

JACOB MORONI OLSON

AUTONOMY · CONTROLS · PERCEPTION

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EXPERIENCE

Fortem Technologies

SENIOR ALGORITHMS ENGINEER

- Researching, developing, and implementing new autonomy and control algorithms for DroneHunter
- Collaborating on estimation and tracking development
- Performing system dynamics analysis to improve control and capture performance
- Designing simulation, visualization, and analysis tools to speed development of new features
- Planning and leading hardware testing and data collections for DroneHunter
- Collaborating and planning development with DroneHunter software team and algorithms team
- C++ | Python | ROS | ArduPilot | OpenCV | PyQt | Qt | Bash | Git | Markdown | LaTeX

Pleasant Grove, Utah

Sep 2019 - Present

BYU MAGICC Lab

RESEARCH ASSISTANT

- Software algorithm and GUI development in Python and C++ with ROS
- Development and testing in a simulation environment using ROS Gazebo
- Implemented research software on multirotor hardware
- Integrated perception sensors such as RGB-D cameras, LIDAR sensors, and ultrasonic sonar sensors
- Gained in-depth understanding of 3D mapping, perception, and localization techniques
- Version control using git

Provo, Utah

Sep 2017 - Oct 2019

Lockheed Martin Procerus Technologies

ENGINEERING INTERN

- Designed and implemented several test fixtures used in production and engineering
- Led a product design change to improve manufacturability and reliability
- Wrote and implemented robust software for test fixtures used in production
- Wrote documentation and build documents for products

Vineyard, Utah

May 2017 - August 2019

Brigham Young University

BYU CAPSTONE

- Worked with a team of five to design and build a production-ready handheld dusting vacuum
- Learned effective design process implementation and functional prototyping procedures
- Surface and solid modeling using CAD software

Provo, Utah

Sep 2016 - Apr 2017

BYU Robotics and Dynamics Lab

UNDERGRAD RESEARCH ASSISTANT

- Applied for and received a grant (ORCA) to fund research
- Calibration and integration of several sensors using Python with ROS
- Mechatronic design using Eagle and data sheets
- Gained in-depth understanding of robotics platforms including compliant and soft robotics

Provo, Utah

Sep 2016 - Apr 2017

Autoliv

MECHANICAL ENGINEERING INTERN

- Member of research and development team for frontal airbag modules
- Worked independently and with teams to model and build various test fixtures
- Modeled a variety of complex parts using solid and surface modeling in Solidworks

Ogden, Utah

May 2016 - Aug 2016

EDUCATION

Brigham Young University

MASTERS IN MECHANICAL ENGINEERING

- 3.93 GPA
- Thesis: Collaborative UAV Planning, Mapping, and Exploration in GPS-Denied Environments

Provo, Utah

December 2019

Brigham Young University

B.S. IN MECHANICAL ENGINEERING · MINOR IN BUSINESS MANAGEMENT

- 3.81 GPA
- Four-year Academic Scholarship - half tuition

Provo, Utah

Apr 2017

COURSEWORK & QUALIFICATIONS

AUTONOMOUS SYSTEMS

FLIGHT DYNAMICS AND CONTROL

DEEP LEARNING

ROBOTIC VISION

ROBOTICS AND CONTROLS

OPTIMIZATION

C++ GUI DESIGN

LINEAR & NONLINEAR SYSTEM THEORY

SECRET SECURITY CLEARANCE | PART 107 REMOTE PILOT LICENSE

- SLAM, Kalman Filters, Particle Filters, Markov Decision Processes
- Develop autopilot flight stack for fixed wing and multirotor UAVs
- Develop and implement several deep neural network architectures and techniques
- Object tracking, structure from motion, visual odometry, obstacle avoidance
- PID, state space control, loopshaping, and kinematics of manipulators
- Modeling and design of several optimization techniques
- Object Oriented Programming and GUI design using Qt and OSG
- Stability analysis and controller design