

# MASTER PROJECT: Qualitative Properties of the Multilayered Structure - Fluid Interactions Coupled PDE Systems

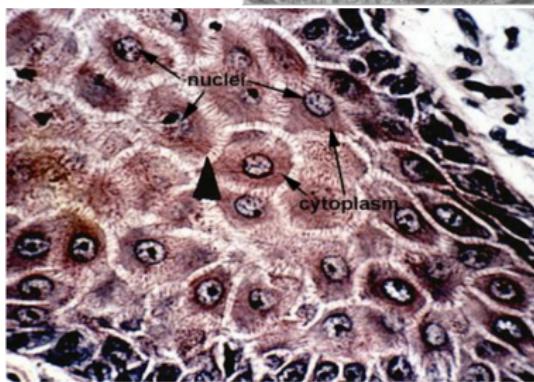
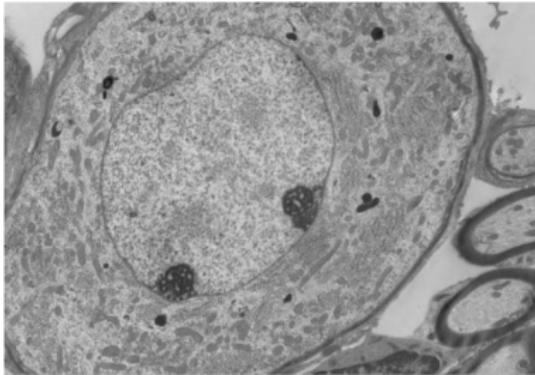
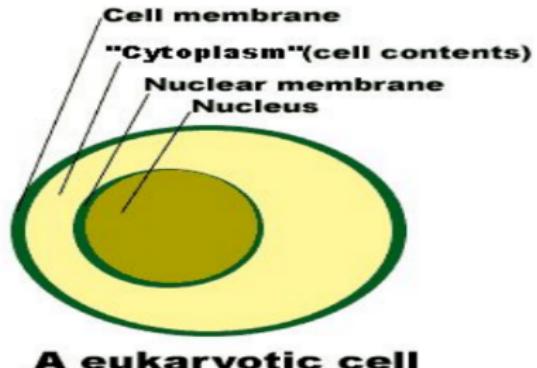
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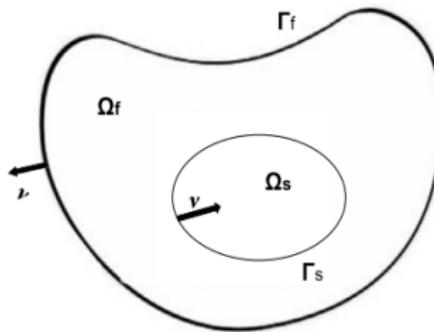
October 16, 2025

# Motivation



## Geometry

- $\Omega_f \subseteq \mathbb{R}^3$ , Lipschitz bounded domain
- $\Omega_s \subseteq \mathbb{R}^3$ ,  $\Omega_s \subset\subset \Omega_f$
- $\partial\Omega_s = \Gamma_s$
- $\partial\Omega_f = \Gamma_s \cup \Gamma_f$



# Introduction of First Model

$$\begin{cases} u_t - \Delta u = 0 \text{ in } (0, T) \times \Omega_f \\ u|_{\Gamma_f} = 0 \text{ on } (0, T) \times \Gamma_f; \end{cases} \quad (1)$$

$$\begin{cases} \frac{\partial^2}{\partial t^2} h_j - \Delta h_j + h_j = \frac{\partial w}{\partial \nu}|_{\Gamma_j} - \frac{\partial u}{\partial \nu}|_{\Gamma_j} \text{ on } (0, T) \times \Gamma_j \\ h_j|_{\partial \Gamma_j \cap \partial \Gamma_I} = h_I|_{\partial \Gamma_j \cap \partial \Gamma_I} \text{ on } (0, T) \times (\partial \Gamma_j \cap \partial \Gamma_I), \text{ for all } 1 \leq I \leq K \\ \text{such that } \partial \Gamma_j \cap \partial \Gamma_I \neq \emptyset \\ \left. \frac{\partial h_j}{\partial \eta_j} \right|_{\partial \Gamma_j \cap \partial \Gamma_I} = - \left. \frac{\partial h_I}{\partial \eta_I} \right|_{\partial \Gamma_j \cap \partial \Gamma_I} \text{ on } (0, T) \times (\partial \Gamma_j \cap \partial \Gamma_I), \text{ for all } 1 \leq I \leq K \\ \text{such that } \partial \Gamma_j \cap \partial \Gamma_I \neq \emptyset \end{cases} \quad (2)$$

$$\begin{cases} w_{tt} - \Delta w = 0 \text{ on } (0, T) \times \Omega_s \\ w_t|_{\Gamma_j} = \frac{\partial}{\partial t} h_j = u|_{\Gamma_j} \text{ on } (0, T) \times \Gamma_j, \text{ for } j = 1, \dots, K \end{cases} \quad (3)$$

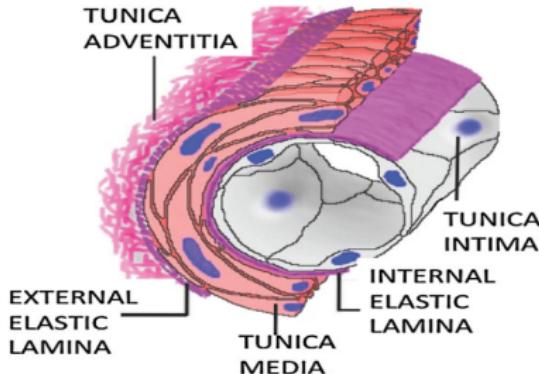
$$\begin{aligned} [u(0), h_1(0), \frac{\partial}{\partial t} h_1(0), \dots, h_K(0), \frac{\partial}{\partial t} h_K(0), w(0), w_t(0)] \\ = [u_0, h_{01}, h_{11}, \dots, h_{0K}, h_{1K}, w_0, w_1] \end{aligned} \quad (4)$$

where  $\Gamma_s = \cup_{j=1}^K \overline{\Gamma_j}$  and  $\Gamma_i \cap \Gamma_j = \emptyset$ , for  $i \neq j$ .

# Earlier Works

Generally, single layered or moving boundary FSI Systems

- George Avalos
- Lorena Bociu
- Scott Hansen
- Igor Kukavica
- Irena Lasiecka
- Hyesuk Lee
- Roberto Triggiani
- Amjad Tuffaha
- Justin Webster
- Enrique Zuazua
- etc.



- 2014, Fluid-Multi-layered-structure Interaction, Existence of weak solutions
- 2015, Regularity and Regularization effects of the same problem
- 2015, Numerical Results: unconditional stability for the same problem

# Functional Settings

$$\begin{aligned}\mathbf{H} = & \{[u_0, h_{01}, h_{11}, \dots, h_{0K}, h_{1K}, w_0, w_1] \in L^2(\Omega_f) \times H^1(\Gamma_1) \times L^2(\Gamma_1) \times \dots \\ & \times H^1(\Gamma_K) \times L^2(\Gamma_K) \times H^1(\Omega_s) \times L^2(\Omega_s), \text{ such that for each } 1 \leq j \leq K : \\ & (i) w_0|_{\Gamma_j} = h_{0j}; \\ & (ii) h_{0j}|_{\partial\Gamma_j \cap \partial\Gamma_l} = h_{0l}|_{\partial\Gamma_j \cap \partial\Gamma_l} \text{ on } \partial\Gamma_j \cap \partial\Gamma_l, \text{ for all } 1 \leq l \leq K \text{ such that} \\ & \partial\Gamma_j \cap \partial\Gamma_l \neq \emptyset\}\end{aligned}\tag{5}$$

