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Relativistic non-ideal flows

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Abstract

Stuff emits radiation when it falls into a black hole. I'd like to see exactly how much of it.

1 Notational preface

I will use greek indices ($\mu, \nu, \rho \dots$) to denote 4-dimensional indices ranging from 0 to 3, and latin indices ($i, j, k \dots$) to denote 3-dimensional indices ranging from 1 to 3.

I will use the “mostly plus” metric for flat Minkowski space-time, $\eta_{\mu\nu} = \text{diag}(-, +, +, +)$: therefore four-velocities will have square norm $u^\mu u_\mu = -1$. I will use Einstein summation convention: if an index appears multiple times in the same monomial, it is meant to be summed over

Take a diffeomorphism $x \rightarrow y$, with Jacobian matrix $\partial y^\mu / \partial x^\nu$. The indices of contravariant vectors, trasforming as

$$V^\mu \rightarrow \left(\frac{\partial y^\mu}{\partial x^\nu} \right) V^\nu \quad (1.1)$$

will be denoted as upper indices, while the indices of covariant vectors, trasforming as

$$V_\mu \rightarrow \left(\frac{\partial x^\nu}{\partial y^\mu} \right) V_\nu \quad (1.2)$$

will be denoted as lower indices; the same applies to higher rank tensors.

Unless otherwise specified, I will work in geometrized units, where $c = G = 1$.

Take a tensor with many indices, T_{IJ} , where I is shorthand for the n indices $\mu\nu\rho \dots$ and the same applies to J . These indices can be symmetrized and antisymmetrized, and I will use the following conventions:

$$T_{(I)J} = \frac{1}{n!} \sum_{\sigma \in S_n} T_{\sigma(I)J} \quad (1.3)$$

$$T_{[I]J} = \frac{1}{n!} \sum_{\sigma \in S_n} \text{sign } \sigma T_{\sigma(I)J} \quad (1.4)$$

where $S_n \ni \sigma$ is the group of permutations of n elements, and $\text{sign } \sigma$ is 1 if σ is an even permutation (it can be obtained in an even number of pair swaps) and -1 otherwise.

2 Useful formulas

2.1 Nobili

Tensor calculus The covariant derivative keeps account of the shifting of the basis vectors:

$$\nabla_\mu A^\nu = \partial_\mu A^\nu + \Gamma_{\alpha\mu}^\nu A^\alpha \quad (2.1)$$

The rank-3 objects Γ are called Christoffel symbols. They are not tensors! they depend on the choice of basis e_α , and they satisfy $\nabla_\mu e_\alpha = \Gamma_{\mu\alpha}^\nu e_\nu$.

If we have the metric, they can be calculated as:

$$\Gamma_{\nu\rho}^\mu = \frac{1}{2} g^{\mu\alpha} \left(\partial_\rho g_{\alpha\nu} + \partial_\nu g_{\alpha\rho} - \partial_\alpha g_{\nu\rho} \right) \quad (2.2)$$

This also tells us that they are symmetric in the lower two indices: $\Gamma_{\nu\rho}^\mu = \Gamma_{\rho\nu}^\mu$.

The divergence of a vector field A^μ can be calculated as:

$$\nabla_\mu A^\mu = \frac{1}{\sqrt{-g}} \partial_\mu \left(\sqrt{-g} A^\mu \right) \quad (2.3)$$

where g is the determinant of the metric.

We can also define the D'Alembertian operator $\square = \nabla_\mu \nabla^\mu = \nabla_\mu \partial^\mu$, which can only act on scalars, and it does so like:

$$\square A = \nabla_\mu (\partial^\mu A) = \frac{1}{\sqrt{-g}} \partial_\mu (\sqrt{-g} \partial^\mu A) \quad (2.4)$$

If we differentiate and antisymmetrize (so, take the rotor of) an antisymmetric tensor $F_{[\mu\nu]}$, the Christoffel symbols cancel:

$$\nabla_{[\mu} F_{\nu\rho]} = \partial_{[\mu} F_{\nu\rho]} \quad (2.5)$$

The derivative with respect to proper time is $\frac{d}{d\tau} = u^\mu \partial_\mu$.

