

AI Planning for Autonomy

## Problem Set V: Delete Relaxation

1. Discuss in your group the heuristics you used in project 1. Are any of them related to the domain independent heuristics we have covered in class?

- What is the (optimal) delete relaxation heuristic  $h^+$ ? How would it be interpreted in pacman?
- What is the relationship between  $h^{max}$ ,  $h^+$ , and  $h^{add}$ ? What about  $h^*$ ?

2. In a blocks-world problem, the agent's aim is to stack the blocks as in Figure 1.

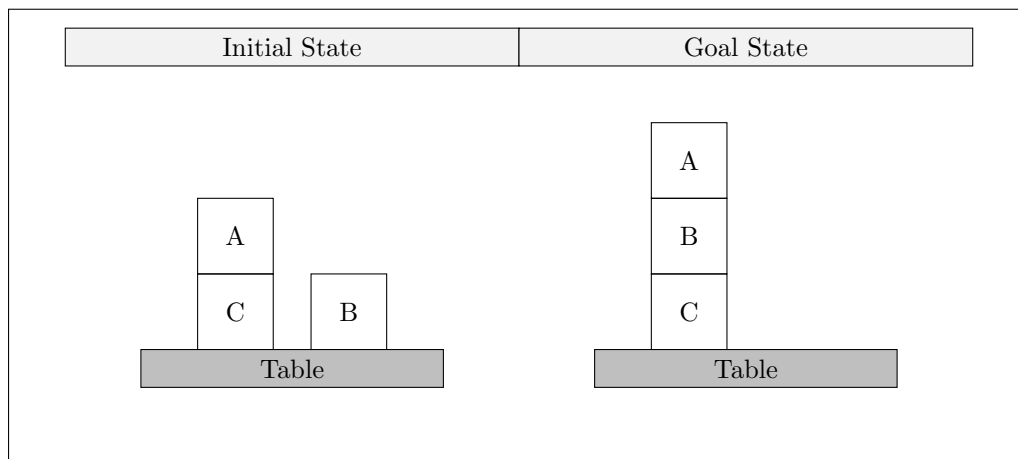


Figure 1: An Initial (Left hand side) and Goal (Right hand side) state of a blocks-world problem.

There are several important classes of domain-independent heuristics. Recall the delete relaxation based heuristics from Lectures:

- Compute  $h^{add}(s_0)$  for the 4 operators blocks-world problem.
- Compute  $h^{max}(s_0)$  for the 4 operators blocks-world problem.