



DIGITAL IMAGE PROCESSING-1

Unit 3: Lecture 27-28

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Unit 3: Image Enhancement

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Last Session

- K L Transform
- Singular Value Decomposition (SVD)

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Today's Session

- Introduction to Image Enhancement
- Point Operations

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Image Enhancement

- Objective:
 - To process an image so that the result is more suitable than the original image for a *specific* application
 - Techniques are problem/image dependent
 - Methods used for X-ray image enhancement are different from enhancing satellite images
 - One of the most interesting and '*visually appealing*' areas of image processing

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Image Enhancement

- Image enhancement is the process of enhancing the quality of a given image for analysis
 - Aim is to improve the quality so that image analysis is accurate, leading to an improvement in the reliability of the image processing applications

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Image Enhancement

- Very first step in Digital Image Processing
- It is purely subjective
 - It improves subjective qualities of images
- **It is a cosmetic procedure**

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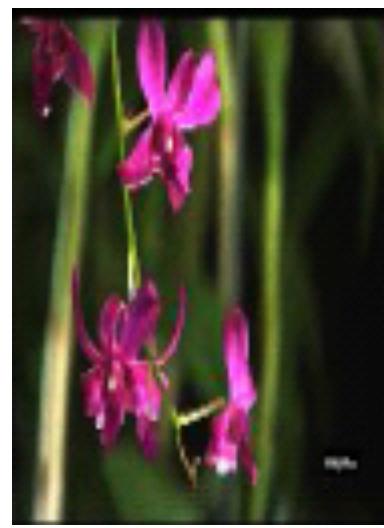
Need for Image Enhancement

- Often necessary to extract various features of an image or objects present in image
- Often the quality of acquired image is not satisfactory due to factors such as brightness, contrast, blur, unnatural colours, noise and artefacts

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Need for Image Enhancement

- Image is not visually acceptable sometimes



- ▶ Reasons:
 - ▶ Poor illumination
 - ▶ Wrong setting of lens aperture

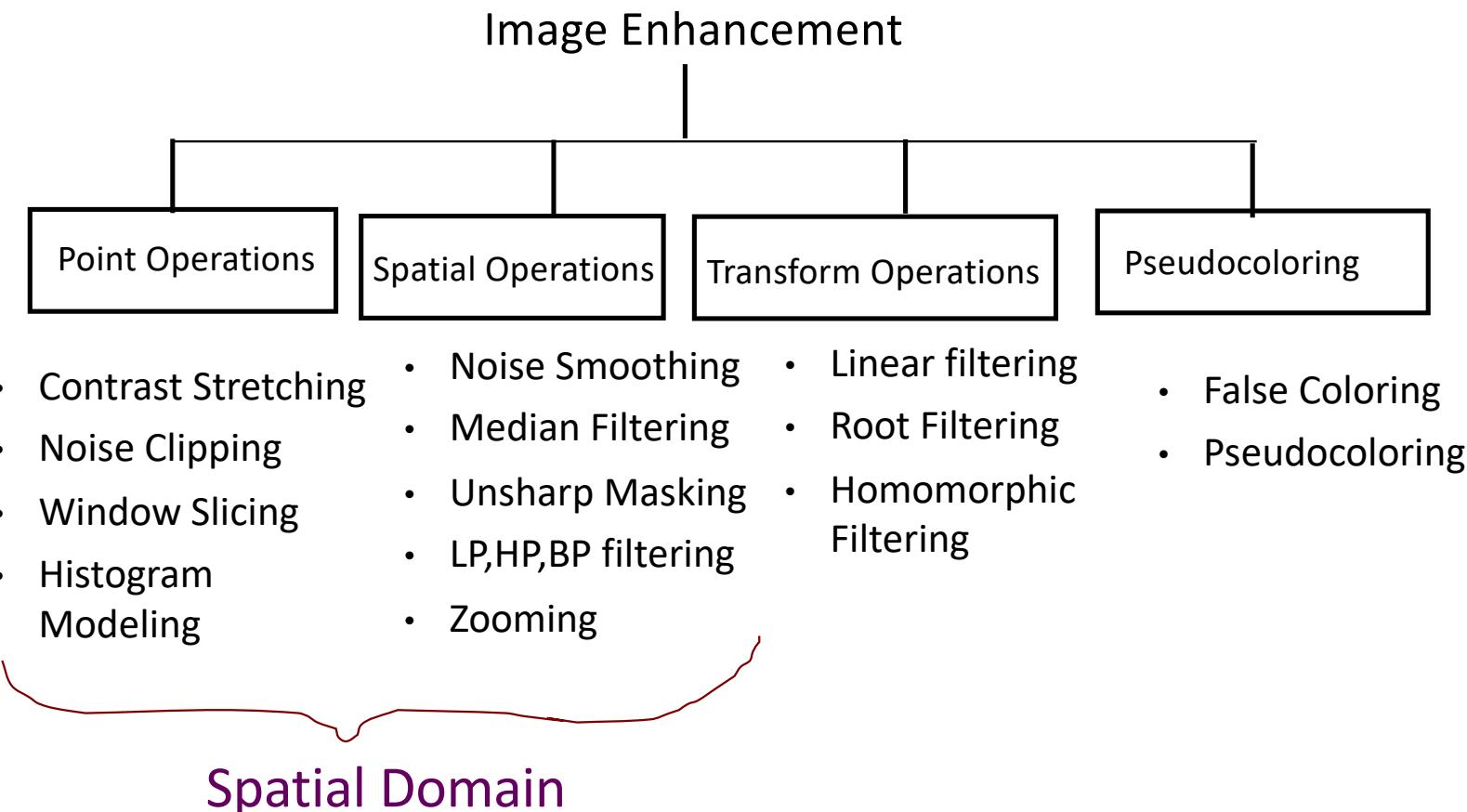
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Types of Enhancement Techniques

- Types (depending on domain):
 - Spatial Domain (Image plane)
 - Frequency Domain (Modifying Fourier transform of image)
 - Joint Spatial-Frequency Domain (eg. Wavelet domain)

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Types of Enhancement Techniques



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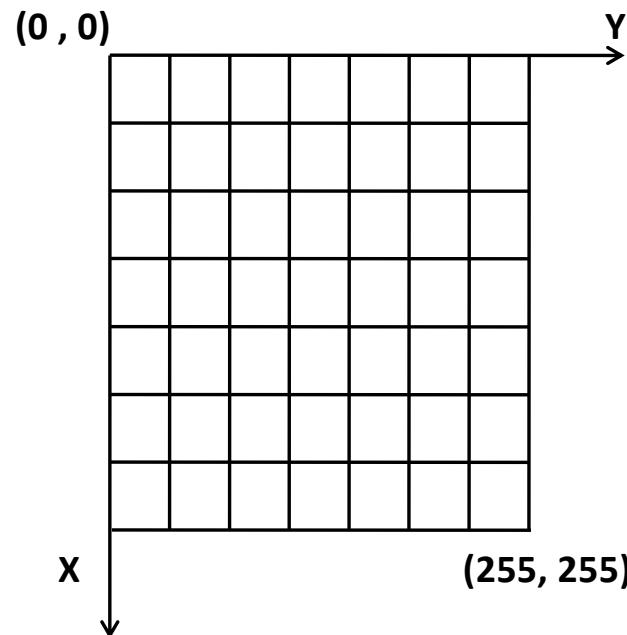
Spatial Domain

- Spatial: Working in space i.e.(given image)
- Spatial Domain: Aggregate of pixels composing an image. Working with pixel values or raw data
- Spatial Domain Methods: Methods that operate directly on these pixels

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Spatial Domain

- In an image with size 256×256 , (x, y) can assume any value from $(0, 0)$ to $(255, 255)$.