With the accompanying inner product

$$\begin{aligned}\langle \Phi_0, \tilde{\Phi}_0 \rangle_{\mathbf{H}} = & \langle u_0, \tilde{u}_0 \rangle_{\Omega_f} + \sum_{j=1}^K \left\langle \nabla h_{0j}, \nabla \tilde{h}_{0j} \right\rangle_{\Gamma_j} + \sum_{j=1}^K \left\langle h_{0j}, \tilde{h}_{0j} \right\rangle_{\Gamma_j} \\ & + \sum_{j=1}^K \left\langle h_{1j}, \tilde{h}_{1j} \right\rangle_{\Gamma_j} + \langle \nabla w_0, \nabla \tilde{w}_0 \rangle_{\Omega_s} + \langle w_1, \tilde{w}_1 \rangle_{\Omega_s}\end{aligned}\tag{6}$$

where

$$\begin{aligned}\Phi_0 &= [u_0, h_{01}, h_{11}, \dots, h_{0K}, h_{1K}, w_0, w_1] \in \mathbf{H} \text{ and} \\ \tilde{\Phi}_0 &= [\tilde{u}_0, \tilde{h}_{01}, \tilde{h}_{11}, \dots, \tilde{h}_{0K}, \tilde{h}_{1K}, \tilde{w}_0, \tilde{w}_1] \in \mathbf{H}.\end{aligned}$$

# Functional Settings

For the PDE system given in (1) – (4) if

$\Phi(t) = [u, h_1, \frac{\partial}{\partial t} h_1, \dots, h_K, \frac{\partial}{\partial t} h_K, w, w_1] \in C([0, T]; \mathbf{H})$  then for  
 $\mathbf{A} : D(\mathbf{A}) \subseteq \mathbf{H} \rightarrow \mathbf{H}$ ,

$$\frac{d}{dt} \Phi(t) = \mathbf{A} \Phi(t); \quad \Phi(0) = \Phi_0. \quad (7)$$

where  $\mathbf{A}$  is given as

$$\mathbf{A} = \begin{bmatrix} \Delta & 0 & 0 & \dots & 0 & 0 & 0 & 0 \\ 0 & 0 & I & \dots & 0 & 0 & 0 & 0 \\ -\frac{\partial}{\partial \nu}|_{\Gamma_1} & (\Delta - I) & 0 & \dots & 0 & 0 & \frac{\partial}{\partial \nu}|_{\Gamma_1} & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 0 & I & 0 & 0 \\ -\frac{\partial}{\partial \nu}|_{\Gamma_K} & 0 & 0 & \dots & (\Delta - I) & 0 & \frac{\partial}{\partial \nu}|_{\Gamma_K} & 0 \\ 0 & 0 & 0 & \dots & 0 & 0 & 0 & I \\ 0 & 0 & 0 & \dots & 0 & 0 & \Delta & 0 \end{bmatrix}; \quad (8)$$

# Introduction of First Model

Where the Domain of  $\mathbf{A}$  is given as follows

$$D(\mathbf{A}) = \{[u_0, h_{01}, h_{11}, \dots, h_{0K}, h_{1K}, w_0, w_1] \in \mathbf{H} :$$

(A.i)  $u_0 \in H^1(\Omega_f)$ ,  $h_{1j} \in H^1(\Gamma_j)$  for  $1 \leq j \leq K$ ,  $w_1 \in H^1(\Omega_s)$ ;

(A.ii) (a)  $\Delta u_0 \in L^2(\Omega_f)$ ,  $\Delta w_0 \in L^2(\Omega_s)$ , (b)  $\Delta h_{0j} - \frac{\partial u_0}{\partial \nu} \Big|_{\Gamma_j} + \frac{\partial w_0}{\partial \nu} \Big|_{\Gamma_j} \in L^2(\Gamma_j)$   
for  $1 \leq j \leq K$ ; (c)  $\frac{\partial h_{0j}}{\partial n_j} \Big|_{\partial \Gamma_j} \in H^{-1/2}(\partial \Gamma_j)$ , for  $1 \leq j \leq K$ ;

(A.iii)  $u_0|_{\Gamma_f} = 0$ ,  $u_0|_{\Gamma_j} = h_{1j} = w_1|_{\Gamma_j}$ , for  $1 \leq j \leq K$ ;

(A.iv) For  $1 \leq j \leq K$ :

(a)  $h_{1j}|_{\partial \Gamma_j \cap \partial \Gamma_I} = h_{1I}|_{\partial \Gamma_j \cap \partial \Gamma_I}$  on  $\partial \Gamma_j \cap \partial \Gamma_I$ , for all  $1 \leq I \leq K$  such that

$$\partial \Gamma_j \cap \partial \Gamma_I \neq \emptyset;$$

(b)  $\frac{\partial h_{0j}}{\partial n_j} \Big|_{\partial \Gamma_j \cap \partial \Gamma_I} = -\frac{\partial h_{0I}}{\partial n_I} \Big|_{\partial \Gamma_j \cap \partial \Gamma_I}$  on  $\partial \Gamma_j \cap \partial \Gamma_I$ , for all  $1 \leq I \leq K$

such that  $\partial \Gamma_j \cap \partial \Gamma_I \neq \emptyset\}$ .

(9)

## Part I

# Wellposedness

Theorem ((Wellposedness) G. Avalos, PGG, B. Muha [JDE, 2020])

*The operator  $\mathbf{A} : D(\mathbf{A}) \subseteq \mathbf{H} \rightarrow \mathbf{H}$  defined above generates a  $C_0$ -semigroup of contractions. Consequently, the solution  $\Phi(t) = [u, h_1, \frac{\partial}{\partial t} h_1, \dots, h_K, \frac{\partial}{\partial t} h_K, w, w_1]$  of the PDE model is given by*

$$\Phi(t) = e^{\mathbf{A}t} \Phi_0 \in C([0, T]; \mathbf{H}),$$

*where  $\Phi_0 = [u_0, h_{01}, h_{11}, \dots, h_{0K}, h_{1k}, w_0, w_1] \in D(\mathbf{A})$*

G. Avalos, P. G. Geredeli, B. Muha; "Wellposedness, Spectral Analysis and Asymptotic Stability of a Multilayered Heat-Wave-Wave System ", Journal of Differential Equations 269 (2020), pp. 7129-7156.

## Sketch of Proof

Wellposedness was shown using the Lumer-Phillips Theorem. To this end, they showed

- $\mathbf{A}$  is dissipative; i.e.  $\langle \mathbf{A}\Phi, \Phi \rangle_{\mathbf{H}} \leq 0$  for all  $\Phi \in D(\mathbf{A})$
- Use Lax-Milgram to solve to the static resolvent equation  $(\lambda I - \mathbf{A})\Phi = \Phi^*$  in  $D(\mathbf{A})$ ; i.e.  $\mathbf{A}$  is maximally dissipative
- Recover of the other structure solution variables given initial data; i.e.

$$h_{0j} = \frac{1}{\lambda} h_{1j} + \frac{1}{\lambda} h_{0j}^*, \text{ for } 1 \leq j \leq K,$$
$$w_0 = \frac{1}{\lambda} w_1 + \frac{1}{\lambda} w_0^*.$$

# Dissipativity of $\mathbf{A}$

Given data  $\Phi_0$  in  $D(\mathbf{A})$ ,

$$\begin{aligned} \langle \mathbf{A}\Phi_0, \Phi_0 \rangle_{\mathbf{H}} &= -||\nabla u_0||_{\Omega_f}^2 + 2i \sum_{j=1}^K \operatorname{Im} \langle \nabla h_{1j}, \nabla h_{0j} \rangle_{\Gamma_j} \\ &\quad + 2i \sum_{j=1}^K \operatorname{Im} \langle h_{1j}, h_{0j} \rangle_{\Gamma_j} + 2i \operatorname{Im} \langle \nabla w_1, \nabla w_0 \rangle_{\Omega_s}, \end{aligned} \quad (10)$$

which gives  $\operatorname{Re} \langle \mathbf{A}\Phi_0, \Phi_0 \rangle_{\mathbf{H}} \leq 0$ . Since  $\Phi_0$  was arbitrary, it follows that  $\mathbf{A}$  is dissipative.

