

(4.3)

HW 7

$$\vec{F} = \langle -y, x \rangle$$

a) Q (0,1)

$$W = \int_P^{(0,0)} \vec{F} \cdot d\vec{r} + \int_{(0,0)}^Q \vec{F} \cdot d\vec{r} \rightarrow d\vec{r} = \langle 0, dy, 0 \rangle$$

$$d\vec{r} = \langle dx, 0, 0 \rangle$$

$$\int_P^{(0,0)} \langle -y, x, 0 \rangle \cdot \langle dx, 0, 0 \rangle = \int_P^{(0,0)} -y dx$$

$$= -yx \Big|_{(0,1)}^{(0,0)} = 0 + 0 = \underline{0}$$

$$\int_{(0,0)}^{(1,0)} \langle -y, x \rangle \cdot \langle 0, dy \rangle = \int_{(0,0)}^{(1,0)} x dy = xy \Big|_{(0,0)}^{(1,0)} = \underline{0 - 0 = 0}$$

$$\boxed{W = 0}$$

b) $y = 1 - x \rightarrow \frac{dy}{dx} = \frac{d}{dx}(1-x) \rightarrow dy = -dx$

$$\int_{+1}^0 \langle -y, x \rangle \cdot \langle dx, dy \rangle = \int_0^1 -y dx + x dy$$

$$\int_1^0 -y dx - x dx = \int_0^1 (1-x) dx - x dx$$

$$= \int_1^0 -1 dx = -x \Big|_1^0 = 0 + 1 = \boxed{1}$$

c) $\vec{r} = \langle \cos \theta, \sin \theta \rangle \quad \vec{F} = \langle -\sin \theta, \cos \theta \rangle$

and $d\vec{r} = \langle -\sin \theta, \cos \theta \rangle d\theta$

so $W = \int_0^{\pi/2} \langle -\sin \theta, \cos \theta \rangle \cdot \langle -\sin \theta, \cos \theta \rangle d\theta$

$$= \int_0^{\pi/2} (\sin^2 \theta + \cos^2 \theta) d\theta$$

$$= \int_0^{\pi/2} d\theta = \boxed{\pi/2}$$

no torque, since force is directed down \vec{r} . Thus momentum is conserved.

4.4

a) $L_1 = L_2 \quad I_1 \omega_1 = I_2 \omega_2$

$$\omega_2 = \frac{I_1 \omega_1}{I_2} = \frac{\cancel{m} r_1^2 \omega_1}{\cancel{m} r_2^2}$$

$$\omega_2 = \left(\frac{r_1}{r_2}\right)^2 \omega_1$$

b) Work is done down to increase kinetic energy.

$$W = \int_{r_1}^{r_2} \vec{F}_T \cdot d\vec{r}$$

$$\vec{F}_T = \frac{mv^2}{r}$$

$$v = r \omega$$

$$\vec{F}_T = m \left(r \cdot \left(\frac{r_1}{r}\right)^2 \right)^2 \omega_1^2$$

$$= \frac{m r r_1^4 \omega_1^2}{r^4}$$

$$W = - \int_{r_1}^{r_2} \frac{m r_1^4 \omega_1^2}{r^3} dr = \left. \frac{m r_1^4 \omega_1^2}{2 r^2} \right|_{r_1}^{r_2}$$

Since \vec{F} is antiparallel to $d\vec{r}$

$$\frac{m r_1^4 \omega_1^2}{2 r_2^2} - \frac{m r_1^4 \omega_1^2}{2}$$

$$\begin{aligned}
 \text{c)} \quad & \frac{1}{2} I_1 \omega_1^2 \rightarrow \frac{1}{2} I_2 \omega_2^2 \\
 & \frac{1}{2} m_1 r_2^2 \omega_2^2 - \frac{1}{2} m_1 r_1^2 \omega_1^2 = \Delta KE \\
 & \frac{1}{2} m_1 r_2^2 \left(\frac{r_1}{r_2} \right)^4 \omega_1^2 = \frac{m_1 r_1^4 \omega_1^2}{2 r_2^2}
 \end{aligned}$$

$$\text{Thus } \left[\frac{m_1 r_1^4 \omega_1^2}{2 r_2^2} - \frac{m_1 r_1^2 \omega_1^2}{2} \right]$$

Which is the same answer as the work done.

4.8

$$PE_0 = mgh$$

$$PE = mgR \cos \theta$$



$$h = R$$

$$E = mgR = \frac{1}{2} mv^2 + MgR \cos \theta$$

$$mgR - MgR \cos \theta = \frac{1}{2} mv^2$$

$$\vec{F} = m\vec{a}$$

$$\vec{F} = \frac{mv^2}{R}$$

$$\vec{F} = \frac{mv^2}{R} = mg \cos \theta - N$$

The puck has Normal force and gravitational force

$$mv^2 = Rmg \cos \theta - N \cdot R$$

$$\begin{aligned}
 2mgR - 2mgR \cos \theta &= mgR \cos \theta - N \cdot R \\
 N &= mg(3 \cos \theta - 2)
 \end{aligned}$$

(4.8) continued...

$$N = mg(3 \cos \theta - 2)$$

We are looking for when N becomes zero, (where the Puck leaves the sphere).

$$3 \cos \theta - 2 = 0$$

$$\cos \theta = \frac{2}{3}$$

$$\theta = 48.19^\circ$$

(measured from the top of sphere)