

Problem 1

c) i) Implement a KF to estimate the joint augmented aircraft states.

First, combine the Aircraft A and Aircraft B DT LTI matrices.

$$\underset{\text{FS}}{F_s} = \begin{bmatrix} F_A & 0 \\ 0 & F_B \end{bmatrix} \quad A_s = \begin{bmatrix} A_A & 0 \\ 0 & A_B \end{bmatrix} \quad W_s = \begin{bmatrix} W & 0 \\ 0 & W \end{bmatrix} \quad \underset{\text{FS}}{P_s} = \begin{bmatrix} P_A & 0 \\ 0 & P_B \end{bmatrix}$$

Now, form a new Q_s matrix:

$$\underline{Z}_s = dt \begin{bmatrix} -A_s & \underset{\text{FS}}{P_s} W_s \underset{\text{FS}}{P_s}' \\ 0 & A_s' \end{bmatrix}$$

$$e^{\underline{Z}_s} = \exp(\underline{Z}_s) = \begin{bmatrix} (\dots) & \underset{\text{FS}}{P_s}^{-1} Q_s \\ 0 & \underset{\text{FS}}{P_s}' \end{bmatrix} \Rightarrow Q_s = (\underset{\text{FS}}{P_s}')' [\underset{\text{FS}}{P_s}^{-1} Q_s] \quad (\text{from } e^{\underline{Z}_s} \text{ matrix})$$

$$\underset{\text{QS}}{Q_s} = \begin{bmatrix} 0.83 & 2.50 & 0.03 & 0.10 & 0 & 0 & 0 & 0 \\ 2.50 & 10.00 & 0.07 & 0.33 & 0 & 0 & 0 & 0 \\ 0.03 & 0.07 & 0.21 & 0.63 & 0 & 0 & 0 & 0 \\ 0.10 & 0.33 & 0.63 & 2.31 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0.83 & 2.50 & 0.07 & 0.03 \\ 0 & 0 & 0 & 0 & 2.50 & 10.00 & 0.03 & 0.17 \\ 0 & 0 & 0 & 0 & 0.07 & 0.03 & 0.21 & 0.67 \\ 0 & 0 & 0 & 0 & 0.03 & 0.17 & 0.67 & 2.50 \end{bmatrix}$$

$$\underset{\text{HS}}{H_s} = \begin{bmatrix} H & 0 \\ H & -H \end{bmatrix} \Rightarrow Y_s(u) = H X_s(u) + V_D(u)$$

Top "row" handles original Aircraft A "direct" measurements,
bottom "row" is the result of the Aircraft B measurements
being a sum of Aircraft A measurement plus transponder measurements.

$$Y_D(u) = r_A(u) - r_B(u)$$

$\hookrightarrow H \quad \quad \quad \hookrightarrow -H$

$$\underset{\text{RS}}{R_s} = \begin{bmatrix} R_A & 0 \\ 0 & R_B \end{bmatrix}$$

$$R_s = \begin{bmatrix} 20 & 0.05 & 0 & 0 \\ 0.05 & 20 & 0 & 0 \\ 0 & 0 & 10 & 0.15 \\ 0 & 0 & 0.15 & 10 \end{bmatrix} \quad (m^2)$$