

A SMOOTH CATEGORY PROOF OF THE HOSOKAWA-KAWAUCHI SOLID TORUS UNKNOTTING CRITERION FOR 2-KNOTS

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ABSTRACT. Hosokawa and Kawauchi showed that in the piecewise linear case, a closed connected surface of genus n in \mathbb{R}^4 is unknotted if and only if it bounds a (piecewise linear) solid torus of genus n . Restricting to the case of 2-knots (genus 0), we provide an explicit and self-contained proof of this unknotting criterion in the smooth case, i.e. we show that some smooth 2-knot in \mathbb{R}^4 is ambient isotopic to a surface in $\mathbb{R}^3 \times \{0\}$ (unknotted) if and only if it bounds some smooth 3-ball in \mathbb{R}^4 . Although this result is well-known as a formal consequence of previous work, including by Moise and Munkres, we choose to provide a direct argument using standard machinery such as collaring and isotopy extension for expository purposes.

1. INTRODUCTION

In classical knot theory, Rolfsen [Rol03] (chapter 2.B, exercise 10) gives that some knot $K_1 \subset \mathbb{R}^3$ is ambient isotopic to the *unknot* if it lies in a plane. In informal terms, an unknot is subset of \mathbb{R}^3 that can be 'untangled'. If K_1 were a piece of string, then, intuitively, the string is unknotted if it doesn't have any knots in it. [Rol03] gives an alternate yet equivalent definition for K_1 to be the unknot: that K_1 is equivalent to the unknot if and only if it is bounded by an embedded 2-disk in \mathbb{R}^3 .

Now consider a 2-knot $K_2 \subset \mathbb{R}^4$. The higher dimensional analogue for the plane-definition of classical unknotting is for K_2 to be ambient isotopic to $\mathbb{R}^3 \times \{0\}$, i.e. it can be deformed ambiently to the 3-dimensional plane (Klingmann [Kli73]). The connection to the classical definition is easy to see. We call such a 2-knot *unknotted*. In practice, this definition extends to any closed connected surface in \mathbb{R}^4 , i.e. it is possible for any such surface to be considered unknotted. A surface that is not unknotted is called a *knotted surface*.

In 1979, Hosokawa and Kawauchi [HK79] proved that for some general piecewise linear closed connected surface $F_n \subset \mathbb{R}^4$ of genus n (for which a piecewise linear K_2 is an example of), F_n is unknotted if and only if it bounds a piecewise linear solid torus T_n (of genus n). This harkens back to the two equivalent unknot definitions in the classical case.

In this note, we provide an explicit and self-contained proof of the equivalence of the two previously mentioned unknotting criteria, isolated to the case of smooth 2-knots. This particular case is not covered by Hosokawa and Kawauchi's [HK79] piecewise linear proof, but is often cited as a formal consequence in geometric topology due to the uniqueness of piecewise linear and smooth structures on 3-manifolds (Moise [Moi77] and Munkres [Mun60] respectively), and the absence of pseudo-isotopy obstructions in 3-dimensions¹ (Cerf [Cer68]). Here, we shall avoid the complex machinery of Cerf [Cer68] and rely on standard isotopy extension arguments as presented by Hirsch in his 1997 book [Hir97] for our proofs.

¹Cerf's key result in his 1968 paper [Cer68] is that in 3-dimensions, pseudo-isotopy (a weaker definition than standard isotopy) and isotopy coincide. This results underpins the modern isotopy extension theorems, such as in Hirsch [Hir97].

2. BACKGROUND AND PRELIMINARIES

We define smooth 2-knots as follows, with definitions taken from Kamada [Kam17].

Definition 2.1. A *smooth surface knot* is a smooth submanifold of \mathbb{R}^4 that is diffeomorphic to a closed connected surface. Similarly, a *piecewise linear surface knot* is a piecewise linear submanifold of \mathbb{R}^4 that is homeomorphic to a closed connected surface.

Definition 2.2. A *2-knot* is a surface knot that is diffeomorphic to the 2-sphere, S^2 .

