \sin \omega t + \dots + t^{k-1} e^{-\sigma t} \sin \omega t$$

Unstable

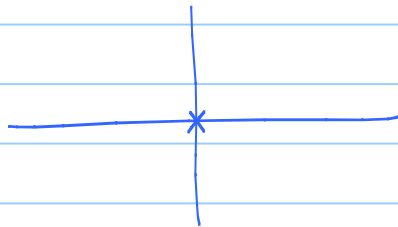
5. Single pair of roots on
 $j\omega$ axis



$$y(t) = \sin \omega t$$

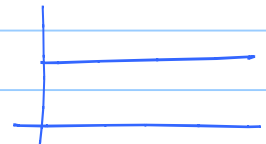


6. Single pole at origin

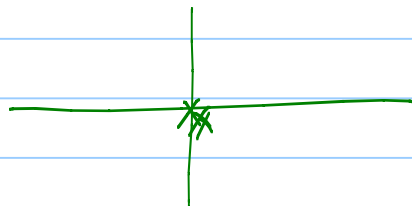


$$G(s) = \frac{1}{s}$$

$$y(t) = 1, t \geq 0$$



7. Multiple poles at origin
 k times



$$y(t) = \frac{t^{k-1}}{(k-1)!}$$

Unstable

$$a_3 s^3 + a_2 s^2 + a_1 s + a_0 = 0$$

$$\begin{array}{c|ccc} s^3 & a_3 & a_1 & 0 \\ s^2 & a_2 & a_0 & 0 \\ s^1 & b_1 & b_2 & \\ s^0 & c_1 & & \end{array}$$

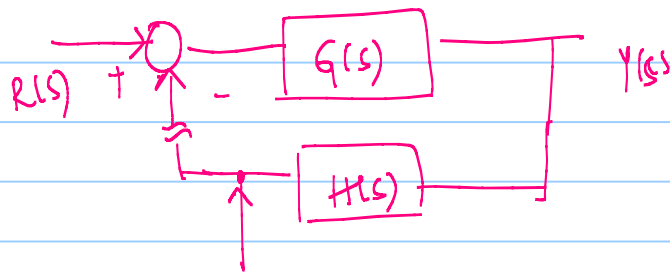
$$b_1 = \frac{a_2 a_1 - a_3 a_0}{a_2}$$

$$b_2 = \frac{a_2 \times 0 - a_3 \times 0}{a_2}$$

$$c_1 = \frac{b_1 a_0 - b_2 a_2}{b_1}$$

$$a_4 s^4 + a_3 s^3 + a_2 s^2 + a_1 s + a_0 = 0$$

$$\begin{array}{c|ccc} s^4 & a_4 & a_2 & a_0 \\ s^3 & a_3 & a_1 & 0 \\ s^2 & \frac{a_3 a_2 - a_4 a_1}{a_3} & \frac{a_3 a_0 - a_4 \times 0}{a_3} & 0 \\ s^1 & \frac{b_1 a_1 - b_2 a_3}{b_1} & 0 & \\ s^0 & \frac{c_1 b_2 - b_1 \times 0}{c_1} & 0 & \end{array}$$



$$OLTF = \underline{G(s)H(s)}$$

$$Y(s) = \underbrace{G(s)H(s)}_{OLTF} R(s)$$

$$CLTF = \frac{G(s)}{1 + \underbrace{G(s)H(s)}_{OLTF}}$$

RH Criteria :

CLTF characteristic eqⁿ = $1 + G(s)H(s)$ — apply the procedure ,

Root locus , Bode plots , Nyquist :

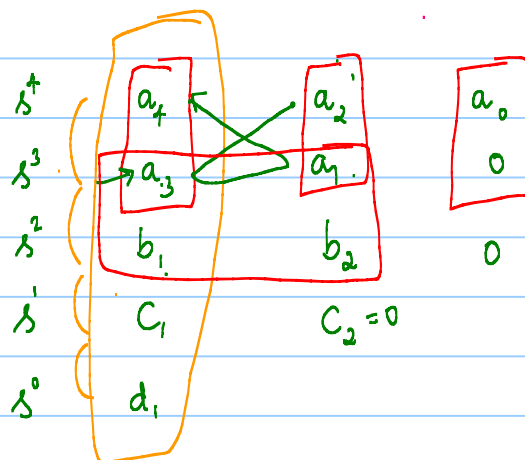
Start with $G(s)H(s)$ then apply the procedure.

