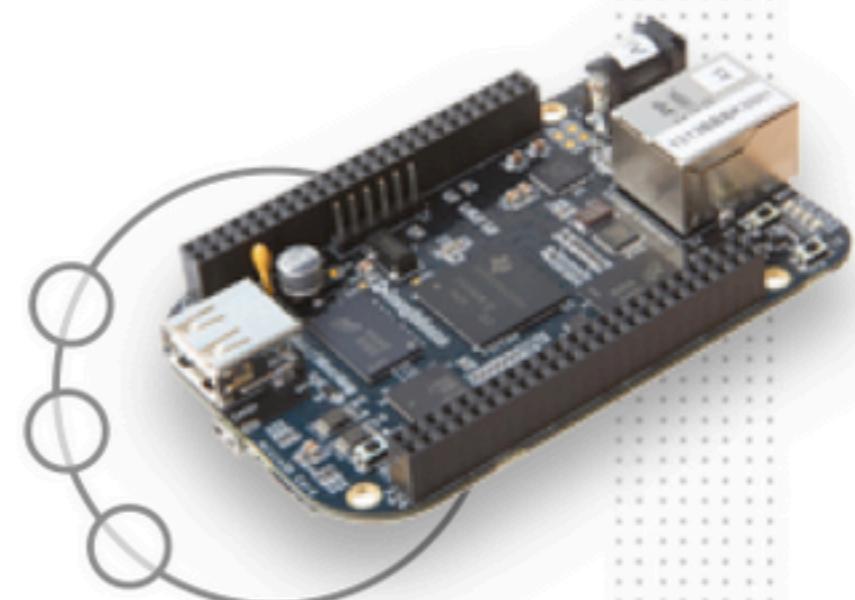


BeagleBoard.org

**Linux and web servers for teaching
electronics**



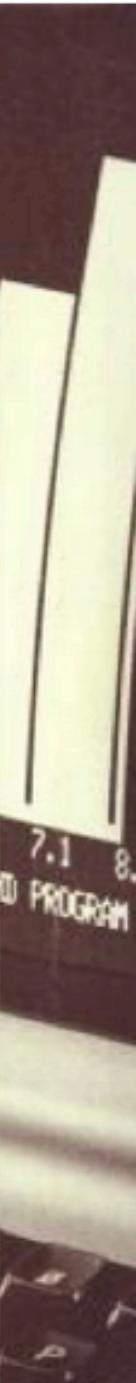
