Names: Brian Tang (bt3), Joseph Adamo (jdadamo2), Kyle Jew (kjew2)

**Team Name:** thread\_beast

**Affiliation:** On-Campus students

List of kernels consuming more than 90% of program time:

None, highest is [CUDA memcpy HtoD] at 30.04% of time.

List of CUDA API calls consuming more than 90% of program time:

None, highest is cudaStreamCreateWithFlags at 41.19% of time.

Kernels and API calls difference:

Kernels are programmer-defined C functions and when launched, are executed N times in parallel by N different threads. However, CUDA API calls are pre-defined extensions to the C language and meant for easing the experience for programmers to set up programs for execution by the device.

### **Output of rai running MXNET on CPU:**

"Loading fashion-mnist data... done

Loading model... done

**New Inference** 

EvalMetric: {'accuracy': 0.8154}

18.26user 4.46system 0:09.56elapsed 237%CPU (0avgtext+0avgdata 6047060maxresident)k

Oinputs+2824outputs (Omajor+1601873minor)pagefaults Oswaps"

**Program run time:** 9.56 seconds

Output of rai running MXNET on GPU:

"Loading fashion-mnist data... done

Loading model... done

**New Inference** 

EvalMetric: {'accuracy': 0.8154}

4.97user 3.25system 0:04.59elapsed 179%CPU (0avgtext+0avgdata 2968484maxresident)k

Oinputs+4536outputs (Omajor+733238minor)pagefaults Oswaps"

**Program run time:** 4.59 seconds

Whole Program Execution Time: 1 minute 16.47 seconds

# **Op Times:**

Python m2.1.py:

Op Time: 12.307846

Op Time: 59.309954

Correctness: 0.7653

At 100 images:

Op Time: 1.082469

Op Time: 5.923644

Correctness: 0.767

At 1000 images:

Op Time: 0.108870

Op Time: 0.590093

Correctness: 0.76

At 10000 images:

Op Time: 10.855807

Op Time: 60.478481

Correctness: 0.7653

### Milestone 3:

# **Correctness and Timing at 100 images:**

Op Time: 0.000282

Op Time: 0.000924

Correctness: 0.76 Model: ece408

4.84user 2.65system 0:06.72elapsed 111%CPU (0avgtext+0avgdata 2783704maxresi

dent)k

Oinputs+4560outputs (Omajor+636682minor)pagefaults Oswaps

### At 1000 images:

Op Time: 0.002764

Op Time: 0.009408

Correctness: 0.767 Model: ece408

4.82user 2.77system 0:04.38elapsed 173%CPU (0avgtex

t+0avgdata 2811072maxresident)k

Oinputs+4560outputs (Omajor+641440minor)pagefaults Oswaps

### At 10000 images:

Op Time: 0.027439

Op Time: 0.093477

Correctness: 0.7653 Model: ece408

5.19user 3.16system 0:04.87elapsed 171%CPU (0avgtext+0avgdata 2981280maxresident)k

