## The FLP Theorem

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## The Distributed Consensus Problem

Definition

# Consensus protocol

### Definition (Consensus protocol)

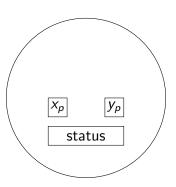
A **consensus protocol** is an asynchronous system of N processes ( $N \ge 2$ ). Each process p has a one-bit **input register**  $x_p$ , an **output register**  $y_p$  with values in  $\{\bot, 0, 1\}$  and an unbounded amount of internal storage.

**Initial states** prescribe fixed starting values for all but the input register; in particular, the output register starts with value  $\perp$ .

p acts deterministically according to a **transition** function.

## Decision states

The states in which the output register has value 0 or 1 are distinguished as being **decision states**. The transition function cannot change the value of the output register once the process has reached a decision state; that is, the output register is "write-once".



# Message system

A **message** is a pair (p, m), where p is the name of the destination process and m is a "message value" from a fixed universe M.

### Definition (Message system)

The **message system** mantains a multiset, called the **message buffer**, of messages that have been sent but not yet delivered. It supports two abstract operations:

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send(p,m): Places (p,m) in the message buffer.
```

receive(p): Deletes some message (p, m) from the buffer and returns m, in which case we say (p, m) is **delivered**, or returns the special null marker  $\varnothing$  and leaves the buffer unchanged.

## Partial correctness

A configuration C has **decision value** v if some process p is in a decision state with  $y_p = v$ .

#### Definition (Partial correctness)

A consensus protocol is **partially correct** if:

- No accessible configuration has more than one decision value.
- ② For each  $v \in \{0,1\}$ , some accessible configuration has decision value v.

# Total correctness in spite of one fault

A process p is **nonfaulty** in run if it takes infinitely many steps, otherwise it is **faulty**.

A run is **admissible** if at most one process is faulty and all messages sent to nonfaulty processes are eventually received.

A run is **deciding** if some process reaches a decision state.

### Definition (Total correctness in spite of one fault)

A consensus protocol P is **totaly correct in spite of one fault** if it is partially correct and every admissibile run is deciding.

## Main result

### Theorem (Fischer, Lynch, Paterson 1985)

No consensus protocol is totally correct in spite of one fault.

A configuration is **bivalent** if the set of decision values of configurations reachable from it has 2 elements. It is instead 0-valent or 1-valent according to the corresponding value.

### Proof (sketch).

Given an initial bivalent configuration, we construct an admissible run that at each stage results in another bivalent configuration.

## Lemma 1

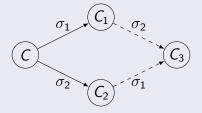
#### Lemma

Suppose that from some configuration C, the schedules  $\sigma_1$ ,  $\sigma_2$  lead to configurations  $C_1$ ,  $C_2$  respectively. If the sets of processes taking steps in  $\sigma_1$  and  $\sigma_2$ , respectively, are disjoint, then  $\sigma_2$  can be applied to  $C_1$  and  $\sigma_1$  can be applied to  $C_2$ , and both lead to the same configuration  $C_3$ .

In other words: schedules about disjoint processes commute with each other.

## Proof of Lemma 1

### Proof (Lemma 1).



Because the sets of processes are disjoint, an event in  $\sigma_1$  applicable to C is applicable to  $C_2$  as well.

Because of determinism, after all events are processed they must end up in the same state.



## Lemma 2

#### Lemma

P has a bivalent initial configuration.

Proof (Lemma 2).



## Lemma 3

#### Lemma

Let C be a bivalent configuration of P, and let e=(p,m) be an event that is applicable to C. Let C be the set of configurations reachable from C without applying e, and let  $\mathcal{D}=e(C)=\{e(E)|E\in \mathcal{C} \text{ and } e \text{ is applicable to } E\}$ . Then,  $\mathcal{D}$  contains a bivalent configuration.

In other words: given a bivalent configuration and an event *e* applicable to it, we construct another bivalent configuration having *e* as the last applied event.

## Proof of Lemma 3

Proof (Lemma 3).

## Proof of main result

Proof (main result).