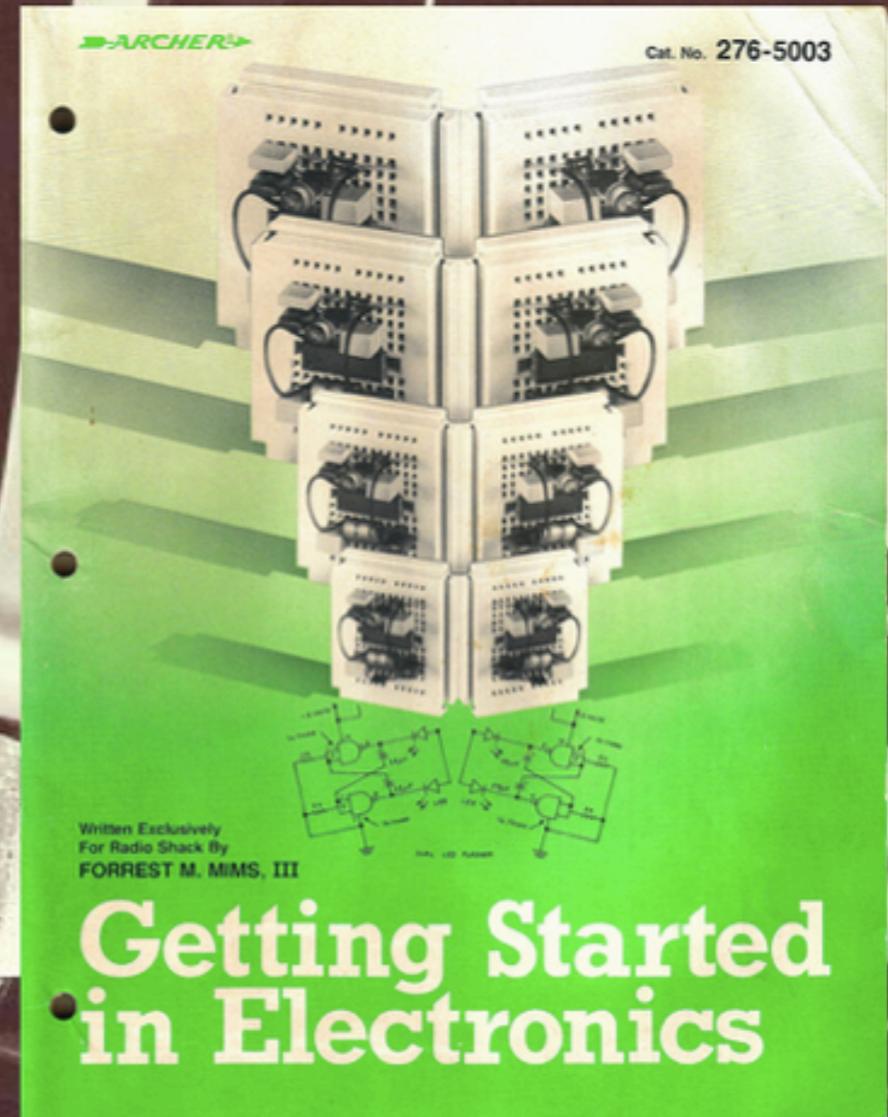
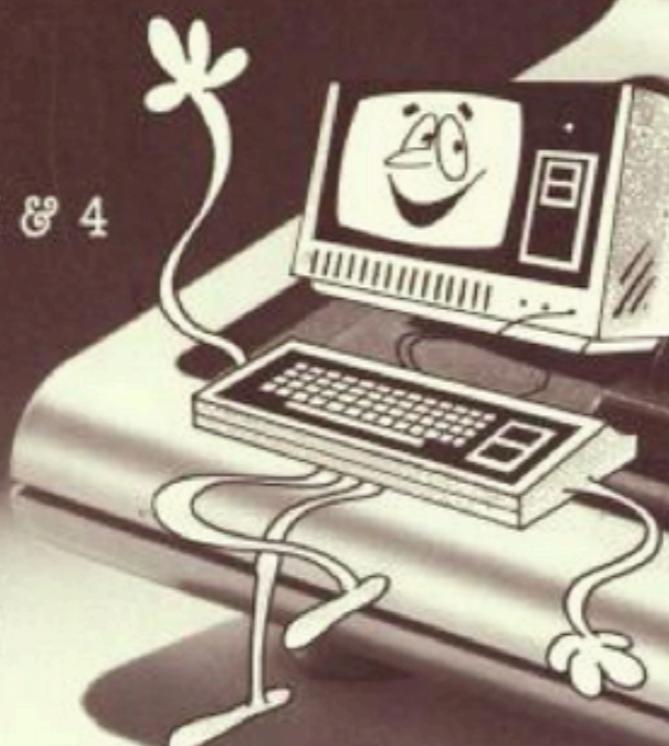
Jason Kridner
Co-Founder
BeagleBoard.org