# Maximality of $\mathbf{A}$

The author solves the following static problem with the Lax-Milgram Theorem. Given parameter  $\lambda > 0$ , suppose  $\Phi = [u_0, h_{01}, h_{11}, \dots, h_{0K}, h_{1K}, w_0, w_1] \in D(\mathbf{A})$  is a solution of the equation

$$(\lambda I - \mathbf{A})\Phi = \Phi^*, \quad (11)$$

where  $\Phi^* = [u_0^*, h_{01}^*, h_{11}^*, \dots, h_{0K}^*, h_{1K}^*, w_0^*, w_1^*] \in \mathbf{H}$ .

# Maximality of $\mathbf{A}$

In PDE terms, the abstract equation above becomes

$$\begin{cases} \lambda u_0 - \Delta u_0 = u_0^* \text{ in } \Omega_f \\ u_0|_{\Gamma_f} = 0 \text{ on } \Gamma_f; \end{cases} \quad (12)$$

and for  $1 \leq j \leq K$ ,

$$\begin{cases} \lambda h_{0j} - h_{1j} = h_{0j}^* \text{ in } \Gamma_j \\ \lambda h_{1j} - \Delta h_{0j} + h_{0j} - \frac{\partial w_0}{\partial \nu} + \frac{\partial u_0}{\partial \nu} = h_{1j}^* \text{ in } \Gamma_j \\ u_0|_{\Gamma_j} = h_{1j} = w_1|_{\Gamma_j} \text{ in } \Gamma_j \\ h_{0j}|_{\partial \Gamma_j \cap \partial \Gamma_l} = h_{0l}|_{\partial \Gamma_j \cap \partial \Gamma_l} \text{ on } \partial \Gamma_j \cap \partial \Gamma_l, \text{ for all } 1 \leq l \leq K \text{ such that} \\ \quad \partial \Gamma_j \cap \partial \Gamma_l \neq \emptyset \\ \frac{\partial h_{0j}}{\partial n_j} \Big|_{\partial \Gamma_j \cap \partial \Gamma_l} = -\frac{\partial h_{0l}}{\partial n_l} \Big|_{\partial \Gamma_j \cap \partial \Gamma_l} \text{ on } \partial \Gamma_j \cap \partial \Gamma_l, \text{ for all } 1 \leq l \leq K \text{ such that} \\ \quad \partial \Gamma_j \cap \partial \Gamma_l \neq \emptyset; \end{cases} \quad (13)$$

and also

$$\begin{cases} \lambda w_0 - w_1 = w_0^* \text{ in } \Omega_s \\ \lambda w_1 - \Delta w_0 = w_1^* \text{ in } \Omega_s \end{cases} \quad (14)$$

# Maximality of $\mathbf{A}$

Define the sets

$$\begin{aligned}\mathcal{V} = & \{[\psi_1, \dots, \psi_K] \in H^1(\Gamma_1) \times \dots \times H^1(\Gamma_k) \mid \text{For all } 1 \leq j \leq K, \\ & \psi_j|_{\partial\Gamma_j \cap \partial\Gamma_I} = \psi_I|_{\partial\Gamma_j \cap \partial\Gamma_I}, \text{ for all } 1 \leq I \leq K \text{ such that } \partial\Gamma_j \cap \partial\Gamma_I \neq \emptyset\}\end{aligned}\quad (15)$$

and

$$\mathbf{W} \equiv \left\{ [\varphi, \psi_1, \dots, \psi_K, \xi] \in H_{\Gamma_f}^1(\Omega_f) \times \mathcal{V} \times H^1(\Omega_s) \mid \varphi|_{\Gamma_j} = \psi_j = \xi|_{\Gamma_j}, \text{ for } 1 \leq j \leq K \right\}; \quad (16)$$

If  $\Phi = [u_0, h_{01}, h_{11}, \dots, h_{0K}, h_{1K}, w_0, w_1] \in D(\mathbf{A})$  solves (11), then necessarily its solution components  $[u_0, h_{11}, \dots, h_{1K}, w_1] \in \mathbf{W}$  satisfy for  $[\varphi, \psi, \xi] \in \mathbf{H}$ ,

$$\left\langle \mathbf{B} \begin{bmatrix} \varphi \\ \psi_1 \\ \vdots \\ \psi_K \\ \xi \end{bmatrix}, \begin{bmatrix} u_0 \\ h_{11} \\ \vdots \\ h_{1K} \\ w_1 \end{bmatrix} \right\rangle_{\mathbf{W}^* \times \mathbf{W}} = \mathbf{F}_\lambda \left( \begin{bmatrix} \varphi \\ \psi \\ \xi \end{bmatrix} \right); \quad (17)$$

# Maximality of $\mathbf{A}$

where

$$\begin{aligned}\mathbf{F}_\lambda \left( \begin{bmatrix} \varphi \\ \psi \\ \xi \end{bmatrix} \right) &= \langle u_0^*, \varphi \rangle_{\Omega_f} + \sum_{j=1}^K \left[ \left\langle h_{1j}^*, \psi_j \right\rangle_{\Gamma_j} - \frac{1}{\lambda} \left\langle \nabla h_{0j}^*, \nabla \psi_j \right\rangle_{\Gamma_j} \right. \\ &\quad \left. - \frac{1}{\lambda} \left\langle h_{0j}^*, \psi_j \right\rangle_{\Gamma_j} \right] + \langle w_1^*, \xi \rangle_{\Omega_s} - \frac{1}{\lambda} \langle \nabla w_0^*, \nabla \xi \rangle_{\Omega_s}\end{aligned}\quad (18)$$

and

$$\begin{aligned}\left\langle \mathbf{B} \begin{bmatrix} \varphi \\ \psi_1 \\ \vdots \\ \psi_K \\ \xi \end{bmatrix}, \begin{bmatrix} \tilde{\varphi} \\ \tilde{\psi}_1 \\ \vdots \\ \tilde{\psi}_K \\ \tilde{\xi} \end{bmatrix} \right\rangle_{\mathbf{W}^* \times \mathbf{W}} &= \lambda \langle \varphi, \tilde{\varphi} \rangle_{\Omega_f} + \langle \nabla \varphi, \nabla \tilde{\varphi} \rangle_{\Omega_f} + \lambda \left\langle \xi, \tilde{\xi} \right\rangle_{\Omega_s} + \left\langle \nabla \xi, \nabla \tilde{\xi} \right\rangle_{\Omega_s} \\ &\quad + \sum_{j=1}^K \left[ \lambda \left\langle \psi_j, \tilde{\psi}_j \right\rangle_{\Gamma_j} + \frac{1}{\lambda} \left\langle \nabla \psi_j, \nabla \tilde{\psi}_j \right\rangle_{\Gamma_j} + \frac{1}{\lambda} \left\langle \psi_j, \tilde{\psi}_j \right\rangle_{\Gamma_j} \right]\end{aligned}$$

## Theorem (Lax-Milgram)

Let  $X$  be a Hilbert space and  $a(\cdot, \cdot)$  a continuous  $X$ -elliptic bilinear form. Then given  $f \in X$ , there exists a unique  $u \in X$  such that

$$a(u, v) = \langle f, v \rangle_X, \quad \text{for every } v \in X.$$

Since it is clear that  $\mathbf{B} \in \mathcal{L}(\mathbf{W}, \mathbf{W}^*)$  is  $\mathbf{W}$ -elliptic; by the Lax-Milgram Theorem, the equation (17) has a unique solution

$$[u_0, h_{11}, \dots, h_{1K}, w_1] \in \mathbf{W}. \tag{19}$$

It was then showed this solution is in  $D(\mathbf{A})$ .

## Introduction of Second Model

The model was improved from a heat-wave-wave model to a Stokes-wave-Lamé model. The author has shown similar results of wellposedness for this model.

