

MASTER PROJECT: Qualitative Properties of the Multilayered Structure - Fluid Interactions Coupled PDE Systems

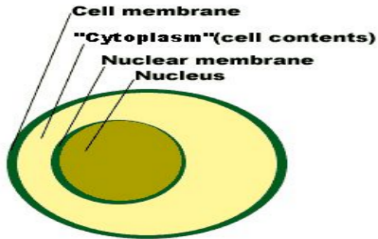
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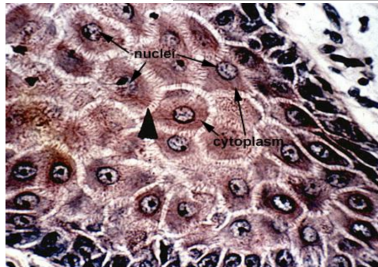
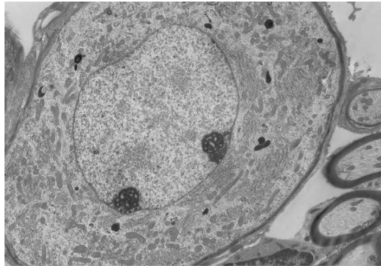
Clemson University

October 16, 2025

Motivation

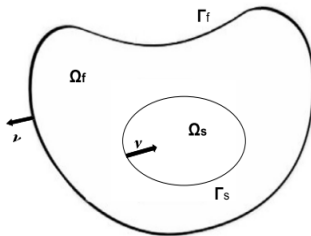


A eukaryotic cell



Geometry

- $\Omega_f \subseteq \mathbb{R}^3$, Lipschitz bounded domain
- $\Omega_s \subseteq \mathbb{R}^3$, $\Omega_s \subset\subset \Omega_f$
- $\partial\Omega_s = \Gamma_s$
- $\partial\Omega_f = \Gamma_s \cup \Gamma_f$



Introduction of First Model

$$\begin{cases} u_t - \Delta u = 0 \text{ in } (0, T) \times \Omega_f \\ u|_{\Gamma_f} = 0 \text{ on } (0, T) \times \Gamma_f; \end{cases} \quad (1)$$

$$\begin{cases} \frac{\partial^2}{\partial t^2} h_j - \Delta h_j + h_j = \frac{\partial w}{\partial \nu}|_{\Gamma_j} - \frac{\partial u}{\partial \nu}|_{\Gamma_j} \text{ on } (0, T) \times \Gamma_j \\ h_j|_{\partial\Gamma_j \cap \partial\Gamma_l} = h_l|_{\partial\Gamma_j \cap \partial\Gamma_l} \text{ on } (0, T) \times (\partial\Gamma_j \cap \partial\Gamma_l), \text{ for all } 1 \leq l \leq K \\ \text{such that } \partial\Gamma_j \cap \partial\Gamma_l \neq \emptyset \\ \frac{\partial h_j}{\partial n_j} \Big|_{\partial\Gamma_j \cap \partial\Gamma_l} = -\frac{\partial h_l}{\partial n_l} \Big|_{\partial\Gamma_j \cap \partial\Gamma_l} \text{ on } (0, T) \times (\partial\Gamma_j \cap \partial\Gamma_l), \text{ for all } 1 \leq l \leq K \\ \text{such that } \partial\Gamma_j \cap \partial\Gamma_l \neq \emptyset \end{cases} \quad (2)$$

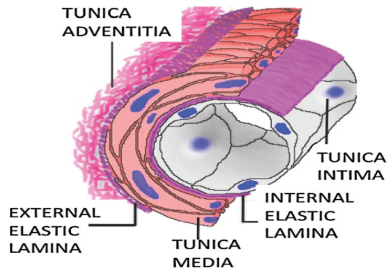
$$\begin{cases} w_{tt} - \Delta w = 0 \text{ on } (0, T) \times \Omega_s \\ w_t|_{\Gamma_j} = \frac{\partial}{\partial t} h_j = u|_{\Gamma_j} \text{ on } (0, T) \times \Gamma_j, \text{ for } j = 1, \dots, K \end{cases} \quad (3)$$

$$\begin{aligned} [u(0), h_1(0), \frac{\partial}{\partial t} h_1(0), \dots, h_K(0), \frac{\partial}{\partial t} h_K(0), w(0), w_t(0)] \\ = [u_0, h_{01}, h_{11}, \dots, h_{0K}, h_{1K}, w_0, w_1] \end{aligned} \quad (4)$$

where $\Gamma_s = \cup_{j=1}^K \overline{\Gamma_j}$ and $\Gamma_i \cap \Gamma_j = \emptyset$, for $i \neq j$.

Generally, single layered or moving boundary FSI Systems

- George Avalos
- Lorena Bociu
- Scott Hansen
- Igor Kukavica
- Irena Lasiecka
- Hyesuk Lee
- Roberto Triggiani
- Amjad Tuffaha
- Justin Webster
- Enrique Zuazua
- etc.



- 2014, Fluid-Multi-layered-structure Interaction, Existence of weak solutions
- 2015, Regularity and Regularization effects of the same problem
- 2015, Numerical Results: unconditional stability for the same problem

$$\begin{aligned}
 \mathbf{H} = & \{[u_0, h_{01}, h_{11}, \dots, h_{0K}, h_{1K}, w_0, w_1] \in L^2(\Omega_f) \times H^1(\Gamma_1) \times L^2(\Gamma_1) \times \dots \\
 & \times H^1(\Gamma_K) \times L^2(\Gamma_K) \times H^1(\Omega_s) \times L^2(\Omega_s), \text{ such that for each } 1 \leq j \leq K : \\
 & (i) w_0|_{\Gamma_j} = h_{0j}; \\
 & (ii) h_{0j}|_{\partial\Gamma_j \cap \partial\Gamma_l} = h_{0l}|_{\partial\Gamma_j \cap \partial\Gamma_l} \text{ on } \partial\Gamma_j \cap \partial\Gamma_l, \text{ for all } 1 \leq l \leq K \text{ such that} \\
 & \partial\Gamma_j \cap \partial\Gamma_l \neq \emptyset\}
 \end{aligned} \tag{5}$$

With the accompanying inner product

$$\begin{aligned}
 \langle \Phi_0, \tilde{\Phi}_0 \rangle_{\mathbf{H}} = & \langle u_0, \tilde{u}_0 \rangle_{\Omega_f} + \sum_{j=1}^K \langle \nabla h_{0j}, \nabla \tilde{h}_{0j} \rangle_{\Gamma_j} + \sum_{j=1}^K \langle h_{0j}, \tilde{h}_{0j} \rangle_{\Gamma_j} \\
 & + \sum_{j=1}^K \langle h_{1j}, \tilde{h}_{1j} \rangle_{\Gamma_j} + \langle \nabla w_0, \nabla \tilde{w}_0 \rangle_{\Omega_s} + \langle w_1, \tilde{w}_1 \rangle_{\Omega_s}
 \end{aligned} \tag{6}$$

where

$$\Phi_0 = [u_0, h_{01}, h_{11}, \dots, h_{0K}, h_{1K}, w_0, w_1] \in \mathbf{H} \text{ and}$$

$$\tilde{\Phi}_0 = [\tilde{u}_0, \tilde{h}_{01}, \tilde{h}_{11}, \dots, \tilde{h}_{0K}, \tilde{h}_{1K}, \tilde{w}_0, \tilde{w}_1] \in \mathbf{H}.$$

