

Vibrations

Modeling and Equations of Motion

Single degree of freedom (SDOF):

$$m\ddot{x} + c\dot{x} + kx = f(t)$$

Rotational form:

$$I\ddot{\theta} + c_{\theta}\dot{\theta} + k_{\theta}\theta = M(t)$$

Equivalent parameters:

$$\omega_n = \sqrt{\frac{k}{m}}, \quad \zeta = \frac{c}{2\sqrt{km}}$$

Free Vibration

Undamped ($c = 0$):

$$x(t) = A \cos(\omega_n t) + B \sin(\omega_n t)$$

Damped ($0 < \zeta < 1$):

$$x(t) = e^{-\zeta\omega_n t} (A \cos \omega_d t + B \sin \omega_d t)$$
$$\omega_d = \omega_n \sqrt{1 - \zeta^2}$$

Critical damping:

$$c_c = 2\sqrt{km}$$

Logarithmic decrement:

$$\delta = \frac{1}{n} \ln \left(\frac{x(t)}{x(t+nT_d)} \right) = \frac{2\pi\zeta}{\sqrt{1 - \zeta^2}}$$

Forced Vibration (Harmonic)

Harmonic force:

$$f(t) = F_0 \cos \omega t$$

Steady-state response amplitude:

$$X(\omega) = \frac{F_0/k}{\sqrt{(1 - r^2)^2 + (2\zeta r)^2}} \quad r = \frac{\omega}{\omega_n}$$

Phase angle:

$$\tan \phi = \frac{2\zeta r}{1 - r^2}$$

Resonance frequency:

$$\omega_r = \omega_n \sqrt{1 - 2\zeta^2}$$

General Forcing

Impulse response function:

$$h(t) = \frac{1}{m\omega_d} e^{-\zeta\omega_n t} \sin(\omega_d t)$$

Convolution integral:

$$x(t) = \int_0^t h(t - \tau) f(\tau) d\tau$$

Step response:

$$x(t) = \frac{F_0}{k} \left[1 - e^{-\zeta\omega_n t} \left(\cos \omega_d t + \frac{\zeta}{\sqrt{1 - \zeta^2}} \sin \omega_d t \right) \right]$$

Frequency Response and Transmissibility

Force transmissibility:

$$T_F = \frac{\sqrt{1 + (2\zeta r)^2}}{\sqrt{(1 - r^2)^2 + (2\zeta r)^2}}$$

Motion transmissibility:

$$T_X = \frac{1}{\sqrt{(1 - r^2)^2 + (2\zeta r)^2}}$$

Vibration isolation region:

$$r > \sqrt{2}$$

Two-Degree-of-Freedom Systems

Matrix form:

$$\mathbf{M}\ddot{\mathbf{x}} + \mathbf{C}\dot{\mathbf{x}} + \mathbf{K}\mathbf{x} = \mathbf{f}(t)$$

Undamped eigenvalue problem:

$$(\mathbf{K} - \omega^2 \mathbf{M})\boldsymbol{\phi} = 0$$

Natural frequencies:

$$\det(\mathbf{K} - \omega^2 \mathbf{M}) = 0$$

Mode shape orthogonality:

$$\boldsymbol{\phi}_i^T \mathbf{M} \boldsymbol{\phi}_j = 0, \quad \boldsymbol{\phi}_i^T \mathbf{K} \boldsymbol{\phi}_j = 0 \quad (i \neq j)$$

Modal coordinates:

$$\mathbf{x} = \boldsymbol{\Phi} \mathbf{q}$$

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Vibration Absorbers

Primary mass response (undamped absorber):

$$\omega_a = \sqrt{\frac{k_a}{m_a}}$$

Tuned absorber condition:

$$\omega_a = \omega_n$$

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Vibration Measurement

Log decrement (experimental):

$$\zeta \approx \frac{\delta}{2\pi} \quad (\zeta \ll 1)$$

Frequency from FFT peak:

$$\omega = 2\pi f$$

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