

# JACOB MORONI OLSON

AUTONOMY · CONTROLS · PERCEPTION

1322 N 950 W, OREM, UTAH 84057

☎ 714.598.5938 | ✉ JacobMoroniOlson@gmail.com | 📱 JacobMoroni | 🌐 JacobMoroni

## EXPERIENCE

### Fortem Technologies

Pleasant Grove, Utah

SENIOR CONTROLS ENGINEER

Sep 2019 - Present

- Researching, developing, and implementing new autonomy and control algorithms for DroneHunter
- Collaborating on estimation, tracking, and swarm behavior development
- Performing system dynamics analysis to improve capture performance
- Designing simulation, visualization, and analysis tools to speed development of new features
- Planning and leading hardware testing and data collections for DroneHunter
- Collaborating and planning development with DroneHunter software team and algorithms team

### BYU MAGICC Lab

Provo, Utah

RESEARCH ASSISTANT

Sep 2017 - Oct 2019

- Software algorithm and GUI development in Python and C++ with ROS
- Development and testing in a simulation environment using ROS Gazebo
- Implemented research software on multirotor hardware
- Integrated perception sensors such as RGB-D cameras, LIDAR sensors, and ultrasonic sonar sensors
- Gained in-depth understanding of 3D mapping, perception, and localization techniques
- Version control using git

### Lockheed Martin Procerus Technologies

Vineyard, Utah

ENGINEERING INTERN

May 2017 - August 2019

- Designed and implemented several test fixtures used in production and engineering
- Led a product design change to improve manufacturability and reliability
- Wrote and implemented robust software for test fixtures used in production
- Assisted with debugging and building production software
- Wrote documentation and build documents for products

### Brigham Young University

Provo, Utah

BYU CAPSTONE

Sep 2016 - Apr 2017

- Worked with a team of five to design and build a production-ready handheld dusting vacuum
- Learned effective design process implementation and functional prototyping procedures
- Surface and solid modeling using CAD software

### BYU Robotics and Dynamics Lab

Provo, Utah

UNDERGRAD RESEARCH ASSISTANT

Sep 2016 - Apr 2017

- Applied for and received a grant (ORCA) to fund research
- Calibration and integration of several sensors using Python with ROS
- Mechatronic design using Eagle and data sheets
- Gained in-depth understanding of robotics platforms including compliant and soft robotics

### Autoliv

Ogden, Utah

MECHANICAL ENGINEERING INTERN

May 2016 - Aug 2016

- Member of research and development team for frontal airbag modules
- Worked independently and with teams to model and build various test fixtures
- Modeled a variety of complex parts using solid and surface modeling in Solidworks
- Presented findings to 10+ managers and acting president

## EDUCATION

### Brigham Young University

Provo, Utah

MASTERS IN MECHANICAL ENGINEERING

December 2019

- 3.93 GPA
- Thesis: Collaborative UAV Planning, Mapping, and Exploration in GPS-Denied Environments

### Brigham Young University

Provo, Utah

B.S. IN MECHANICAL ENGINEERING · MINOR IN BUSINESS MANAGEMENT

Apr 2017

- 3.81 GPA
- Four-year Academic Scholarship - half tuition

## COURSEWORK

|                                  |  |
|----------------------------------|--|
| AUTONOMOUS SYSTEMS               | • SLAM, Kalman Filters, Particle Filters, Markov Decision Processes              |
| FLIGHT DYNAMICS AND CONTROL      | • Develop autopilot flight stack for fixed wing and multirotor UAVs              |
| DEEP LEARNING                    | • Develop and implement several deep neural network architectures and techniques |
| ROBOTIC VISION                   | • Object tracking, structure from motion, visual odometry, obstacle avoidance    |
| ROBOTICS AND CONTROLS            | • PID, state space control, loopshaping, and kinematics of manipulators          |
| OPTIMIZATION                     | • Modeling and design of several optimization techniques                         |
| C++ GUI DESIGN                   | • Object Oriented Programming and GUI design using Qt and OSG                    |
| LINEAR & NONLINEAR SYSTEM THEORY | • Stability analysis and controller design                                       |