It follows that a *smooth 2-knot* is a smooth surface knot that is diffeomorphic to the 2-sphere, S^2 . Equivalently, a *smooth 2-knot* is a smoothly embedded 2-sphere in \mathbb{R}^4 .²

2.1. Smooth 3-Balls. We also must define our smooth 3-balls, for which we extend the definition for 3-balls in a manifold given by Munkres' book [Mun00] to the smooth case.

Definition 2.3. A 3-manifold B^3 is called a *3-ball* if it is homeomorphic as manifolds to the closed unit ball of dimension 3.

Definition 2.4. A 3-manifold B^3 is called a *smooth 3-ball* if it is diffeomorphic as manifolds to the closed unit ball of dimension 3.

An immediate consequence of this definition is that the boundary of B^3 , denoted ∂B^3 , is such that $\partial B^3 = S^2$ i.e. the 2-sphere, which makes ∂B^3 trivially a 2-knot when embedded in \mathbb{R}^4 .

2.2. Unique Structures on 3-Balls. We turn to Moise [Moi77], who proved that any 3-manifold (such as a 3-ball) admits a unique piecewise linear structure. Munkres' [Mun60] prior work takes this further, proving that every piecewise linear 3-manifold admits a unique smooth structure.³ We put this together to attain the following theorem:

Theorem 2.5. *Any 3-ball admits a unique smooth structure up to diffeomorphism.*

2.3. Collaring Theorem. Morris W. Hirsch's book *Differential Topology* [Hir97] will provide many of our preliminary definitions and some of the theorems that we shall use later in our proofs. Others will be taken from Lee [Lee12]. The first of these relate to collars of boundaries of manifolds and tubular neighbourhoods of submanifolds.

Definition 2.6. A *collar* on some manifold M is an embedding

$$f : \partial M \times [0, \delta) \rightarrow M$$

such that $f(x, 0) = x$.

The collaring theorem, proven by Hirsch, states that every manifold boundary has a collar.

Theorem 2.7. *Let M be some manifold. Then ∂M has a collar.*

²We see that these statements are equivalent by picking some diffeomorphism from the 2-sphere to the smooth 2-knot and composing it with the inclusion map, which gives a smooth embedding. Conversely, the image of some smoothly embedded 2-sphere gives a closed embedded 2-dimensional submanifold of \mathbb{R}^4 , precisely our smooth surface knot.

³A result that, interestingly, does not hold in some higher dimensions.

2.4. Isotopy Extension. We have the isotopy extension theorem, an important result that we shall use to extend isotopies from our 3-balls to the entirety of \mathbb{R}^4 . This is contained in chapter 8 of [Hir97], as theorem 1.3.⁴ We note here the specific case for \mathbb{R}^4 , as is relevant to us.

Theorem 2.8. *Let $V \subset \mathbb{R}^4$ be a compact submanifold. Let $F : V \times [0, 1] \rightarrow \mathbb{R}^4$ be an isotopy of V . If $F(V \times [0, 1]) \subset \mathbb{R}^4$ is contained in some open set $U \subset \mathbb{R}^4$, then F extends to an ambient isotopy of \mathbb{R}^4 with compact support.⁵*

2.5. Hirsch's Smoothing Theorem. Also in his book *Differential Topology*, Hirsch [Hir97] proves the following corollary to the isotopy extension theorems regarding n -manifolds, which shall be relevant to us.

Theorem 2.9. *For $i = 0, 1$, let W_i be n -manifolds without boundary that are the union of two closed n -dimensional submanifolds M_i, N_i with the property that*

$$M_i \cap N_i = \partial M_i = \partial N_i,$$

which we denote as V_i .

Let $h : W_0 \rightarrow W_1$ be a homeomorphism that diffeomorphically maps M_0 and N_0 to M_1 and N_1 , respectively. Then there exists a diffeomorphism $f : W_0 \rightarrow W_1$ such that $f(M_0) = M_1$ and $f(N_0) = f(N_1)$ with $f|_{V_0} = h|_{V_0}$. Additionally, f can be chosen to coincide with h outside a given neighbourhood of V_i .