Getting Started With TRS-80[®] BASIC

For use with Models I, III & 4

Radio Shack

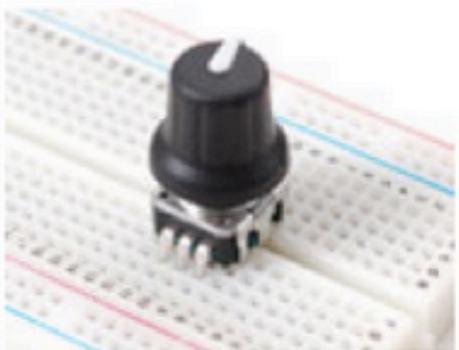
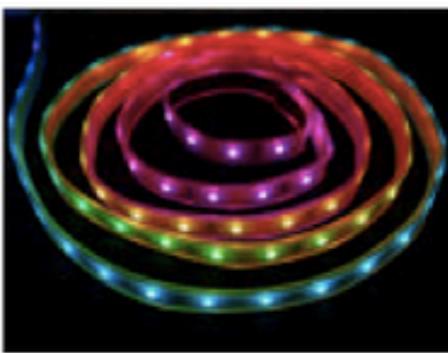
The biggest name in little computers*



CUSTOM MANUFACTURED IN THE U.S.A. BY RADIO SHACK, A DIVISION OF TANUT CORPORATION

<http://www.sandywalsh.com/2012/07/01/archive.html>

<http://newcome.wordpress.com/2009/12/15/make-electronics-the-new-engineers-notebook/>



<http://www.adafruit.com/>

 **beagleboard.org**



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Development Platform

OPEN PCB

Display

Prototyping

Tools & Equipment

Electronic Components

Wireless

Power

Smart Home

HOME > PROTOTYPING > ELECTRONIC BRICK

BROWSE BY

CATEGORY

- Chassis and Shield (2)
- Sensor Brick (17)
- Light and Sound (3)
- Button and Switch (6)
- Communication (1)
- Display Brick (2)
- Misc brick (1)
- Cable and Wires (2)

SHOPPING CART

You have no items in your shopping cart.

COMPARE PRODUCTS

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POPULAR TAGS

ethernet ethernet,wiznet foca
nRF24L01 wiznet,ethernet

[VIEW ALL TAGS >](#)

ELECTRONIC BRICK

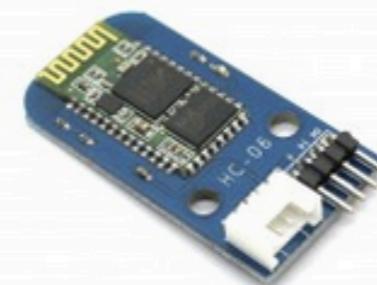
Items 1 to 10 of 24 total

Page: 1 [2](#) [3](#) Next

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Electronic Brick - HC06 Serial Bluetooth Brick

[2 Review\(s\)](#) | Add Your Review

This Serial Bluetooth brick is easy to use module compatible with existing Stem Basic Shield. It designs for transparent wireless serial connection setup. [Learn More](#)

[Add to Wishlist](#) [Add to Compare](#)

\$12.00
\$10.00

[ADD TO CART](#)



Electronic Brick - DHT11 Humidity Temperature Sensor Brick

[2 Review\(s\)](#) | Add Your Review

DHT11 electronic brick of digital temperature & humidity sensor features a digital temperature & humidity sensor complex with a calibrated digital signal output. Its single-bus operation, extremely small size and low consumption enable it to be used in HVAC, automotive, weather stations, dehumidifier and other applications. [Learn More](#)

[Add to Wishlist](#) [Add to Compare](#)

\$4.50
\$3.00

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**[http://imall.iteadstudio.com/
prototyping/electronic-brick.html](http://imall.iteadstudio.com/prototyping/electronic-brick.html)**

