

## Math 6108 Homework 2

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### Problem 1.

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1. Let  $S = \{(x, y) \in \mathbf{R}^2 \mid x \geq 0, y \geq 0\}$ . Then  $S$  is not a subspace of  $\mathbf{R}^2$  because  $(1, 0) \in S$ , but  $-(1, 0) = (-1, 0) \notin S$ ; that is,  $S$  is not closed under scalar multiplication in  $\mathbf{R}^2$ .
2. Let  $S = \{f \in \mathcal{P}^3 \mid f(4) = 0\}$ . Then  $S$  is a subspace of  $\mathcal{P}^3$ . To see this, let  $f, g \in S$ , and let  $a \in \mathbf{R}$ . Then  $(f + g)(4) = f(4) + g(4) = 0$ , so  $f + g \in S$ , and  $(af)(4) = af(4) = 0$ , so  $af \in S$ . Finally,  $\mathbf{0} \in S$  because  $\mathbf{0}(4) = 0$ , so  $S$  is nonempty. This shows that  $S$  is a subspace of  $\mathcal{P}^3$ .
3. Let  $S = \{f \in \mathcal{P}^4 \mid f(4) = 2\}$ . Then  $S$  is not a subspace of  $\mathcal{P}^4$  because  $\mathbf{0} \notin S$ , as  $\mathbf{0}(4) = 0 \neq 2$ . A subspace must contain the zero element of the larger space.
4. Let  $S = \{f \in \mathcal{F} \mid f'(x) + f(x) = 2\}$ . Then  $S$  is not a subspace of  $\mathcal{F}$  because  $\mathbf{0} \notin S$ , as  $\mathbf{0}'(x) + \mathbf{0}(x) = 0 \neq 2$ .
5. Let  $S = \{f \in \mathcal{F} \mid f''(x) - 2f(x) = 0\}$ . Then  $S$  is a subspace of  $\mathcal{F}$ . To see this, let  $f, g \in S$ , and let  $a \in \mathbf{R}$ . Then  $(f + g)''(x) - 2(f + g)(x) = f''(x) - 2f(x) + g''(x) - 2g(x) = 0$ , so  $f + g \in S$ , and  $(af)''(x) - 2(af)(x) = a(f''(x) - 2f(x)) = 0$ , so  $af \in S$ . This shows that  $S$  is a subspace of  $\mathcal{F}$ .

### Problem 2.

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Let  $\mathcal{C}$  and  $\mathcal{D}$  denote the sets of all continuous and differentiable functions. Then  $\mathcal{C}$  and  $\mathcal{D}$  are subspaces of  $\mathcal{F}$ . This is because continuity and differentiability are preserved under addition and scalar multiplication. That is, if  $f, g$  are continuous functions, and  $a \in \mathbf{R}$ , then  $f + g$  and  $af$  are continuous functions. Similarly, if  $f, g$  are differentiable, and  $a \in \mathbf{R}$ , then  $f + g$  and  $af$  are differentiable. Since  $\mathbf{0} \in \mathcal{C}$ , and  $\mathbf{0} \in \mathcal{D}$ , it follows that  $\mathcal{C}$  and  $\mathcal{D}$  are subspaces of  $\mathcal{F}$ .

### Problem 3.

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Let  $V$  be a vector space over a field  $\mathbb{F}$ , and let  $S \subseteq V$  be nonempty. Then  $S$  is subspace of  $V$  if and only if  $S$  is closed under linear combinations.

*Proof.* Let  $S$  be a subspace of  $V$ , let  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n \in S$ , let  $c_1, c_2, \dots, c_n \in \mathbf{R}$ , and let  $\mathbf{v} = c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \dots + c_n\mathbf{v}_n$ . If  $\mathbf{u}_i = c_i\mathbf{v}_i$ , then  $\mathbf{u}_i \in S$  for  $i = 1$  to  $n$  because subspaces are closed under scalar multiplication. Furthermore,  $\mathbf{v} = \mathbf{u}_1 + \mathbf{u}_2 + \dots + \mathbf{u}_n$ ; therefore,  $\mathbf{v} \in S$  because subspaces are closed under addition (we have to apply this inductively). Thus,  $S$  is closed under linear combinations.

Suppose that  $S$  is closed under linear combinations. If  $\mathbf{v}_1, \mathbf{v}_2 \in S$ , then  $\mathbf{v}_1 + \mathbf{v}_2$  is a linear combination of elements of  $S$  and therefore also in  $S$ . Similarly, if  $a \in \mathbb{F}$ , then  $a\mathbf{v}_1$  is a linear combination of elements of  $S$  and therefore also in  $S$ . Hence,  $S$  is a subspace of  $V$ .  $\square$

### Problem 4.

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Let  $S_1$  and  $S_2$  be subspaces of a vector space  $V$  over a field  $\mathbb{F}$ . Then  $S_1 \cap S_2$  is a subspace of  $V$ .

*Proof.* Since  $S_1$  and  $S_2$  are subspaces they both contain  $\mathbf{0} \in S$ . Therefore,  $\mathbf{0} \in S_1 \cap S_2$ , so  $S_1 \cap S_2$  is nonempty.

Let  $\mathbf{v}_1, \mathbf{v}_2 \in S_1 \cap S_2$ , and let  $a \in \mathbb{F}$ . Then for  $i \in \{1, 2\}$ ,  $\mathbf{v}_1, \mathbf{v}_2 \in S_i$ , so  $\mathbf{v}_1 + \mathbf{v}_2 \in S_i$ , and  $a\mathbf{v}_1 \in S_i$  because  $S_i$  is subspace of  $V$ . Therefore,  $\mathbf{v}_1 + \mathbf{v}_2 \in S_1 \cap S_2$ , and  $a\mathbf{v}_1 \in S_1 \cap S_2$ .

