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1 Notation

Definition 1 (4.1.1 Kreyszig).

- A linear operator $A : D(A) \subseteq X \rightarrow Y$ is said to be **bounded** if there exists a $C > 0$ such that

$$\|Au\|_Y \leq C\|u\|_X, \quad \text{for every } u \in D(A)$$

Otherwise it is said to be **unbounded**.

- A linear operator $A : D(A) \subseteq X \rightarrow Y$ is said to be **densely defined** if $\overline{D(A)} = X$
- A linear operator $A : D(A) \subseteq X \rightarrow Y$ is said to be **closed** if the **graph**

$$G(A) = \{(u, Au) \mid u \in D(A)\} \subseteq X \times Y$$

is closed as a subspace of $X \times Y$

Definition 2 (7.2 Kreyszig).

Let $X \neq \{0\}$ be a complex normed space and $T : \mathcal{D}(T) \subseteq X \rightarrow X$ be a linear operator. With T we associate the operator

$$T_\lambda = T - \lambda I$$

where λ is a complex number and I is the identity operator on $\mathcal{D}(T)$. If T_λ has an inverse, we denote it by $R_\lambda(T)$ and call it the **resolvent operator** of T or, simply, the **resolvent** of T . If it is clear which operator we are discussing, we will write R_λ .

Definition 3 (7.2-1 (Regular value, resolvent set, spectrum)).

Let $X \neq \{0\}$ be a complex normed space and $T : \mathcal{D}(T) \subseteq X \rightarrow X$ be a linear operator. A regular value λ of T is a complex number such that

- $R_\lambda(T)$ exists,

- $R_\lambda(T)$ is bounded,

- $R_\lambda(T)$ is densely defined.

The resolvent set $\rho(T)$ of T is the set of all regular values λ of T . Its complement $\sigma(T) = \mathbb{C} \setminus \rho(T)$ in the complex plane \mathbb{C} is called the **spectrum** of T , and a $\lambda \in \sigma(T)$ is called a **spectral value** of T . Furthermore, the spectrum $\sigma(T)$ is partitioned into three disjoint sets as follows.

The **point spectrum** or discrete spectrum $\sigma_p(T)$ is the set such that $R_\lambda(T)$ does not exist. A $\lambda \in \sigma_p(T)$ is called an **eigenvalue** of T .

The **continuous spectrum** $\sigma_c(T)$ is the set such that $R_\lambda(T)$ exists and is densely defined, but it unbounded.

The **residual spectrum** $\sigma_r(T)$ is the set such that $R_\lambda(T)$ exists, but is not densely defined (may or may not be bounded).

2 3.1 Weak Solutions of Elliptic Boundary Value Problems

Theorem 1 (3.1.4 (Lax-Milgram)).

Let V be a Hilbert space and $a(\cdot, \cdot)$ a continuous V -elliptic bilinear form. Then given $f \in V$, there exists a unique $u \in V$ such that

$$a(u, v) = (f, v), \quad \text{for every } v \in V.$$

If $a(\cdot, \cdot)$ is also symmetric then the functional $J : V \rightarrow \mathbb{R}$ defined by

$$J(v) = \frac{1}{2}a(v, v) - (f, v)$$

attains its minimum at u .

Theorem 2 (3.1.5 (Babuska-Brezzi)).

Let Σ, V be Hilbert spaces and $a : \Sigma \times \Sigma \rightarrow \mathbb{R}, b : \Sigma \times V \rightarrow \mathbb{R}$, bilinear forms which are continuous. Let

$$Z = \{\sigma \in \Sigma \mid b(\sigma, v) = 0, \quad \text{for every } v \in V\}.$$

Assume that $a(\cdot, \cdot)$ is Z -elliptic, i.e. there exists a constant $\alpha > 0$ such that

$$a(\sigma, \sigma) \geq \alpha \|\sigma\|_{\Sigma}^2, \quad \text{for every } \sigma \in Z.$$

Assume further that there exists a constant $\beta > 0$ such that

$$\sup_{\tau \in \Sigma} \frac{b(\tau, v)}{\|\tau\|_{\Sigma}} \geq \beta \|v\|_V.$$

Then if $\kappa \in \Sigma$ and $l \in V$, there exists a unique pair $(\sigma, u) \in \Sigma \times V$ such that

$$\begin{aligned} a(\sigma, \tau) + b(\tau, u) &= (\kappa, \tau), \quad \text{for every } \tau \in \Sigma \\ b(\sigma, v) &= (l, v), \quad \text{for every } v \in V. \end{aligned}$$

3 4.3 C_0 Semigroups

Definition 4 (4.3.1).