Oinputs+4560outputs (Omajor+734975minor)pagefaults Oswaps

### **NVPROF Execution:**

```
Mate Terminal
GPU activities: 70.00% 160.81ms 2 80.407ms 25.593ms 135.22ms mxnet::op::forward kernel(float*, float const *, float const *, int, int, int, int, int, int)

14.79% 33.987ms 20 1.6993ms 1.0880us 31.835ms [CUDA memcpy HtoD]

6.47% 14.865ms 2 7.4324ms 2.9116ms 11.953ms void mshadow::cuda::MapPlanLargeKernel<mshadow::syr::ScalarExp<float>, mshadow::Tensor<mshadow::expr::Plan<mshadow::expr::BinaryMapExp<mshadow::op:.mul, mshadow::expr::ScalarExp<float>, mshadow::Tensor<mshadow::gpu, unsigned int, mshadow::spp; plan<mshadow::expr::BinaryMapExp<mshadow::op:.mul, mshadow::expr::ScalarExp<float>, mshadow::Tensor<mshadow::gpu, unsigned int, mshadow::spp; plan<mshadow::ppi, int=4, float>, 
     GPU activities
                                                                                                                                                                                                                                                                                                                                                                                                                             kernel(float*, float const *, float const *, int, int, int, int, int, int)
                                                                                                                                                                                                                                                                                                                                          volta_sgemm_32x128_tn
[CUDA memset]
[CUDA memcpy DtoH]
                                                                                                                                                                                                                                                                                                                          bus void mshadow::cuda::MapPlanKernel<mshadow::sv::saveto, int=8, mshadow::expr::Plan<mshadow::Tensor<mshadow::gpu, in
<mshadow::red::maximum, mshadow::Tensor<mshadow::gpu, int=3, float>, float, int=3, bool=1, int=2>, float>>(mshadow::gpu
                        gned int, msh
API calls:
                                                                                                                                                                                                       142.62ms 14.143us 1.62382s cudaStreamCreateWithFlags 113.83ms 66.688us 2.49922s cudaMemGetInfo
                                                                                                                                                                                                       142.62ms
113.83ms
427.27ms
29.284ms
7.6525ms
68.938us
185.93us
                                                                                                                                                                                                                                                                                                 135.23ms
                                                                                                                                                                                                                                                                                                                                           cudaDeviceSynchronize
                                                                                                                                                                                                                                                    21.657us
427ns
1.2430us
                                                                                                                                                                                                                                                                                                32.020ms
19.383ms
11.035ms
                                                                                                                                                                                    912
216
29
66
4
                                                                                                                                                                                                                                                                                                                                            cudaEventCreateWithFlags
                                                                                                                                                                                                                                                    2.7910us
5.7100us
420.93us
                                                                                                                                                                                                                                                                                               10.911ms
4.6163ms
1.8489ms
                                                                                                                                                                                                       672.09us
292.74us
                                                                                                                                                                                                                                                                                                                                            cudaStreamSynchronize
                                                                                                                                                                                                                                                                                                                                              cudaGetDeviceProperties
```

Many issues with trying to install NVVP. We had the disk space failure problem and then referred to the Instructor's answer in the Piazza Post @352. The steps detailed by Ayush were not successful for us, as we were being denied access to install the runfile from CUDA download page. "Access Denied. The

username you have entered cannot authenticate with Duo Security. Please contact system administrator".

As it seems there are no Office Hours until Monday earliest, please excuse us our allow a late submission for this Nvidia profiling portion. We have been successful in performing everything else required in this milestone but have run into logistic problems with NVVP (it seems many other groups have the same problems).

#### Milestone 4:

### Optimization 1: Shared Memory Convolution

Due to the exclusive use of global memory, the basic convolution kernel is extremely limited by the memory bandwidth. This is a lot slower than the peak performance speeds of GPUs, so a good place to start when it comes to optimizations is to reduce global memory reads. For this optimization we achieve this by placing x and k into blocks of shared memory. We allocate a block of size (TILE\_WIDTH + K - 1) \* (TILE\_WIDTH + K - 1) of memory for x and a block of size K \* K for k. For each input feature map c, we then use the 1st K \* K threads of a given block to load in k, then had all threads load in x. Once k and x are loaded into shared memory, we do the standard convolution where each thread within the acceptable domain preforms K \* K operations before moving onto the next input feature map c and repeating the process of loading and calculating. (Results and conclusions provided with NVPROF evidence below)

