Preview

- What is Pthreads
- □ The Thread ID
- The Thread Creation
- The thread Termination
- The pthread_join() function
- Mutex
- The pthread_cancel function
- □ The pthread_cleanup_push() function
- □ The pthread_cleanup_pop() function

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What are Pthreads?

- □ Hardware vendors had implemented their own proprietary versions of threads.
- □ For a requirement of <u>standardized</u> <u>programming interface</u>, this interface has been specified by the IEEE POSIX 1003.1c standard (<u>1995</u>) (POSIX thread).
- Pthreads are defined as a set of C language programming types and procedure calls, implemented with a header file <pthread.h>

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The Thread ID

- A Process ID (pid_t) for a process is unique in the system.
- But a thread ID (pthread_t) has significance only within the context of the process where it belongs.
- Even though unsigned long (Linux), unsigned integer (Solaries 9) is used represent a pthread_t, a function ptread_equal() must be used to compare thread ID.

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The Thread ID

#include <phread.h>

/*returns non-zero if equal, return 0 otherwise */
int pthread_equal(pthread_t t1, pthread_t t2);

#include <phread.h>

/*returns thread ID of the calling thread */
pthread_t pthread_self(void);

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The thread Creation

- Initially, your main() program comprises a single, default thread.
- All other threads must be explicitly created by the programmer
- pthread_create() function creates a new thread and makes it executable. This routine <u>can be</u> <u>called any number of times from anywhere within</u> <u>your code</u>.
- Once created, threads are peers, and may create other threads. <u>There is no implied hierarchy</u> <u>or dependency between threads</u>

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The thread Creation

- $\hfill\Box$ att point to structure of pthread atribute. If att is NULL, a default attribute will be used
- start_routing point to <u>address of a void function</u> with no parameter or
- We can save parameters to typeless pointer arg and be able to pass to the function.
- When multiple threads are created, there is no guarantee which runs first. It is depends on the thread scheduler.

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The thread Creation

- On success, pthread_create() returns 0; on error, it returns an error number, and the contents of *thread are undefined.
 - **EAGAIN** Insufficient resources to create another thread, or a <u>system-imposed limit on</u> the number of threads was encountered.
 - **EINVAL** Invalid settings in attr.
 - **EPERM** No permission to set the scheduling policy and parameters specified in *attr*.

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```
The thread Creation
pthread_attr_t
   ■ int
            flags
   ■ int
            stacksize
            contentionscope
   ■ int
   int
            inheritsched
   int
            detachstate
            sched
   int
   struct sched_param
                               param
   struct timespec starttime deadline period
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```

Compile with pthread()

To compile a program with pthrad, we need provide pthread library to linker.

Ex)

Program file Name: example.c Executable file name: example Step 1) create object cord example.o

gcc -c example.c Step 2) create an executable code example

gcc –pthread –o example example.o

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```
createTh.c: Demonstrate creation of threads

finclude (addio.h)
finclude (addio.h)
finclude (addio.h)
finclude (addio.h)
finclude (addio.h)
finclude (addio.h)

finclude (pthread.h)
foodine NUM_THREADS 5

void 'PrintHello(void 'threadid)

int tid;
tid = (int)threadid;
printf("Hello World! It's me, thread fid!\n", tid);
pthread_exit(NULL);

int main(int argc, char 'argv(])

{
pthread_exit(NULL);
foot(tex)cKNUM_THREADS;
tidt rc, t,
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tidt rc,
t,
foot(tex)cKNUM_THREADS;
tidt rc,
t,
foot(tex)cKNUM_THREADS;
```

```
createTh2.c: Demonstrate creation of threads
createTh2.c: Demonstrate creation of threads

vectors

include Catedib.D

finiteDed Catedib.D

fedfise NUC_TREADS 5

static ptread_t seturementhreadID()

// the function pointed by each thread by passing different parameter

void "PrinteDelovai" cthreadid)

int tidy

tid = (int)threadid,
pthread_t id = seturementhreadID(); //set a thread id
pthread_t id = seturementhreadID(); //set a thread id
pthread_t id = seturementhreadID(); //set a thread id tw\n*, tid, id);
pthread_axit (DULL);

int main(mat argo, char "argy(1))

{
   pthread_t threads()mathread that different argument
   for(to-pt-codeN_TREADS();
   int re, ;
   //reset five threads pointing same function with different argument
   for(to-pt-codeN_TREADS();
   int re, ;