Ultimate goal of the above mentioned technique is Stability of of CLTF

$$a_4 s^4 + a_3 s^3 + a_2 s^2 + a_1 s + a_0 = 0$$

$$a_i \neq 0 \quad i=0,1,2,3,4$$

+ve



$$b_1 = \frac{a_2 a_3 - a_1 a_4}{a_3}$$

$$b_2 = \frac{a_0 a_3 - a_4 \times 0}{a_3}$$

$$c_1 = \frac{a_1 b_1 - a_3 b_2}{b_1}$$

$$c_2 = \frac{b_1 \times 0 - a_3 \times 0}{b_1} = 0$$

$$d_1 = \frac{b_2 c_1 - c_2 b_1}{c_1}$$

$$① \quad q(s) = 2s^4 + s^3 + 3s^2 + 5s + 10 = 0$$

$$s^4 \quad 2 \quad 3 \quad 10$$

$$s^3 \quad 1 \quad 5 \quad 0$$

$$s^2 \quad b_1 = -7 \quad b_2 = 10$$

$$s^1 \quad c_1 = 45/7 \quad c_2 = 0$$

$$s^0 \quad d_1 = 10$$

$$b_1 = \frac{3 \times 1 - 5 \times 2}{1} = -7$$

$$b_2 = \frac{10 \times 1 - 2 \times 0}{1} = 10$$

$$c_1 = \frac{5 \times -7 - 10 \times 1}{-7} = \frac{45}{7}$$

$$d_1 = \frac{10 \times \frac{45}{7} - (-7) \times 0}{\frac{45}{7}}$$

Since two sign changes in the first column of RHP Table implies 2 poles in RHP

\therefore Closed loop system is unstable

$$② \quad q(s) = s^4 + s^3 + 2s^2 + 2s + 3 = 0$$

$$\begin{array}{rcll} + & s^4 & (& 1 \quad 2 \quad 3 \\ + & s^3 & & 1 \quad 2 \quad \epsilon > 0 \\ - & + & s^2 & \nearrow \epsilon \quad 3 \\ + & - & s^1 & \frac{2\epsilon - 3}{\epsilon} \quad 0 \\ + & + & s^0 & 3 \end{array}$$

$$\lim_{\epsilon \rightarrow 0} \frac{2\epsilon - 3}{\epsilon} = \lim_{\epsilon \rightarrow 0} 2 - \frac{3}{\epsilon} = -\text{Ve number}$$

\Rightarrow Two poles in RHP & system is unstable
2 poles in LHP

OR

$$s = 1/2$$

$$\left(\frac{1}{2}\right)^4 + \left(\frac{1}{2}\right)^3 + 2\left(\frac{1}{2}\right)^2 + 2\left(\frac{1}{2}\right) + 3 = 0$$

$$1 + 2 + 2z^4 + 2z^3 + 3z^4 = 0 \quad \begin{array}{rcll} + & z^4 & 3 & 2 \quad 1 \\ + & z^3 & 2 & 1 \end{array}$$

$$\Rightarrow \text{Two sign changes.} \quad \begin{array}{rcll} + & z^2 & 1/2 & 1 \\ - & z^1 & -3 & 0 \\ + & z^0 & 1 & \end{array}$$

Hence two unstable poles

$$T(s) = \frac{20}{s^8 + s^7 + 12s^6 + 22s^5 + 39s^4 + 59s^3 + 48s^2 + 38s + 20}$$

Table 1

s^8	1	12	39	48	20
s^7	1	22	59	38	0
s^6	-1	-2	1	2	(got by $\div 10$)
s^5	1	3	2	0	(got by $\div 20$)

s^4	1	3	2	
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s^3	4	6	0	
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s^2	$\frac{3}{2}$	$\frac{2}{2}$		
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s^1	$\frac{2}{3}$	0		
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s^0	4			
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$$U(s) = s^4 + 3s^2 + 2$$

$$\frac{dU(s)}{ds} = 4s^3 + 6s$$

x by 2

Table 2 → 4 roots on jw axis (solving $U(s)$)

$$s^4 + 3s^2 + 2 = 0$$

→ 2 sign changes \Rightarrow 2 roots in RHP

$$s = \pm j, \pm j\sqrt{2}$$

→ Remaining 2 roots in LHP.

