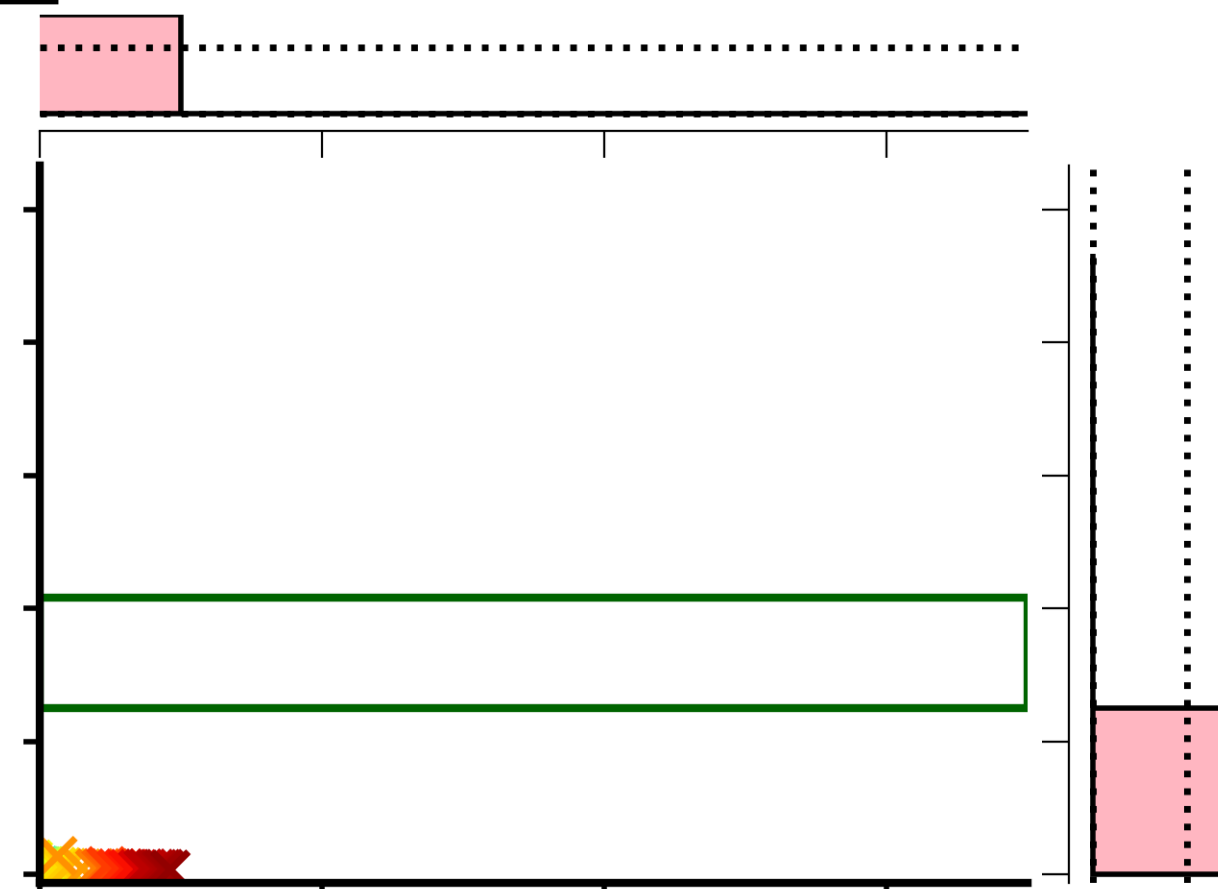
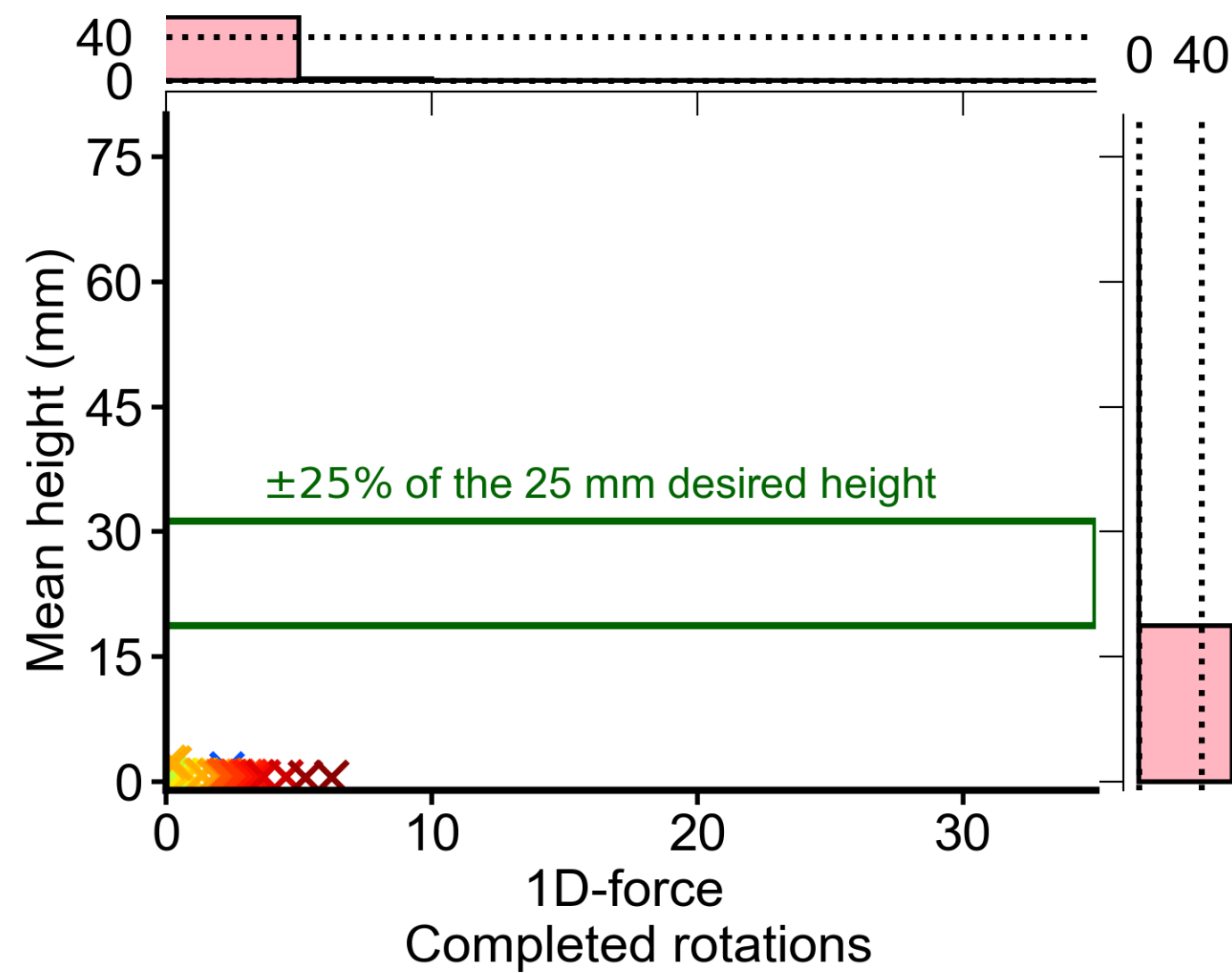