Functional Settings

For the PDE system given in (1) – (4) if

$\Phi(t) = [u, h_1, \frac{\partial}{\partial t} h_1, \dots, h_K, \frac{\partial}{\partial t} h_K, w, w_1] \in C([0, T]; \mathbf{H})$ then for $\mathbf{A} : D(\mathbf{A}) \subseteq \mathbf{H} \rightarrow \mathbf{H}$,

$$\frac{d}{dt}\Phi(t) = \mathbf{A}\Phi(t); \quad \Phi(0) = \Phi_0. \quad (7)$$

where \mathbf{A} is given as

$$\mathbf{A} = \begin{bmatrix} \Delta & 0 & 0 & \dots & 0 & 0 & 0 & 0 \\ 0 & 0 & I & \dots & 0 & 0 & 0 & 0 \\ -\frac{\partial}{\partial \nu}|_{\Gamma_1} & (\Delta - I) & 0 & \dots & 0 & 0 & \frac{\partial}{\partial \nu}|_{\Gamma_1} & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 0 & I & 0 & 0 \\ -\frac{\partial}{\partial \nu}|_{\Gamma_K} & 0 & 0 & \dots & (\Delta - I) & 0 & \frac{\partial}{\partial \nu}|_{\Gamma_K} & 0 \\ 0 & 0 & 0 & \dots & 0 & 0 & 0 & I \\ 0 & 0 & 0 & \dots & 0 & 0 & \Delta & 0 \end{bmatrix}; \quad (8)$$

Introduction of First Model

Where the Domain of **A** is given as follows

$$D(\mathbf{A}) = \{[u_0, h_{01}, h_{11}, \dots, h_{0K}, h_{1K}, w_0, w_1] \in \mathbf{H} :$$

$$(\mathbf{A.i}) \ u_0 \in H^1(\Omega_f), \ h_{1j} \in H^1(\Gamma_j) \text{ for } 1 \leq j \leq K, \ w_1 \in H^1(\Omega_s);$$

$$(\mathbf{A.ii})(a) \ \Delta u_0 \in L^2(\Omega_f), \ \Delta w_0 \in L^2(\Omega_s), \ (b) \ \Delta h_{0j} - \frac{\partial u_0}{\partial \nu} \Big|_{\Gamma_j} + \frac{\partial w_0}{\partial \nu} \Big|_{\Gamma_j} \in L^2(\Gamma_j)$$

$$\text{for } 1 \leq j \leq K; (c) \ \frac{\partial h_{0j}}{\partial n_j} \Big|_{\partial \Gamma_j} \in H^{-1/2}(\partial \Gamma_j), \text{ for } 1 \leq j \leq K;$$

$$(\mathbf{A.iii}) \ u_0|_{\Gamma_f} = 0, u_0|_{\Gamma_j} = h_{1j} = w_1|_{\Gamma_j}, \text{ for } 1 \leq j \leq K;$$

$$(\mathbf{A.iv}) \text{ For } 1 \leq j \leq K :$$

$$(a) \ h_{1j}|_{\partial \Gamma_j \cap \partial \Gamma_l} = h_{1l}|_{\partial \Gamma_j \cap \partial \Gamma_l} \text{ on } \partial \Gamma_j \cap \partial \Gamma_l, \text{ for all } 1 \leq l \leq K \text{ such that}$$

$$\partial \Gamma_j \cap \partial \Gamma_l \neq \emptyset;$$

$$(b) \ \frac{\partial h_{0j}}{\partial n_j} \Big|_{\partial \Gamma_j \cap \partial \Gamma_l} = - \frac{\partial h_{0l}}{\partial n_l} \Big|_{\partial \Gamma_j \cap \partial \Gamma_l} \text{ on } \partial \Gamma_j \cap \partial \Gamma_l, \text{ for all } 1 \leq l \leq K$$

$$\text{such that } \partial \Gamma_j \cap \partial \Gamma_l \neq \emptyset\}.$$

(9)

Part I

Theorem ((Wellposedness) G. Avalos, PGG, B. Muha [JDE, 2020])

The operator $\mathbf{A} : D(\mathbf{A}) \subseteq \mathbf{H} \rightarrow \mathbf{H}$ defined above generates a C_0 -semigroup of contractions. Consequently, the solution $\Phi(t) = [u, h_1, \frac{\partial}{\partial t} h_1, \dots, h_K, \frac{\partial}{\partial t} h_K, w, w_1]$ of the PDE model is given by

$$\Phi(t) = e^{\mathbf{A}t} \Phi_0 \in C([0, T]; \mathbf{H}),$$

where $\Phi_0 = [u_0, h_{01}, h_{11}, \dots, h_{0K}, h_{1K}, w_0, w_1] \in D(\mathbf{A})$

G. Avalos, P. G. Geredeli, B. Muha; "Wellposedness, Spectral Analysis and Asymptotic Stability of a Multilayered Heat-Wave-Wave System ", Journal of Differential Equations 269 (2020), pp. 7129-7156.

Wellposedness was shown using the Lumer-Phillips Theorem. To this end, they showed

- \mathbf{A} is dissipative; i.e. $\langle \mathbf{A}\Phi, \Phi \rangle_{\mathbf{H}} \leq 0$ for all $\Phi \in D(\mathbf{A})$
- Use Lax-Milgram to solve to the static resolvent equation $(\lambda I - \mathbf{A})\Phi = \Phi^*$ in $D(\mathbf{A})$; i.e. \mathbf{A} is maximally dissipative
- Recover of the other structure solution variables given initial data; i.e.

$$h_{0j} = \frac{1}{\lambda} h_{1j} + \frac{1}{\lambda} h_{0j}^*, \text{ for } 1 \leq j \leq K,$$
$$w_0 = \frac{1}{\lambda} w_1 + \frac{1}{\lambda} w_0^*.$$

Dissipativity of \mathbf{A}

Given data Φ_0 in $D(\mathbf{A})$,

$$\begin{aligned}\langle \mathbf{A}\Phi_0, \Phi_0 \rangle_{\mathbf{H}} = & -\|\nabla u_0\|_{\Omega_f}^2 + 2i \sum_{j=1}^K \operatorname{Im} \langle \nabla h_{1j}, \nabla h_{0j} \rangle_{\Gamma_j} \\ & + 2i \sum_{j=1}^K \operatorname{Im} \langle h_{1j}, h_{0j} \rangle_{\Gamma_j} + 2i \operatorname{Im} \langle \nabla w_1, \nabla w_0 \rangle_{\Omega_s}, \quad (10)\end{aligned}$$

which gives $\operatorname{Re} \langle \mathbf{A}\Phi_0, \Phi_0 \rangle_{\mathbf{H}} \leq 0$. Since Φ_0 was arbitrary, it follows that \mathbf{A} is dissipative.

The author solves the following static problem with the Lax-Milgram Theorem. Given parameter $\lambda > 0$, suppose $\Phi = [u_0, h_{01}, h_{11}, \dots, h_{0K}, h_{1K}, w_0, w_1] \in D(\mathbf{A})$ is a solution of the equation

$$(\lambda I - \mathbf{A})\Phi = \Phi^*, \quad (11)$$

where $\Phi^* = [u_0^*, h_{01}^*, h_{11}^*, \dots, h_{0K}^*, h_{1K}^*, w_0^*, w_1^*] \in \mathbf{H}$.