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Spatial Domain

- Applying transform modifies the image

$$g(x,y) = T f(x,y)$$

where,

$f(x,y)$ is original image

T is transformation applied on $f(x,y)$

$g(x,y)$ is new modified image

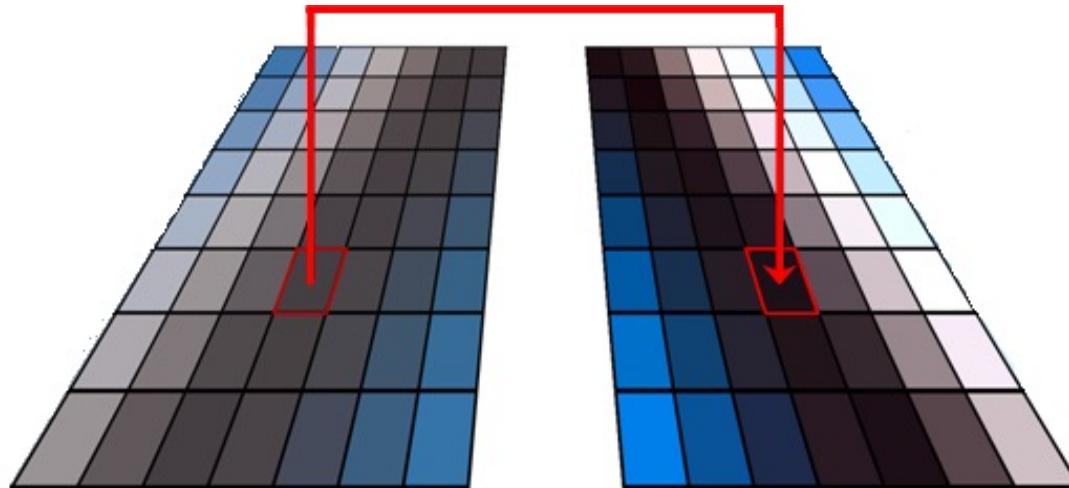
- In spatial domain techniques it is ‘ T ’ that changes
- Spatial domain enhancement is carried out in two ways:
 - ❑ Point processing
 - ❑ Neighborhood processing (Spatial operations)

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Point Processing

- Here, we work on single pixel i.e. T is 1×1 operator

$$g(x, y) = T[f(x, y)]$$



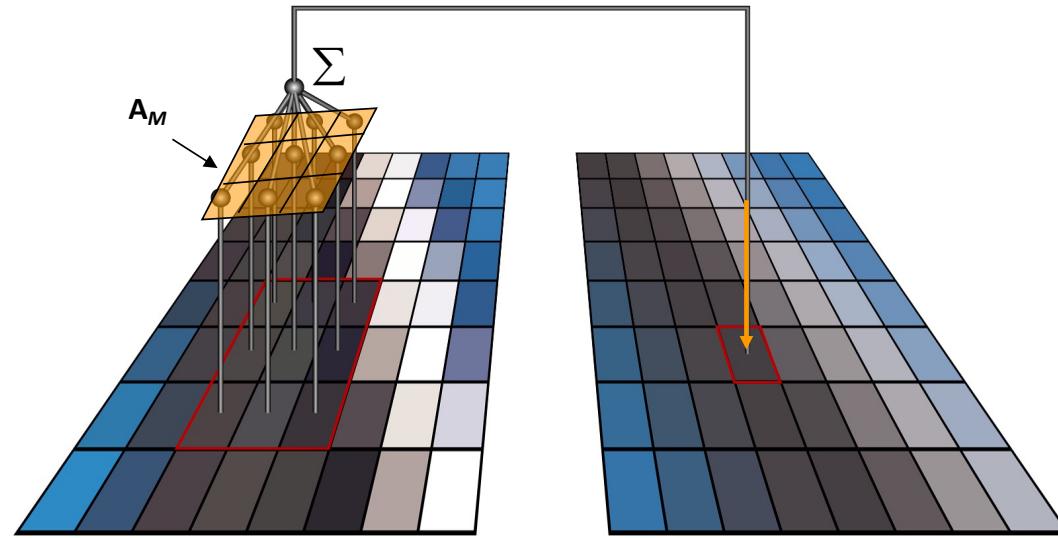
In this case, g depends only on the value of f at a single point (x, y) and T becomes an intensity (also called a gray-level, or mapping) transformation function of the form $s = T(r)$

s and r denote, respectively, the intensity of g and f at any point (x, y)

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Neighbourhood Processing

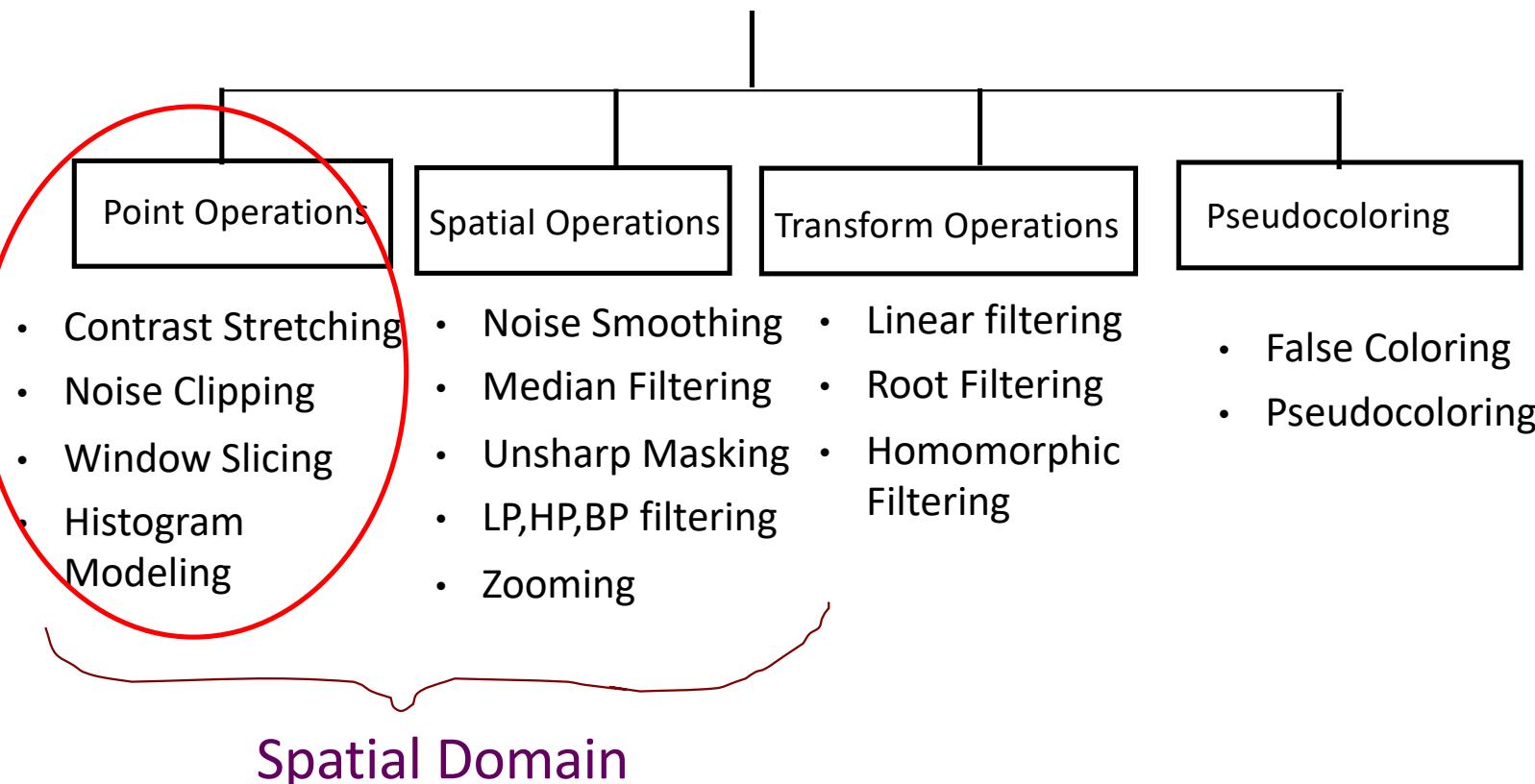
- **Spatial Operations:** Each pixel is modified according to values in a small neighborhood called mask(*small matrix whose values are termed as weights*)