Ex:

$$G(s) = \frac{k(s+2)(s+1)}{(s+0.1)(s-1)}$$

$$1 + G(s) = 0 \quad \text{--- Characteristic eqn}$$

$$\frac{(s+0.1)(s-1) + k(s+2)(s+1)}{(s+0.1)(s-1)} = 0$$

$$\Rightarrow (s+0.1)(s-1) + k(s+2)(s+1) = 0$$

$$(1+k)s^2 + (3k-0.9)s + (2k-0.1) = 0$$

s^2	$(1+k)$	$(2k-0.1)$
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s^1	$3k-0.9$	0
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s^0	$2k-0.1$	
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Case (i): No poles in RHP.

all the elements in the first column must be positive

$$\Rightarrow 1+k > 0 \quad k > -1$$

$$\Rightarrow 3k-0.9 > 0 \quad k > 0.3 \quad \Rightarrow k > 0.3$$

$$\Rightarrow 2k-0.1 > 0 \quad k > 0.05$$

Case (ii): Only one pole in RHP

either first two entries or last two entries of the first column of RH Table must have same sign (and other combinations also possible)

$$+ \quad 1+k > 0$$

$$-1 < k < 0.05$$

$$- \quad 3k-0.9 < 0$$

$$- \quad 2k-0.1 < 0$$

Case (iii): Two poles in RHP

$$+ \quad 1+k > 0$$

$$- \quad 3k-0.9 < 0 \quad 0.05 < k < 0.3$$

$$+ \quad 2k-0.1 > 0$$

Ex: $\ddot{x}(t) - (k+2)\dot{x} + (2k+5)x = 0$

Apply LT \rightarrow

$$(s^2 - (k+2)s + (2k+5))X(s) = 0$$

$$s^2 - (k+2)s + (2k+5) = 0$$

$$s^2 \quad | \quad 2k+5$$

$$s^1 \quad | \quad -(k+2) \quad 0$$

$$s^0 \quad | \quad (2k+5)$$

Case (i): Stable

$$k+2 < 0 \rightarrow \begin{aligned} -(k+2) &> 0 & 2k+5 &> 0 \\ k &< -2 & k &> -2.5 \end{aligned}$$

$$-2.5 < k < -2$$

case (ii): Marginally Stable

$$K+2=0 \quad K=-2 \quad \text{or} \quad K=-2.5$$

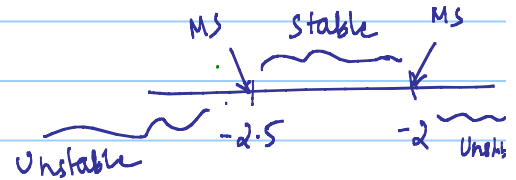
When $K=-2.5$ $s^2 + 0.5s = 0 \Rightarrow s = 0, -0.5$

$$Y(s) = G(s)R(s)$$

case (iii): Unstable

$$K > -2 \quad K < -2.5$$

b) $-2.5 < K < -2$



$$s_{1,2} = \frac{(K+2) \pm \sqrt{(K+2)^2 - 4 \times (2K+5)}}{2}$$

For critically damped

$$-2.5 < K < -2$$

$$(K+2)^2 - 4(2K+5) = 0$$

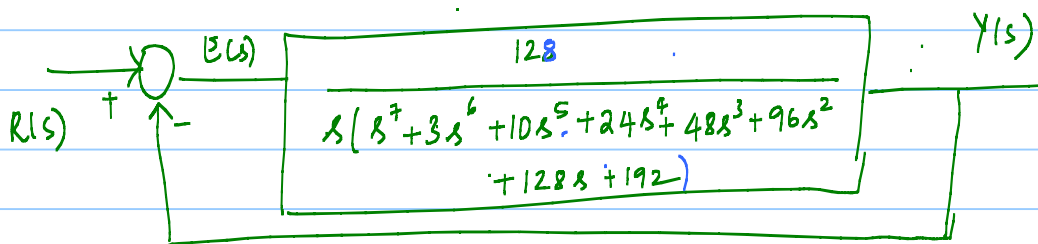
$$K = -2.47, \quad [+6.47] \text{ out of stable range}$$

Overdamped case:

$$-2.5 < K < -2.47 \quad ((K+2)^2 - 4(2K+5)) > 0$$

Underdamped case:

$$-2.47 < K < -2 \quad ((K+2)^2 - 4(2K+5)) < 0$$



Find the no of poles of closed loop system in RHP, LHP + jw axis.