Maximality of **A**

In PDE terms, the abstract equation above becomes

$$\begin{cases} \lambda u_0 - \Delta u_0 = u_0^* & \text{in } \Omega_f \\ u_0|_{\Gamma_f} = 0 & \text{on } \Gamma_f; \end{cases} \quad (12)$$

and for $1 \leq j \leq K$,

$$\begin{cases} \lambda h_{0j} - h_{1j} = h_{0j}^* & \text{in } \Gamma_j \\ \lambda h_{1j} - \Delta h_{0j} + h_{0j} - \frac{\partial w_0}{\partial \nu} + \frac{\partial u_0}{\partial \nu} = h_{1j}^* & \text{in } \Gamma_j \\ u_0|_{\Gamma_j} = h_{1j} = w_1|_{\Gamma_j} & \text{in } \Gamma_j \\ h_{0j}|_{\partial\Gamma_j \cap \partial\Gamma_l} = h_{0l}|_{\partial\Gamma_j \cap \partial\Gamma_l} & \text{on } \partial\Gamma_j \cap \partial\Gamma_l, \text{ for all } 1 \leq l \leq K \text{ such that} \\ & \partial\Gamma_j \cap \partial\Gamma_l \neq \emptyset \\ \frac{\partial h_{0j}}{\partial n_j} \Big|_{\partial\Gamma_j \cap \partial\Gamma_l} = -\frac{\partial h_{0l}}{\partial n_l} \Big|_{\partial\Gamma_j \cap \partial\Gamma_l} & \text{on } \partial\Gamma_j \cap \partial\Gamma_l, \text{ for all } 1 \leq l \leq K \text{ such that} \\ & \partial\Gamma_j \cap \partial\Gamma_l \neq \emptyset; \end{cases} \quad (13)$$

and also

$$\begin{cases} \lambda w_0 - w_1 = w_0^* & \text{in } \Omega_s \\ \lambda w_1 - \Delta w_0 = w_1^* & \text{in } \Omega_s \end{cases} \quad (14)$$

Maximality of \mathbf{A}

Define the sets

$$\mathcal{V} = \{[\psi_1, \dots, \psi_K] \in H^1(\Gamma_1) \times \dots \times H^1(\Gamma_K) \mid \text{For all } 1 \leq j \leq K, \\ \psi_j|_{\partial\Gamma_j \cap \partial\Gamma_l} = \psi_l|_{\partial\Gamma_j \cap \partial\Gamma_l}, \text{ for all } 1 \leq l \leq K \text{ such that } \partial\Gamma_j \cap \partial\Gamma_l \neq \emptyset\} \quad (15)$$

and

$$\mathbf{W} \equiv \left\{ [\varphi, \psi_1, \dots, \psi_K, \xi] \in H_{\Gamma_f}^1(\Omega_f) \times \mathcal{V} \times H^1(\Omega_s) \mid \varphi|_{\Gamma_j} = \psi_j = \xi|_{\Gamma_j}, \text{ for } 1 \leq j \leq K \right\}; \quad (16)$$

If $\Phi = [u_0, h_{01}, h_{11}, \dots, h_{0K}, h_{1K}, w_0, w_1] \in D(\mathbf{A})$ solves (11), then necessarily its solution components $[u_0, h_{11}, \dots, h_{1K}, w_1] \in \mathbf{W}$ satisfy for $[\varphi, \psi, \xi] \in \mathbf{H}$,

$$\left\langle \mathbf{B} \begin{bmatrix} \varphi \\ \psi_1 \\ \vdots \\ \psi_K \\ \xi \end{bmatrix}, \begin{bmatrix} u_0 \\ h_{11} \\ \vdots \\ h_{1K} \\ w_1 \end{bmatrix} \right\rangle_{\mathbf{W}^* \times \mathbf{W}} = \mathbf{F}_\lambda \left(\begin{bmatrix} \varphi \\ \psi \\ \xi \end{bmatrix} \right); \quad (17)$$

Maximality of **A**

where

$$\begin{aligned} \mathbf{F}_\lambda \left(\begin{bmatrix} \varphi \\ \psi \\ \xi \end{bmatrix} \right) &= \langle u_0^*, \varphi \rangle_{\Omega_f} + \sum_{j=1}^K \left[\langle h_{1j}^*, \psi_j \rangle_{\Gamma_j} - \frac{1}{\lambda} \langle \nabla h_{0j}^*, \nabla \psi_j \rangle_{\Gamma_j} \right. \\ &\quad \left. - \frac{1}{\lambda} \langle h_{0j}^*, \psi_j \rangle_{\Gamma_j} \right] + \langle w_1^*, \xi \rangle_{\Omega_s} - \frac{1}{\lambda} \langle \nabla w_0^*, \nabla \xi \rangle_{\Omega_s} \end{aligned} \quad (18)$$

and

$$\begin{aligned} \left\langle \mathbf{B} \begin{bmatrix} \varphi \\ \psi_1 \\ \vdots \\ \psi_K \\ \xi \end{bmatrix}, \begin{bmatrix} \tilde{\varphi} \\ \tilde{\psi}_1 \\ \vdots \\ \tilde{\psi}_K \\ \tilde{\xi} \end{bmatrix} \right\rangle_{\mathbf{W}^* \times \mathbf{W}} &= \lambda \langle \varphi, \tilde{\varphi} \rangle_{\Omega_f} + \langle \nabla \varphi, \nabla \tilde{\varphi} \rangle_{\Omega_f} + \lambda \langle \xi, \tilde{\xi} \rangle_{\Omega_s} + \langle \nabla \xi, \nabla \tilde{\xi} \rangle_{\Omega_s} \\ &\quad + \sum_{j=1}^K \left[\lambda \langle \psi_j, \tilde{\psi}_j \rangle_{\Gamma_j} + \frac{1}{\lambda} \langle \nabla \psi_j, \nabla \tilde{\psi}_j \rangle_{\Gamma_j} + \frac{1}{\lambda} \langle \psi_j, \tilde{\psi}_j \rangle_{\Gamma_j} \right] \end{aligned}$$

Theorem (Lax-Milgram)

Let X be a Hilbert space and $a(\cdot, \cdot)$ a continuous X -elliptic bilinear form. Then given $f \in X$, there exists a unique $u \in X$ such that

$$a(u, v) = \langle f, v \rangle_X, \quad \text{for every } v \in X.$$

Since it is clear that $\mathbf{B} \in \mathcal{L}(\mathbf{W}, \mathbf{W}^*)$ is \mathbf{W} -elliptic; by the Lax-Milgram Theorem, the equation (17) has a unique solution

$$[u_0, h_{11}, \dots, h_{1K}, w_1] \in \mathbf{W}. \quad (19)$$

It was then showed this solution is in $D(\mathbf{A})$.

Intoduction of Second Model

The model was improved from a heat-wave-wave model to a Stokes-wave-Lamé model. The author has shown similar results of wellposedness for this model.

Introduction of Second Model

$$\begin{cases} u_t - \operatorname{div}(\nabla u + \nabla^T u) + \nabla p = 0 & \text{in } (0, T) \times \Omega_f \\ \operatorname{div}(u) = 0 & \text{in } (0, T) \times \Omega_f \\ u|_{\Gamma_f} = 0 & \text{on } (0, T) \times \Gamma_f; \end{cases} \quad (20)$$

$$\begin{cases} h_{tt} - \Delta_{\Gamma_s} h = [\nu \cdot \sigma(w)]|_{\Gamma_s} - [\nu \cdot (\nabla u + \nabla^T u)]|_{\Gamma_s} + p\nu & \text{on } (0, T) \times \Gamma_s, \end{cases} \quad (21)$$

$$\begin{cases} w_{tt} - \operatorname{div} \sigma(w) + w = 0 & \text{on } (0, T) \times \Omega_s \\ w_t|_{\Gamma_s} = h_t = u|_{\Gamma_s} & \text{on } (0, T) \times \Gamma_s \end{cases} \quad (22)$$

$$[u(0), h(0), h_t(0), w(0), w_1(0)] = [u_0, h_0, h_1, w_0, w_1] \in \mathbf{H} \quad (23)$$