Covariant acceleration is defined as:

$$a^\nu = u^\mu \nabla_\mu u^\nu \quad (2.6)$$

Curvature The curvature of spacetime is fully described by the Riemann curvature tensor, which is a fourth rank tensor: for any generic vector V^μ ,

$$R^\mu_{\nu\rho\sigma} V^\nu \stackrel{\text{def}}{=} [\nabla_\rho, \nabla_\sigma] V^\mu \quad (2.7)$$

It can be calculated using the Christoffel symbols, and while they are not tensors $R^\mu_{\nu\rho\sigma}$ is one. This result follows by direct computation from formula (2.7).

$$R^\mu_{\nu\rho\sigma} = \partial_\rho \Gamma^\mu_{\nu\sigma} - \partial_\sigma \Gamma^\mu_{\nu\rho} + \Gamma^\mu_{\rho\lambda} \Gamma^\lambda_{\sigma\nu} - \Gamma^\mu_{\sigma\lambda} \Gamma^\lambda_{\rho\nu} \quad (2.8)$$

The Christoffel symbols can be nonzero if we choose certain coordinates even for flat spacetime, but the Riemann tensor is zero iff the spacetime is flat.

Geodesics If we have a path $x^\mu(\lambda)$, we would like to see if it is a geodesic, that is, if it is stationary with respect to path length. To do this we can stationarize the action corresponding to the lagrangian $\mathcal{L}(x, \dot{x}) = g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu$ (where we use $\dot{x} = dx/d\lambda$). The Lagrange equations then are:

$$\ddot{x}^\mu + \Gamma^\mu_{\nu\rho} \dot{x}^\nu \dot{x}^\rho = 0 \quad (2.9)$$

Where Γ are the Christoffel symbols, which can be calculated by differentiating the metric, as shown in (2.2). \mathcal{L} is an integral of these Lagrange equations.

If the parameter λ is taken to be the proper time s , then the equation is

$$\frac{du^\mu}{ds} + \Gamma^\mu_{\nu\rho} u^\nu u^\rho = 0 \quad (2.10)$$

Notice that this is equivalent to the covariant acceleration (2.6) being zero.

Fermi-Walker transport Take a general vector field $V^\mu(s)$ defined along a curve, with its tangent vector u^μ whose covariant acceleration is a^μ . Then we say that V^μ is transported according to Fermi-Walker iff it satisfies

$$\dot{V}^\mu = u^\nu \nabla_\nu V^\mu = V^\rho (u^\mu a_\rho - a^\mu u_\rho) \quad (2.11)$$

This condition is always satisfied by $V^\mu = u^\mu$, since $a^\mu u_\mu = 0$, whether or not the curve is a geodesic. The tangent vector is *parallel* transported only for geodesics.

Tetrads and projectors We want to work in a reference in which the velocity u^μ is purely timelike. This can always be found by the equivalence principle. Such a reference can be completed into what is called a tetrad, for which the metric becomes the Minkowski metric in a neighbourhood of the point we consider.

We call the velocity $u^\mu = V_{(0)}^\mu$, and add to it three other vectors $V_{(i)}^\mu$ such that

$$g_{\mu\nu} V_{(\alpha)}^\mu V_{(\beta)}^\nu = \eta_{(\alpha)(\beta)} \quad (2.12)$$

where the brackets around the indices denote the fact that they label four vectors, not the components of a tensor.

We can choose the vectors $V_{(i)}^\mu$ so that they are Fermi-Walker transported along the worldline defined by u^μ : this allows us to find the relativistic equivalent of a nonrotating frame of reference.

