2016 Software Design and Simulation Score Sheet

r creating and testing the robot program. (25 Points)	Possible Points	Score
OFTWARE DESIGN PROCESS (85 points)		
 Evidence that a software design process was followed Identifying the required operations (e.g., locomotion/drive, chassis rotate, arm lift/bend/rotate/extend, claw rotate/open,) Designing each required operation (e.g., flow charting the steps involved, consideration of user interface, etc.) Coding and Verification (how correct operation of the robot program is validated) Release and Maintenance (version control, managing changes/updates) 	30	
Comments:		
Evidence of custom software design versus using the default robot		
program	15	
Comments:		
Evidence that advanced simulation techniques were utilized to verify the correct program operation (e.g., Simulink, virtual world, external mode, etc.)	20	
Comments:		
Evidence that test and debug techniques were considered (e.g., debug terminal, print to screen, real-time debugger, external mode/in-the-loop,		
etc.)	10	
Comments:		
Evidence that the program functionality is connected to the teams' scoring objectives/strategies.	10	
Comments:		

Team Number:	School:	 Page 1 of 2
		1 ago 1 01 <u>-</u>

SC	PFTWARE DESIGN PRACTICES (40 points)		
•	Consideration of good software design practices (e.g., commenting, naming conventions, code simplicity, code modularity/portability)	15	
	Comments:	,	
•	Consideration of error conditions and response actions. (e.g., illegal operations, invalid states, motor/servo stop limits, out of bounds values, etc.)	15	
	Comments:		
CL	ARITY OF DESIGN AND DESCRIPTION (10 points)		
•	Clarity of design and description (well written, easy to follow, no excess material/information)	10	
	Comments:	<u> </u>	
	Total	125	
		<u>÷5</u>	<u>÷ 5</u>
	Final score:	25	

ludge name/number (print):	