Gravitational Wave Exercises @ Jena

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Exercises for the Gravitational Waves course. The exercise sheets can be found on the webpage.

1 Quadrupole approximation

The procedure to find the quadrupole approximation for the GW emitted by a Newtonian system is in the form:

- 1. determine the density $\rho(\vec{x}, t)$;
- 2. calculate the trace-free inertia tensor $Q^{ij}(t)$;
- 3. calculate the gravitational wave strain h_{ij} .

Two point particles

In order to model the point-like nature of the particles we can write an expression for the density as a sum of two delta-functions, whose positions oscillate on the x axis with an amplitude R:

$$\rho(\vec{x},t) = m\delta(\vec{x} - \vec{x}_1(t)) + m\delta(\vec{x} - \vec{x}_2(t)), \qquad (1.1)$$

where

$$\vec{x}_1(t) = R \begin{bmatrix} \cos(\omega t + \phi) \\ 0 \\ 0 \end{bmatrix}$$
 and $\vec{x}_2(t) = -\vec{x}_1(t)$. (1.2)

So, the trace-free inertia tensor will be given by

$$Q^{ij}(t) = \int \rho(\vec{x}, t) \left(x^i x^j - \frac{1}{3} \delta^{ij} r^2 \right) d^3 x \tag{1.3}$$

$$= m \sum_{k=1,2} \left(x_k^i x_k^j - \frac{1}{3} \delta^{ij} r^2 \right) \tag{1.4}$$

$$=2mR^{2}\begin{bmatrix}\cos^{2}(\omega t+\phi)-1/3 & 0 & 0\\ 0 & -1/3 & 0\\ 0 & 0 & -1/3\end{bmatrix}.$$
 (1.5)

The second derivative of this tensor will be given by

$$\ddot{Q}^{ij}(t) = 4mR^2\omega^2 \begin{bmatrix} \sin^2 - \cos^2 & 0 & 0\\ 0 & 0 & 0\\ 0 & 0 & 0 \end{bmatrix}.$$
 (1.6)

Now, in order to compute the gravitational wave strain we need the projection tensor $\Lambda_{ij,kl}$. If the propagation direction we are interested in is \vec{k} , then the tensor

$$P_{ij} = \delta_{ij} - \frac{k_i k_j}{|k|^2} = \delta_{ij} - n_i n_j$$
 (1.7)

will project a vector onto the subspace orthogonal to \vec{k} ; and the tensor

$$\Lambda_{ij,kl} = P_{ik}P_{jl} - \frac{1}{2}P_{ij}P_{kl} \tag{1.8}$$

$$= \delta_{ik}\delta_{jl} - n_i n_k \delta_{jl} - \delta_{ik} n_j n_l + \frac{1}{2} n_i n_k n_j n_l - \frac{1}{2} \delta_{ij} \delta_{kl} + \frac{1}{2} \delta_{ij} n_k n_l + \frac{1}{2} n_i n_j \delta_{kl} , \qquad (1.9)$$

will project a rank-2 tensor onto the corresponding subspace.

Then, the gravitational wave emission will look like:

$$h_{ij}(t) = \frac{2}{r} \frac{G}{c^4} \Lambda_{ij,kl} \ddot{Q}_{kl}(t - r/c)$$

$$= \frac{2}{r} \frac{G}{c^4} \Lambda_{ij,xx} \left(\sin^2(\omega t - \omega r/c + \phi) - \cos^2(t - \omega r/c + \phi) \right)$$

$$= -\frac{2}{r} \frac{G}{c^4} \left(\delta_{ix} \delta_{jx} - n_i n_x \delta_{jx} - \delta_{ix} n_j n_x + \frac{1}{2} n_i n_x n_j n_x - \frac{1}{2} \delta_{ij} \delta_{xx} + \frac{1}{2} \delta_{ij} n_x n_x + \frac{1}{2} n_i n_j \delta_{xx} \right)$$

$$\times \cos \left(2\omega \left(r - \frac{r}{c} \right) + \phi \right)$$

$$(1.12)$$

which we can express explicitly by writing out

$$\vec{n} = \begin{bmatrix} \sin \theta \cos \varphi \\ \sin \theta \sin \varphi \\ \cos \theta \end{bmatrix} . \tag{1.13}$$

A free-falling particle

Ellipsoid rotating along its axis

Two particles in circular Newtonian orbit

$$\rho(\vec{x},t) = m_1 \delta(\vec{x} - \vec{x}_1(t)) + m_2 \delta(\vec{x} - \vec{x}_2(t)), \qquad (1.14)$$

where

$$in\vec{x}_1(t) = r \begin{bmatrix} \cos(\omega t + \phi) \\ -\sin(\omega t + \phi) \\ 0 \end{bmatrix}$$
 and $\vec{x}_2(t) = -\vec{x}_1(t)$. (1.15)

For simplicity, we will also assume that the radius r is constant — this cannot be precisely the case, since there will be some amount of power lost because of the GW emission, but it is a reasonable approximation.

So, the trace-free inertia tensor will be given by

$$Q^{ij}(t) = \int \rho(\vec{x}, t) \left(x^i x^j - \frac{1}{3} \delta^{ij} r^2 \right) d^3 x$$
 (1.16)

$$= \sum_{k=1,2} m_k \left(x_k^i x_k^j - \frac{1}{3} \delta^{ij} r^2 \right) \tag{1.17}$$

$$= 2mr^{2} \begin{bmatrix} \cos^{2} - 1/3 & -\cos \sin \\ -\cos \sin & \sin^{2} - 1/3 \end{bmatrix},$$
 (1.18)

where we write only the upper-left 2x2 submatrix in Q^{ij} , since the other entries are constant, and we omit the argument of the sines and cosines (which is always $\omega t + \phi$).

The second derivative of this tensor will be given by

$$\ddot{Q}^{ij}(t) = 4mr^2\omega^2 \begin{bmatrix} \sin^2 - \cos^2 & 2\sin\cos\\ 2\sin\cos & \cos^2 - \sin^2 \end{bmatrix}.$$
 (1.19)

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