# Introduction of Second Model

$$\begin{cases} u_t - \operatorname{div}(\nabla u + \nabla^T u) + \nabla p = 0 & \text{in } (0, T) \times \Omega_f \\ \operatorname{div}(u) = 0 & \text{in } (0, T) \times \Omega_f \\ u|_{\Gamma_f} = 0 & \text{on } (0, T) \times \Gamma_f; \end{cases} \quad (20)$$

$$h_{tt} - \Delta_{\Gamma_s} h = [\nu \cdot \sigma(w)]|_{\Gamma_s} - [\nu \cdot (\nabla u + \nabla^T u)]|_{\Gamma_s} + p\nu \quad \text{on } (0, T) \times \Gamma_s, \quad (21)$$

$$\begin{cases} w_{tt} - \operatorname{div} \sigma(w) + w = 0 & \text{on } (0, T) \times \Omega_s \\ w_t|_{\Gamma_s} = h_t = u|_{\Gamma_s} & \text{on } (0, T) \times \Gamma_s \end{cases} \quad (22)$$

$$[u(0), h(0), h_t(0), w(0), w_1(0)] = [u_0, h_0, h_1, w_0, w_1] \in \mathbf{H} \quad (23)$$

Here,  $\Delta_{\Gamma_s}(\cdot)$  is the Laplace Beltrami operator, and the stress tensor  $\sigma(\cdot)$  constitutes the Lamé system of elasticity on the “thick” layer. Namely, for function  $v$  in  $\Omega_s$ ,

$$\sigma(v) = 2\mu\epsilon(v) + \lambda[I_3 \cdot \epsilon(v)]I_3,$$

where strain tensor  $\epsilon(\cdot)$  is given by

$$\epsilon_{ij} = \frac{1}{2} \left( \frac{\partial v_j}{\partial x_i} + \frac{\partial v_i}{\partial x_j} \right), \quad 1 \leq i, j \leq 3$$

# Functional Settings

With the following Hilbert space

$$\mathbf{H} = \{[u_0, h_0, h_1, w_0, w_1] \in [L^2(\Omega_f)]^3 \times [H^1(\Gamma_s)]^2 \times [L^2(\Gamma_s)]^2 \times [H^1(\Omega_s)]^3 \times [L^2(\Omega_s)]^3 \mid \operatorname{div}(u_0) = 0, u_0 \cdot \nu|_{\Gamma_f} = 0, \text{ and } w_0|_{\Gamma_s} = h_0\} \quad (24)$$

with the inner product

$$\langle \Phi_0, \tilde{\Phi}_0 \rangle_{\mathbf{H}} = \langle u_0, \tilde{u}_0 \rangle_{\Omega_f} + \langle \nabla_{\Gamma_s}(h_0), \nabla_{\Gamma_s}(\tilde{h}_0) \rangle_{\Gamma_s} + \langle h_1, \tilde{h}_1 \rangle_{\Gamma_s} \quad (25)$$

$$+ \langle \sigma(w_0), \epsilon(\tilde{w}_0) \rangle_{\Omega_s} + \langle w_0, \tilde{w}_0 \rangle_{\Omega_s} + \langle w_1, \tilde{w}_1 \rangle_{\Omega_s} \quad (26)$$

where

$$\Phi_0 = [u_0, h_0, h_1, w_0, w_1] \in \mathbf{H}; \tilde{\Phi}_0 = [\tilde{u}_0, \tilde{h}_0, \tilde{h}_1, \tilde{w}_0, \tilde{w}_1] \in \mathbf{H} \quad (27)$$

# Elimination of Pressure

Elimination of the pressure will be important to formulate the PDE in (20) – (23) as an ODE. To this end, by using the matching velocity condition and  $u$  being divergence free it follows  $p$  is harmonic, or

$$\Delta p(t) = 0 \text{ in } \Omega_f. \quad (28)$$

Subsequently, by multiplying by  $\nu|_{\Gamma_s}$  and using the matching velocity condition the author obtains the following boundary condition for the pressure variable  $p$ :

$$p + \frac{\partial p}{\partial \nu} = \operatorname{div} (\nabla(u) + \nabla^T(u)) \cdot \nu|_{\Gamma_s} + [(\nabla u + \nabla^T u) \cdot \nu - \Delta_{\Gamma_s}(h) - \nu \cdot \sigma(w)|_{\Gamma_s}] \cdot \nu|_{\Gamma_s} \quad (29)$$

Since  $u$  is divergence free,

$$\frac{\partial p}{\partial \nu} = [\operatorname{div} (\nabla u + \nabla^T u)] \cdot \nu \text{ on } \Gamma_f.$$

Thus the pressure variable  $p(t)$ , can formally be written pointwise in time as

$$p(t) = \mathcal{P}_1(u(t)) + \mathcal{P}_2(h(t)) + \mathcal{P}_3(w(t))$$

where each  $\mathcal{P}_i(\cdot)$  will be given on the next slide.

# Elimination of Pressure

$$p(t) = \mathcal{P}_1(u(t)) + \mathcal{P}_2(h(t)) + \mathcal{P}_3(w(t))$$

$$\begin{cases} \Delta \mathcal{P}_1(u) = 0 & \text{in } \Omega_f, \\ \mathcal{P}_1(u) = \operatorname{div} (\nabla(u) + \nabla^T(u)) \cdot \nu|_{\Gamma_s} + ([(\nabla u + \nabla^T u)] \cdot \nu) \cdot \nu|_{\Gamma_s} & \text{on } \Gamma_s, \\ \frac{\partial \mathcal{P}_1(u)}{\partial \nu} = \operatorname{div} (\nabla(u) + \nabla^T(u)) \cdot \nu|_{\Gamma_f} & \text{on } \Gamma_f, \end{cases} \quad (30)$$

$$\begin{cases} \Delta \mathcal{P}_2(h) = 0 & \text{in } \Omega_f, \\ \mathcal{P}_2(h) = -\Delta_{\Gamma_s}(h) \cdot \nu|_{\Gamma_s} & \text{on } \Gamma_s, \\ \frac{\partial \mathcal{P}_2(h)}{\partial \nu} = 0 & \text{on } \Gamma_f, \end{cases} \quad (31)$$

and

$$\begin{cases} \Delta \mathcal{P}_3(w) = 0 & \text{in } \Omega_f, \\ \mathcal{P}_3(w) = -[\nu \cdot \sigma(w)|_{\Gamma_s}] \cdot \nu|_{\Gamma_s} & \text{on } \Gamma_s, \\ \frac{\partial \mathcal{P}_3(w)}{\partial \nu} = 0 & \text{on } \Gamma_f. \end{cases} \quad (32)$$

Also note

$$p_0 = \mathcal{P}_1(u_0) + \mathcal{P}_2(h_0) + \mathcal{P}_3(w_0). \quad (33)$$

# Functional Settings

It follows, the PDE system given in (20) – (23) may be associated with an abstract ODE in the Hilbert space  $\mathbf{H}$ ; namely,

$$\begin{cases} \frac{d}{dt}\Phi(t) = \mathbf{A}\Phi(t) \\ \Phi(0) = \Phi_0 \end{cases} \quad (34)$$

where  $\Phi(t) = [u(t), h(t), h_t(t), w(t), w_1(t)]$ , and  $\Phi_0 = [u_0, h_0, h_1, w_0, w_1]$ . Here, the operator  $\mathbf{A} : D(\mathbf{A}) \subseteq \mathbf{H} \rightarrow \mathbf{H}$  is defined by

$$\mathbf{A} = \begin{bmatrix} \operatorname{div}(\nabla(\cdot) + \nabla^T(\cdot)) & 0 & 0 & 0 & 0 \\ 0 & 0 & I & 0 & 0 \\ -[\nu \cdot (\nabla(\cdot) + \nabla^T(\cdot))]|_{\Gamma_s} & \Delta_{\Gamma_s}(\cdot) & 0 & \nu \cdot \sigma(\cdot)|_{\Gamma_s} & 0 \\ 0 & 0 & 0 & 0 & I \\ 0 & 0 & 0 & \operatorname{div} \sigma(\cdot) - I & 0 \end{bmatrix} + \begin{bmatrix} -\nabla \mathcal{P}_1(\cdot) & -\nabla \mathcal{P}_2(\cdot) & 0 & -\nabla \mathcal{P}_3(\cdot) & 0 \\ 0 & 0 & 0 & 0 & 0 \\ \mathcal{P}_1(\cdot)\nu & \mathcal{P}_2(\cdot)\nu & 0 & \mathcal{P}_3(\cdot)\nu & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \quad (35)$$

Here, the “pressure” operators  $\mathcal{P}_i$  are as defined above.

