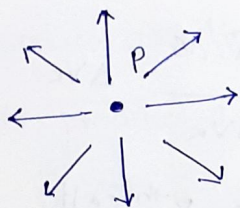


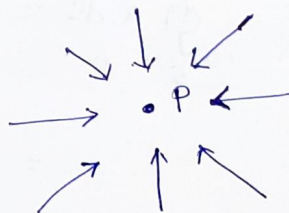
Divergence of a Vector and Divergence Theorem

The divergence of \vec{A} at a given point 'P' is the outward flux per unit volume as the volume shrinks about P

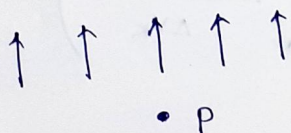
$$\text{div } \vec{A} = \nabla \cdot \vec{A} = \lim_{\Delta V \rightarrow 0} \frac{\oint \vec{A} \cdot d\vec{s}}{\Delta V}$$



Positive divergence



Negative divergence



Zero divergence

ΔV = volume enclosed by the closed surface "S" in which point "P" is located.

Divergence theorem

$$\oint_S \vec{A} \cdot d\vec{s} = \int_V \nabla \cdot \vec{A} \, dV$$

The divergence theorem states that the total outward flux of a vector field \vec{A} through the closed surface S is same as the volume integral of the divergence of \vec{A} .

$$\begin{aligned} \oint_S \vec{A} \cdot d\vec{s} &= \sum_K \oint_{S_K} \vec{A} \cdot d\vec{s} \\ &= \sum_K \frac{\oint_{S_K} \vec{A} \cdot d\vec{s}}{\Delta V_K} \Delta V_K \end{aligned}$$

ΔV_K = volume of the K^{th} cell

S_K = K^{th} cell closed surface area

$$\begin{aligned} &= \sum_K \left(\lim_{\Delta V_K \rightarrow 0} \frac{\oint_{S_K} \vec{A} \cdot d\vec{s}}{\Delta V_K} \right) \Delta V_K \\ &= \int_V \nabla \cdot \vec{A} \, dV \end{aligned}$$

divergence of a vector in different coordinate systems

$$\nabla \cdot \vec{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}$$

[In Cartesian coordinate system]

$$\nabla \cdot \vec{A} = \frac{1}{s} \frac{\partial}{\partial s} (s A_s) + \frac{1}{s} \frac{\partial A_\phi}{\partial \phi} + \frac{\partial A_z}{\partial z} \quad [\text{In cylindrical coordinate system}]$$

$$\nabla \cdot \vec{A} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 A_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (A_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial (A_\phi)}{\partial \phi} \quad [\text{In Spherical coordinate system}]$$

Properties of the divergence of a vector field

1) It produces a scalar field

$$2) \nabla \cdot (\vec{A} + \vec{B}) = \nabla \cdot \vec{A} + \nabla \cdot \vec{B}$$

$$3) \nabla \cdot (V \vec{A}) = V \nabla \cdot \vec{A} + \vec{A} \cdot \nabla V \quad \text{where } \vec{A} \text{ is a vector} \\ V \text{ is a scalar}$$

1) Determine the divergence of the following vector fields

$$(a) \vec{P} = x^2 y z \hat{a}_x + x z \hat{a}_z$$

$$(b) \vec{Q} = s \sin \phi \hat{a}_s + s^2 z \hat{a}_\phi + z \cos \phi \hat{a}_z$$

$$(c) \vec{T} = \frac{1}{r^2} \cos \theta \hat{a}_r + r \sin \theta \cos \phi \hat{a}_\theta + \cos \theta \hat{a}_\phi$$

Solution :

$$(a) \vec{P} = x^2 y z \hat{a}_x + x z \hat{a}_z$$

$$\nabla \cdot \vec{P} = \frac{\partial}{\partial x} P_x + \frac{\partial}{\partial y} P_y + \frac{\partial}{\partial z} P_z$$

$$\nabla \cdot \vec{P} = \frac{\partial}{\partial x} (x^2 y z) + \frac{\partial}{\partial y} (0) + \frac{\partial}{\partial z} (x z)$$

$$\nabla \cdot \vec{P} = 2 x y z + x$$

$$(b) \vec{Q} = s \sin \phi \hat{a}_s + s^2 z \hat{a}_\phi + z \cos \phi \hat{a}_z$$

$$\nabla \cdot \vec{Q} = \frac{1}{s} \frac{\partial}{\partial s} (s Q_s) + \frac{1}{s} \frac{\partial}{\partial \phi} (Q_\phi) + \frac{\partial}{\partial z} (Q_z)$$

$$\nabla \cdot \vec{Q} = \frac{1}{s} \frac{\partial}{\partial s} (s \cdot s \sin \phi) + \frac{1}{s} \frac{\partial}{\partial \phi} (s^2 z) + \frac{\partial}{\partial z} (z \cos \phi)$$