### Optimization 2: Unrolling + Matrix Multiplication

We also set out to try to fundamentally alter the method of forward-propagation calculation and see if it had any impact on performance. As described in Chapter 16 of the book, it's possible to unroll the inputs k and x into large matrices to that the convolution step becomes a simple matrix multiplication. We unrolled k from a 4D M \* C \* K \* K tensor to a 2D M \* (C\*K\*K) matrix. This only had to be done once due to k being the same for all batch elements. For x, we iterated over batch elements B on the CPU and for each element b, unrolled it form a 3D array of size H \* C \* W to a 2D array of size ((W-K+1)\*(H-K+1)) \* (C\*K\*K), after which we performed a shared-memory matrix multiplication in a separate kernel. We iterated over b sequentially due to the fact that unrolling x duplicated a lot of elements, and for large x inputs unrolling the entire 4D tensor might cause x\_unrolled to be too large for our memory. Thus, we expect this method to not work as effectively when B is large as that will require more kernel calls. Despite this, switching to this method might prove highly beneficial, as even if the base unroll + matrix multiply method is comparable in speed to convolution, there are many known ways to improve upon the matrix multiplication kernel to speed it up further. (Results and conclusions provided with NVPROF evidence below)

# Optimization 3: Sweeping Parameters for Best Values

As our third optimization attempt, we went over our original convolution implementation and our unrolling + matrix multiplication optimization to see if various parameter tweaks could improve performance even more. Specifically, we experimented with changing block sizes and number of threads until we found a value that gave the best performance. Generally, we noticed that tweaking block sizes were not as flexible because of resulting memory access problems. However, we found success in experimenting with thread counts because with certain block dim parameters, we can find ways to minimize control divergence. (Results and conclusions provided with NVPROF evidence below)

### **NVPROF Performance Analysis and Comparison**

Original Implementation (No Optimizations)

```
fashion-mnist data... done
                           NVPROF is profiling process 268, command: python m4.1.py
  oading model... done
           Time: 0.025635
             rme. 0.135242
ectness: 0.7653 Model: ece408
8== Profiling application: python m4.1.py
                             Profiling
                                                               result:
                                                                                                                                                                                                                                                                                                \label{eq:mxnet::op::forward_kernel(float*, float const *, float const *, int, int, int, int, int, int) \\ [CUDA memcpy HtoD] 
                                                                                                  160.81ms
                                                                                                 33.987ms
14.865ms
                                                                                                                                                        2 7.4324ms 2.9116ms 11.953ms void mshadow::cuda::MapPlanLargeKernel<mshadow::sv::saveto, int=8, int=1024, mshadow::expr::Plan<mshadow::expr::Plan<mshadow::expr::Plan<mshadow::expr::BinaryMapExp<mshadow::op::mul, mshadow::expr::SalarExp<float>, mshadow::Tensor<mshadow::gpu,
                                                                  w::gpu,
int=4, float>, float, int=1>, float>>(mshadow::gpu, unsigned int, mshadow::shape<int=2>, int=4, int)
3.45% 7.9172ms 1 7.9172ms 7.9172ms volta sgemm 128x128 tn
3.45% 7.2042ms 2 3.6021ms 24.896us 7.1793ms void op generic_tensor_kernel<int=2, float, float, float, int=256, cudnnGenericOp_t=7, cudnnNanPropa etion_t=0, cudnnDimOrder_t=0, int=1>(cudnnTensorStruct, float*, cudnnTensorStruct, float const *, cudnnTensorStruct, float*, float*, float, float*, float*
                                                                                                                                                                              4.3539ms 4.3539ms 4.3539ms
                                                                                                                                                                                                                                                                                             void cudnn::detail::pooling_fw_4d_kernel<float, float, cudnn::detail::maxpooling_func<float, cudnnNa
                                                               int=0, bool=0>(cudnnTensorStruct, float const *, cudnn::detail::pooling_fw_4d_kernel<float, float, cudnn::detail::maxpooling_func<float, cudnnNanPropagation_t=, cudnnTensorStruct*, cudnnPoolingStruct, float, cudnnNanPropagation_t=, cudnnTensorStruct*, cudnnPoolingStruct, int, cudnn::reduced_divisor, float)

0.18% 405.05us 1 405.05us 405.05us 405.05us void mshadow::cuda::MapPlanLargeKernel<mshadow::sv::saveto, int=8, int=1024, mshadow::expr::Plan<mshadow::gpu, int=2, float>, float>, float>, mshadow::expr::Plan<mshadow::expr::ScalarExp<float>, float>, float>, mshadow::Shape<int=2>, int=2, int)
    ropagation t=0>
```