Let X be a Banach space and $\{S(t)\}_{t \geq 0}$ be a family of bounded linear operators on X . It is said to be a C_0 semigroup if the following are true:

- $S(0) = I$, the identity of X
- $S(t+s) = S(t)S(s)$, for all $t, s \geq 0$
- For every $u \in X$

$$S(t)u \rightarrow u \quad \text{as } t \downarrow 0$$

Theorem 3 (4.3.1).

Let $\{S(t)\}_{t \geq 0}$ be a C_0 -semigroup on X . Then there exists $M \geq 1$ and ω such that

$$\|S(t)\| \leq M e^{\omega t}, \quad \text{for all } t \geq 0$$

Definition 5 (4.3.2).

If $M = 1$ and $\omega = 0$, so that $\|S(t)\| \leq 1$ for all $t \geq 0$, we say that $\{S(t)\}$ is a **contraction semigroup**.

Definition 6 (4.3.3).

Let $\{S(t)\}_{t \geq 0}$ be a C_0 semigroup on X . The **infinitesimal generator** of the semigroup is a linear operator A given by

$$D(A) = \left\{ u \in X \mid \lim_{t \downarrow 0} \frac{S(t)u - u}{t} \text{ exists} \right\}$$

$$Au = \lim_{t \downarrow 0} \frac{S(t)u - u}{t}, \quad u \in D(A)$$

Theorem 4 (4.3.2).

Let $\{S(t)\}_{t \geq 0}$ be a C_0 semigroup and let A be its infinitesimal generator. Let $u \in D(A)$. Then

$$S(t)u \in C^1([0, \infty); X) \cap C([0, \infty); X)$$

and

$$\frac{d}{dt}(S(t)u) = AS(t)u = S(t)Au$$

Proof.

Let $u \in D(A)$. Then

$$\left(\frac{S(h) - I}{h} \right) S(t)u = S(t) \left(\frac{S(h) - I}{h} \right) \rightarrow S(t)Au$$

as $h \downarrow 0$, by the definition of A . Thus $S(t)u \in D(A)$ and

$$AS(t)u = S(t)Au = D^+S(t)u.$$

Next consider

$$\frac{S(t)u - S(t-h)u}{h} = S(t-h)\frac{S(h)u - u}{h}$$

Hence

$$\frac{S(t)u - S(t-h)u}{h} - S(t)Au = S(t-h)\left(\frac{S(h)u - u}{h} - Au\right) + (S(t-h) - S(t))Au.$$

But

$$\begin{aligned} \left\| S(t-h)\left(\frac{S(h)u - u}{h} - Au\right) \right\| &\leq M e^{\omega t} \left\| \frac{S(h)u - u}{h} - Au \right\| \\ &\rightarrow 0 \quad \text{as } h \downarrow 0 \end{aligned}$$

and

$$\|(S(t-h) - S(t))Au\| \rightarrow 0 \quad \text{as } h \downarrow 0$$

by the boundedness of $S(t)$.

Thus,

$$D^-S(t)u = S(t)Au = D^+S(t)u$$

and thus

$$\frac{d}{dt}(S(t)u) = AS(t)u = S(t)Au$$

Similarly, by the boundedness of $S(t)$, the map $t \mapsto S(t)Au$ is continuous so $S(t)u \in C^1([0, \infty); X)$ \square

Remark 1 (4.3.3). *If A is the infinitesimal generator of a C_0 semigroup $\{S(t)\}$ then we know by the above theorem that*

$$u(t) = S(t)u_0$$

defines the unique solution of the initial value problem

$$\left. \begin{aligned} \frac{du(t)}{dt} &= Au(t), \quad t \geq 0 \\ u(0) &= u_0 \end{aligned} \right\}$$

4 4.4 The Hille-Yosida Theorem

Theorem 5 (4.4.3 (Hille Yosida)).

A linear unbounded operator A on a Banach space X is the infinitesimal generator of a contraction semigroup if and only if

- *A is closed*
- *A is densely defined*
- *For every $\lambda > 0$, $(\lambda I - A)^{-1}$ is a bounded linear operator and*

$$\|(\lambda I - A)^{-1}\| \leq \frac{1}{\lambda}$$

5 Pazy Stuff

Definition 7.