NEW

BLOG

SUPPORT

IMALL

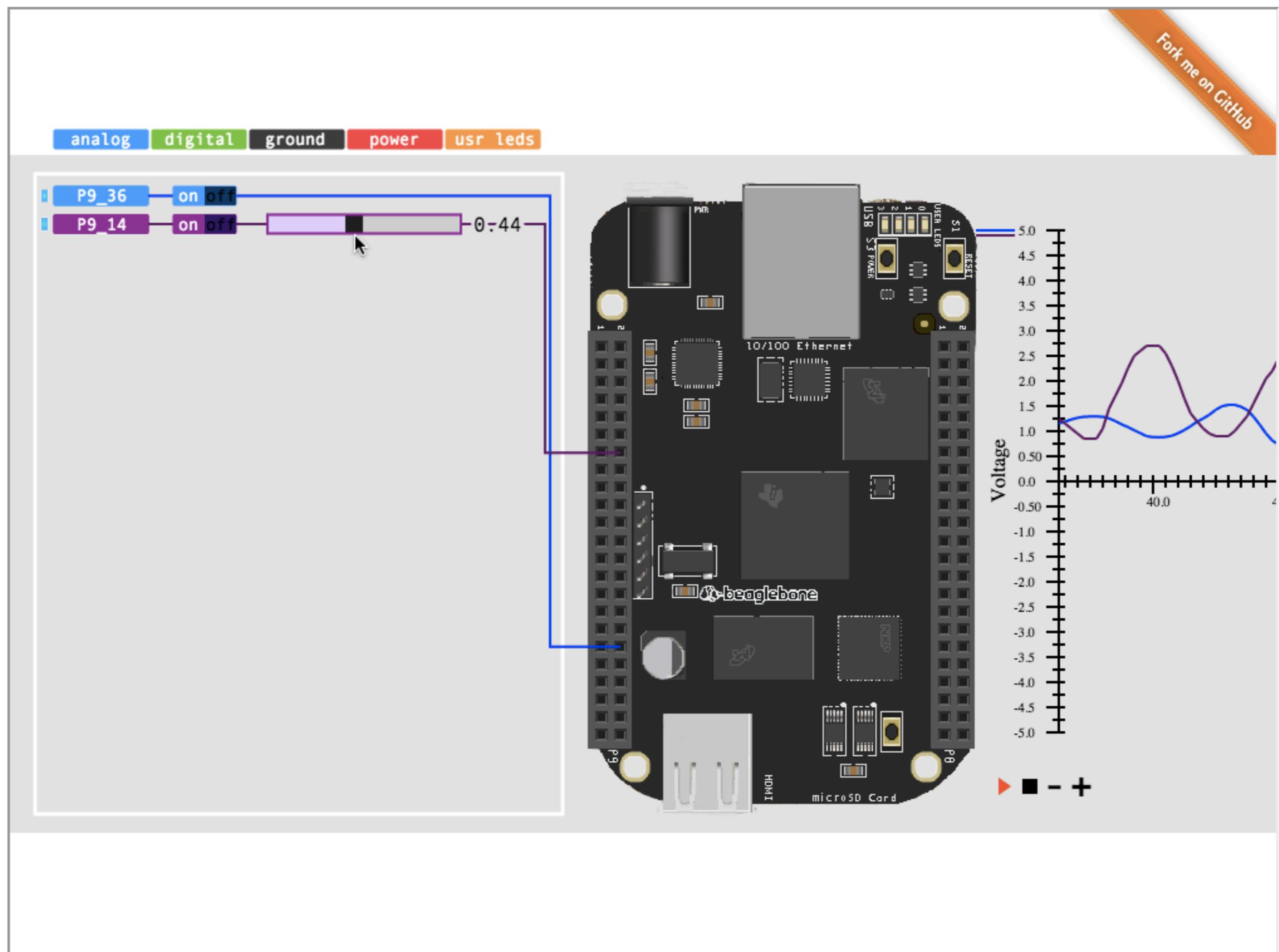
analog digital ground power usr leds

Welcome to the beaglebone user interface!

This interface allows you to play with analog to digital converters, digital pins (including inputs, outputs, and pwms), and the user leds located at the top of the board. Hovering over the buttons indicates which pins correspond to what type. Click and drag the button within the white rectangle and select a pin. The input button requires both an input and an output. The graph to the right will display the voltage of the corresponding pin. Use the zoom in or zoom out to alter the graph, stop to stop recording voltages, and play again to reset. Enjoy!