This shows that  $S_1 \cap S_2$  is a subspace of  $V$ . □

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### Problem 5.

1. Let  $S = \{1 + x^2, 1 + x, x^2 - x\} \subseteq \mathcal{P}^2$ . Then  $S$  is linearly dependent because

$$c_1(x^2 - x) + c_2(1 + x^2) + c_3(1 + x) = 0$$

if we choose  $c_1 = 1$ ,  $c_2 = -1$ , and  $c_3 = 1$ . Furthermore,  $x^2 - x = 1 + x^2 + (-1)(1 + x)$ .

2. Let  $S = \{\cos(x), \sin(x), 1\} \subseteq \mathcal{F}$ . Then  $S$  is linearly independent. To see this, let  $c_1, c_2, c_3 \in \mathbf{R}$ , and suppose that

$$c_1 \cos(x) + c_2 \sin(x) + c_3 = 0.$$

This must be true for all  $x \in \mathbf{R}$  by the definition of scalar multiplication and addition in  $\mathcal{F}$ ; in particular, if  $x = 0$ , then we obtain  $c_1 = -c_3$ , and if  $x = \pi$ , then we obtain  $c_1 = c_3$ . Thus,  $c_1 = c_3 = 0$ . This means that  $c_2 \sin(x) = 0$ . Taking  $x = \frac{\pi}{2}$ , we get  $c_2 = 0$ . Thus,  $c_1 = c_2 = c_3 = 0$ . This means that  $S$  is linearly independent.

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### Problem 6.

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### Problem 7.

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### Problem 8.

Let  $S$  be the set of all symmetric matrices in  $\mathbf{R}^{n \times n}$ .

1.  $S$  is a subspace of  $\mathbf{R}^{n \times n}$ .

*Proof.* Clearly,  $S$  is nonempty (it contains, for example, the zero matrix). Let  $A, B \in S$ , and let  $a \in \mathbf{R}$ . Then  $(A + B)^T = A^T + B^T = A + B$ , so  $A + B \in S$ . Furthermore,  $(aA)^T = aA^T$ , so  $aA \in S$ . This shows that  $S$  is a subspace of  $\mathbf{R}^{n \times n}$ . □

2. Let  $[A]_{k\ell}$  mean taking the element in the  $k$ th row and  $\ell$ th column of a matrix  $A$ . Define  $B = \{A^{ij} : 1 \leq j \leq i \leq n\}$ , where  $A^{ij} \in \mathbf{R}^{n \times n}$  is defined by

$$A_{k\ell}^{ij} = \begin{cases} 1 & (k, \ell) = (i, j) \text{ or } (k, \ell) = (j, i) \\ 0 & \text{otherwise,} \end{cases}$$

for  $k, \ell = 1, 2, \dots, n$ . Then  $B$  is a basis for  $S$ .

*Proof.* We need to show that  $B$  is linearly independent and that  $\text{span}(B) = S$ .

1. Suppose that

$$\sum_{A^{ij} \in B} c_{ij} A^{ij} = \mathbf{0}$$

for some  $\{c_{ij} : 1 \leq j \leq i \leq n\} \subseteq \mathbf{R}$ . For  $\ell \leq k$ , we have

$$\sum_{1 \leq j \leq i \leq n} c_{ij} a_{k\ell}^{ij} = 0.$$

Since  $\ell \leq k$ , and  $j \leq i$ , the definition of  $A_{k\ell}^{ij}$  implies that only the term  $c_{k\ell} A_{k\ell}^{k\ell}$  is nonzero. Then we get  $c_{k\ell} = 0$ . Since  $\ell \leq k$  were arbitrary, it follows that  $c_{ij} = 0$  for all  $1 \leq j \leq i \leq n$ , so  $B$  is linearly independent.

2. If  $(i, j) \neq (k, \ell)$  and  $(i, j) \neq (\ell, k)$ , then  $A_{k\ell}^{ij} = 0 = A_{\ell k}^{ij}$ . If  $(i, j) = (k, \ell)$ , then  $A_{k\ell}^{ij} = 1 = A^{ij} \ell k$ . Hence,  $A^{ij} = (A^{ij})^T$  for all  $1 \leq i \leq j \leq n$ . Thus  $B \subseteq S$ , which implies that every element of  $\text{span}(B)$  is a linear combination of elements of  $S$ . Since  $S$  is a subspace by part 1. and subspaces are closed under linear combination by Problem 3., it follows that  $\text{span}(B) \subseteq S$ .

Conversely, let  $C \in S$  be a symmetric matrix. Since

$$\begin{aligned} \left[ \sum_{A^{ij} \in B} C_{ij} A^{ij} \right]_{k\ell} &= \sum_{1 \leq j \leq i \leq n} C_{ij} A_{k\ell}^{ij} \\ &= \begin{cases} C_{k\ell} & \ell \leq k \\ C_{\ell k} (= C_{k\ell}) & k \leq \ell \end{cases} \\ &= C_{k\ell} \end{aligned}$$

by the symmetry of  $C$ , we must have

$$C = \sum_{A^{ij} \in B} C_{ij} A^{ij}.$$

Thus,  $C \in \text{span}(B)$ . This shows that  $S \subseteq \text{span}(B)$ . Since  $S \subseteq \text{span}(B)$ , and  $\text{span}(B) \subseteq S$ , it follows that  $\text{span}(B) = S$ .

This completes the proof that  $B$  is a basis for  $S$ . □