Best Parameters for Original Implementation (Optimization 3)

```
**Running nyprof python m4.1.py**
Loading fashion-mist data... done
==267== MVPROF is profiling process 267, command: python m4.1.py**
Loading model... done

New Inference
Op Time: 0.030198
Op
```

When looking for parameter optimizations for our original milestone 3 implementation of convolution, we discovered a large room for improvement. We believe that our original block dimensions were causing lots of control divergence which resulted in more GPU usage and longer op time. By using blocks with 256 threads instead of 1024, we found a 10% boost in kernel GPU efficiency and 0.04s speedup.

# Shared Memory Convolution (Optimization 1)

```
Loading fashion-mnist data...done
==267== NVPROF is profiling process 267, command: python m4.1.py
Loading model... done
New Inference
Op Time: 0.485119
Op Time: 0.129944
Correctness: 0.7653 Model: ece408
==267== Profiling application: python m4.1.py
==267== Profiling result:
Type Time(%) Time Calls Avg Min Max Name
6PU activities: 71.19% 175.01ms 2 87.506ms 45.087ms 129.93mm xxnet::op::forward kernel(float*, float const *, float const *, int, int, int, int, int, int)
13.66% 33.5390ms 20 1.6795ms 1.1200us 31.437ms [CUDA memcpy HtoD]
6.90% 16.956ms 2 8.4778ms 3.0478ms 13.998ms void mshadow::cuda::MapPlanLargeKernel<mshadow::sv::saveto, int=8, int=1024, mshadow::expr::Plan<mshadow::pgu, int=4, float>, float>, mshadow::expr::Plan<mshadow::expr::BinaryMapExp<mshadow::expr::ScalarExp<float>, mshadow::Tensor<mshadow::gpu, int=4, float>, float, mshadow::sppu, int=4, float>, float, int=1>, float>>(rden) float>, float) float>, fl
```

Even though our functionality for shared memory convolution was sound and conceptually it made sense as an optimization, we were surprised to more GPU activity by our forward kernel compared to the original convolution implementation (by about 1.19%). We believe an explanation for this is that since our shared memory implementation required much more boundary checks, we created more room for control divergence However, we did see a small amount of speedup. This makes sense because using shared memory optimizes the speed, considering that accesses to shared memory is much faster than global memory accesses.

Unrolling + Matrix Multiplication (Optimization 2)

With unrolling and matrix multiplication, we saw our optimization pay off with improvements in kernel GPU usage. Each individual kernel involved in this optimization (unroll and matrix multiply) was more efficient in terms of GPU usage compared to our original convolution implementation (70% kernel GPU activity). However, one downside is that we noticed this optimization affected the total op time, taking about 0.11 seconds longer than the original convolution. This may be attributed to the fact that we are looping through batch elements and launching two kernels.

### Best Parameters for Unrolling + Matrix Multiplication (Optimization 3)

When sweeping parameters to improve performance for unrolling+matrix multiplication, we looked into the grid and block dimensions that we used to launch the unroll kernel and matrix multiply kernel. We did not have much success changing the block size used to launch the unroll kernel because any size other than 1024 would cause an illegal memory access. However, tweaking block dimensions for the matrix multiply kernel helped. By changed the number of threads in the block from 576 (blockDim(24,24)) to 256 (blockDim(16,16)), we noticed a 3% more efficient GPU activity (from 57.54% to 54.38%). Additionally, the op time dropped by .03 seconds (0.134484 s to 0.161680 s). This success can be attributed to the fact we found the most optimal thread count in a block such that there is less control divergence happening in the kernel.