Here, $\Delta_{\Gamma_s}(\cdot)$ is the Laplace Beltrami operator, and the stress tensor $\sigma(\cdot)$ constitutes the Lamé system of elasticity on the “thick” layer. Namely, for function v in Ω_s ,

$$\sigma(v) = 2\mu\epsilon(v) + \lambda[I_3 \cdot \epsilon(v)]I_3,$$

where strain tensor $\epsilon(\cdot)$ is given by

$$\epsilon_{ij} = \frac{1}{2} \left(\frac{\partial v_j}{\partial x_i} + \frac{\partial v_i}{\partial x_j} \right), \quad 1 \leq i, j \leq 3$$

With the following Hilbert space

$$\mathbf{H} = \{[u_0, h_0, h_1, w_0, w_1] \in [L^2(\Omega_f)]^3 \times [H^1(\Gamma_s)]^2 \times [L^2(\Gamma_s)]^2 \times [H^1(\Omega_s)]^3 \times [L^2(\Omega_s)]^3 \mid \operatorname{div}(u_0) = 0, u_0 \cdot \nu|_{\Gamma_f} = 0, \text{ and } w_0|_{\Gamma_s} = h_0\} \quad (24)$$

with the inner product

$$\langle \Phi_0, \tilde{\Phi}_0 \rangle_{\mathbf{H}} = \langle u_0, \tilde{u}_0 \rangle_{\Omega_f} + \langle \nabla_{\Gamma_s}(h_0), \nabla_{\Gamma_s}(\tilde{h}_0) \rangle_{\Gamma_s} + \langle h_1, \tilde{h}_1 \rangle_{\Gamma_s} \quad (25)$$

$$+ \langle \sigma(w_0), \epsilon(\tilde{w}_0) \rangle_{\Omega_s} + \langle w_0, \tilde{w}_0 \rangle_{\Omega_s} + \langle w_1, \tilde{w}_1 \rangle_{\Omega_s} \quad (26)$$

where

$$\Phi_0 = [u_0, h_0, h_1, w_0, w_1] \in \mathbf{H}; \tilde{\Phi}_0 = [\tilde{u}_0, \tilde{h}_0, \tilde{h}_1, \tilde{w}_0, \tilde{w}_1] \in \mathbf{H} \quad (27)$$

Elimination of Pressure

Elimination of the pressure will be important to formulate the PDE in (20) – (23) as an ODE. To this end, by using the matching velocity condition and u being divergence free it follows p is harmonic, or

$$\Delta p(t) = 0 \text{ in } \Omega_f. \quad (28)$$

Subsequently, by multiplying by $\nu|_{\Gamma_s}$ and using the matching velocity condition the author obtains the following boundary condition for the pressure variable p :

$$p + \frac{\partial p}{\partial \nu} = \operatorname{div} (\nabla(u) + \nabla^T(u)) \cdot \nu|_{\Gamma_s} + [(\nabla u + \nabla^T u) \cdot \nu - \Delta_{\Gamma_s}(h) - \nu \cdot \sigma(w)|_{\Gamma_s}] \cdot \nu|_{\Gamma_s} \quad (29)$$

Since u is divergence free,

$$\frac{\partial p}{\partial \nu} = [\operatorname{div} (\nabla u + \nabla^T u)] \cdot \nu \text{ on } \Gamma_f.$$

Thus the pressure variable $p(t)$, can formally be written pointwise in time as

$$p(t) = \mathcal{P}_1(u(t)) + \mathcal{P}_2(h(t)) + \mathcal{P}_3(w(t))$$

where each $\mathcal{P}_i(\cdot)$ will be given on the next slide.

Elimination of Pressure

$$p(t) = \mathcal{P}_1(u(t)) + \mathcal{P}_2(h(t)) + \mathcal{P}_3(w(t))$$

$$\begin{cases} \Delta \mathcal{P}_1(u) = 0 & \text{in } \Omega_f, \\ \mathcal{P}_1(u) = \operatorname{div} (\nabla(u) + \nabla^T(u)) \cdot \nu|_{\Gamma_s} + [(\nabla u + \nabla^T u)] \cdot \nu \cdot \nu|_{\Gamma_s} & \text{on } \Gamma_s, \\ \frac{\partial \mathcal{P}_1(u)}{\partial \nu} = \operatorname{div} (\nabla(u) + \nabla^T(u)) \cdot \nu|_{\Gamma_f} & \text{on } \Gamma_f, \end{cases} \quad (30)$$

$$\begin{cases} \Delta \mathcal{P}_2(h) = 0 & \text{in } \Omega_f, \\ \mathcal{P}_2(h) = -\Delta_{\Gamma_s}(h) \cdot \nu|_{\Gamma_s} & \text{on } \Gamma_s, \\ \frac{\partial \mathcal{P}_2(h)}{\partial \nu} = 0 & \text{on } \Gamma_f, \end{cases} \quad (31)$$

and

$$\begin{cases} \Delta \mathcal{P}_3(w) = 0 & \text{in } \Omega_f, \\ \mathcal{P}_3(w) = -[\nu \cdot \sigma(w)|_{\Gamma_s}] \cdot \nu|_{\Gamma_s} & \text{on } \Gamma_s, \\ \frac{\partial \mathcal{P}_3(w)}{\partial \nu} = 0 & \text{on } \Gamma_f. \end{cases} \quad (32)$$

Also note

$$p_0 = \mathcal{P}_1(u_0) + \mathcal{P}_2(h_0) + \mathcal{P}_3(w_0). \quad (33)$$

Functional Settings

It follows, the PDE system given in (20) – (23) may be associated with an abstract ODE in the Hilbert space \mathbf{H} ; namely,

$$\begin{cases} \frac{d}{dt} \Phi(t) = \mathbf{A} \Phi(t) \\ \Phi(0) = \Phi_0 \end{cases} \quad (34)$$

where $\Phi(t) = [u(t), h(t), h_t(t), w(t), w_1(t)]$, and $\Phi_0 = [u_0, h_0, h_1, w_0, w_1]$. Here, the operator $\mathbf{A} : D(\mathbf{A}) \subseteq \mathbf{H} \rightarrow \mathbf{H}$ is defined by

$$\mathbf{A} = \begin{bmatrix} \operatorname{div} (\nabla(\cdot) + \nabla^T(\cdot)) & 0 & 0 & 0 & 0 \\ 0 & 0 & I & 0 & 0 \\ -[\nu \cdot (\nabla(\cdot) + \nabla^T(\cdot))] |_{\Gamma_s} & \Delta_{\Gamma_s}(\cdot) & 0 & \nu \cdot \sigma(\cdot) |_{\Gamma_s} & 0 \\ 0 & 0 & 0 & 0 & I \\ 0 & 0 & 0 & \operatorname{div} \sigma(\cdot) - I & 0 \end{bmatrix} + \begin{bmatrix} -\nabla \mathcal{P}_1(\cdot) & -\nabla \mathcal{P}_2(\cdot) & 0 & -\nabla \mathcal{P}_3(\cdot) & 0 \\ 0 & 0 & 0 & 0 & 0 \\ \mathcal{P}_1(\cdot) \nu & \mathcal{P}_2(\cdot) \nu & 0 & \mathcal{P}_3(\cdot) \nu & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \quad (35)$$

Here, the “pressure” operators \mathcal{P}_i are as defined above.

