ECE 6561 – Computing for Control Systems

Topical Outline

Introductory Topics in Controls
Principles of Feedback Control
Standard Control Architectures

Implementation Issues

Stability and Effect of Time Delays Common I/O models Sensor Processing

Advanced Control Concepts Hybrid Systems

Introductory Topics in Software Engineering Software Reuse Object-Oriented Controls Component-Based Design

Real-Time Computing for Controls

Threads and Processes Scheduling Intertask Communication Methods Real-Time Operating Systems

Distributed Computing for Controls

Network Communication Protocols Suitable for Controls Interprocess Communication Models Networked Control Systems

Case Studies

Application of these techniques to process control, robotics, and uninhabited autonomous vehicles.

Projects will be given that include some of the following topics: implementing a multi-threaded control system using a real-time operating system, running control code distributed over a network, designing control of mobile robots using a distributed computing architecture.