$$\nabla \cdot \vec{Q} = \frac{1}{s} \times 2 s \sin \phi + \frac{1}{s} (0) + \cos \phi$$

$$\nabla \cdot \vec{Q} = 2 \sin \phi + \cos \phi$$

$$(c) \vec{T} = \frac{1}{r^2} \cos \theta \hat{a}_r + r \sin \theta \cos \phi \hat{a}_\theta + \cos \theta \hat{a}_\phi$$

$$\nabla \cdot \vec{T} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 T_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (T_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} (T_\phi)$$

$$\nabla \cdot \vec{T} = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \times \frac{1}{r^2} \cos \theta \right) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (r \sin \theta \cos \phi \sin \theta) +$$

$$\frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} (\cos \theta)$$

$$\begin{aligned}
 &= 0 + \frac{1}{r \sin \theta} \frac{d}{d\theta} (r \sin^2 \theta \cos \phi) + 0 \\
 &= 0 + \frac{1}{r \sin \theta} \frac{d}{d\theta} (r \sin^2 \theta \cos \phi) + 0 \\
 &= 0 + \frac{1}{\cancel{r \sin \theta}} \times \cancel{2r \sin \theta} \cos \theta \cos \phi \\
 &= 2 \cos \theta \cos \phi
 \end{aligned}$$

2) Determine the divergence of the following vector fields and evaluate them at specified points

- (a) $\vec{A} = yz \hat{a}_x + 4xy \hat{a}_y + y \hat{a}_z$ at $(1, -2, 3)$
 (b) $\vec{B} = 8z \sin \phi \hat{a}_s + 3s z^2 \cos \phi \hat{a}_\phi$ at $(5, \pi/2, 1)$
 (c) $\vec{C} = 2r \cos \theta \cos \phi \hat{a}_r + r^{1/2} \hat{a}_\phi$ at $(1, \pi/6, \pi/3)$

Solution: (a) $\vec{A} = yz \hat{a}_x + 4xy \hat{a}_y + y \hat{a}_z$

$$\begin{aligned}
 \nabla \cdot \vec{A} &= \frac{\partial}{\partial x} A_x + \frac{\partial}{\partial y} A_y + \frac{\partial}{\partial z} A_z \\
 &= \frac{\partial}{\partial x} (yz) + \frac{\partial}{\partial y} (4xy) + \frac{\partial}{\partial z} (y) \\
 &= 0 + 4x + 0 = 4x \Big|_{(1, -2, 3)} = 4
 \end{aligned}$$

(b) $\vec{B} = 8z \sin \phi \hat{a}_s + 3s z^2 \cos \phi \hat{a}_\phi$

$$\nabla \cdot \vec{B} = \frac{1}{s} \frac{\partial}{\partial s} (s B_s) + \frac{1}{s} \frac{\partial}{\partial \phi} (B_\phi) + \frac{\partial}{\partial z} (B_z)$$

$$\nabla \cdot \vec{B} = \frac{1}{s} \frac{\partial}{\partial s} (s \cdot 8z \sin \phi) + \frac{1}{s} \frac{\partial}{\partial \phi} (3s z^2 \cos \phi) + \frac{\partial}{\partial z} (0)$$

$$\nabla \cdot \vec{B} = \frac{1}{s} 2s z \sin \phi + \frac{1}{s} 3s z^2 (-\sin \phi)$$

$$\begin{aligned}
 \nabla \cdot \vec{B} &= 2z \sin \phi - 3z^2 \sin \phi \Big|_{(5, \pi/2, 1)} = 2 \times 1 \times \sin \frac{\pi}{2} - 3 \times 1^2 \times \sin \frac{\pi}{2} \\
 &= 2 - 3 = -1
 \end{aligned}$$

$$\vec{C} = 2r \cos \theta \cos \phi \hat{r} + r^{1/2} \hat{\phi}$$

(41)

$$\nabla \cdot \vec{C} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 C_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (C_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} (C_\phi)$$

$$\nabla \cdot \vec{C} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \times 2r \cos \theta \cos \phi) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (0 \times \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} (r^{1/2})$$

$$\nabla \cdot \vec{C} = \frac{1}{r^2} \frac{\partial}{\partial r} (2r^3 \cos \theta \cos \phi) + 0 + 0$$

$$\nabla \cdot \vec{C} = \frac{1}{r^2} \times 6r^2 \cos \theta \cos \phi$$

$$\nabla \cdot \vec{C} = 6 \cos \theta \cos \phi$$

$$\nabla \cdot \vec{C} \Big| = 6 \times \cos \frac{\pi}{6} \cos \frac{\pi}{3} = 6 \times \frac{\sqrt{3}}{2} \times \frac{1}{2} = \frac{6\sqrt{3}}{4} = 1.5\sqrt{3}$$

$$(1, \pi/6, \pi/3) = 2.5980$$