The domain $D(\mathbf{A})$ of the generator \mathbf{A} is characterized as follows

$$[u_0, h_0, h_1, w_0, w_1] \in D(\mathbf{A}) \Leftrightarrow$$

$$(\mathbf{A.i}) \quad u_0 \in [H^1(\Omega_f)]^3, \quad h_1 \in [H^1(\Gamma_s)]^2, \quad w_1 \in [H^1(\Omega_s)]^3;$$

(**A.ii**) There exists an associated $L^2(\Omega_f)$ -function $p_0 = p_0(u_0, h_0, w_0)$ such that

$$[\operatorname{div} (\nabla u_0 + \nabla^T u_0) - \nabla p_0] \in L^2(\Omega_f)$$

Consequently, p_0 is harmonic and so one has the boundary traces

$$(\mathbf{a}) \quad \left[p_0|_{\Gamma_f}, \frac{\partial p_0}{\partial \nu}|_{\Gamma_f} \right] \in H^{-1/2}(\Gamma_f) \times H^{-3/2}(\Gamma_f);$$

$$(\mathbf{b}) \quad (\nabla u_0 + \nabla^T u_0) \cdot \nu \in H^{-3/2}(\Gamma_f),$$

$$(\mathbf{A.iii}) \quad \operatorname{div} \sigma(w_0) \in L^2(\Omega_s); \text{ consequently, } \nu \cdot \sigma \in H^{-1/2}(\Gamma_s),$$

$$(\mathbf{A.iv}) \quad \Delta_{\Gamma_s}(h_0) + [\nu \cdot \sigma(w_0)]_{\Gamma_s} - [(\nabla u_0 + \nabla^T u_0) \cdot \nu]_{\Gamma_s} + [p_0 \nu]_{\Gamma_s} \in L^2(\Gamma_s),$$

$$(\mathbf{A.v}) \quad u_0|_{\Gamma_f} = 0, \quad u_0|_{\Gamma_s} = h_1 = w_1|_{\Gamma_s}$$

Theorem ((Wellposedness) PGG [JEE, 2024])

With reference to the problem (20) – (23), the operator $\mathbf{A} : D(\mathbf{A}) \subseteq \mathbf{H} \rightarrow \mathbf{H}$, defined in (35), generates a C_0 -semigroup of contractions on \mathbf{H} . Consequently, the solution $\Phi(t) = [u(t), h(t), h_t(t), w(t), w_t(t)]$ of (20) – (23), or equivalently (34), is given by

$$\Phi(t) = e^{\mathbf{A}t} \Phi_0 \in C([0, T]; \mathbf{H}),$$

where $\Phi_0 = [u_0, h_0, h_1, w_0, w_1] \in D(\mathbf{A})$.

Geredeli, P.G. An inf-sup approach to C_0 -semigroup generation for an interactive composite structure-Stokes PDE dynamics. J. Evol. Equ. 24, 50 (2024).
<https://doi.org/10.1007/s00028-024-00978-3>

Similarly, wellposedness was shown using the Lumer-Phillips Theorem as the problem is still linear. They showed

- \mathbf{A} is dissipative
- Show that \mathbf{A} is maximally dissipative using Babuska-Brezzi to solve to the static resolvent equation $(\lambda I - \mathbf{A})\Phi = \Phi^*$ for $\Phi \in D(\mathbf{A})$

Similar to the previous model, the authors shows \mathbf{A} is maximally dissipative. It follows, given data Φ in $D(\mathbf{A})$,

$$\begin{aligned}\langle \mathbf{A}\Phi, \Phi \rangle_{\mathbf{H}} = & -\frac{1}{2} \left\| \nabla(u_0) + \nabla^T(u_0) \right\|^2 + 2i \operatorname{Im} \left[\langle \nabla_{\Gamma_s}(h_1), \nabla_{\Gamma_s}(h_0) \rangle_{\Gamma_s} \right. \\ & + \langle \sigma(w_1), \epsilon(w_0) \rangle_{\Omega_s} \\ & \left. + \langle w_1, w_0 \rangle_{\Omega_s} + \langle \sigma(w_1), \epsilon(w_0) \rangle_{\Omega_s} + \langle w_1, w_0 \rangle_{\Omega_s} \right]\end{aligned}$$

which gives $\operatorname{Re} \langle \mathbf{A}\Phi, \Phi \rangle_{\mathbf{H}} \leq 0$. Since Φ was arbitrary, it follows that \mathbf{A} is dissipative.

The author solves the following static problem to show \mathbf{A} is maximal with the Babuska-Brezzi Theorem. Suppose $\Phi \in D(\mathbf{A})$ is a solution of the equation

$$(\lambda I - \mathbf{A})\Phi = \Phi^*, \quad (36)$$

where $\lambda > 0$, $\Phi = [u_0, h_0, h_1, w_0, w_1]$, and $\Phi^* = [u_0^*, h_0^*, h_1^*, w_0^*, w_1^*] \in \mathbf{H}$.

Theorem (Babuska-Brezzi)

Let Σ , V be Hilbert spaces and $a : \Sigma \times \Sigma \rightarrow \mathbb{R}$, $b : \Sigma \times V \rightarrow \mathbb{R}$, bilinear forms which are continuous. Let

$$Z = \{\sigma \in \Sigma \mid b(\sigma, v) = 0, \text{ for every } v \in V\}.$$

Assume that $a(\cdot, \cdot)$ is Z -elliptic, i.e. there exists a constant $\alpha > 0$ such that

$$a(\sigma, \sigma) \geq \alpha \|\sigma\|_{\Sigma}^2, \text{ for every } \sigma \in Z.$$

Assume further that there exists a constant $\beta > 0$ such that

$$\sup_{\tau \in \Sigma} \frac{b(\tau, v)}{\|\tau\|_{\Sigma}} \geq \beta \|v\|_V.$$

Then if $\kappa \in \Sigma$ and $l \in V$, there exists a unique pair $(\sigma, u) \in \Sigma \times V$ such that

$$\begin{aligned} a(\sigma, \tau) + b(\tau, u) &= \langle \kappa, \tau \rangle_{\Sigma}, \quad \text{for every } \tau \in \Sigma \\ b(\sigma, v) &= \langle l, v \rangle_V, \quad \text{for every } v \in V. \end{aligned} \tag{37}$$

In PDE terms, the resolvent equation will generate the following relations, where p_0 is given via (33):

$$\begin{cases} \lambda u_0 - \operatorname{div} (\nabla u_0 + \nabla^T u_0) + \nabla p_0 = u_0^* \text{ in } \Omega_f \\ \operatorname{div} (u_0) = 0 \text{ in } \Omega_f \\ u_0|_{\Gamma_f} = 0 \text{ on } \Gamma_f; \end{cases} \quad (38)$$

$$\begin{cases} \lambda h_0 - h_1 = h_0^* \text{ in } \Gamma_s \\ \lambda h_1 + [\nu \cdot (\nabla u_0 + \nabla^T u_0)]|_{\Gamma_s} - \Delta_{\Gamma_s}(h_0) - [\nu \cdot \sigma(w_0)]|_{\Gamma_s} - p_0 \nu = h_1^* \text{ in } \Gamma_s \end{cases} \quad (39)$$

$$\begin{cases} \lambda w_0 - w_1 = w_0^* \text{ in } \Omega_s \\ \lambda w_1 - \operatorname{div} \sigma(w_0) + w_0 = w_1^* \text{ in } \Omega_s \\ w_1|_{\Gamma_s} = h_1 = u_0|_{\Gamma_s} \text{ on } \Gamma_s \end{cases} \quad (40)$$

The author used the following outline

- Solve the decomposed stokes flow for \mathbf{u} and p
- Generate a weak formulation for the “thin” (h_1) and “thick” (w_1) variables
- Recover of the other structure solution variables h_0 and w_0 given data $h_0^* \in H^1(\Gamma_s)$ and $w_0^* \in H^1(\Omega_s)$; i.e.