// re pthread_create(threads(t), NUL, Printhello, (void ")ti);
   if (ret-o)
        (
        printf("In main: creating thread bd\n*, ti)
        re - pthread_create(threads(t), NUL, Printhello, (void ")ti);
   if (ret-o)
        (
        printf("ENDOR; return code from pthread_create() is bd\n*, rc);
        exit(1);
   }
}

pthread_exit(NULL);
exit(0);
}
```

```
threadrace.c: Demonstrate race condition with multiple threads

include sphread.h>
finclude sphread.h>
finclude setdio.h>
finclude <
```

The thread Termination

- If any thread within a process call exit or _exit system call, then the entire process terminate.
- A <u>single thread</u> inside a process can be terminated by three ways.
 - The thread can simply return from the start routine
 - The thread can be cancelled by another thread by calling pthread_cancel() function in the same process.
 - The thread can call **phread_exit(**)

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The thread Termination

#include <pthread>
void pthread exit(void *rval ptr);

The rval_ptr: typeless pointer. This pointer is available to other threads in the process by calling the pthread_join() system call.

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Thread Synchronization

- Joining" is <u>one way to accomplish</u> <u>synchronization between threads</u>.
- There are three methods to synchronization between threads
 - Mutexes
 - Joining
 - Condition variables

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Mutexes

- □ A **Mutex** is a variable that can be in one of two state: unlock (0), lock(1).
- Modification to the value of a Mutex in the unlock and lock operations are executed indivisibly.
 - Lock operation check mutex value and if mutex =1, set mutex=0; if mutex = 0; sleep on the mutex queue
 - Unlock operation set mutex =1;
- Mutexes are <u>used to prevent data inconsistencies</u> due to race conditions
- Mutexes are used for serializing shared resources.
- If a global resource is accessed by several thread, the global resource should have a **Mutex** associated with it.

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Mutexes

- Scenario to avoid race condition without mutex (using variable lock)
 - Each thread need check lock variable before entering a critical region.
 - If lock =0 then a thread can enter to a critical region.
 - If lock = 1 then other thread cannot enter the critical region.
 - Once a thread finish its job in the critical region, set lock = 0 and let other thread enter the critical region.

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```
Mutexes

repeat
while lock ≠ 0 do
; (no-operation)
lock = 1

Critical Section

lock = 0;

Remainder Section

until false

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1. Initially lock = 0.
2. A process (or thread) P₁ tries get into critical section. A process check lock value = 0.
3. Process P₂ CPU time is over and go to ready state, before updating lock = 1.
4. Process P₂ tries get into critical section. P₂ check lock value lock = 0.
5. P₂ set lock = 1 and go to Critical section. Now P₁ and P₂ are in the critical section. Now P₁ and P₂ are in the critical section at the same time
```

```
threadrace.c. Demonstrate mace condition with multiple threads

**include opthread.h>
**sinclude datalio.h>
**
```

```
threadracel.e:
Demonstrate to use mutex to avoid race condition between multiple threads

****
**Include opthread.h>
****
**Include catdic.h>
**Include catdic.h

**In
```

The pthread_join() #include <pthread.h> int pthread_join(pthread_t thread, void **value_ptr); The pthread_join() function suspends execution of the calling thread until the target thread terminates, unless the target thread has already terminated. The typeless pointer **value_ptr can be used to pass more than a single value (used as return value from the fuction). Return 0 if no error Return error number on failure BEINVAL - not joinable thread BERCH - no such a thread

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□ EDEADLK -dead lock

```
/*thJoinx.c; demonstrate two thread without phread_join() function */
#include <pthread.h>
#include <pthread.h>
#include <pthread.h>
#include <stdio.h>

void *thrd fil(void *); /* for thread 1 */
void *thrd fil(void *); /* for thread 2 */
void err_sys(char *, int); /* error function */
int main()

int rc;
pthread_t tidl, tid2;
void 'tret;
/* create the first thread */
printf("About to create the first thread\n");
if ((rc=pthread_create(stidl, NULL, thrd_fl, NULL)) != 0)
err_sys("ERROR; return code from pthread_create() is", rc);
/* create second thread */
printf("About to create the second thread\n");
if ((rc=pthread_create(stid2, NULL, thrd_f2, NULL)) != 0)
err_sys("ERROR; return code from pthread_create() is", rc);
exit(0);
}

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```

```
The pthread_join()

/* for thread 1 */
void *thrd_fl(void *arg)
{
    sleep(5);
    printf("Thread 1 is about to finish \n");
    return ((void *) 1);
}

