```
view_frames Result

Recorded at time: 1754533813.534
```

base_link

Broadcaster: /robot_state_publisher
Average rate: 10.203 Hz
Most recent transform: 1754533813.452 (0.083 sec old)
Buffer length: 4.901 sec

scanner_mount

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1754533813.534 sec old)
Buffer length: 0.000 sec

LMS-511

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1754533813.534 sec old)
Buffer length: 0.000 sec

LMS_511_scan_plane