$$h_0 = \frac{1}{\lambda} h_1 + \frac{1}{\lambda} h_0^* \quad (41)$$

$$w_0 = \frac{1}{\lambda} w_1 + \frac{1}{\lambda} w_0^* \quad (42)$$

Decomposition of Stokes Flow

Decomposition of the Stokes flow into two parts

Zero force and Dirichlet boundary data $g \in H^{1/2}(\Gamma_s)$: solution is $[u_1(g), p_1(g)]$

$$\begin{cases} \lambda u_1 - \operatorname{div} (\nabla u_1 + \nabla^T u_1) + \nabla p_1 = 0 & \text{in } \Omega_f \\ \operatorname{div} (u_1) = \frac{\int_{\Gamma_s} (g \cdot \nu) d\Gamma_s}{\operatorname{meas}(\Omega_f)} & \text{in } \Omega_f \\ u_1|_{\Gamma_s} = g & \text{on } \Gamma_s \\ u_1|_{\Gamma_f} = 0 & \text{on } \Gamma_f, \end{cases} \quad (43)$$

With force term u_0^* , zero Dirichlet data and zero divergence: solution is $[u_2(u_0^*), p_2(u_0^*)]$

$$\begin{cases} \lambda u_2 - \operatorname{div} (\nabla u_2 + \nabla^T u_2) + \nabla p_2 = u_0^* & \text{in } \Omega_f \\ \operatorname{div} (u_2) = 0 & \text{in } \Omega_f \\ u_2|_{\Gamma_f} = 0 & \text{on } \Gamma_f \end{cases} \quad (44)$$

The unique $\{u_0, p_0\}$ of (38) may then be expressed as

$$u_0 = u_1(g|_{\Gamma_s}) + u_2(u_0^*); \quad p_0 = p_1(g|_{\Gamma_s}) + p_2(u_0^*) + c_0, \quad (45)$$

where c_0 is the (presently) unknown constant component of the pressure p_0 of (38).

Define the space

$$\mathbf{S} = \{(\varphi, \psi) \in [H^1(\Gamma_s)]^2 \times [H^1(\Omega_s)]^3 \mid \varphi = \psi|_{\Gamma_s}\}.$$

The last relation now gives us the following mixed variational formulation in terms of the “thin” and “thick” structure variables h_1 and w_1 : Namely,

$$\begin{aligned} \mathbf{a}([h_1, w_1], [\varphi, \psi]) + \mathbf{b}([\varphi, \psi], c_0) &= \mathbf{F}([\varphi, \psi]), \text{ for all } [\varphi, \psi] \in \mathbf{S} \\ \mathbf{b}([h_1, w_1], r) &= 0, \text{ for all } r \in \mathbb{R}. \end{aligned} \quad (46)$$

Where

$\mathbf{a}(\cdot, \cdot) : \mathbf{S} \times \mathbf{S} \rightarrow \mathbb{R}$, $\mathbf{b}(\cdot, \cdot) : \mathbf{S} \times \mathbb{R} \rightarrow \mathbb{R}$, and the functional $\mathbf{F}(\cdot)$ are defined as follows

$$\begin{aligned} \mathbf{a}([\phi, \xi], [\tilde{\phi}, \tilde{\xi}]) = & \lambda \langle \phi, \tilde{\phi} \rangle_{\Gamma_s} + \frac{1}{\lambda} \langle \nabla_{\Gamma_s} \phi, \nabla_{\Gamma_s} \tilde{\phi} \rangle_{\Gamma_s} \\ & + \lambda \langle \xi, \tilde{\xi} \rangle_{\Omega_s} + \frac{1}{\lambda} \langle \sigma(\xi), \epsilon(\tilde{\xi}) \rangle_{\Omega_s} + \frac{1}{\lambda} \langle \xi, \tilde{\xi} \rangle_{\Omega_s} \\ & + \langle \nabla u_1(\xi|_{\Gamma_s}) + \nabla^T u_1(\xi|_{\Gamma_s}), \nabla \tilde{u}(\tilde{\phi}) + \nabla^T \tilde{u}(\tilde{\phi}) \rangle_{\Omega_f} \\ & + \lambda \langle u_1(\xi|_{\Gamma_s}), \tilde{u}(\tilde{\phi}) \rangle_{\Omega_f}, \end{aligned}$$

$$\mathbf{b}([\tilde{\phi}, \tilde{\xi}], r) = -r \langle v, \tilde{\phi} \rangle_{\Gamma_s},$$

and

$$\begin{aligned} \mathbf{F}([\tilde{\phi}, \tilde{\xi}]) = & - \langle \nabla u_2(u_0^*) + \nabla^T u_2(u_0^*), \nabla \tilde{u}(\tilde{\phi}) + \nabla^T \tilde{u}(\tilde{\phi}) \rangle_{\Omega_f} \\ & - \frac{1}{\lambda} \langle \nabla_{\Gamma_s} h_0^*, \nabla_{\Gamma_s} \tilde{\phi} \rangle_{\Gamma_s} - \frac{1}{\lambda} \langle \sigma(w_0^*), \epsilon(\tilde{\xi}) \rangle_{\Omega_s} \\ & - \lambda \langle u_2(u_0^*), \tilde{u}(\tilde{\phi}) \rangle_{\Omega_f} + \langle u_0^*, \tilde{u}(\tilde{\phi}) \rangle_{\Omega_f} \\ & + \langle h_1^*, \tilde{\phi} \rangle_{\Gamma_s} + \langle w_1^*, \tilde{\xi} \rangle_{\Omega_s} - \frac{1}{\lambda} \langle w_0^*, \tilde{\xi} \rangle_{\Omega_s}. \end{aligned}$$

inf sup condition

Given $r \in \mathbb{R}$, let $z \in [H^1(\Gamma_s)]^2$ satisfy

$$\Delta_{\Gamma_s} z = \operatorname{sgn}(r) \nu \text{ on } \Gamma_s$$

It is easily seen that $\|\nabla_{\Gamma_s} z\|_{\Gamma_s} \leq C \|\nu\|_{\Gamma_s}$. Now, taking into account that $\gamma : H^1(\Omega_s) \rightarrow H^{1/2}(\Gamma_s)$ is a surjective map, and so it has a continuous right inverse $\gamma^+(z)$, we have

$$\begin{aligned} \sup_{[\eta, \varsigma]} \frac{\mathbf{b}([\eta, \varsigma], r)}{\|[\eta, \varsigma]\|_{\mathbf{S}}} &\geq \frac{\mathbf{b}([z, \gamma^+(z)], r)}{\|z\|_{[H^1(\Gamma_s)]^2}} \\ &= \frac{-r \int_{\Gamma_s} \nu \cdot z d\Gamma_s}{\|z\|_{[H^1(\Gamma_s)]^2}} \\ &= -r \operatorname{sgn}(r) \frac{\int_{\Gamma_s} \Delta_{\Gamma_s} z \cdot z d\Gamma_s}{\|z\|_{[H^1(\Gamma_s)]^2}} \\ &= |r| \frac{\int_{\Gamma_s} |\nabla_{\Gamma_s} z|^2 d\Gamma_s}{\|z\|_{[H^1(\Gamma_s)]^2}} \\ &= |r| \|z\|_{[H^1(\Gamma_s)]^2} \end{aligned}$$

which yields that the inf-sup condition holds with the constant $\beta = \|z\|_{[H^1(\Gamma_s)]^2}$.

By the Babuska-Brezzi Theorem, it is then shown that this unique solution is in $D(\mathbf{A})$.