# Functional Settings

The domain  $D(\mathbf{A})$  of the generator  $\mathbf{A}$  is characterized as follows

$$[u_0, h_0, h_1, w_0, w_1] \in D(\mathbf{A}) \Leftrightarrow$$

(**A.i**)  $u_0 \in [H^1(\Omega_f)]^3$ ,  $h_1 \in [H^1(\Gamma_s)]^2$   $w_1 \in [H^1(\Omega_s)]^3$ ;

(**A.ii**) There exists an associated  $L^2(\Omega_f)$ -function

$$p_0 = p_0(u_0, h_0, w_0) \text{ such that}$$

$$[\operatorname{div} (\nabla u_0 + \nabla^T u_0) - \nabla p_0] \in L^2(\Omega_f)$$

Consequently,  $p_0$  is harmonic and so one has the boundary traces

(a)  $[p_0|_{\Gamma_f}, \frac{\partial p_0}{\partial \nu}|_{\Gamma_f}] \in H^{-1/2}(\Gamma_f) \times H^{-3/2}(\Gamma_f)$ ;

(b)  $(\nabla u_0 + \nabla^T u_0) \cdot \nu \in H^{-3/2}(\Gamma_f)$ ,

(**A.iii**)  $\operatorname{div} \sigma(w_0) \in L^2(\Omega_s)$ ; consequently,  $\nu \cdot \sigma \in H^{-1/2}(\Gamma_s)$ ,

(**A.iv**)  $\Delta_{\Gamma_s}(h_0) + [\nu \cdot \sigma(w_0)]|_{\Gamma_s} - [(\nabla u_0 + \nabla^T u_0) \cdot \nu]|_{\Gamma_s}$   
 $+ [p_0 \nu]|_{\Gamma_s} \in L^2(\Gamma_s)$ ,

(**A.v**)  $u_0|_{\Gamma_f} = 0$ ,  $u_0|_{\Gamma_s} = h_1 = w_1|_{\Gamma_s}$

# Wellposedness

Theorem ((Wellposedness) PGG [JEE, 2024])

*With reference to the problem (20) – (23), the operator  $\mathbf{A} : D(\mathbf{A}) \subseteq \mathbf{H} \rightarrow \mathbf{H}$ , defined in (35), generates a  $C_0$ -semigroup of contractions on  $\mathbf{H}$ . Consequently, the solution  $\Phi(t) = [u(t), h(t), h_t(t), w(t), w_t(t)]$  of (20) – (23), or equivalently (34), is given by*

$$\Phi(t) = e^{\mathbf{A}t} \Phi_0 \in C([0, T]; \mathbf{H}),$$

where  $\Phi_0 = [u_0, h_0, h_1, w_0, w_1] \in D(\mathbf{A})$ .

Geredeli, P.G. An inf-sup approach to  $C_0$ -semigroup generation for an interactive composite structure-Stokes PDE dynamics. J. Evol. Equ. 24, 50 (2024).  
<https://doi.org/10.1007/s00028-024-00978-3>

# Sketch of Proof

Similarly, wellposedness was shown using the Lumer-Phillips Theorem as the problem is still linear. They showed

- $\mathbf{A}$  is dissipative
- Show that  $\mathbf{A}$  is maximally dissipative using Babuska-Brezzi to solve to the static resolvent equation  $(\lambda I - \mathbf{A})\Phi = \Phi^*$  for  $\Phi \in D(\mathbf{A})$

# Dissipativity of $\mathbf{A}$

Similar to the previous model, the authors shows  $\mathbf{A}$  is maximally dissipative. It follows, given data  $\Phi$  in  $D(\mathbf{A})$ ,

$$\begin{aligned}\langle \mathbf{A}\Phi, \Phi \rangle_{\mathbf{H}} = & -\frac{1}{2} \|\nabla(u_0) + \nabla^T(u_0)\|^2 + 2i\text{Im} \left[ \langle \nabla_{\Gamma_s}(h_1), \nabla_{\Gamma_s}(h_0) \rangle_{\Gamma_s} \right. \\ & + \langle \sigma(w_1), \epsilon(w_0) \rangle_{\Omega_s} \\ & \left. + \langle w_1, w_0 \rangle_{\Omega_s} + \langle \sigma(w_1), \epsilon(w_0) \rangle_{\Omega_s} + \langle w_1, w_0 \rangle_{\Omega_s} \right]\end{aligned}$$

which gives  $\text{Re } \langle \mathbf{A}\Phi, \Phi \rangle_{\mathbf{H}} \leq 0$ . Since  $\Phi$  was arbitrary, it follows that  $\mathbf{A}$  is dissipative.

# Maximality of $\mathbf{A}$

The author solves the following static problem to show  $\mathbf{A}$  is maximal with the Babuska-Brezzi Theorem. Suppose  $\Phi \in D(\mathbf{A})$  is a solution of the equation

$$(\lambda I - \mathbf{A})\Phi = \Phi^*, \quad (36)$$

where  $\lambda > 0$ ,  $\Phi = [u_0, h_0, h_1, w_0, w_1]$ , and  
 $\Phi^* = [u_0^*, h_0^*, h_1^*, w_0^*, w_1^*] \in \mathbf{H}$ .

## Theorem (Babuska-Brezzi)

Let  $\Sigma, V$  be Hilbert spaces and  $a : \Sigma \times \Sigma \rightarrow \mathbb{R}$ ,  $b : \Sigma \times V \rightarrow \mathbb{R}$ , bilinear forms which are continuous. Let

$$Z = \{\sigma \in \Sigma \mid b(\sigma, v) = 0, \text{ for every } v \in V\}.$$

Assume that  $a(\cdot, \cdot)$  is  $Z$ -elliptic, i.e. there exists a constant  $\alpha > 0$  such that

$$a(\sigma, \sigma) \geq \alpha \|\sigma\|_{\Sigma}^2, \text{ for every } \sigma \in Z.$$

Assume further that there exists a constant  $\beta > 0$  such that

$$\sup_{\tau \in \Sigma} \frac{b(\tau, v)}{\|\tau\|_{\Sigma}} \geq \beta \|v\|_V.$$

Then if  $\kappa \in \Sigma$  and  $I \in V$ , there exists a unique pair  $(\sigma, u) \in \Sigma \times V$  such that

$$\begin{aligned} a(\sigma, \tau) + b(\tau, u) &= \langle \kappa, \tau \rangle_{\Sigma}, \quad \text{for every } \tau \in \Sigma \\ b(\sigma, v) &= \langle I, v \rangle_V, \quad \text{for every } v \in V. \end{aligned} \tag{37}$$

# Maximality of $\mathbf{A}$

In PDE terms, the resolvent equation will generate the following relations, where  $p_0$  is given via (33):

$$\begin{cases} \lambda u_0 - \operatorname{div}(\nabla u_0 + \nabla^T u_0) + \nabla p_0 = u_0^* \text{ in } \Omega_f \\ \operatorname{div}(u_0) = 0 \text{ in } \Omega_f \\ u_0|_{\Gamma_f} = 0 \text{ on } \Gamma_f; \end{cases} \quad (38)$$

$$\begin{cases} \lambda h_0 - h_1 = h_0^* \text{ in } \Gamma_s \\ \lambda h_1 + [\nu \cdot (\nabla u_0 + \nabla^T u_0)]|_{\Gamma_s} - \Delta_{\Gamma_s}(h_0) - [\nu \cdot \sigma(w_0)]|_{\Gamma_s} - p_0 \nu = h_1^* \text{ in } \Gamma_s \end{cases} \quad (39)$$

$$\begin{cases} \lambda w_0 - w_1 = w_0^* \text{ in } \Omega_s \\ \lambda w_1 - \operatorname{div} \sigma(w_0) + w_0 = w_1^* \text{ in } \Omega_s \\ w_1|_{\Gamma_s} = h_1 = u_0|_{\Gamma_s} \text{ on } \Gamma_s \end{cases} \quad (40)$$

