# JACOB DONENFELD

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#### **EDUCATION**

# Harvey Mudd College

August 2017 - Present

B.S. in Computer Science and Mathematics

#### CARRIER OBJECTIVE

To keep learning throughout my life as I spread my love and knowledge for robotics.

#### TECHNICAL STRENGTHS

Programming Languages

C++, Python, Java, Matlab, Racket, R, Lolcode

Other

Solidworks, Latex, Adobe Suite, CNC CAD/CAM, Lasercutting, Building

#### **EXPERIENCE**

### Research in the Lab for Autonomous, Intelligent Robots, HMC

2018-Present

· Researched planning an optimal driving path to maximize information gain for a pollution sensor mapping pollution in a 4D spacio-temporal graph of position vs. pollution over time. Paper to be completed before March for IROS 2019.

# Computational Biology Research, HMC

2017-2018

· Worked on an algorithm for the cophylogeny reconstruction problem, adding functionality through software development.

# Consumer Behavior Researcher, UCLA Management School

2016-2017

· Studied consumer behavior on how souvenirs and mementos influence spending habits by surveying tourists and non tourists.

# Robotics Instructor, Rolling Robots Camp

2015-2016

· Taught children how to code in Python and Scratch, design models, print in a 3D printer, and general teamwork skills.

# AWARDS

### Winner, HackTech, Caltech's Hackathon

2018

· Won a grant and mentorship from 1517 fund for building a smart trigger lock for a nerf gun at Caltechs 36 hour hackathon.

#### Finalist, MuddHacks, Harvey Mudd's Hackathon

2017

· Built a drink dispenser and mixer, allowing for combinations of any drinks or a customized drink through inputted amounts of mL/drink. Worked with a group 4, I handled software, systems, and electronics.

#### 4th Place, FIRST Robotics International Competition

2017

· Responsible for autonomous control of the robot, fusing data from computer vision and wheel encoders to locate and control the robot to desired waypoints.

#### **LEADERSHIP**

# President, Mudd Makerspace

2018-Present

· Manage budget, provide mentorship, host workshops, and fund projects for students.

#### RELEVANT COURSEWORK PRIOR TO SUMMER 2019

# Engineering Mathematics, HMC

Spring 2019

· "Applications of differential equations, linear algebra, and probability to engineering problems in multiple disciplines. Mathematical modeling, dimensional analysis, scale, approximation, model validation, Laplace Transforms"

# Experimental Engineering, HMC

Spring 2019

· "The primary purpose of the course is to teach basic instrumentation and measurement techniques; good lab report practice; technical report writing; analysis and presentation of data; the usage of experimental results for engineering design purposes; and the beginnings of professional practice." Capstone project created an autonomous underwater robot.

# Data Structures and Program Development, HMC

Spring 2019

· Learned abstract data types such as priority queues, dynamic dictionaries, and disjoint sets, with their efficient data structures and analysis of them. Also covers storage allocation and reclamation.

# Aerial Robotics, University of Pennsylvania

Freshman Summer

· Online class on quadrotor theory, kinematics, dynamics, linear and nonlinear control, smooth trajectory generation, and multirobot planning, and Euler angles and quaternions.

# Engineering Systems, HMC

Fall 2018

· "An introduction to the concepts of modern engineering, emphasizing modeling, analysis, synthesis, design, and control."

# Principles of Computer Science, HMC

Fall 2018

· Covered "information structures, functional programming, object-oriented programming, grammars, logic, logic programming, correctness, algorithms, complexity analysis, finite-state machines, basic processor architecture, and theoretical limitations."

# Discrete Mathematics, HMC

Fall 2018

· Rigorous proof-based class on combinatorics, number theory, and graph theory.

### Advanced Intro to Computer Science, HMC

Fall 2017

· Covered state-machines, recursive backtracking, artificial intelligence, circuit design and computer foundations, and assembly.