Part II

Stability Types

- Strong Stability
- Polynomial Stability
- Exponential Stability

Theorem ((Strong Stability) G. Avalos, PGG, B. Muha [JDE, 2020])

For the modeling generator $\mathbf{A} : D(\mathbf{A}) \subseteq \mathbf{H} \rightarrow \mathbf{H}$ of (1) – (4), one has $\sigma(\mathbf{A}) \cap i\mathbb{R} = \emptyset$. Consequently, the C_0 -semigroup $\{e^{\mathbf{A}t}\}_{t \geq 0}$ given in Theorem 1 is strongly stable. That is, the solution $\Phi(t)$ of the PDE (1) – (4) tends asymptotically to the zero state for all initial data $\Phi_0 \in \mathbf{H}$

G. Avalos, P. G. Geredeli, B. Muha; “Wellposedness, Spectral Analysis and Asymptotic Stability of a Multilayered Heat-Wave-Wave System”, Journal of Differential Equations 269 (2020), pp. 7129-7156.

Theorem ((Strong Stability) [Arendt-Batty, 1988])

Let $T(t)_{t \geq 0}$ be a bounded C_0 -semigroup on a reflexive Banach space X , with generator \mathbf{A} . Assume that $\sigma_p(\mathbf{A}) \cap i\mathbb{R} = \emptyset$, where $\sigma_p(\mathbf{A})$ is the point spectrum of \mathbf{A} . If $\sigma(\mathbf{A}) \cap i\mathbb{R}$ is countable then $T(t)_{t \geq 0}$ is strongly stable.

Recall: $\sigma(\mathbf{A}) = \sigma_p(\mathbf{A}) \cup \sigma_c(\mathbf{A}) \cup \sigma_r(\mathbf{A})$

Note that $\sigma(\mathbf{A}) \cap i\mathbb{R} = \emptyset$ is equivalent to showing $i\mathbb{R} \subseteq \rho(\mathbf{A})$

To this end the authors checked

- $0 \in \rho(\mathbf{A})$
- The continuous spectrum
- The eigenvalues of \mathbf{A}^*

Given $\Phi^* = [u_0^*, h_{01}^*, h_{11}^*, \dots, h_{0K}^*, h_{1K}^*, w_0^*, w_1^*] \in \mathbf{H}$, the problem is to find $\Phi = [u_0, h_{01}, h_{11}, \dots, h_{0K}, h_{1K}, w_0, w_1] \in D(\mathbf{A})$ which solves

$$\mathbf{A}\Phi = \Phi^* \quad (47)$$

It follows

$$w_1 = w_0^* \in H^1(\Omega_s) \quad (48)$$

$$h_{1j} = h_{0j}^* \in H^1(\Gamma_j), \text{ for } 1 \leq j \leq K \quad (49)$$

and

$$\begin{cases} \Delta u_0 = u_0^* \\ u_0|_{\Gamma_f} = 0 \\ u_0|_{\Gamma_s} = w_0^*|_{\Gamma_s} \end{cases} \quad (50)$$

Recall the set (to be used on the next slide)

$$\begin{aligned} \mathcal{V} = \{ & [\psi_1, \dots, \psi_K] \in H^1(\Gamma_1) \times \dots \times H^1(\Gamma_K) \mid \text{For all } 1 \leq j \leq K, \\ & \psi_j|_{\partial\Gamma_j \cap \partial\Gamma_l} = \psi_l|_{\partial\Gamma_j \cap \partial\Gamma_l}, \text{ for all } 1 \leq l \leq K \text{ such that } \partial\Gamma_j \cap \partial\Gamma_l \neq \emptyset \} \end{aligned} \quad (51)$$

And define the set

$$\chi \equiv \left\{ [\psi, \xi] \in \mathcal{V} \times H^1(\Omega_s) \mid \psi_j = \xi|_{\Gamma_j} \text{ for } 1 \leq j \leq K \right\}. \quad (52)$$

Testing with these equations, it follows

$$\begin{aligned} & \langle \nabla w_0, \nabla \xi \rangle_{\Omega_s} + \sum_{j=1}^K \left[\langle \nabla h_{0j}, \nabla \psi_j \rangle_{\Gamma_j} + \langle h_{0j}, \psi_j \rangle_{\Gamma_j} \right] \\ &= - \langle w_1^*, \xi \rangle_{\Omega_s} - \sum_{j=1}^K \left[\langle h_{1j}^*, \psi_j \rangle_{\Gamma_j} + \left\langle \frac{\partial u_0}{\partial \nu}, \psi_j \right\rangle_{\Gamma_j} \right], \end{aligned} \quad (53)$$

Since the bilinear form $b(\cdot, \cdot) : \chi \rightarrow \mathbb{R}$, given by

$$b([\psi, \xi], [\tilde{\psi}, \tilde{\xi}]) = \langle \nabla \xi, \nabla \tilde{\xi} \rangle_{\Omega_s} + \sum_{j=1}^K \left[\langle \nabla \psi_j, \nabla \tilde{\psi}_j \rangle_{\Gamma_j} + \langle \psi_j, \tilde{\psi}_j \rangle_{\Gamma_j} \right] \quad (54)$$

for every $[\psi, \xi], [\tilde{\psi}, \tilde{\xi}] \in \chi$, is continuous and χ -elliptic, then by Lax-Milgram, there exists a unique solution

$$\varphi = [(h_{01}, h_{02}, \dots, h_{0K}), w_0] \in \chi \quad (55)$$

(Then shown to be in $D(\mathbf{A})$)

$$\beta, i\beta \notin \sigma_c(\mathbf{A}), \beta \neq 0$$

Assume to the contrary. Then since $\sigma_c(\mathbf{A}) \subseteq \sigma_{\text{app}}(\mathbf{A})$ there exists a sequence $\{\Phi_n\} = \{[u_n, h_{1n}, \xi_{1n}, \dots, h_{Kn}, \xi_{Kn}, w_{0n}, w_{1n}]\} \subseteq D(\mathbf{A})$ which satisfy for $n \in \mathbb{N}$

$$\|\Phi_n\|_{\mathbf{H}} = 1 \text{ and } \|(i\beta I - \mathbf{A})\Phi_n\|_{\mathbf{H}} < \frac{1}{n}$$

$$\beta, i\beta \notin \sigma_r(\mathbf{A}), \beta \neq 0$$

It is known that for a closed and densely defined operator \mathbf{A} , if $\lambda \in \sigma_r(\mathbf{A})$ then $\bar{\lambda} \in \sigma_p(\mathbf{A}^*)$. It follows

$\mathbf{A}^* : D(\mathbf{A}^*) \subseteq \mathbf{H} \rightarrow \mathbf{H}$ is given by

$$\mathbf{A}^* = \begin{bmatrix} \Delta & 0 & 0 & \dots & 0 & 0 & 0 & 0 \\ 0 & 0 & -I & \dots & 0 & 0 & 0 & 0 \\ -\frac{\partial}{\partial \nu}|_{\Gamma_1} & (I - \Delta) & 0 & \dots & 0 & 0 & -\frac{\partial}{\partial \nu}|_{\Gamma_1} & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 0 & -I & 0 & 0 \\ -\frac{\partial}{\partial \nu}|_{\Gamma_K} & 0 & 0 & \dots & (I - \Delta) & 0 & -\frac{\partial}{\partial \nu}|_{\Gamma_K} & 0 \\ 0 & 0 & 0 & \dots & 0 & 0 & 0 & -I \\ 0 & 0 & 0 & \dots & 0 & 0 & -\Delta & 0 \end{bmatrix};$$

$D(\mathbf{A}) = D(\mathbf{A}^*)$, $i\beta$ is not an eigenvalue of \mathbf{A}^* so $i\beta \notin \sigma_r(\mathbf{A})$

By the spectral analysis, the authors concluded there is strong stability for any initial data in $D(\mathbf{A})$.

