

```

clc,clear,close
%eyes open
load('C:\Users\fould\MATLAB Drive\MobileSensorData\eyes_open')
ax2 = Acceleration.X.^2;
ay2 = Acceleration.Y.^2;
az2 = Acceleration.Z.^2;

g = sqrt(ax2 + ay2 + az2);
g1 = g;
t = Acceleration.Timestamp;
std_open = std(g)
mean_open = mean(g)

figure(1)
hold on
plot(g)
xlabel('time')
ylabel('gravity (m/s^2)')
title('measured gravity over time (eyes open)')

%eyes closed
load('C:\Users\fould\MATLAB Drive\MobileSensorData\eyes_closed')
ax2 = Acceleration.X.^2;
ay2 = Acceleration.Y.^2;
az2 = Acceleration.Z.^2;

g = sqrt(ax2 + ay2 + az2);
g2 = g;
t = Acceleration.Timestamp;
std_closed = std(g)
mean_closed = mean(g)

plot(g)
xlabel('time')
ylabel('gravity (m/s^2)')
title('measured gravity over time')
legend('eyes open','eyes closed')
hold off

K = std_open/(std_open + std_closed);
g1 = g1(1:numel(g2));
g3 = g1 + K.*(g2-g1)
std3 = (1-K)*std_open

```

```
std_open =
```

```
0.1450
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```
mean_open =
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```
9.7961
```

```
std_closed =
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```
0.2434
```

mean_closed =

9.7733

g3 =

10.1877

9.8929

9.7288

9.7929

9.6631

9.7421

9.7701

9.8153

9.8109

9.9620

9.8349

9.6526

9.7513

9.6654

9.9444

9.6594

9.8357

9.8169

9.5621

9.8578

9.7581

9.8038

9.6672

9.7787

9.7726

9.6202

9.9939

9.7016

10.0024

9.6195

9.7444

9.6673

9.8775

9.7881

9.9911

9.6569

9.9508

9.6566

9.7299

9.8292

9.7524

9.7719

9.8121

9.6179

9.9230

9.6471

std3 =

0.0909