# Sketch of Proof

The author used the following outline

- Solve the decomposed stokes flow for  $\mathbf{u}$  and  $p$
- Generate a weak formulation for the “thin” ( $h_1$ ) and “thick” ( $w_1$ ) variables
- Recover of the other structure solution variables  $h_0$  and  $w_0$  given data  $h_0^* \in H^1(\Gamma_s)$  and  $w_0^* \in H^1(\Omega_s)$ ; i.e.

$$h_0 = \frac{1}{\lambda} h_1 + \frac{1}{\lambda} h_0^* \quad (41)$$

$$w_0 = \frac{1}{\lambda} w_1 + \frac{1}{\lambda} w_0^* \quad (42)$$

# Decomposition of Stokes Flow

Decomposition of the Stokes flow into two parts

Zero force and Dirichlet boundary data  $g \in H^{1/2}(\Gamma_s)$ : solution is  $[u_1(g), p_1(g)]$

$$\begin{cases} \lambda u_1 - \operatorname{div} (\nabla u_1 + \nabla^T u_1) + \nabla p_1 = 0 \text{ in } \Omega_f \\ \operatorname{div} (u_1) = \frac{\int_{\Gamma_s} (g \cdot \nu) d\Gamma_s}{\operatorname{meas}(\Omega_f)} \text{ in } \Omega_f \\ u_1|_{\Gamma_s} = g \text{ on } \Gamma_s \\ u_1|_{\Gamma_f} = 0 \text{ on } \Gamma_f, \end{cases} \quad (43)$$

With force term  $u_0^*$ , zero Dirichlet data and zero divergence: solution is  $[u_2(u_0^*), p_2(u_0^*)]$

$$\begin{cases} \lambda u_2 - \operatorname{div} (\nabla u_2 + \nabla^T u_2) + \nabla p_2 = u_0^* \text{ in } \Omega_f \\ \operatorname{div} (u_2) = 0 \text{ in } \Omega_f \\ u_2|_{\Gamma_f} \text{ on } \Gamma_f \end{cases} \quad (44)$$

The unique  $\{u_0, p_0\}$  of (38) may then be expressed as

$$u_0 = u_1(g|_{\Gamma_s}) + u_2(u_0^*); \quad p_0 = p_1(g|_{\Gamma_s}) + p_2(u_0^*) + c_0, \quad (45)$$

where  $c_0$  is the (presently) unknown constant component of the pressure  $p_0$  of (38).

# Maximality of $\mathbf{A}$

Define the space

$$\mathbf{S} = \{(\varphi, \psi) \in [H^1(\Gamma_s)]^2 \times [H^1(\Omega_s)]^3 \mid \varphi = \psi|_{\Gamma_s}\}.$$

The last relation now gives us the following mixed variational formulation in terms of the “thin” and “thick” structure variables  $h_1$  and  $w_1$ : Namely,

$$\begin{aligned} \mathbf{a}([h_1, w_1], [\varphi, \psi]) + \mathbf{b}([\varphi, \psi], c_0) &= \mathbf{F}([\varphi, \psi]), \text{ for all } [\varphi, \psi] \in \mathbf{S} \\ \mathbf{b}([h_1, w_1], r) &= 0, \text{ for all } r \in \mathbb{R}. \end{aligned} \quad (46)$$

Where

$\mathbf{a}(\cdot, \cdot) : \mathbf{S} \times \mathbf{S} \rightarrow \mathbb{R}$ ,  $\mathbf{b}(\cdot, \cdot) : \mathbf{S} \times \mathbb{R} \rightarrow \mathbb{R}$ , and the functional  $\mathbf{F}(\cdot)$  are defined as follows

# Maximality of $\mathbf{A}$

$$\begin{aligned}\mathbf{a}([\phi, \xi], [\tilde{\phi}, \tilde{\xi}]) &= \lambda \left\langle \phi, \tilde{\phi} \right\rangle_{\Gamma_s} + \frac{1}{\lambda} \left\langle \nabla_{\Gamma_s} \phi, \nabla_{\Gamma_s} \tilde{\phi} \right\rangle_{\Gamma_s} \\ &\quad + \lambda \left\langle \xi, \tilde{\xi} \right\rangle_{\Omega_s} + \frac{1}{\lambda} \left\langle \sigma(\xi), \epsilon(\tilde{\xi}) \right\rangle_{\Omega_s} + \frac{1}{\lambda} \left\langle \xi, \tilde{\xi} \right\rangle_{\Omega_s} \\ &\quad + \left\langle \nabla u_1(\xi|_{\Gamma_s}) + \nabla^T u_1(\xi|_{\Gamma_s}), \nabla \tilde{u}(\tilde{\phi}) + \nabla^T \tilde{u}(\tilde{\phi}) \right\rangle_{\Omega_f} \\ &\quad + \lambda \left\langle u_1(\xi|_{\Gamma_s}), \tilde{u}(\tilde{\phi}) \right\rangle_{\Omega_f}, \\ \mathbf{b}([\tilde{\phi}, \tilde{\xi}], r) &= -r \left\langle v, \tilde{\phi} \right\rangle_{\Gamma_s},\end{aligned}$$

and

$$\begin{aligned}\mathbf{F}([\tilde{\phi}, \tilde{\xi}]) &= - \left\langle \nabla u_2(u_0^*) + \nabla^T u_2(u_0^*), \nabla \tilde{u}(\tilde{\phi}) + \nabla^T \tilde{u}(\tilde{\phi}) \right\rangle_{\Omega_f} \\ &\quad - \frac{1}{\lambda} \left\langle \nabla_{\Gamma_s} h_0^*, \nabla_{\Gamma_s} \tilde{\phi} \right\rangle_{\Gamma_s} - \frac{1}{\lambda} \left\langle \sigma(w_0^*), \epsilon(\tilde{\xi}) \right\rangle_{\Omega_s} \\ &\quad - \lambda \left\langle u_2(u_0^*), \tilde{u}(\tilde{\phi}) \right\rangle_{\Omega_f} + \left\langle u_0^*, \tilde{u}(\tilde{\phi}) \right\rangle_{\Omega_f} \\ &\quad + \left\langle h_1^*, \tilde{\phi} \right\rangle_{\Gamma_s} + \left\langle w_1^*, \tilde{\xi} \right\rangle_{\Omega_s} - \frac{1}{\lambda} \left\langle w_0^*, \tilde{\xi} \right\rangle_{\Omega_s}.\end{aligned}$$

# inf sup condition

Given  $r \in \mathbb{R}$ , let  $z \in [H^1(\Gamma_s)]^2$  satisfy

$$\Delta_{\Gamma_s} z = \operatorname{sgn}(r) \nu \text{ on } \Gamma_s$$

It is easily seen that  $\|\nabla_{\Gamma_s} z\|_{\Gamma_s} \leq C \|\nu\|_{\Gamma_s}$ . Now, taking into account that

$\gamma : H^1(\Omega_s) \rightarrow H^{1/2}(\Gamma_s)$  is a surjective map, and so it has a continuous right inverse  $\gamma^+(z)$ , we have

$$\begin{aligned} \sup_{[\eta, \varsigma]} \frac{\mathbf{b}([\eta, \varsigma], r)}{\|[\eta, \varsigma]\|_{\mathbf{s}}} &\geq \frac{\mathbf{b}([z, \gamma^+(z)], r)}{\|z\|_{[H^1(\Gamma_s)]^2}} \\ &= \frac{-r \int_{\Gamma_s} \nu \cdot z d\Gamma_s}{\|z\|_{[H^1(\Gamma_s)]^2}} \\ &= -r \operatorname{sgn}(r) \frac{\int_{\Gamma_s} \Delta_{\Gamma_s} z \cdot z d\Gamma_s}{\|z\|_{[H^1(\Gamma_s)]^2}} \\ &= |r| \frac{\int_{\Gamma_s} |\nabla_{\Gamma_s} z|^2 d\Gamma_s}{\|z\|_{[H^1(\Gamma_s)]^2}} \\ &= |r| \|z\|_{[H^1(\Gamma_s)]^2} \end{aligned}$$

which yields that the inf-sup condition holds wth the constant  $\beta = \|z\|_{[H^1(\Gamma_s)]^2}$ .

# Conclusion

By the Babuska-Brezzi Theorem, it is then shown that this unique solution is in  $D(\mathbf{A})$ .