2.6. Fixing a Collar of the 3-Ball. We also present a lemma that will be used twice across our proofs. This lemma uses a result from Smale [Sma59] to show that any orientation preserving diffeomorphism on some boundary of a smooth 3-ball extends to a diffeomorphism of the whole ball that is the identity on some collar of the 3-ball.

Lemma 2.10. *Let $B_{C^\infty}^3$ be a smooth 3-ball. Let $c : \partial B_{C^\infty}^3 \times [0, 1] \rightarrow B_{C^\infty}^3$ be a smooth collar, which exists via the collaring theorem (2.7).*

Then for every orientation preserving diffeomorphism $\varphi : \partial B_{C^\infty}^3 \rightarrow \partial B_{C^\infty}^3$ there is a diffeomorphism $\Phi : B_{C^\infty}^3 \rightarrow B_{C^\infty}^3$ such that

$$\Phi|_{B_{C^\infty}^3} = \varphi \text{ and } \Phi|_{c(\partial B_{C^\infty}^3 \times [\epsilon, \delta])} = \text{id}$$

for some $0 < \epsilon < \delta$.

Proof. By [Sma59], we have that $\text{Diff}^+(S^2)$, the group of orientation preserving diffeomorphisms of S^2 , is path connected. Note that as $\partial B_{C^\infty}^3$ and S^2 are diffeomorphic by definition, we have that $\text{Diff}^+(S^2) \cong \text{Diff}^+(\partial B_{C^\infty}^3)$.

Let $\varphi \in \text{Diff}^+(\partial B_{C^\infty}^3)$ be arbitrary. Now, we can choose some smooth isotopy $\varphi_t : \partial B_{C^\infty}^3 \rightarrow \partial B_{C^\infty}^3$ such that $\varphi_0 = \text{id}$ and $\varphi_1 = \varphi$.

Let $0 < \epsilon < \delta$. We define a new isotopy on the collar $c : \partial B_{C^\infty}^3 \times [0, 1] \rightarrow B_{C^\infty}^3$ by

$$\varphi'_t(c(x, s)) = c(\varphi_{\rho(s)t}(x), s)$$

where $\rho(s) = 1$ for $0 \leq s \leq \epsilon/2$ and $\rho(s) = 0$ for $\epsilon \leq s$, varying smoothly between.

By the general isotopy extension theorem (see Hirsch [Hir97] chapter 8) we can extend this isotopy to some ambient isotopy $\Phi_t : B_{C^\infty}^3 \rightarrow B_{C^\infty}^3$ that is such that

$$\Phi_1|_{B_{C^\infty}^3} = \varphi \text{ and } \Phi_1|_{c(\partial B_{C^\infty}^3 \times [\epsilon, \delta])} = \text{id}.$$

Hence, Φ_1 satisfies our conditions. □

⁴Hirsch uses the word *diffeotopy* instead of *ambient isotopy*, but the meaning is the same.

⁵*Compact support* here simply guarantees that there are no changes near infinity.

3. THE HOSOKAWA-KAWAUCHI PIECEWISE LINEAR SOLID-TORUS UNKNOTTING CRITERION

Throughout this section until the next, we take all objects to be in the piecewise linear category.

In their 1979 paper *Unknotted Surfaces in Four-Spaces*, Hosokawa and Kawauchi [HK79] define *unknottedness* of some closed, connected surface as the existence of some solid torus of the same genus that bounds the surface.

Definition 3.1. Formally, for some closed, connected surface F_n of genus n in \mathbb{R}^4 , F_n is *unknotted* if there exists some solid torus⁶ of genus n , T_n , with the boundary of T_n , denoted ∂T_n , such that

$$\partial T_n = F_n.$$

Otherwise, F_n is said to be *knotted*.

In our case, we restrict ourselves to 2-knots as our surfaces. A 2-knot is a surface of genus 0, which follows from the fact it is diffeomorphic to S^2 , which has genus 0 by definition. Similarly, we have that a solid torus of genus 0, i.e. a 0 genus handlebody, is a 3-ball.