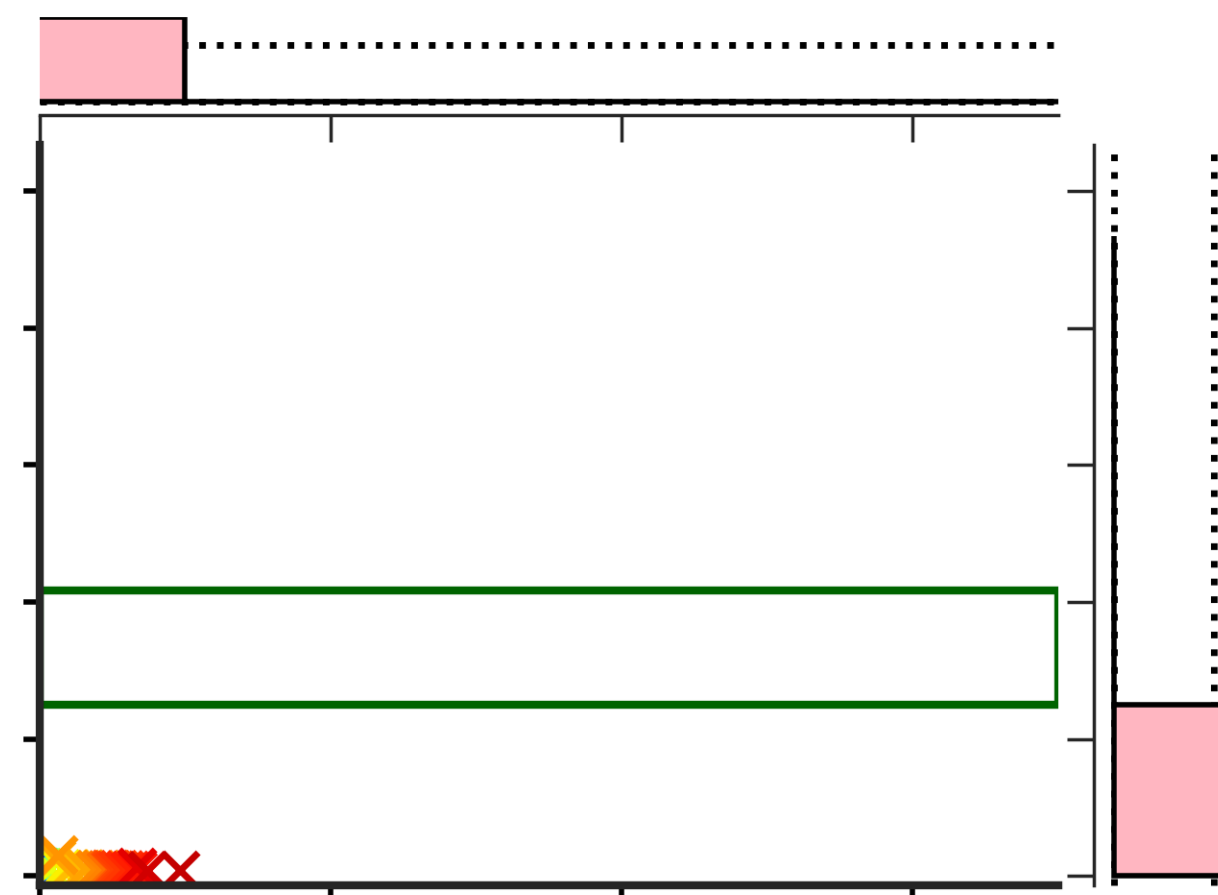
No-force



Contact-force



1D-force
Completed rotations



3D-force