## Part II

## Stability Types

- Strong Stability
- Polynomial Stability
- Exponential Stability

# Strong Stability

Theorem ((Strong Stability) G. Avalos, PGG, B. Muha [JDE, 2020])

*For the modeling generator  $\mathbf{A} : D(\mathbf{A}) \subseteq \mathbf{H} \rightarrow \mathbf{H}$  of (1) – (4), one has  $\sigma(\mathbf{A}) \cap i\mathbb{R} = \emptyset$ . Consequently, the  $C_0$ -semigroup  $\{e^{\mathbf{A}t}\}_{t \geq 0}$  given in Theorem 1 is strongly stable. That is, the solution  $\Phi(t)$  of the PDE (1) – (4) tends asymptotically to the zero state for all initial data  $\Phi_0 \in \mathbf{H}$*

G. Avalos, P. G. Geredeli, B. Muha; "Wellposedness, Spectral Analysis and Asymptotic Stability of a Multilayered Heat-Wave-Wave System ", Journal of Differential Equations 269 (2020), pp. 7129-7156.

# Sketch of Proof

Theorem ((Strong Stability) [Arendt-Batty, 1988])

Let  $T(t)_{t \geq 0}$  be a bounded  $C_0$ -semigroup on a reflexive Banach space  $X$ , with generator  $\mathbf{A}$ . Assume that  $\sigma_p(\mathbf{A}) \cap i\mathbb{R} = \emptyset$ , where  $\sigma_p(\mathbf{A})$  is the point spectrum of  $\mathbf{A}$ . If  $\sigma(\mathbf{A}) \cap i\mathbb{R}$  is countable then  $T(t)_{t \geq 0}$  is strongly stable.

Recall:  $\sigma(\mathbf{A}) = \sigma_p(\mathbf{A}) \cup \sigma_c(\mathbf{A}) \cup \sigma_r(\mathbf{A})$

Note that  $\sigma(\mathbf{A}) \cap i\mathbb{R} = \emptyset$  is equivalent to showing  $i\mathbb{R} \subseteq \rho(\mathbf{A})$

To this end the authors checked

- $0 \in \rho(\mathbf{A})$
- The continuous spectrum
- The eigenvalues of  $\mathbf{A}^*$

$$0 \in \rho(\mathbf{A})$$

Given  $\Phi^* = [u_0^*, h_{01}^*, h_{11}^*, \dots, h_{0K}^*, h_{1K}^*, w_0^*, w_1^*] \in \mathbf{H}$ , the problem is to find  $\Phi = [u_0, h_{01}, h_{11}, \dots, h_{0K}, h_{1K}, w_0, w_1] \in D(\mathbf{A})$  which solves

$$\mathbf{A}\Phi = \Phi^* \quad (47)$$

It follows

$$w_1 = w_0^* \in H^1(\Omega_s) \quad (48)$$

$$h_{1j} = h_{0j}^* \in H^1(\Gamma_j), \text{ for } 1 \leq j \leq K \quad (49)$$

and

$$\begin{cases} \Delta u_0 = u_0^* \\ u_0|_{\Gamma_f} = 0 \\ u_0|_{\Gamma_s} = w_0^*|_{\Gamma_s} \end{cases} \quad (50)$$

Recall the set (to be used on the next slide)

$$\begin{aligned} \mathcal{V} = & \{[\psi_1, \dots, \psi_K] \in H^1(\Gamma_1) \times \dots \times H^1(\Gamma_k) \mid \text{For all } 1 \leq j \leq K, \\ & \psi_j|_{\partial\Gamma_j \cap \partial\Gamma_l} = \psi_l|_{\partial\Gamma_j \cap \partial\Gamma_l}, \text{ for all } 1 \leq l \leq K \text{ such that } \partial\Gamma_j \cap \partial\Gamma_l \neq \emptyset\} \end{aligned} \quad (51)$$

$$0 \in \rho(\mathbf{A})$$

And define the set

$$\chi \equiv \left\{ [\psi, \xi] \in \mathcal{V} \times H^1(\Omega_s) \mid \psi_j = \xi|_{\Gamma_j} \text{ for } 1 \leq j \leq K \right\}. \quad (52)$$

Testing with these equations, it follows

$$\begin{aligned} & \langle \nabla w_0, \nabla \xi \rangle_{\Omega_s} + \sum_{j=1}^K \left[ \langle \nabla h_{0j}, \nabla \psi_j \rangle_{\Gamma_j} + \langle h_{0j}, \psi_j \rangle_{\Gamma_j} \right] \\ &= - \langle w_1^*, \xi \rangle_{\Omega_s} - \sum_{j=1}^K \left[ \left\langle h_{1j}^*, \psi_j \right\rangle_{\Gamma_j} + \left\langle \frac{\partial u_0}{\partial \nu}, \psi_j \right\rangle_{\Gamma_j} \right], \end{aligned} \quad (53)$$

Since the bilinear form  $b(\cdot, \cdot) : \chi \rightarrow \mathbb{R}$ , given by

$$b([\psi, \xi], [\tilde{\psi}, \tilde{\xi}]) = \langle \nabla \xi, \nabla \tilde{\xi} \rangle_{\Omega_s} + \sum_{j=1}^K \left[ \langle \nabla \psi_j, \nabla \tilde{\psi}_j \rangle_{\Gamma_j} + \langle \psi_j, \tilde{\psi}_j \rangle_{\Gamma_j} \right] \quad (54)$$

for every  $[\psi, \xi], [\tilde{\psi}, \tilde{\xi}] \in \chi$ , is continuous and  $\chi$ -elliptic, then by Lax-Milgram, there exists a unique solution

$$\varphi = [(h_{01}, h_{02}, \dots, h_{0K}), w_0] \in \chi \quad (55)$$

(Then shown to be in  $D(\mathbf{A})$ )

$$\beta, i\beta \notin \sigma_c(\mathbf{A}), \beta \neq 0$$

Assume to the contrary. Then since  $\sigma_c(\mathbf{A}) \subseteq \sigma_{\text{app}}(\mathbf{A})$  there exists a sequence  $\{\Phi_n\} = \{[u_n, h_{1n}, \xi_{1n}, \dots, h_{Kn}, \xi_{Kn}, w_{0n}, w_{1n}]\} \subseteq D(\mathbf{A})$  which satisfy for  $n \in \mathbb{N}$

$$\|\Phi_n\|_{\mathbf{H}} = 1 \text{ and } \|(i\beta I - \mathbf{A})\Phi_n\|_{\mathbf{H}} < \frac{1}{n}$$

$$\beta, i\beta \notin \sigma_r(\mathbf{A}), \beta \neq 0$$

It is known that for a closed and densely defined operator  $\mathbf{A}$ , if  $\lambda \in \sigma_r(\mathbf{A})$  then  $\bar{\lambda} \in \sigma_p(\mathbf{A}^*)$ . It follows

$\mathbf{A}^* : D(\mathbf{A}^*) \subseteq \mathbf{H} \rightarrow \mathbf{H}$  is given by

$$\mathbf{A}^* = \begin{bmatrix} \Delta & 0 & 0 & \dots & 0 & 0 & 0 & 0 \\ 0 & 0 & -I & \dots & 0 & 0 & 0 & 0 \\ -\frac{\partial}{\partial \nu}|_{\Gamma_1} & (I - \Delta) & 0 & \dots & 0 & 0 & -\frac{\partial}{\partial \nu}|_{\Gamma_1} & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 0 & -I & 0 & 0 \\ -\frac{\partial}{\partial \nu}|_{\Gamma_K} & 0 & 0 & \dots & (I - \Delta) & 0 & -\frac{\partial}{\partial \nu}|_{\Gamma_K} & 0 \\ 0 & 0 & 0 & \dots & 0 & 0 & 0 & -I \\ 0 & 0 & 0 & \dots & 0 & 0 & -\Delta & 0 \end{bmatrix};$$

$$D(\mathbf{A}) = D(\mathbf{A}^*), i\beta \text{ is not an eigenvalue of } \mathbf{A}^* \text{ so } i\beta \notin \sigma_r(\mathbf{A})$$

# Conclusion

By the spectral analysis, the authors concluded there is strong stability for any initial data in  $D(\mathbf{A})$ .