Let us give this theorem for 2-knots, as will be relevant to us.

Theorem 3.2. *Some 2-knot K in \mathbb{R}^4 is unknotted if and only if K bounds a piecewise linear 3-ball in \mathbb{R}^4 .*

Hosokawa and Kawauchi [HK79] then go on to show that their definition for unknottedness is equivalent to that given by Manfred Klingmann in *Kurven auf orientierbaren Flächen* [Kli73], which is stated explicitly in the former as follows:

Theorem 3.3. *F_n is unknotted in \mathbb{R}^4 if and only if F_n is piecewise linear ambient isotopic to a surface in $\mathbb{R}^3 \times \{0\}$.*

We shall be using the smooth version of Klingmann's unknottedness definition to prove our if and only if relationship between 2-knots bounding 3-balls and unknottedness. Hence we can rewrite our theorem 3.2 by replacing the unknottedness property with that given in 3.3, as follows:

Theorem 3.4. *Some 2-knot K bounds a piecewise linear 3-ball in \mathbb{R}^4 if and only if K is piecewise linear ambient isotopic to a surface in $\mathbb{R}^3 \times \{0\}$, i.e. K is unknotted.*

So we have established that the main theorem (theorem 3.4) holds in the piecewise linear category. It will now be our task to prove such a statement holds in the smooth category.

⁶A solid torus of genus n is a piecewise linear handlebody of genus n .

4. THE SOLID-TORUS UNKNOTTING CRITERION FOR 2-KNOTS IN THE SMOOTH CATEGORY

Our proof will be composed of three lemmas.

Lemma 4.1. *Any 2-knot K bounding a piecewise linear 3-ball B^3 embedded in \mathbb{R}^4 is such that K also bounds a smooth 3-ball $B_{C^\infty}^3$ in \mathbb{R}^4 .*

Proof. We have that K bounds B^3 . As such, B^3 must agree with the smooth structure of K in some neighbourhood of K . We uniquely smooth B^3 relative to K ⁷ by theorem 2.5 to obtain some smooth 3-ball $B_{C^\infty}^3$ also bounded by K . We will show that this is smoothly embedded in \mathbb{R}^4 .

Now, glue a second copy of B^3 along K to obtain a 3-manifold without boundary⁸

$$W = B^3 \cup_K B^3.$$

We denote these piecewise linear 3-balls M and N . Note that $M \cap N = K$. Both M and N admit unique smooth structures by theorem 2.5. We can smooth one copy relative to K , say M , as previously shown, such that M carries the smooth structure $B_{C^\infty}^3$.

Now, take

$$h : W \rightarrow W$$

to be the identity homeomorphism. h obviously restricts to diffeomorphisms on M and N (as it takes them onto themselves). By theorem 2.9, we can choose some global diffeomorphism $\varphi : W \rightarrow W$ such that

$$\varphi(M) = h(M) \text{ and } \varphi|_K = h|_K.$$

Restricting this φ to just M we obtain $\varphi(M) = h(M) = B_{C^\infty}^3$. Noting that φ is a diffeomorphism and fixes M at the boundary, we have that $\varphi(M) = B_{C^\infty}^3$ is a smooth 3-ball bounded by K .

We must extend φ to a diffeomorphism in \mathbb{R}^4 to show that $B_{C^\infty}^3 \subset \mathbb{R}^4$. As W is a smooth submanifold of \mathbb{R}^4 and we have that $\varphi : W \rightarrow W$ is a diffeomorphism that is the identity on K , the boundary, we can define an isotopy Φ_t such that $\Phi_0 = \text{id}$ and $\Phi_1 = \varphi$. We can then extend this isotopy to all of \mathbb{R}^4 (via the isotopy extension theorem 2.8). So Φ_1 is a diffeomorphism on \mathbb{R}^4 that takes B^3 to $B_{C^\infty}^3$ whilst keeping K fixed. So K bounds a smooth 3-ball $B_{C^\infty}^3$. \square