It is useful to project tensors onto the space-like and time-like subspaces defined by our tetrad (and we wish to do so in a coordinate-independent manner, so just taking the 0th and i -th components in the tetrad will not suffice). We therefore define the projectors:

$$h_{\mu\nu} = u_\mu u_\nu + g_{\mu\nu} \quad \pi_{\mu\nu} = -u_\mu u_\nu \quad (2.13)$$

respectively onto the space- and time-like subspaces.

Metrics The simplest physically relevant one is the Schwarzschild metric. It describes a spherically symmetric object of mass M , in spherical coordinates. Defining $\Phi = -M/r$, we have:

$$ds^2 = -(1 + 2\Phi) dt^2 + \frac{1}{1 + 2\Phi} dr^2 + r^2 (d\theta^2 + \sin^2 \theta d\varphi^2) \quad (2.14)$$

or, equivalently,

$$g_{\mu\nu} = \text{diag} \left(-(1 + 2\Phi), \frac{1}{1 + 2\Phi}, r^2, r^2 \sin^2 \theta \right) \quad (2.15)$$

We can see that it approaches the flat metric $\eta_{\mu\nu} = \text{diag}(-, +, +, +)$ in the limit $M \rightarrow 0$. Its determinant is $g = -r^4 \sin^2 \theta$.

Fluid mechanics In usual relativistic single-body mechanics, we use the 4-velocity u^μ and the corresponding 4-momentum $p^\mu = mu^\mu$. The 0-th component of this vector is the energy of the body, while the i -th components are its momentum: we then have $p^\mu p_\mu = m^2 = E^2 - |p|^2$.

When dealing with a continuum, we will have a certain density of particles per unit of volume, we call this n . The current of particles is then $N^\mu = nu^\mu$. If these particles have a certain rest mass m_0 , we can then define the vector $\rho_0 u^\mu = m_0 n u^\mu = m_0 N^\mu$.

This satisfies a conservation equation: $\nabla_\mu (\rho_0 u^\mu) = 0$.

Particles in a fluid can have three kinds of energy we concern ourselves with: mass, kinetic energy and other forms of energy (thermal, chemical, nuclear...). We can always perform a change of coordinates to bring us to a frame in which the kinetic energy is zero. We write the sum of the other two forms of energy as $\rho = \rho_0(1 + \epsilon)$. So, ϵ is the ratio of the internal non-mass energy to the mass.

Now, the vector ρu^μ describes the flux of energy. We can then write the equation for the conservation of momentum:

$$f^\mu = \nabla_\nu (\rho u^\mu u^\nu) \quad (2.16)$$

Ideal fluids They are fluids with $\eta = \zeta = \kappa = 0$, that is, without viscosity (neither compressive nor shear) nor heat transmission. They are described by the following stress-energy tensor:

$$T^{\mu\nu} = \rho u^\mu u^\nu + p h^{\mu\nu} \quad (2.17)$$

Spherical accretion We work with the Schwarzschild metric (2.14); we treat a fluid with 4-velocity u^μ in spherical coordinates, since the problem we are looking at is stationary and spherically symmetric the velocity is:

$$u^\mu = \begin{pmatrix} \gamma^2/y \\ yv \\ 0 \\ 0 \end{pmatrix} \quad (2.18)$$

where we define the Lorentz factor as usual, $\gamma = (1 - v^2)^{-1/2}$, and $y = \gamma\sqrt{1 + 2\Phi}$.

The conservation of mass holds: if ρ_0 is the rest mass density of the fluid, we must have $\nabla_\mu(\rho_0 u^\mu) = 0$. This, using the formula for covariant divergence (2.3), yields:

$$\frac{d}{dr}(\rho_0 y v r^2) = 0 \quad (2.19)$$

In the newtonian limit both γ and y approach 1; also, the infalling mass rate \dot{M} at a certain radius is $\rho_0(r)v(r)4\pi r^2$. Then, by continuity to the newtonian limit, the quantity which is constant wrt the radius must be $\dot{M}/(4\pi)$.