Theorem ((Strong Stability) PGG [JDE, 2025])

With reference to problem (20) – (23), zero is an eigenvalue for the generator $\mathbf{A} : D(\mathbf{A}) \subseteq \mathbf{H} \rightarrow \mathbf{H}$. Consequently the solution $\{e^{\mathbf{A}t}\}|_{[Null(\mathbf{A})]^\perp}$ decays to the zero state for any initial data $\Phi_0 = [u_0, h_0, h_1, w_0, w_1] \in [Null(\mathbf{A})]^\perp$.

Pelin G. Geredeli, Spectral analysis and asymptotic decay of the solutions to multilayered structure-Stokes fluid interaction PDE system, Journal of Differential Equations, Volume 427, 2025, Pages 1-25, ISSN 0022-0396, <https://doi.org/10.1016/j.jde.2025.01.080>.

As a reminder

Theorem ((Strong Stability) [Arendt-Batty, 1988])

Let $T(t)_{t \geq 0}$ be a bounded C_0 -semigroup on a reflexive Banach space X , with generator \mathbf{A} . Assume that $\sigma_p(\mathbf{A}) \cap i\mathbb{R} = \emptyset$, where $\sigma_p(\mathbf{A})$ is the point spectrum of \mathbf{A} . If $\sigma(\mathbf{A}) \cap i\mathbb{R}$ is countable then $T(t)_{t \geq 0}$ is strongly stable.

It is then checked

- Zero is an eigenvalue
- The continuous spectrum
- The eigenvalues of \mathbf{A}^*

Zero is an Eigenvalue

For $\Phi = [u_0, h_0, h_1, w_0, w_1] \in D(\mathbf{A})$, it follows $\mathbf{A}\Phi = 0$ implies

$$\operatorname{div}(\nabla u_0 + \nabla^T u_0) - \nabla p = 0 \text{ in } \Omega_f$$

$$\boxed{h_1 = 0} \text{ in } \Gamma_s$$

$$-\nu \cdot (\nabla u_0 + \nabla^T u_0)|_{\Gamma_s} + \Delta_{\Gamma_s}(h_0) + \nu \cdot \sigma(w_0)|_{\Gamma_s} + p\nu = 0 \text{ in } \Gamma_s$$

$$\boxed{w_1 = 0} \text{ in } \Omega_s$$

$$\operatorname{div} \sigma(w_0) - w_0 = 0 \text{ in } \Omega_s$$

Dissipativity shows

$$0 = \operatorname{Re} \langle \mathbf{A}\Phi, \Phi \rangle = \frac{1}{2} \|\nabla u_0 + \nabla^T u_0\|^2 \implies \boxed{u_0 = 0}$$

$$\boxed{p = c_0 = \text{constant}}$$

Zero is an Eigenvalue

Define $S = \{[f, g] \in H^1(\Gamma_s) \times H^1(\Omega_s) \mid f = g|_{\Gamma_s}\}$.

Testing the previous equations with f, g ,

$$\begin{aligned}\mathbf{B}([h_0, w_0], [f, g]) &= \langle \nabla_{\Gamma_s}(h_0), \nabla_{\Gamma_s}(f) \rangle_{\Gamma_s} + \langle \sigma(w_0), \epsilon(g) \rangle_{\Omega_s} + \langle w_0, g \rangle_{\Omega_s} \\ &= \langle c_0 \nu, f \rangle_{\Gamma_s}\end{aligned}$$

As $B(\cdot, \cdot)$ is continuous and S-elliptic, using Lax-Milgram finds $\{h_0, w_0\} \in S$. (Then in $D(\mathbf{A})$)

$$\text{Null}(\mathbf{A}) = \text{Span} \left\{ \begin{bmatrix} 0 \\ h_0 \\ 0 \\ w_0 \\ 0 \end{bmatrix} \right\}$$

$$\text{Null}(\mathbf{A})^\perp = \left\{ [\tilde{u}_0, \tilde{h}_0, \tilde{h}_1, \tilde{w}_0, \tilde{w}_1] \in \mathbf{H} \mid \int_{\Gamma_s} \nu \cdot \tilde{h}_0 d\Gamma_s = 0 \right\}$$

$$\beta, i\beta \notin \sigma_p(\mathbf{A}), \beta \neq 0$$

For $\Phi = [u_0, h_0, h_1, w_0, w_1]$,

$$[i\beta I - \mathbf{A}]\Phi = 0$$

Thus we see there is an overdetermined eigenvalue problem

$$-\beta^2 w_0 - \operatorname{div} \sigma(w_0) + w_0 = 0 \text{ in } \Omega_s$$

$$w_0|_{\Gamma_s} = 0 \text{ on } \Gamma_s$$

$$\nu \cdot \sigma(w_0) = -c_0 \nu \text{ on } \Gamma_s$$

Assumption for (fixed) given β , assume that the only solution to the above overdetermined problem is $w_0 = 0$ (and necessarily $c_0 = 0$).

$$\beta, i\beta \notin \sigma_c(\mathbf{A}), \beta \neq 0$$

Assume to the contrary. Then since $\sigma_c(\mathbf{A}) \subseteq \sigma_{\text{app}}(\mathbf{A})$ there exists a sequence $\{\Phi_n\} = \{[u_{0n}, h_{0n}, h_{1n}, w_{0n}, w_{1n}]\} \subseteq D(\mathbf{A})$ such that

$$\|\Phi_n\| = 1 \text{ and } \|(i\beta I - \mathbf{A})\Phi_n\|_{\mathbf{H}} < \frac{1}{n}$$

$$\beta, i\beta \notin \sigma_r(\mathbf{A}), \beta \neq 0$$

It is known that for a closed and densely defined operator \mathbf{A} , if $\lambda \in \sigma_r(\mathbf{A})$ then $\bar{\lambda} \in \sigma_p(\mathbf{A}^*)$. It follows

$\mathbf{A}^* : D(\mathbf{A}^*) \subseteq \mathbf{H} \rightarrow \mathbf{H}$ is given by

$$\mathbf{A}^* = \begin{bmatrix} \operatorname{div}(\nabla(\cdot) + \nabla^T(\cdot)) & 0 & 0 & 0 & 0 \\ 0 & 0 & -I & 0 & 0 \\ -[\nu \cdot (\nabla(\cdot) + \nabla^T(\cdot))]|_{\Gamma_s} & -\Delta_{\Gamma_s}(\cdot) & 0 & -\nu \cdot \sigma(\cdot)|_{\Gamma_s} & 0 \\ 0 & 0 & 0 & 0 & -I \\ 0 & 0 & 0 & -\operatorname{div} \sigma(\cdot) + I & 0 \end{bmatrix} + \begin{bmatrix} -\nabla \mathcal{P}_1(\cdot) & \nabla \mathcal{P}_2(\cdot) & 0 & \nabla \mathcal{P}_3(\cdot) & 0 \\ 0 & 0 & 0 & 0 & 0 \\ \mathcal{P}_1(\cdot)\nu & -\mathcal{P}_2(\cdot)\nu & 0 & -\mathcal{P}_3(\cdot)\nu & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \quad (56)$$

$D(\mathbf{A}) = D(\mathbf{A}^*)$, $i\beta$ is not an eigenvalue of \mathbf{A}^* so $i\beta \notin \sigma_r(\mathbf{A})$

It is important to note that $0 \in \rho(\mathbf{A}|_{\text{Null}(\mathbf{A})^\perp})$. In other words, the resolvent of $\mathbf{A}|_{\text{Null}(\mathbf{A})^\perp}$.

By the spectral analysis, the author showed that there is strong stability for any initial data taken in $\text{Null}(\mathbf{A})^\perp$.

Topics

- Stokes Model polynomial decay
- Lack of exponential decay
- Navier-Stokes model

Thank You!