/* for thread 2 */
void *thrd_f2(void *arg)
{
    sleep(5);
    printf("Thread 2 is about to finish \n");
    return ((void *) 2);
}

void err_sys(char *str, int msg)
{
    printf ("as &d\n", str, msg);
    exit (1);
}

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```

```
The pthread_join()

/* for thread 1 */
void *thrd_fl(void *arg)
{
    sleep(1);
    printf("Thread 1 is about to finish \n");
    return ((void *) 1);
}
/* for thread 2 */
void * thrd_f2(void *arg)
{
    sleep(1);
    printf("Thread 2 is about to finish \n");
    return ((void *) 2);
}

void err_sys(char *str, int msg)
{
    printf ("%s %d\n", str, msg);
    exit (1);
}

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```

```
* "highlike: demonstrate without phread_join() function */
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##inclose certicin().
##inclose certicin().
##inclose certicin().
##inclose for metal seculation */
##inclose for metal
```

```
/* thjeini.c: demonstrate phread join() function */
/* synchronizing sequence of thread's job
#include gradio.b>
#include gradio.b>
#include gradio.b>
#include gradio.b>
#include gradio.b
#include gradio.b>
#include gradio.bo
#include g
```

```
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```

```
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```

```
/* thysinic: demonstrate phread_join() function */
/* synchronizing sequence of thread's job*/
#include cattinic.ho
#include cattinic.h
```

```
/* thjoinit.c: demonstrate phread juint) function */
/* synchronizing sequence of thread's jeb*/
fincided cradio.hb
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fincided cradio.hb
fincided primarile in
which is intermined to
void "thread function(void ");
void out; say[chas ", int);
int consists of;
void amin()
{
   pthread; thread in[WINREADS];
   int (,) rc;
   for(i=0) i < WINREADS[; i++)
        if (rc *pthread cented (sthread id[i], NULL, thread function, (void *) i)) !* 0)
        err sys("ENCON] return code from pithread create() is", rc);
   for(i=0) i < WINREADS[; i++)
        if (rc *pthread conj i++)
        if (rc *pthread conj i++)
        if (rd *pthr
```

The pthread_cancel()

- □ The **pthread_cancel**() function requests cancellation of the target thread.
- □ The target thread is cancelled, <u>based on</u> <u>it's ability to be cancelled</u>.
- When cancel ability is deferred, <u>all cancels</u> are held pending in the target thread until the thread changes the cancel ability, calls a function that is a cancellation point.

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The pthread_cancel()

- Cancellation points:
 - pthread_cond_timedwait()
 - pthread_cond_wait()
 - pthread_delay_np()
 - pthread_join()
 - pthread_join_np()
 - pthread_extendedjoin_np()
 - pthread_testcancel()

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// theamost.c demonstrate pthread_cancel() function */
#include_cytimed.hb
#include_cytimed.hb
#include_cytimed.hb
#include_cytimed.hc
#inclu

The pthread_cleanup_push()

#include <pthread.h>
void pthread_cleanup_push(void (*routine)(void *), void *arg);

- The pthread_cleanup_push() function pushes a clean up function routine, to be called with the single argument, arg, when the thread performs one of the following actions.
 - pthread_exit()
 - pthread_cancel()

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The **pthread_cleanup_pop**()

#include <pthread.h>
void pthread_cleanup_pop(int execute);

- □ The **pthread_cleanup_pop**() function pops the last cleanup handler from the cancellation cleanup stack.
- If the execute parameter is nonzero, the handler is called with the argument specified by the pthread_cleanup_push() call with which the handler was registered.

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```
/*thpushpop.c: demonstrate
pthread_cleanup_push() and pthread_cleanup_pop() */
#include finclude cytion.b
#include cytion.b
#incl
```

The pthread_cleanup_pop() void err_sys(char *str, int msg) { printf ("%s td\n", str, msg); exit (1); } void cleanupHandler (void *arg) { printf("Master ask me terminate myself\n"); printf("I will be back!\n"); } void *threadfunc (void *parm) { printf("Sitered secondary thread\n"); /* push clearup function after cancell */ phile (1); printf("Master! Bon't terminate ms! I want live forever!\n"); printf("Master! Don't terminate ms! I want live forever!\n"); printf("Master! Don't terminate ms! I want live forever!\n"); pthread_testcancel(); /* cancel point */ sleep(1); } pthread_cleanup_pop(0); return NULL; }