We also have the Euler equation:

$$(p + \rho)a^\mu = -h^{\mu\nu}\partial_\nu p \quad (2.20)$$

The only interesting component of this is the radial one, so we need to calculate $a^1 = u^\mu \nabla_\mu u^1 = du^1/d\tau + \Gamma_{\mu\nu}^1 u^\mu u^\nu$. To do this we will need the Schwarzschild Christoffel coefficients:

$$\Gamma_{\mu\nu}^1 = \begin{bmatrix} -\frac{2M(\frac{M}{r} - \frac{1}{2})}{r^2} & 0 & 0 & 0 \\ 0 & \frac{2M(\frac{M}{r} - \frac{1}{2})}{r^2(-\frac{2M}{r} + 1)^2} & 0 & 0 \\ 0 & 0 & 2r\left(\frac{M}{r} - \frac{1}{2}\right) & 0 \\ 0 & 0 & 0 & 2r\left(\frac{M}{r} - \frac{1}{2}\right)\sin^2(\theta) \end{bmatrix} \quad (2.21)$$

while the proper-time derivative is $d/d\tau = u^\mu \partial_\mu = yv\partial_1$.

And the equation for the variation of the total internal energy, which holds for ideal fluids at constant entropy:

$$\frac{d\rho}{d\tau} = \frac{p + \rho}{\rho_0} \frac{d\rho_0}{d\tau} \quad (2.22)$$

From these we can show that the quantity $\gamma h \sqrt{1 + 2\Phi}$ (where $h = (p + \rho)/\rho_0$ is the specific enthalpy), is a constant of motion. In the nonrelativistic, weak-field limit this becomes

$$\gamma h \sqrt{1 + 2\Phi} \approx \frac{p}{\rho_0} + \frac{v^2}{2} - \frac{M}{r} + \epsilon = \text{const} \quad (2.23)$$

2.2 Taub

This section summarizes my study of A. H. Taub's review of relativistic fluid dynamics, [Tau78].

Nonrelativistic Nonrelativistic fluid mechanics are described by the equations:

$$\partial_t \rho + \partial_i(\rho v^i) = 0 \quad (2.24a)$$

$$\rho(\partial_t v^i + v^j \partial_j v^i) = \partial_j T^{ij} \quad (2.24b)$$

$$\rho \partial_t E + v^i \partial_i E = \partial_i (T^{ij} v_j + \kappa \partial^i T) \quad (2.24c)$$

where ρ is the density of the fluid, v^i are the components of its velocity, T^{ij} is the stress tensor (or, equivalently, the space-like components of the energy-momentum tensor), E is the energy of the fluid, κ is the thermal conductivity, T is the temperature of the fluid.

The nonrelativistic stress tensor can be written as:

$$T_{ij} = -(p + \xi \partial_k v^k) \delta_{ij} + \eta \partial_{(i} v_{j)} \quad (2.25)$$

where p is the (isotropic) pressure, η the viscosity, ξ is the compression viscosity. We are assuming that the normal stresses are only those exerted by pressure, so the diagonal terms T_{ii} (not summed) must just be $-p$. So, the term $-\xi \partial_k v^k$ must equal $\eta \partial_{(i} v_{i)} = 2\eta \partial_i v_i$ (not summed). Therefore, by isotropy, $\xi = 2\eta/3$.

Note that we are working in Euclidean 3D space, so the metric is the identity and upper and lower indices are equivalent.

The energy is a sum of kinetic and specific energy:

$$E = v^i v_i / 2 + \varepsilon \quad (2.26)$$

where ε is the specific energy (of a type that is different from kinetic) per unit mass.

Relativistic The dynamics of the fluid are described by the conservation of the stress-energy tensor $\nabla_\mu T^{\mu\nu} = 0$ and the conservation of mass $\nabla_\mu (\rho u^\mu) = 0$.