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Types of Enhancement Techniques

Image Enhancement



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Point Processing

- Some important examples of point processing are:
 - Brightness modification
 - Contrast Modification
 - Digital Negative
 - Dynamic range compression
 - Thresholding (noise clipping)
 - Gray level slicing
 - Bit plane slicing
 - Histogram modeling

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Point Processing

- Some important examples of point processing are:

- Brightness modification
- Contrast Modification
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- Histogram modeling

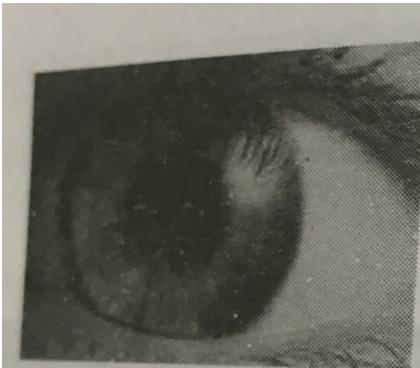
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Brightness Modification

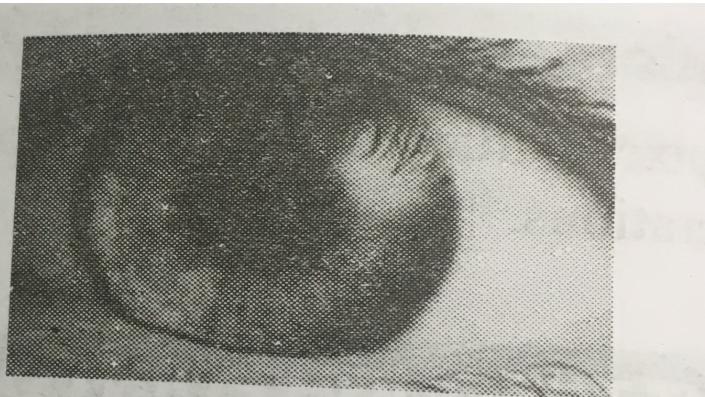
- Brightness depends on the values of pixels
- For changing the brightness, a constant is added to (to increase brightness) or subtracted from(to decrease brightness) luminance of all sample values
- Increasing brightness: $g[m,n] = f[m,n] + k$
- Decreasing brightness: $g[m,n] = f[m,n] - k$

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Brightness Modification



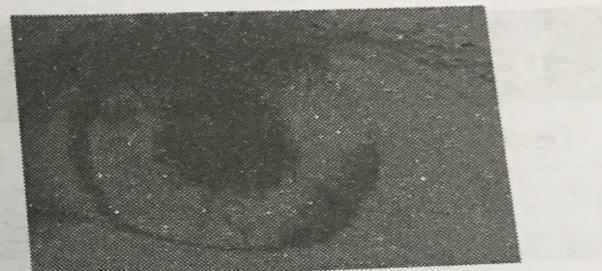
(a) Original image



(b) Brightness-enhanced image



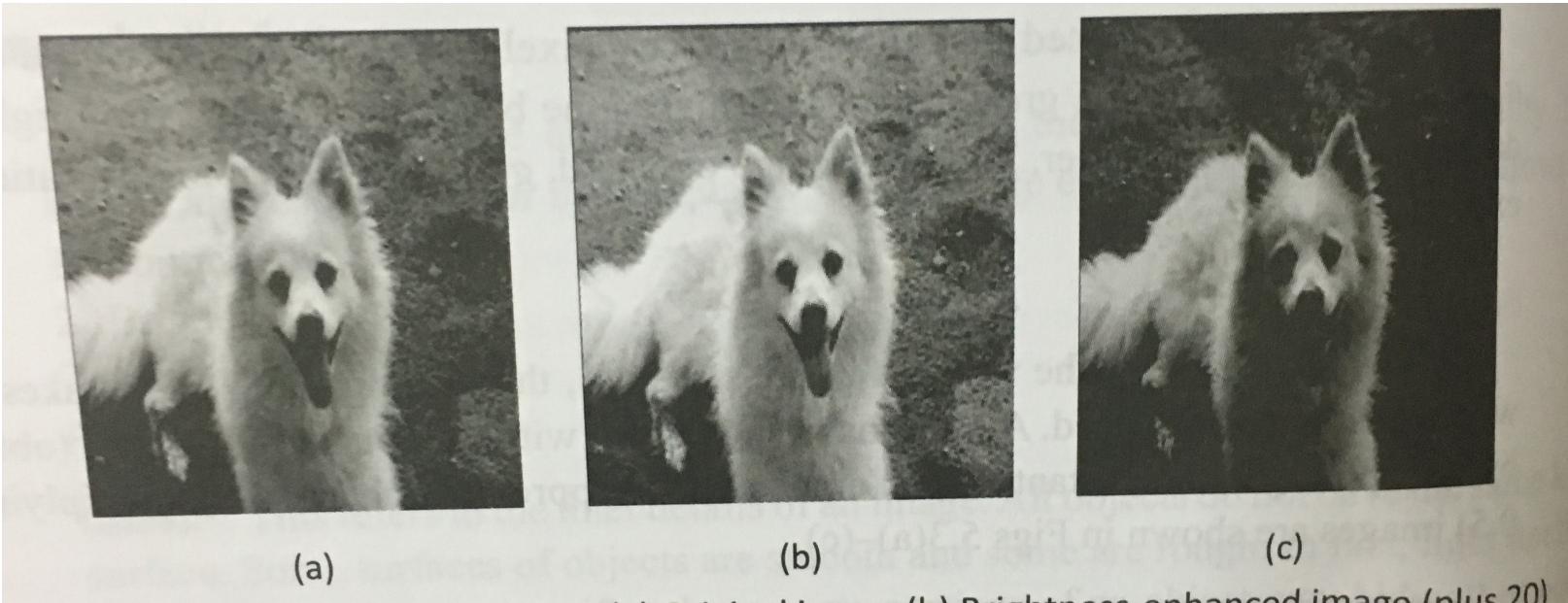
(a) Original image



(b) Brightness-suppressed image

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Brightness Modification



(a) Original image ; (b) Brightness enhanced; (c) Brightness suppressed

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Dynamic Range

- The **Dynamic Range** of an image is the exact subset of gray values $\{0,1,\dots,L-1\}$ that are present in the image.
- **Dynamic Range** refers to how wide a range of values a camera sensor can capture.
- Dynamic range has little to do with contrast (which is primarily a tone curve issue): it is simply a **measure of the highest and lowest possible light amounts a camera can capture** (technically expressed, it is a ratio of these two values)