$$1 + G(s) = 0$$

$$q(s) = s^8 + 3s^7 + 10s^6 + 24s^5 + 48s^4 + 96s^3 + 128s^2 + 192s + 128 = 0$$

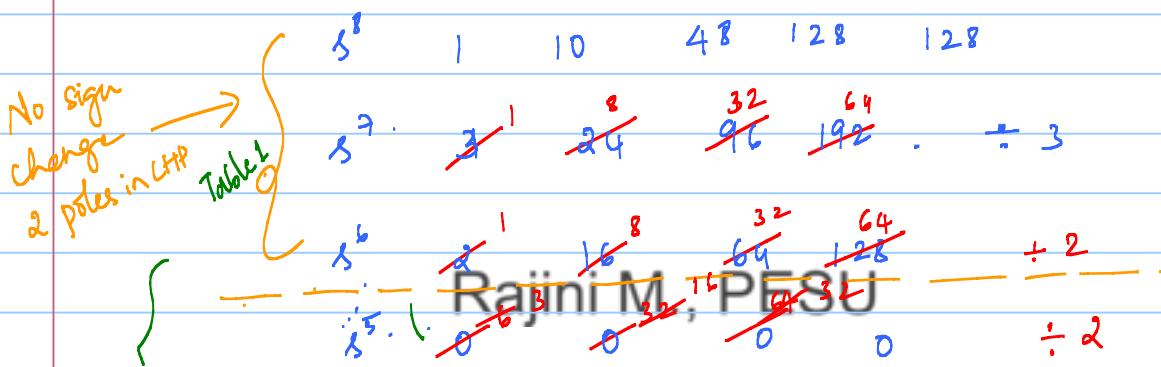


Table 2

$$V(s) = s^6 + 8s^4 + 32s^2 + 64$$

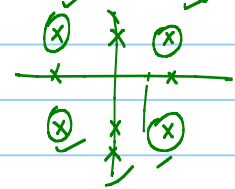
$$\frac{dV(s)}{ds} = 6s^5 + 32s^3 + 64s + 0$$

s^4	$\frac{8}{3}$	$\frac{64}{3}$	$\frac{24}{3}$	$\times \frac{3}{8}$
s^3	-8	-40		$\div 8$
s^2	3	24		$\div 3$
s^1	3	0		
s^0	8			

→ From Table 1, no sign changes \Rightarrow 2 poles in LHP

→ From Table 2, two sign changes \Rightarrow 2 poles in RHP, due to symmetry 2 poles in LHP.

→ Remaining 2 on the jw axis.



$$q(s) = s^5 + s^4 + 4s^3 + 24s^2 + 3s + 63$$

Table 1	s^5	1	4	3	+
	s^4	1	24	63	+
	s^3	-20	-60	0	-
Table 2	s^2	21	63	0	+
	s^1	3	0	0	
	s^0	3			

$$A(s) = 21s^2 + 63s = s^2 + 3$$

$$\frac{dA(s)}{ds} = 2s + 0$$

→ 2 sign changes in Table 1 \Rightarrow 2 roots in RHP

→ Solving $A(s)$, we get roots on jw axis.

→ Remaining roots i.e 1 root on LHP.

$$(1) \quad s^4 + 5s^3 + 2s + 10 = 0$$

$$(2) \quad s^5 + 5s^4 + 14s^3 + 8s^2 - 19s - 10 = 0$$

$$(3) \quad 2s^5 + s^4 + 6s^3 + 3s^2 + s + 1 = 0$$

$$(4) \quad s^5 - s^4 - 2s^3 + 2s^2 - 8s + 8 = 0$$

$$(1) \quad s^4 + 5s^3 + 2s + 10 = 0$$

→ No of roots with positive real part - 2

→ No of roots with ~~ve~~ real part - 2

→ ~~1~~ zero real part - 0

③

$$2s^5 + s^4 + 6s^3 + 3s^2 + s + 1 = 0$$

$$\begin{array}{r} s^5 \quad 2 \quad 6 \quad 1 \\ s^4 \quad 1 \quad 3 \quad 1 \\ s^3 \quad 0 \quad -1 \\ s^2 \quad \frac{3\epsilon+1}{\epsilon} \quad 1 \\ s^1 \quad \frac{-3\epsilon-1-\epsilon^2}{3\epsilon+1} \quad 0 \\ s^0 \quad 1 \end{array}$$

$$\begin{array}{r} +\epsilon \quad -1 \\ \frac{3\epsilon+1}{\epsilon} \quad 1 \\ \frac{3\epsilon+1}{\epsilon} \times -1 - \epsilon \\ \frac{3\epsilon+1}{\epsilon} \\ -3\epsilon-1-\epsilon^2 \\ \frac{3\epsilon+1}{\epsilon} \end{array}$$

- No of roots with positive real part - 2
 → No of roots with -ve real part - 3
 * ————— 1 — zero real part - 0

$$b) s^5 + 5.5s^4 + 14.5s^3 + 8s^2 - 19s - 10 = 0$$

$$\begin{array}{r} s^5 \quad 1 \quad 14.5 \quad -19 \\ s^4 \quad 5.5 \quad 8 \quad -10 \\ s^3 \quad 13.04 \quad -17.18 \quad 0 \\ s^2 \quad 15.27 \quad -10 \quad 0 \\ s^1 \quad -8.64 \quad 0 \quad 0 \\ s^0 \quad -10 \end{array}$$

- No of roots with positive real part - 1
 → No of roots with -ve real part - 4
 * ————— 1 — zero real part - 0