```
┌─────────────────────────────────────┐
│         view_frames Result          │
│                                     │
│  Recorded at time: 1444516416.144   │
└─────────────────────────────────────┘

              base_footprint
                   │
                   │  Broadcaster: /robot_state_publisher
                   │  Average rate: 20.201 Hz
                   │  Most recent transform: 1444516416.625 ( -0.480 sec old)
                   │  Buffer length: 4.950 sec
                   ▼
                base_link
                   │
                   │  Broadcaster: /robot_state_publisher
                   │  Average rate: 20.201 Hz
                   │  Most recent transform: 1444516416.625 ( -0.480 sec old)
                   │  Buffer length: 4.950 sec
                   ▼
            secondary_base_link
                   │
                   │  Broadcaster: /robot_state_publisher
                   │  Average rate: 20.201 Hz
                   │  Most recent transform: 1444516416.625 ( -0.480 sec old)
                   │  Buffer length: 4.950 sec
                   ▼
              head_base_link
                   │
                   │  Broadcaster: /robot_state_publisher
                   │  Average rate: 20.201 Hz
                   │  Most recent transform: 1444516416.625 ( -0.480 sec old)
                   │  Buffer length: 4.950 sec
                   ▼
            head_pan_servo_link
                   │
                   │  Broadcaster: /robot_state_publisher
                   │  Average rate: 12.783 Hz
                   │  Most recent transform: 1444516416.038 ( 0.106 sec old)
                   │  Buffer length: 4.850 sec
                   ▼
           head_pan_bracket_link
                   │
                   │  Broadcaster: /robot_state_publisher
                   │  Average rate: 20.201 Hz
                   │  Most recent transform: 1444516416.625 ( -0.480 sec old)
                   │  Buffer length: 4.950 sec
                   ▼
            head_tilt_servo_link
                   │
                   │  Broadcaster: /robot_state_publisher
                   │  Average rate: 12.783 Hz
                   │  Most recent transform: 1444516416.038 ( 0.106 sec old)
                   │  Buffer length: 4.850 sec
                   ▼
           head_tilt_bracket_link
                   │
                   │  Broadcaster: /robot_state_publisher
                   │  Average rate: 20.201 Hz
                   │  Most recent transform: 1444516416.625 ( -0.480 sec old)
                   │  Buffer length: 4.950 sec
                   ▼
             camera_base_link
                   │
                   │  Broadcaster: /robot_state_publisher
                   │  Average rate: 20.201 Hz
                   │  Most recent transform: 1444516416.625 ( -0.480 sec old)
                   │  Buffer length: 4.950 sec
                   ▼
           camera_base_post_link
                   │
                   │  Broadcaster: /robot_state_publisher
                   │  Average rate: 20.201 Hz
                   │  Most recent transform: 1444516416.625 ( -0.480 sec old)
                   │  Buffer length: 4.950 sec
                   ▼
               camera_link
              ╱           ╲
```

Broadcaster: /robot_state_publisher
Average rate: 20.201 Hz
Most recent transform: 1444516416.625 (-0.480 sec old)
Buffer length: 4.950 sec

Broadcaster: /robot_state_publisher
Average rate: 20.201 Hz
Most recent transform: 1444516416.625 (-0.480 sec old)
Buffer length: 4.950 sec

```
     camera_depth_frame              camera_rgb_frame
           │                              │
```

Broadcaster: /robot_state_publisher
Average rate: 20.201 Hz
Most recent transform: 1444516416.625 (-0.480 sec old)
Buffer length: 4.950 sec

Broadcaster: /robot_state_publisher
Average rate: 20.201 Hz
Most recent transform: 1444516416.625 (-0.480 sec old)
Buffer length: 4.950 sec

```
  camera_depth_optical_frame      camera_rgb_optical_frame
```