Team Number:	School:

2016 Software Design and Simulation Score Sheet

	se: To document the software design process and practices used eating and testing the robot program. (25 Points)	Possible Points	Score
SOFTV	NARE DESIGN PROCESS (180 points))		
	dence of custom software design versus using the default robot gram	50	
Cor	mments:		
• Evi	Idence that a software design process was followed Identifying the required operations (e.g., locomotion/drive, chassis rotate, arm lift/bend/rotate/extend, claw rotate/open,) Designing each required operation (e.g., flow charting the steps involved) Designing a user-interface (e.g., how the robot will be controlled) Test planning (how correct operation of the robot program will be tested)	50	
Cor	mments:		
the the	dence of advanced testing and debugging techniques utilized to verify correct operation of the robot program without depending solely on physical robot (e.g., software simulation via Simulink, virtual world, tware-in-the-loop, etc.)	50	
Cor	mments:		
def	dence that the defined program functionality is applicable to the ined task(s). The program functionality maps clearly to the desired me strategies.	30	
Cor	mments:		
SOFTV	NARE DESIGN PRACTICES (55 points)		
	nsideration of good software design practices (e.g., commenting, naming ventions, code simplicity, modularity)	25	
Cor	mments:		
sto	nsideration of error conditions and response actions. (e.g., motor/servo p limits, out of bounds values, etc.)	15	
	nsideration of code portability and maintainability (e.g., use of iables vs. hardcoding values; use of functions, tasks and subsystems, .)	15	
	mments:		

CLARITY OF DESIGN AND DESCRIPTION (15 points)		
Clarity of design and description.	15	
Comments:		
Total	250	
	÷10	<u>÷ 10</u>
Final score:	25	