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Point Processing

- Brightness modification
- **Contrast Modification**
- Histogram modeling
- Digital Negative
- Dynamic range compression
- Thresholding (noise clipping)
- Gray level slicing
- Bit plane slicing

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Contrast

- Contrast: how much differentiation exists between various tones in an image
- Contrast is determined by the difference in the color and brightness of the object and other objects within the same field of view.

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What is Contrast Stretching?

- Assume an input image with dynamic range from A to B with gray levels r
- Let A and B be 120 and 220 not using full permissible range
- **Mapping it to range C – D or 0 – 255 is called contrast stretching**
- Linear piecewise function is used for this purpose

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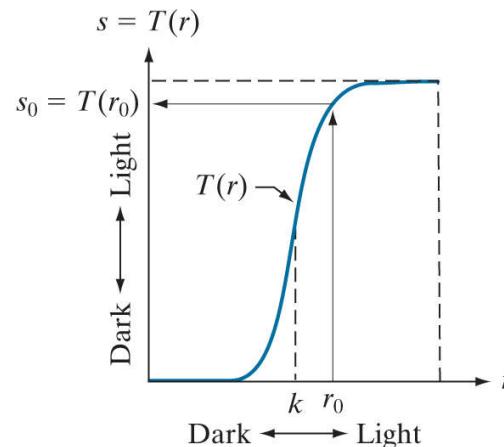
What is Contrast Stretching?

- Low-contrast images can result from poor illumination, lack of dynamic range in the imaging sensor, or even the wrong setting of a lens aperture during image acquisition
- Contrast stretching expands the range of intensity levels in an image so that it spans the ideal full intensity range of the recording medium or display device.

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Contrast Stretching

- Consider the figure below:

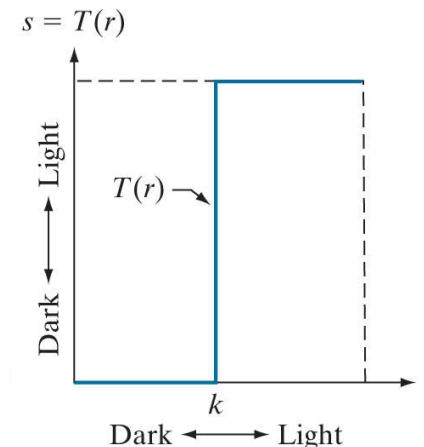


If $T(r)$ has the form as in figure, the result of applying the transformation to every pixel in f to generate the corresponding pixels in g would be to produce an image of higher contrast than the original, by darkening the intensity levels below k and brightening the levels above k

values of r lower than k reduce (darken) the values of s , toward black.

The opposite is true for values of r higher than k . Observe how an intensity value is mapped to obtain the corresponding value

Consider the figure below:



$T(r)$ produces a two-level (binary) image. A mapping of this form is called a thresholding function.

$$g(x, y) = T[f(x, y)]$$

$$s = T(r)$$

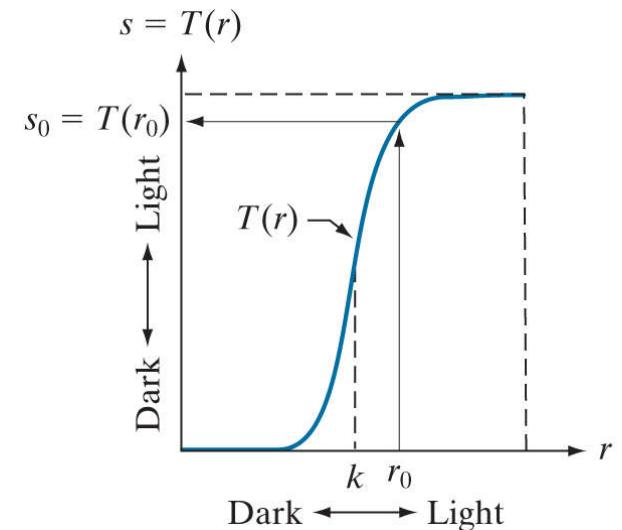
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Contrast Stretching

- It is a linear mapping function used to manipulate the contrast of an image
- Contrast stretching is done by scaling all pixels by a constant k;