Lemma 4.2. *Let K be a 2-knot bounding some smooth 3-ball $B_{C^\infty}^3 \subset \mathbb{R}^4$. Then K is ambient isotopic to S^2 in \mathbb{R}^4 .*

Proof. By definition of smooth 3-balls (definition 2.4), we have that $B_{C^\infty}^3$ is diffeomorphic to D^3 , the closed unit 3-ball, say via $\varphi : B_{C^\infty}^3 \rightarrow D^3$. We have that

$$\varphi(\partial B_{C^\infty}^3) = S^2$$

as φ is a diffeomorphism. Choose some collar $c : \partial B_{C^\infty}^3 \times [0, \delta) \rightarrow B_{C^\infty}^3$ ($\delta \in \mathbb{R}$). Take our φ to be such that $\varphi|_{\partial B_{C^\infty}^3} = \text{id}$ and $\varphi|_{c(\partial B_{C^\infty}^3 \times [0, \delta/2])} = \text{id}$ also. This can be done via lemma 2.10, noting that φ is the identity across the collar and the boundary.

Choose some smooth isotopy φ_t such that $\varphi_0 = \text{id}$ the identity map on $B_{C^\infty}^3$, $\varphi_1 = \varphi$ the original diffeomorphism and then for all t , $\varphi_t|_{c(\partial B_{C^\infty}^3 \times [0, \delta/2])} = \text{id}$.

⁷When we say 'relative to K ' we are choosing the diffeomorphism that keeps a collar of K (which exists by the collaring theorem 2.7) fixed (via 2.10) and extending to the interior via the general isotopy extension theorem (see Hirsch [Hir97] chapter 8) on the isotopy taking id to the diffeomorphism.

⁸The boundary for both copies of the 3-ball cancel and the boundary 'disappears'. This is required to invoke theorem 2.9 later.

We invoke the isotopy extension theorem (2.8) relative to the collar c (i.e. keeping the collar fixed) to extend φ_t to the entirety of \mathbb{R}^4 . We thus have that there exists some ambient isotopy $\Phi : \mathbb{R}^4 \rightarrow \mathbb{R}^4$ such that

$$\Phi_t|_{B_{C^\infty}^3} = \varphi_t \text{ and } \Phi_t|_{\partial B_{C^\infty}^3} = \text{id}$$

for all $t \in [0, 1]$. So we have $\Phi_1(B_{C^\infty}^3) = D^3$ and that $\Phi_1(K) = \partial D^3 = S^2$.

We have shown that $B_{C^\infty}^3$ is ambient isotopic to $D^3 \subset \mathbb{R}^3 \times \{0\}$ in \mathbb{R}^4 via Φ_t . The boundary is preserved under Φ_t such that we may conclude K is ambient isotopic to $S^2 \subset \mathbb{R}^3 \times \{0\}$ in \mathbb{R}^4 as required. \square

Lemma 4.3. *Let K be a 2-knot that is ambient isotopic to S^2 in \mathbb{R}^4 . Then K bounds some smooth 3-ball $B_{C^\infty}^3 \subset \mathbb{R}^4$.*

Proof. By definition, S^2 is ambient isotopic to K , say via some ambient isotopy H_t in \mathbb{R}^4 . Then H_1 is a diffeomorphism such that

$$H_1(S^2) = K.$$

Taking H_1 , a diffeomorphism, on the standard closed unit ball bounded by S^2 , $D^3 \subset \mathbb{R}^3 \times \{0\} \subset \mathbb{R}^4$, gives some

$$H_1(D^3) = B_{C^\infty}^3$$

which is a smooth 3-ball by definition (2.4) as it is diffeomorphic to D^3 . H_1 preserves the boundary as it is a diffeomorphism, i.e.

$$H_1(S^2) = H_1(\partial D^3) = \partial B_{C^\infty}^3 = K.$$

and so K bounds a smooth 3-ball $B_{C^\infty}^3 \subset \mathbb{R}^4$ and we are done. \square

Now, we are able to prove our main theorem.

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