

---

```
function [localmat] = bfun(x_pts, isub)
%
% This function represents the b function in the
% differential equation.
%
%
%%%%%%% Global Variables %%%%%%
global xpts nnodes
global Global_r Global_s Global_u
global rad_bas_type str_bas_type vel_bas_type
global quad_rul
%
%
nevalpts = size(x_pts,1) ;
localmat = x_pts.^2 ;
```

*Published with MATLAB® R2023b*