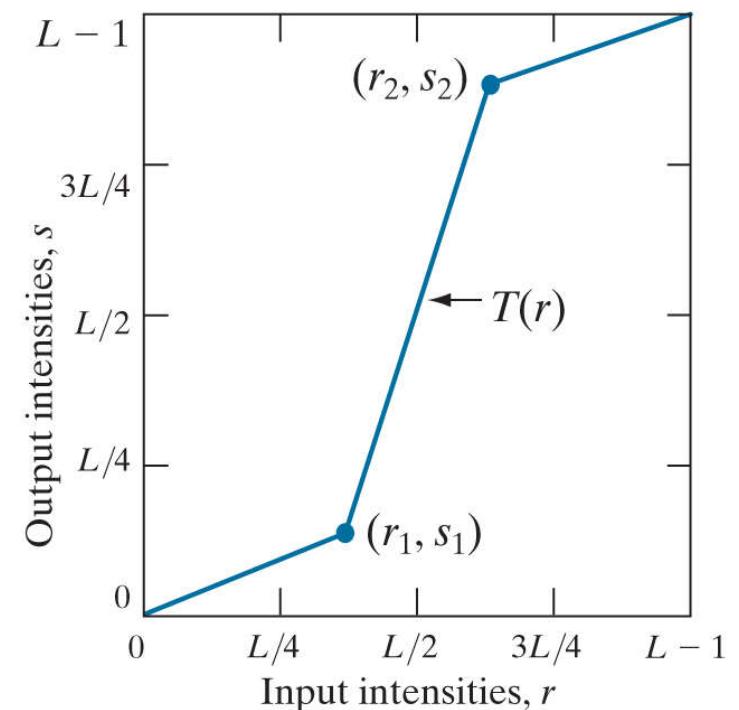
$$g(x,y) = k * f(x,y)$$

- By controlling the slope contrast can be controlled



Contrast Stretching Function

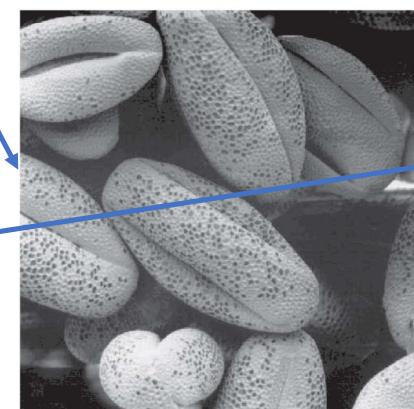
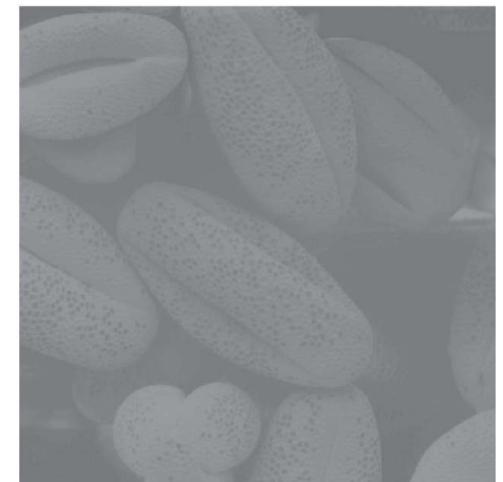
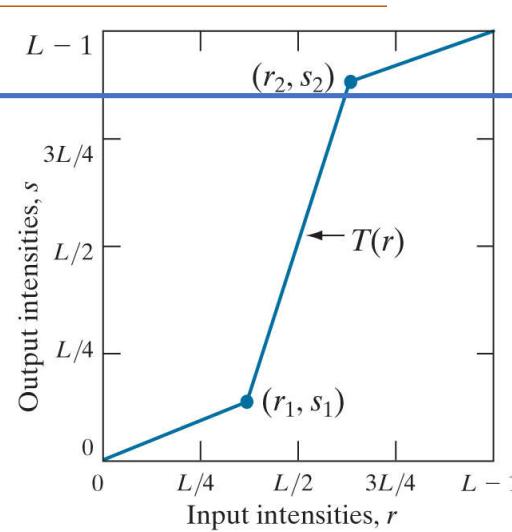
- Figure shows a typical transformation used for contrast stretching.
- The locations of points (r_1, s_1) and (r_2, s_2) control the shape of the transformation function.
- If $r_1=s_1$ and $r_2=s_2$, the transformation is a linear function that produces no changes in intensity.
- If $r_1=r_2$ and $s_1=0$ and $s_2=L-1$, the transformation becomes a thresholding function that creates a binary image
- Intermediate values of (r_1, s_1) and (r_2, s_2) produce various degrees of spread in the intensity levels of the output image, thus affecting its contrast
- In general, $r_1 \leq r_2$ and $s_1 \leq s_2$ is assumed so that the function is valued and monotonically increasing



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Contrast Stretching Function

- Figure b shows an 8-bit image with low contrast.
- Figure c shows the result of contrast stretching, obtained by setting $(r_1, s_1) = (r_{\min}, s_0)$ and $(r_2, s_2) = (r_{\max}, L-1)$ where r_{\min} and r_{\max} denote the minimum and maximum intensity levels in the input image, respectively.
 - The transformation stretched the intensity levels linearly to the full intensity range, $[0, L-1]$.
- Figure d shows the result of using the thresholding function, with $(r_1, s_1) = (m, 0)$ and $(r_2, s_2) = (m, L-1)$ where m is the mean intensity level in the image.



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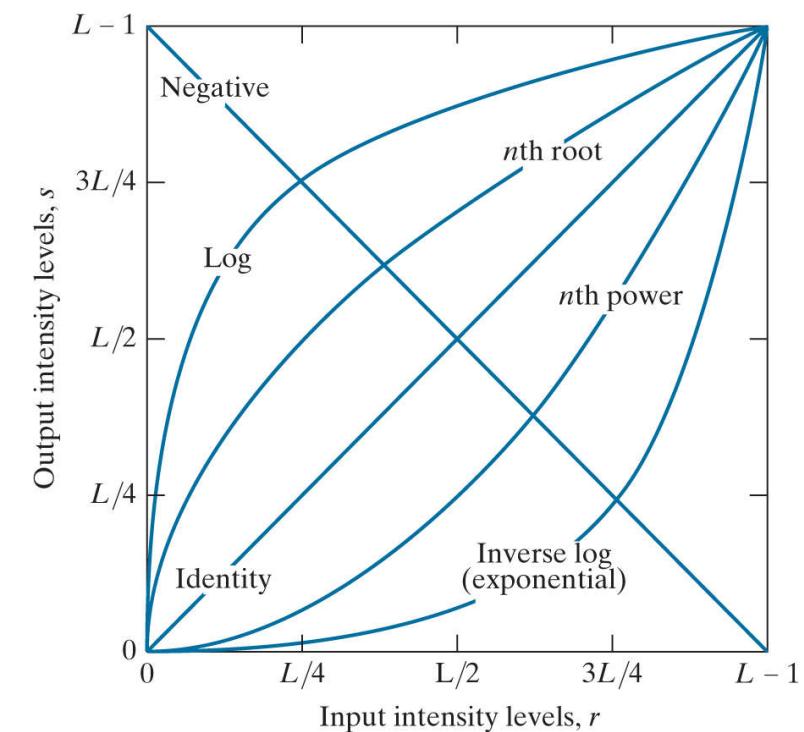
Point Processing

- Brightness modification
- Contrast Modification
- Digital Negative
- Dynamic range compression
- Thresholding (noise clipping)
- Intensity level slicing
- Bit plane slicing
- Histogram modeling

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Intensity Transformations

- Frequently used intensity transformations are:
 - Linear (negative and identity transformations)
 - Logarithmic (log and inverse-log transformations) and
 - Power-law (n th power and n th root transformations)
- The identity function is the trivial case in which the input and output intensities are identical.



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Linear Gray Level Modeling

- A linear transformation of an image is a function that maps each pixel gray level value into another gray level at the same position according to a linear function

$$g(x,y) = T[f(x,y)]$$

- Useful in large applications e.g. X-ray images.
- Inverse transformation reverses light and dark

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Digital Negative

- Digital Negative can be obtained by subtracting each pixel from maximum : $s = L - 1 - r$