## Theorem ((Strong Stability) PGG [JDE, 2025])

*With reference to problem (20) – (23), zero is an eigenvalue for the generator  $\mathbf{A} : D(\mathbf{A}) \subseteq \mathbf{H} \rightarrow \mathbf{H}$ . Consequently the solution  $\{e^{\mathbf{A}t}\}|_{[Null(\mathbf{A})]^\perp}$  decays to the zero state for any initial data  $\Phi_0 = [u_0, h_0, h_1, w_0, w_1] \in [Null(\mathbf{A})]^\perp$ .*

Pelin G. Geredeli, Spectral analysis and asymptotic decay of the solutions to multilayered structure-Stokes fluid interaction PDE system, Journal of Differential Equations, Volume 427, 2025, Pages 1-25, ISSN 0022-0396,  
<https://doi.org/10.1016/j.jde.2025.01.080>.

# Sketch of Proof

As a reminder

Theorem ((Strong Stability) [Arendt-Batty, 1988])

Let  $T(t)_{t \geq 0}$  be a bounded  $C_0$ -semigroup on a reflexive Banach space  $X$ , with generator  $\mathbf{A}$ . Assume that  $\sigma_p(\mathbf{A}) \cap i\mathbb{R} = \emptyset$ , where  $\sigma_p(\mathbf{A})$  is the point spectrum of  $\mathbf{A}$ . If  $\sigma(\mathbf{A}) \cap i\mathbb{R}$  is countable then  $T(t)_{t \geq 0}$  is strongly stable.

It is then checked

- Zero is an eigenvalue
- The continuous spectrum
- The eigenvalues of  $\mathbf{A}^*$

# Zero is an Eigenvalue

For  $\Phi = [u_0, h_0, h_1, w_0, w_1] \in D(\mathbf{A})$ , it follows  $\mathbf{A}\Phi = 0$  implies

$$\operatorname{div} (\nabla u_0 + \nabla^T u_0) - \nabla p = 0 \text{ in } \Omega_f$$

$$h_1 = 0 \text{ in } \Gamma_s$$

$$-\nu \cdot (\nabla u_0 + \nabla^T u_0)|_{\Gamma_s} + \Delta_{\Gamma_s}(h_0) + \nu \cdot \sigma(w_0)|_{\Gamma_s} + p\nu = 0 \text{ in } \Gamma_s$$

$$w_1 = 0 \text{ in } \Omega_s$$

$$\operatorname{div} \sigma(w_0) - w_0 = 0 \text{ in } \Omega_s$$

Dissipativity shows

$$0 = \operatorname{Re} \langle \mathbf{A}\Phi, \Phi \rangle = \frac{1}{2} \|\nabla u_0 + \nabla^T u_0\|^2 \implies u_0 = 0$$

$$p = c_0 = \text{constant}$$

# Zero is an Eigenvalue

Define  $S = \{[f, g] \in H^1(\Gamma_s) \times H^1(\Omega_s) \mid f = g|_{\Gamma_s}\}.$

Testing the previous equations with  $f, g,$

$$\begin{aligned}\mathbf{B}([h_0, w_0], [f, g]) &= \langle \nabla_{\Gamma_s}(h_0), \nabla_{\Gamma_s}(f) \rangle_{\Gamma_s} + \langle \sigma(w_0), \epsilon(g) \rangle_{\Omega_s} + \langle w_0, g \rangle_{\Omega_s} \\ &= \langle c_0 \nu, f \rangle_{\Gamma_s}\end{aligned}$$

As  $B(\cdot, \cdot)$  is continuous and  $S$ -elliptic, using Lax-Milgram finds  $\{h_0, w_0\} \in S.$  (Then in  $D(\mathbf{A})$ )

$$\text{Null}(\mathbf{A}) = \text{Span} \left\{ \begin{bmatrix} 0 \\ h_0 \\ 0 \\ w_0 \\ 0 \end{bmatrix} \right\}$$

$$\text{Null}(\mathbf{A})^\perp = \left\{ [\tilde{u}_0, \tilde{h}_0, \tilde{h}_1, \tilde{w}_0, \tilde{w}_1] \in \mathbf{H} \mid \int_{\Gamma_s} \nu \cdot \tilde{h}_0 d\Gamma_s = 0 \right\}$$

$$\beta, i\beta \notin \sigma_p(\mathbf{A}), \beta \neq 0$$

For  $\Phi = [u_0, h_0, h_1, w_0, w_1]$ ,

$$[i\beta I - \mathbf{A}]\Phi = 0$$

Thus we see there is an overdetermined eigenvalue problem

$$-\beta^2 w_0 - \operatorname{div} \sigma(w_0) + w_0 = 0 \text{ in } \Omega_s$$

$$w_0|_{\Gamma_s} = 0 \text{ on } \Gamma_s$$

$$\nu \cdot \sigma(w_0) = -c_0 \nu \text{ on } \Gamma_s$$

**Assumption** for (fixed) given  $\beta$ , assume that the only solution to the above overdetermined problem is  $w_0 = 0$  (and necessarily  $c_0 = 0$ ).

$$\beta, i\beta \notin \sigma_c(\mathbf{A}), \beta \neq 0$$

Assume to the contrary. Then since  $\sigma_c(\mathbf{A}) \subseteq \sigma_{\text{app}}(\mathbf{A})$  there exists a sequence  $\{\Phi_n\} = \{[u_{0n}, h_{0n}, h_{1n}, w_{0n}, w_{1n}]\} \subseteq D(\mathbf{A})$  such that

$$\|\Phi_n\| = 1 \text{ and } \|(i\beta I - \mathbf{A})\Phi_n\|_{\mathbf{H}} < \frac{1}{n}$$

$$\beta, i\beta \notin \sigma_r(\mathbf{A}), \beta \neq 0$$

It is known that for a closed and densely defined operator  $\mathbf{A}$ , if  $\lambda \in \sigma_r(\mathbf{A})$  then  $\bar{\lambda} \in \sigma_p(\mathbf{A}^*)$ . It follows  
 $\mathbf{A}^* : D(\mathbf{A}^*) \subseteq \mathbf{H} \rightarrow \mathbf{H}$  is given by

$$\mathbf{A}^* = \begin{bmatrix} \operatorname{div}(\nabla(\cdot) + \nabla^T(\cdot)) & 0 & 0 & 0 & 0 \\ 0 & 0 & -I & 0 & 0 \\ -[\nu \cdot (\nabla(\cdot) + \nabla^T(\cdot))]|_{\Gamma_s} & -\Delta_{\Gamma_s}(\cdot) & 0 & -\nu \cdot \sigma(\cdot)|_{\Gamma_s} & 0 \\ 0 & 0 & 0 & 0 & -I \\ 0 & 0 & 0 & -\operatorname{div} \sigma(\cdot) + I & 0 \end{bmatrix} + \begin{bmatrix} -\nabla \mathcal{P}_1(\cdot) & \nabla \mathcal{P}_2(\cdot) & 0 & \nabla \mathcal{P}_3(\cdot) & 0 \\ 0 & 0 & 0 & 0 & 0 \\ \mathcal{P}_1(\cdot)\nu & -\mathcal{P}_2(\cdot)\nu & 0 & -\mathcal{P}_3(\cdot)\nu & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \quad (56)$$

$$D(\mathbf{A}) = D(\mathbf{A}^*), i\beta \text{ is not an eigenvalue of } \mathbf{A}^* \text{ so } i\beta \notin \sigma_r(\mathbf{A})$$

# Conclusion

It is important to note that  $0 \in \rho(\mathbf{A}|_{\text{Null}(\mathbf{A})^\perp})$ . In other words, the resolvent of  $\mathbf{A}|_{\text{Null}(\mathbf{A})^\perp}$ .

By the spectral analysis, the author showed that there is strong stability for any initial data taken in  $\text{Null}(\mathbf{A})^\perp$ .

## Topics

- Stokes Model polynomial decay
- Lack of exponential decay
- Navier-Stokes model

Thank You!