AI Planning for Autonomy

Solution Problem Set IV: Modeling in STRIPS and PDDL

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1.
  For a given set of Blocks B:
F = \{ on(x,y), onTable(x), clear(x), holding(x), armFree \mid x, y \in B \}, \}
O=
\{ \operatorname{stack}(x,y) :
   • Prec: holding(x), clear(y)
   • Add: clear(x), on(x,y), armFree
   • Del: clear(y), holding(x)
| x, y \in B 
  \cup { unstack(x,y):
   • Prec: on(x,y), clear(x), armFree
   • Add: holding(x), clear(y)
   • Del: clear(x), on(x,y), armFree
| x, y \in B 
  \cup { putdown(x):
   • Prec: holding(x)
   • Add: clear(x), onTable(x), armFree
   • Del: holding(x)
| x \in B 
  \cup { pickup(x):
   • Prec: onTable(x), clear(x), armFree
   • Add: holding(x)
   • Del: clear(x), onTable(x), armFree
| x \in B \}
I = \{on(a,c), onTable(c), onTable(b), clear(a), clear(b), armFree\}
G = \{ on(a,b), on(b,c) \}
  2-3. PDDL domains have been created here: http://editor.planning.domains/#read_session=
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