# An Unknown Signal

Symbols, Patterns and Signals

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### 1 Least Squares Regression

The least squares calculations have been implemented in the Segment methods lsr\_polynomial() and lsr\_fn(). They both use the matrix formula: [1]

$$\boldsymbol{A} = (\boldsymbol{X}^T \boldsymbol{X})^{-1} \boldsymbol{X}^T \boldsymbol{Y}$$

Where in the case of the polynomial regression:

$$\boldsymbol{X} = \begin{bmatrix} 1 & x_0 & (x_0)^2 & \dots & (x_0)^k \\ 1 & x_1 & (x_1)^2 & \dots & (x_1)^k \\ \dots & \dots & \dots & \dots \\ 1 & x_k & (x_k)^2 & \dots & (x_k)^k \end{bmatrix}$$

Or in the case of the arbitrary function (f) regression:

$$\boldsymbol{X} = \begin{bmatrix} 1 & f(x_0) \\ 1 & f(x_1) \\ \vdots & \vdots \\ 1 & f(x_k) \end{bmatrix}$$

Y is a vector containing the y values  $y_0$  through to  $y_k$ 

And the result **A** is the list of coefficients, in the order  $a_0 + a_1x + ... + a_kx^k$  or  $a_0 + a_1f(x)$ .

#### Calculating the Error

The Sum Squared Error (SSE) is a method of measuring how well a fitted function (f) fits a dataset of n points, by calculating the difference between the predicted and actual data. [2]

$$SSE = \sum_{i=0}^{n} (y_i - f(x_i))^2$$

This has been implemented in the  $ss\_error()$  function, which is called with an array of predicted y values, and array of actual y values.

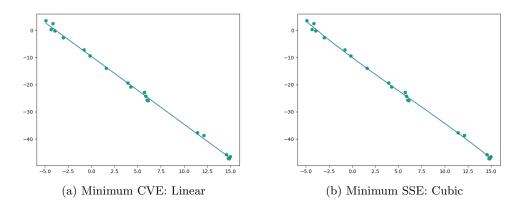


Figure 1: noise\_1.csv computed with different minimums

### 2 Overfitting

Whilst choosing the function with the lowest SSE will find the best fit for the given dataset, it does not prevent overfitting, a type of error where the model fits too closely to the noise in the data, and is therefore unable to accurately predict additional observations. In our case this can be caused by selecting a function class too complex, such as a higher order polynomial than the real function. Cross validation is a technique that can be used to detect this, first we split the data into training and validation sets, then fit a function to the training data, and finally measure the SSE of the validation data when using the fitted function, giving us the cross validation error [3].

K-Fold cross validation is a method of applying cross validation repeatedly across different combinations of training and validation data. To do so we split our data into K equally sized chunks, for 1..K each chunk is used as a validation set, and the other chunks form the training set [4]. This has been implemented by the Segment split() method which returns a list of unique training/validation pairs of length K. This in turn is called by the cross\_validated() method which computes the mean validation error (CVE) for each of the pairs.

#### 3 Method

The compute() function is used to find the best fitting function for a segment out of three choices: a linear function, a polynomial of given degree, or a specified custom function. To prevent overfitting it selects the function with the minimum k-fold cross validation. The importance of this is demonstrated by figure 1, which shows that if we just use the minimum SSE, a higher order polynomial will be incorrectly favoured instead of a linear function; due to the noise in the data.

### 4 Testing

## 5 Training Data

The training data can be evaluated by passing the --evaluate switch to the script.

#### References

[1] E. W. Weisstein, Least squares fitting-polynomial. [Online]. Available: http://mathworld.wolfram.com/LeastSquaresFittingPolynomial.html.

- [2] —, Least squares fitting. [Online]. Available: https://mathworld.wolfram.com/LeastSquaresFitting. html.
- [3] L. Aitchison, Lecture 2: Overfitting, regularisation and cross-validation. [Online]. Available: https://github.com/LaurenceA/intro\_lectures/blob/master/Lecture\_2.ipynb.
- [4] H. Tibshirani, *K-foldcross-validation*, Feb. 2009. [Online]. Available: http://statweb.stanford.edu/~tibs/sta306bfiles/cvwrong.pdf.