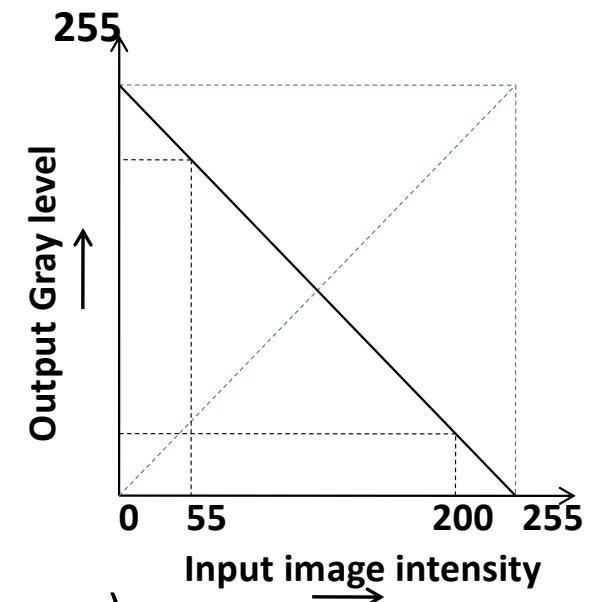
$$g(x,y) = 255 - f(x,y) \quad (\text{where, } f_{\max} = 255)$$

when, $f(x,y) = 0$; $g(x,y) = 255$
 & if $g(x,y) = 255$; $f(x,y) = 0$

Generally,

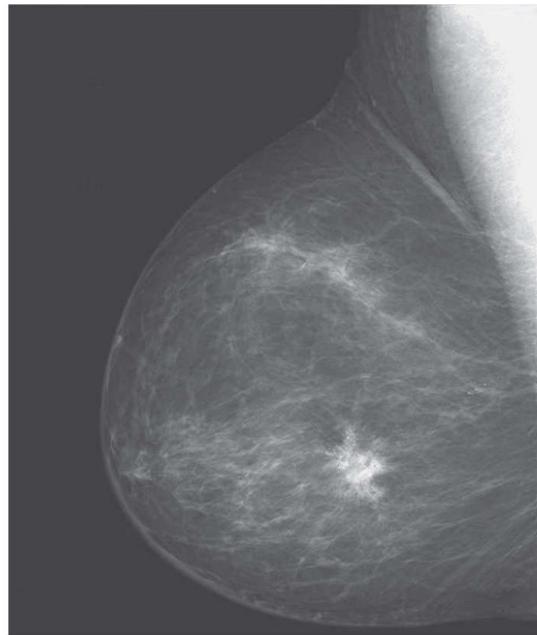
$$g(x,y) = (L-1) - f(x,y)$$

where, L – total number of gray levels (e.g. 256 for 8-bit image)



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Digital Negative



(a) Original image
(digital mammogram)



(b) Negative image

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Point Processing

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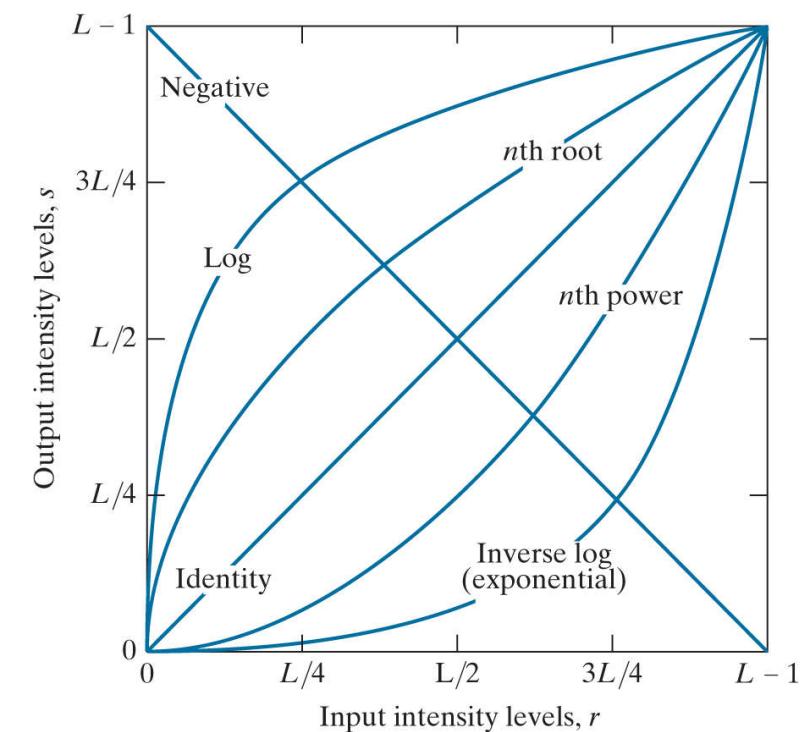
Dynamic Range Compression: Log Transformation

- Log transformations: General form is

$$s = c \log(1 + r)$$

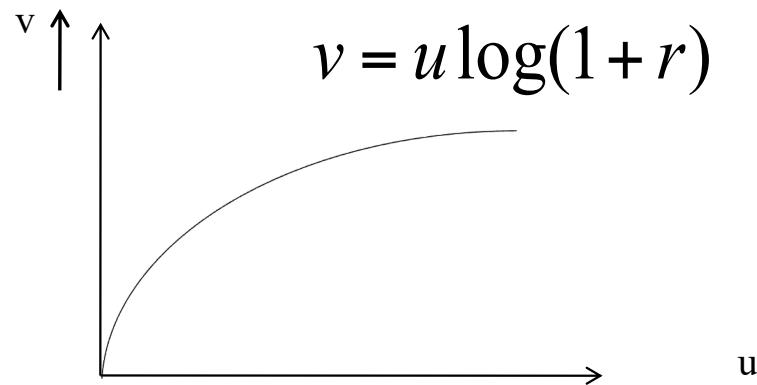
where c is a constant and it is assumed that ≥ 0 .

- Figure shows that this transformation maps a narrow range of low intensity values in the input into a wider range of output levels