Let X be a Banach space with dual space X' . Denote $x' \in X'$ at $x \in X$ by $\langle x', x \rangle$ or $\langle x, x' \rangle$. Define the following set $F(x) \subseteq X'$ as

$$F(x) = \{x' \mid \langle x', x \rangle = \|x\|^2 = \|x'\|^2\}$$

(This set is non-empty by the Hahn-Banach theorem.)

Definition 8 (Dissipativity).

A linear operator A is dissipative if for every $x \in D(A)$ there is a $x' \in F(x)$ such that $\operatorname{Re} \langle Ax, x' \rangle \leq 0$

Definition 9 (Maximal Dissipativity).

A linear operator A is called maximally dissipative if it is dissipative and $R(I - A) = X$.

Theorem 6 (1.4.3 Lumer-Phillips).

- If A is dissipative and there is a $\lambda_0 > 0$ such that $R(\lambda_0 I - A) = X$, then A is the infinitesimal generator of a C_0 semigroup of contractions on X .
- If A is the infinitesimal generator of a C_0 semigroup of contractions on X then $R(\lambda I - A) = X$ for all $\lambda > 0$ and A is dissipative.

Proof.

Let $\lambda > 0$, the dissipativeness of A implies that $\|\lambda x - Ax\| \geq \lambda \|x\|$ (proof skipped) for every $\lambda > 0$ and $x \in D(A)$. Since $R(\lambda_0 I - A) = X$, it follows when $\lambda = \lambda_0$ that $(\lambda_0 I - A)^{-1}$ is a bounded linear operator and thus closed. This implies $\lambda_0 I - A$ is closed and therefore A is also closed. If $R(\lambda I - A) = X$ for every $\lambda > 0$ then $\rho(A) \subseteq \mathbb{R}$ and $\|R_\lambda(A)\| \leq \lambda^{-1}$. It follows by the Hille-Yosida theorem that A is the infinitesimal generator of a C_0 semigroup of contractions on X .

Consider the set $\Lambda = \{\lambda \mid 0 < \lambda < \infty, R(\lambda I - A) = X\}$. Let $\lambda \in \Lambda$. By previous inequality, $\lambda \in \rho(A)$. Since $\rho(A)$ is open, the intersection of $B_r(\lambda) \cap \mathbb{R} \subseteq \Lambda$ and thus Λ is open.

On the other hand, let $\{\lambda_n\} \subseteq \Lambda$ and $\lambda_n \rightarrow \lambda > 0$. For every $y \in X$ there exists an $x_n \in D(A)$ such that

$$\lambda_n x_n - Ax_n = y$$

From the inequality it follows that $\|x_n\| \leq \lambda_n^{-1} \|y\| \leq C$ for some $C > 0$. Now,

$$\begin{aligned} \lambda_m \|x_n - x_m\| &\leq \|\lambda_m(x_n - x_m) - A(x_n - x_m)\| \\ &= |\lambda_n - \lambda_m| \|x_n\| \\ &\leq C |\lambda_n - \lambda_m| \rightarrow 0 \end{aligned}$$

Therefore $\{x_n\}$ is Cauchy. Let $x_n \rightarrow x$. It follows $Ax_n \rightarrow \lambda x - y$. Since A is closed, $x \in D(A)$ and $\lambda x - Ax = y$. Therefore $R(\lambda I - A) = X$ and $\lambda \in \Lambda$. Thus Λ is closed. By assumption, $\Lambda \neq \emptyset$, therefore $\Lambda = (0, \infty)$
If A is the infinitesimal generator of a C_0 semigroup of contractions, $S(t)$, on X , then by the Hille-Yosida theorem $\rho(A) \supseteq (0, \infty)$ and therefore $R(\lambda I - A) = X$ for all $\lambda > 0$. Furthermore if $x \in D(A)$, $x^* \in F(x)$ then

$$|\langle S(t)x, x^* \rangle| \leq \|S(t)x\| \|x^*\| \leq \|x\|^2$$

and therefore,

$$\operatorname{Re} \langle S(t)x - x, x^* \rangle = \operatorname{Re} \langle S(t)x, x^* \rangle - \|x\|^2 \leq 0.$$

By dividing the previous line by $t > 0$ and letting $t \downarrow 0$ yields

$$\operatorname{Re} \langle Ax, x^* \rangle \leq 0.$$

□

Theorem 7 (Lumer-Phillips).

A densely defined operator A is the infinitesimal generator of a C_0 semigroup of contractions if and only if it is maximal dissipative.

6 Bibliography