Any stress-energy tensor can be decomposed in its space and time-like parts in the local rest frame of the fluid:

$$T_{\mu\nu} = w u_\mu u_\nu + w_\mu u_\nu + u_\mu w_\nu + w_{\mu\nu} \quad (2.27)$$

where

$$w = T_{\mu\nu} u^\mu u^\nu = \rho_0 (1 + \varepsilon) \quad (2.28a)$$

$$w_\mu = T_{\nu\sigma} h_\mu^\sigma u^\nu = -\kappa h_\mu^\sigma (\partial_\sigma T + T a_\sigma) \quad (2.28b)$$

$$w_{\mu\nu} = T_{\rho\sigma} h_\mu^\rho h_\nu^\sigma = (p - \xi \theta) h_{\mu\nu} - 2\eta \sigma_{\mu\nu} \quad (2.28c)$$

with $\theta = \nabla_\mu u^\mu$, a_μ is the covariant acceleration, $\sigma_{\sigma\tau} = 1/2 (\nabla_\mu u_\nu + \nabla_\nu u_\mu) h_\sigma^\mu h_\tau^\nu - 1/3 \theta h_{\sigma\tau}$, and as in the nonrelativistic section η is the viscosity, ξ is the compression viscosity, κ is the thermal conductivity, T is the temperature field, p is the pressure, ρ_0 is the rest mass density while $\rho = \rho_0 (1 + \varepsilon)$ is the rest energy.

3 Nobili, Turolla, Zampieri

See [NTZ91].

The cooling function $\Lambda(T)$ is defined by the following relation, which describes the variation in the energy density by radiative processes:

$$\frac{dU}{dt} = n_b^2 (\Gamma(T) - \Lambda(T)) \quad (3.1)$$

where U is the energy density (measured in erg cm^{-3}), n_b is the baryon density (measured in cm^{-3}), while Γ and Λ are the heating and cooling functions, both measured in $\text{erg cm}^3 \text{s}^{-1}$, see [GH12, equation 1].

The cooling function of the infalling gas is

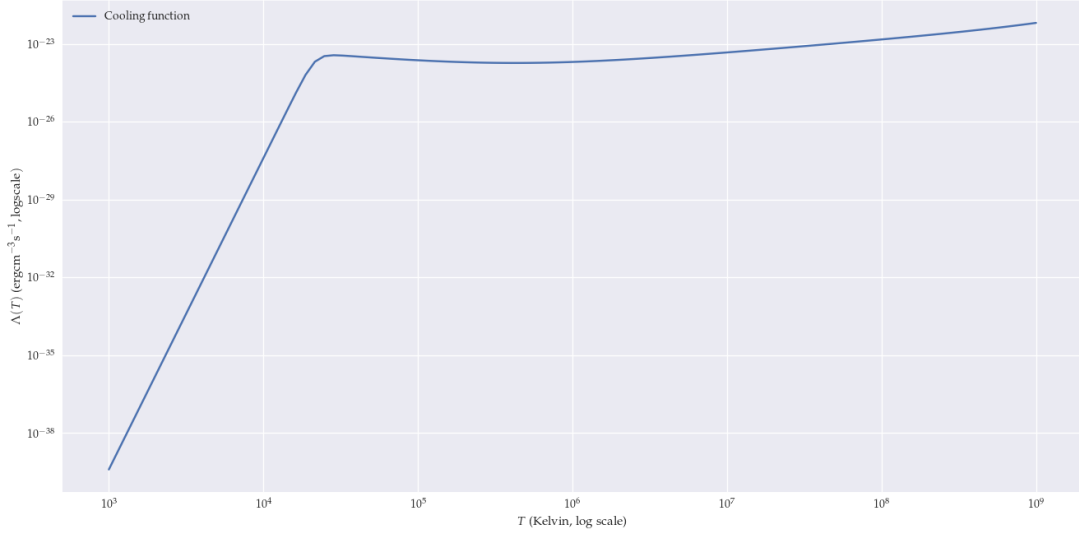


Figure 1: Cooling function graph.

$$\Lambda(T) = \left(\left(1.42 \times 10^{-27} T^{1/2} \left(1 + 4.4 \times 10^{-10} T \right) + 6.0 \times 10^{-22} T^{-1/2} \right)^{-1} + 10^{25} \left(\frac{T}{1.5849 \times 10^4 \text{ K}} \right)^{-12} \right)^{-1} \text{ erg cm}^{-3} \text{ s}^{-1} \quad (3.2)$$

The version of this equation in Stellingwerf and Buff is similar: the first constant is 2.4×10^{-27} instead of 1.42×10^{-27} , and the factor $(1 + 4.4 \times 10^{-10} T)$ is just 1.