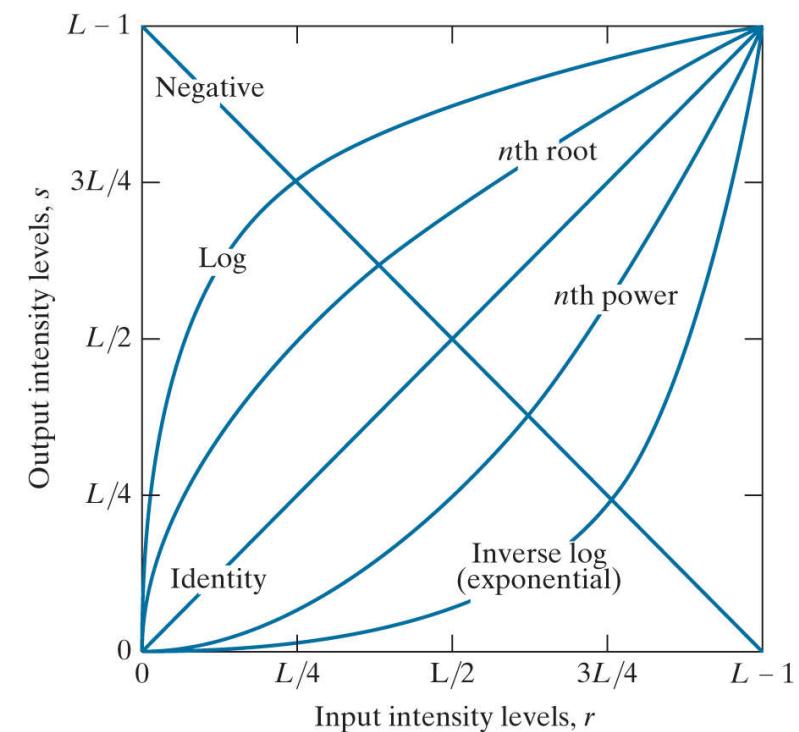


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Dynamic Range Compression

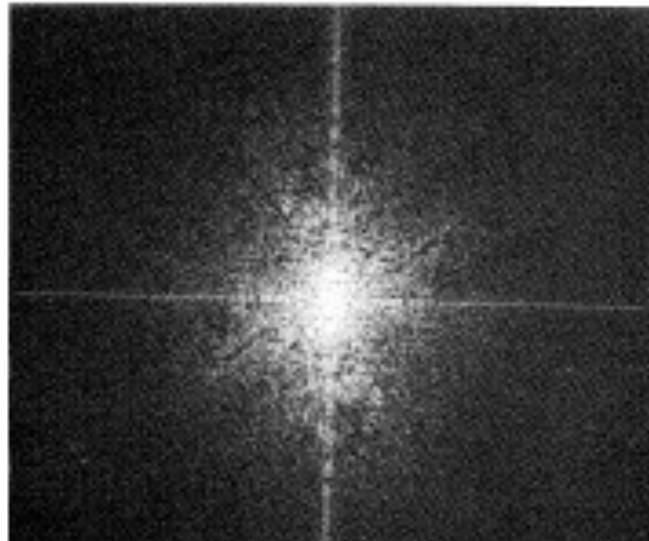


- At times, dynamic range of image exceeds the capability of display device.
- Some pixel values are so large that the other low value pixel gets obscured.
E.g. stars in day time are not visible though present due to large intensity of sun.
- Thus dynamic range needs to be compressed.

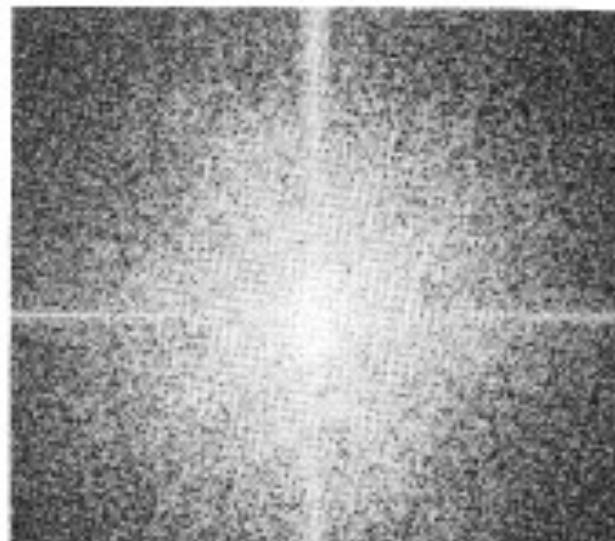


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Dynamic Range Compression



(a) Original



(b) log

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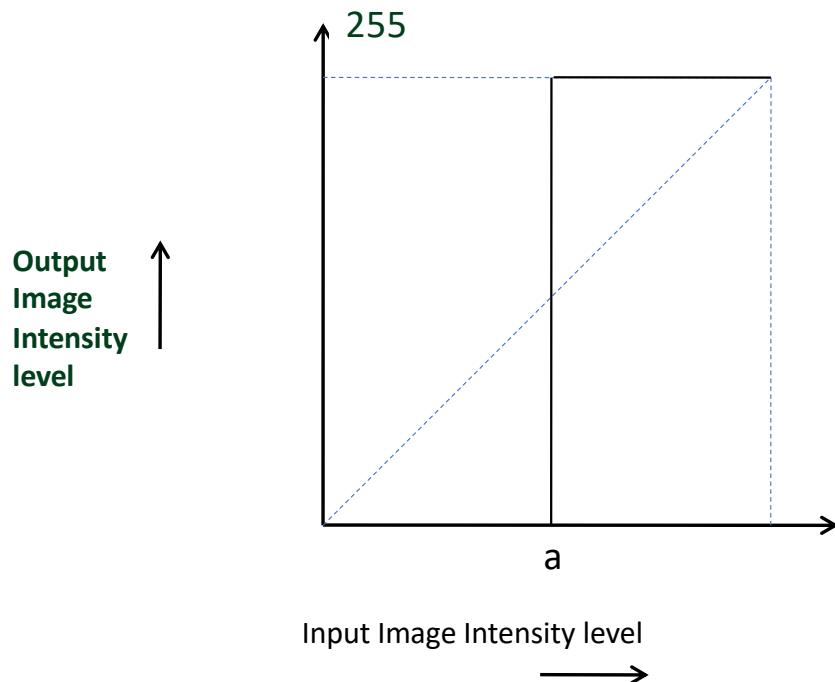
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Non Linear Gray Level Transformation

- Hard thresholding:



- Expression goes as under:

$$v = 0 \quad ; \text{ if } u \leq a$$

$$v = L - 1 ; \text{ if } u > a$$

where, L is number of Gray levels.

- Thresholded image has maximum contrast as it has only BLACK & WHITE gray values.

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Examples

The following matrix represents the pixel values of a 8-bit image (r) , apply thresholding transform assuming that the threshold $m=95$. Find the resulting image pixel values.

Image (r)

110	120	90	130
91	94	98	200
90	91	99	100
82	96	85	90

Answer::

Image (s)

255	255	0	255
0	0	255	255
0	0	255	255
0	255	0	0

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Gray Level / Intensity Level Slicing

- At times, we need to highlight a specific range of gray levels.
eg. X-ray scan, CT scan
- It is similar to thresholding, except that we select a band of gray levels.
- Formulation of Gray level slicing w/o background (Fig.1):

$$\begin{aligned} v &= L-1 && ; \text{ for } a \leq r \leq b \\ &= 0 && ; \text{ otherwise} \end{aligned}$$

- We do not get any background
- Sometimes we may need to retain the background.
- Formulation of Gray level slicing with background (fig. 2):

$$\begin{aligned} v &= L-1 && ; \text{ for } a \leq r \leq b \\ &= u && ; \text{ otherwise} \end{aligned}$$

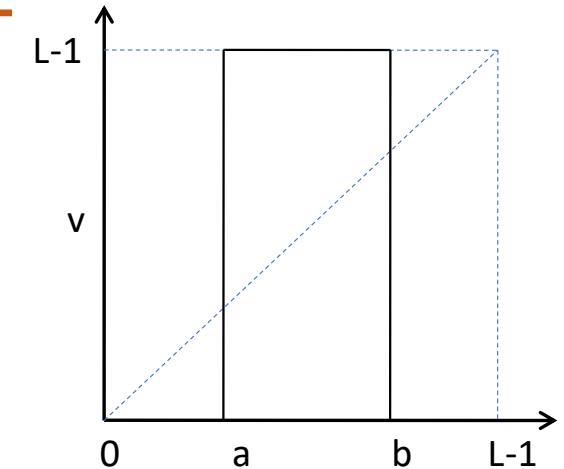


Fig. 1 Slicing w/o background

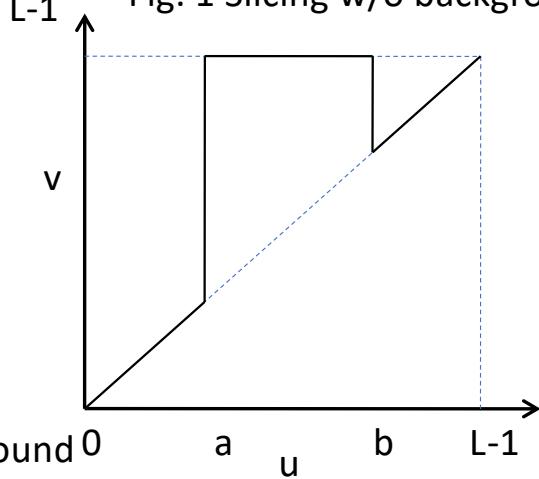


Fig. 2 Slicing with background

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Bit Plane Slicing

- Here, we find the contribution made by each bit to the final image
- Consider a 256×256 image with 256 gray levels i.e. 8-bit representation for each pixel. E.g. BLACK is represented as 00000000 & WHITE by 11111111.
- Consider LSB value of each pixel & plot image. Continue till MSB is reached.
- All 8 images will be binary.

