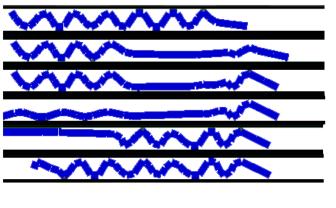


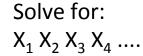
Posture Image I_t

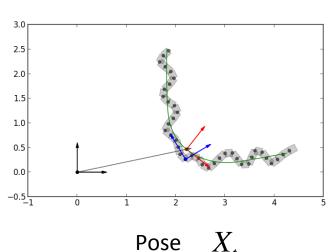


Inputs

Given experience:

 $I_1 I_2 A_1 I_3 I_4 A_3 I_5 I_6 A_5 \dots$





Locomotion Step A_t