4 Thorne's PSTF moment formalism

Following [Tho81].

Given any tensor $A^{\mu_1 \dots \mu_k}$ we can use the tensor $h^{\mu\nu}$ to project it into the space-like subspace defined by the velocity u^μ :

$$A^{\mu_1 \dots \mu_k} \rightarrow (A^{\mu_1 \dots \mu_k})^P = \left(\prod_i h_{v_i}^{\mu_i} \right) A^{v_1 \dots v_k} \quad (4.1)$$

Then, we can take the symmetric part of any (?) tensor as outlined in 'Notational preface' on page 2:

$$A^{\mu_1 \dots \mu_k} \rightarrow (A^{\mu_1 \dots \mu_k})^S = A^{(\mu_1 \dots \mu_k)} \quad (4.2)$$

We can select the trace-free part of a projected, symmetric tensor by

$$A^{\mu_1 \dots \mu_k} \rightarrow (A^{\mu_1 \dots \mu_k})^{TF} = \sum_{i=0}^{\lfloor k/2 \rfloor} (-1)^i \frac{k!(2k-2i-1)!!}{(k-2i)!(2k-1)!!(2i)!!} h^{(\alpha_1 \alpha_2} \dots h^{\alpha_{2i-1} \alpha_{2i}} A^{\alpha_{2i+1} \dots \alpha_k) \beta_1 \dots \beta_i}_{\beta_1 \dots \beta_i} \quad (4.3)$$

To see what this is doing, let us consider its action on a rank-two tensor:

$$A^{\mu\nu} \rightarrow A^{\mu\nu} - \frac{1}{3} h^{\mu\nu} A^\rho_\rho \quad (4.4)$$

Now, let us consider all the unit vectors n^μ in the space normal to the velocity, which have $n_\mu u^\mu = 0$ and $n^\mu n_\mu = 1$. They span a three-dimensional sphere.

If we have a function $F: S^2 \rightarrow \mathbb{R}$, we can decompose it into harmonics as such:

$$F(n) = \sum_{k=0}^{\infty} \mathcal{F}_{\alpha_1 \dots \alpha_k} \prod_{i=0}^k n^{\alpha_i} \quad (4.5)$$

Where the PTSF moments $\mathcal{F}_{\alpha_1 \dots \alpha_k}$ can be computed as

$$\mathcal{F}_{\alpha_1 \dots \alpha_k} = \frac{(2k+1)!!}{4\pi k!} \left(\int F \prod_{i=0}^k n^{\alpha_i} d\Omega \right)^{TF} \quad (4.6)$$

Now, consider a photon, whose trajectory in spacetime is parametrized as $\gamma(\xi)$, with a choice of ξ such that the photon's momentum is

$$p = \frac{d}{d\xi} \quad (4.7)$$

Now, our observer has a timelike velocity u^μ . We can find a spacelike vector n^μ corresponding to the space-like part of the movement of the photon, or

$$p^\mu = (-u^\nu p_\nu)(u^\mu + n^\mu) \quad (4.8)$$

Now, we define a parameter l which corresponds to the space distance the photon moved through in this frame (this is *not* covariant!)

$$l = \int (-u^\nu p_\nu) d\xi \quad (4.9)$$

now, d/dl is parallel to p but it has different length, in fact since $dl/d\xi = (-u^\nu p_\nu)$ it is $d/dl = u + n$.

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