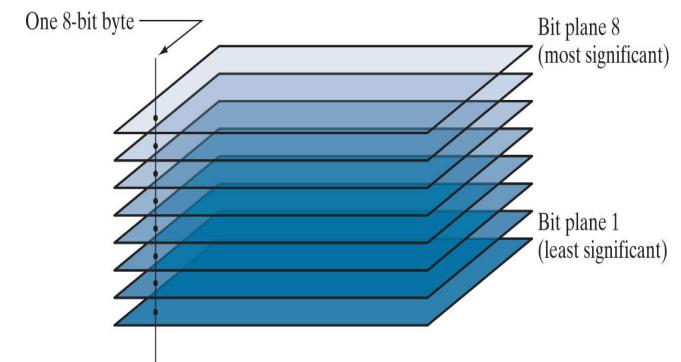


FIGURE 3.13
Bit-planes of an 8-bit image.

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Bit Plane Slicing

Ex. Plot bit planes of the given 3×3 image.

Max. Intensity is 7 thus use only 3 – bits

1	2	0
4	3	2
7	5	2

001	010	000
100	011	010
111	101	010

1	0	0
0	1	0
1	1	0

LSB plane

0	1	0
0	1	1
1	0	1

Middle Plane

0	0	0
1	0	0
1	1	0

MSB Plane

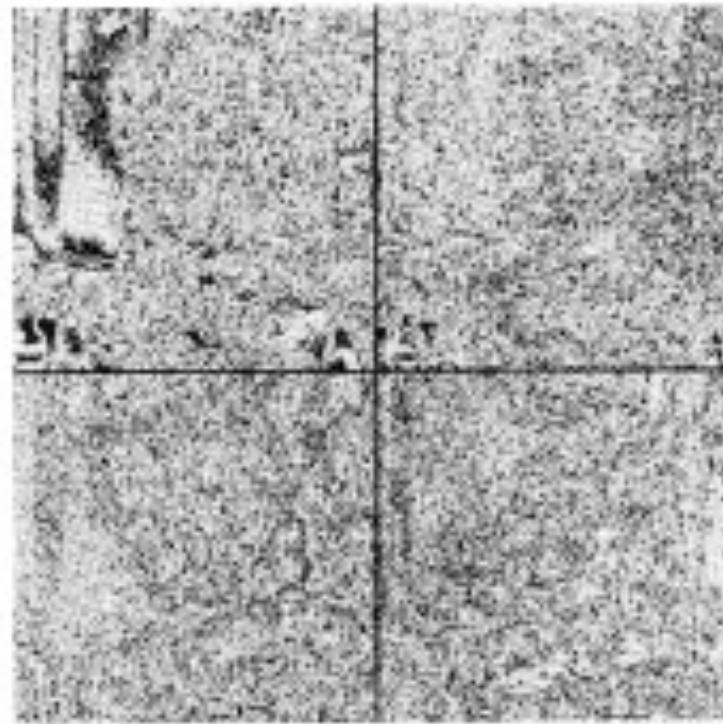
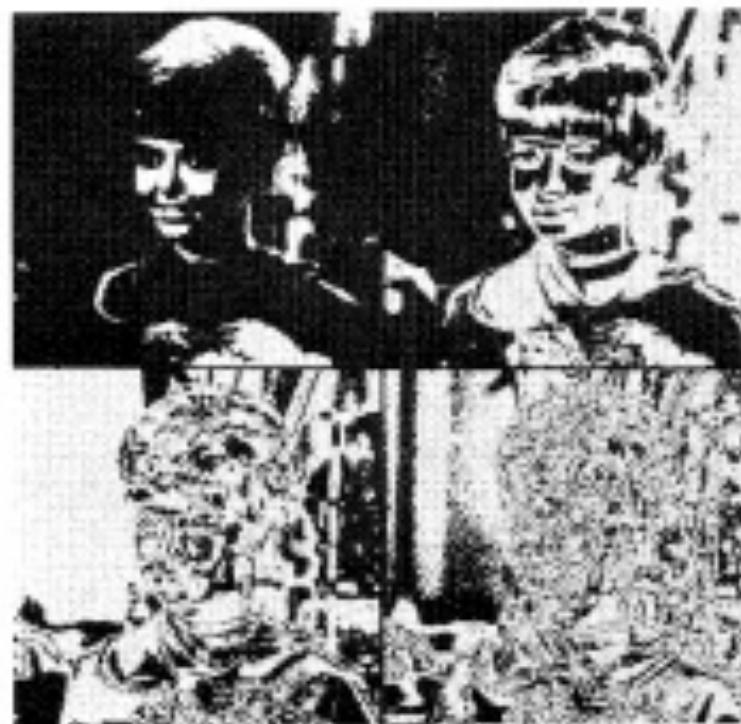
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Bit Plane Slicing

- Observing the images we conclude that
 - Higher order bits contain visually significant data.
 - Lower order bits contain suitable details of image.
- Hence, BPS can be used in Image Compression.
- We can transmit only higher order bits & remove lower order bits.
- E.g. Steganography

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Bit Plane Slicing



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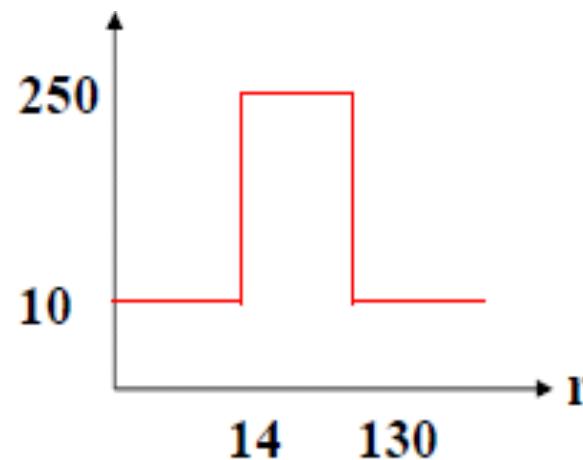
Bit Plane Slicing

Q. A 4x4 image is given as below.

- 1) The image is transformed using the point transform shown.
Find the pixel values of the output image.
- 2) What is the 7-th bit plane of this image

17	64	128	128
15	63	132	133
11	60	142	140
11	60	142	138

.



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Bit Plane Slicing

Pixel values of output Image (s)

250	250	250	250
250	250	10	10
10	250	10	10
10	250	10	10

250: 11111010

10: 00001010

7th Bit plane of Image

1	1	1	1
1	1	0	0
0	1	0	0
0	1	0	0

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Next Session

➤ Point Operations

- Histogram Processing and Equalization



THANK YOU

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