Fork me on GitHub





BeagleBone 101

BeagleBone 101

Software

- Update image
- Cloud9 IDE

Hardware

- Headers
- Capes

BoneScript

Functions

- getPlatform()
- pinMode()
- getPinMode()
- digitalWrite()
- digitalRead()
- shiftOut()
- analogWrite()
- analogRead()
- attachInterrupt()
- detachInterrupt()
- readTextFile()
- writeTextFile()

JavaScript

- console()
- setTimeout()
- clearTimeout()
- setInterval()
- clearInterval()
- typeof operator

Libraries

- require()



Your board is connected!

BeagleBone Black rev 00C0 S/N 3614BBBBK4008 running BoneScript 0.2.4 at 192.168.7.2

BoneScript

Familiar Arduino function calls, exported to the browser

The buttons below will run code in your browser that will impact the LEDs on your BeagleBone. The exact code used in the browser is below and will send messages to your board using [Socket.IO](#).

Turn LEDs on: [run](#)

```
var b=require('bonescript');
b.pinMode('USR0', 'out');
b.pinMode('USR1', 'out');
b.pinMode('USR2', 'out');
b.pinMode('USR3', 'out');
b.digitalWrite('USR0', 1);
b.digitalWrite('USR1', 1);
b.digitalWrite('USR2', 1);
b.digitalWrite('USR3', 1);
```

Turn LEDs off: [run](#)

```
var b=require('bonescript');
b.pinMode('USR0', 'out');
b.pinMode('USR1', 'out');
b.pinMode('USR2', 'out');
b.pinMode('USR3', 'out');
b.digitalWrite('USR0', 0);
b.digitalWrite('USR1', 0);
b.digitalWrite('USR2', 0);
b.digitalWrite('USR3', 0);
```

Restore LEDs to default state: [run](#)

```
var b = require('bonescript');
```

BoneScript

BeagleBone 101

Software

- Update image
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Hardware

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BoneScript

Functions

- getPlatform()
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- digitalWrite()
- digitalRead()
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JavaScript

- console()
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- clearTimeout()
- setInterval()
- clearInterval()
- typeof operator

Libraries

- require()

Demos

- Blink on-board LED
- Blink external LED
- Push button
- Potentiometer



Your board is connected!

BeagleBone Black rev 00C0 S/N 3614BBBBK4008 running BoneScript 0.2.4 at 192.168.7.2

You might be able to see a newer version of this on beagleboard.org/support/bonescript/digitalWrite

digitalWrite(pin, value, [callback])

Write a HIGH or LOW to a digital I/O pin.

NOTE: The 4 USRx LEDs are all able to operate as digital output pins, giving you an always-available output to test your software.

Arguments

- *pin*: the BeagleBone pin identifier
- *value*: the logic level to set the pin
- *callback*: called upon completion

Return value

- true if successful
- false on failure

callback(x)

- *x.err*: error status message

Example

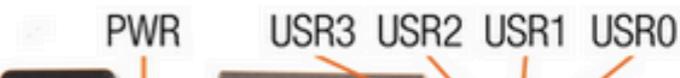
[run](#) [restore](#)

```
1 var b = require('bonescript');
2 b.pinMode('P9_14', b.OUTPUT);
3 b.digitalWrite('P9_14', b.LOW);
```

Bonescript: initialized
Bonescript: initialized

Build and execute instructions

- The USR0 LED is built in, so no circuit assembly is required.



Bring in the web interactions

jQuery Demo

sliderStatus = 0.42

Cloud9 File Edit Find View Goto Run Tools Window Help Preview Run DISK MEMORY Outline Debugger

FAVORITES

- ~
 - am335x_starterware
 - LEDscape
 - openpixelcontrol

FILE SYSTEM

- cloud9
 - _includes
 - _layouts
 - autorun
 - sensortag.js
 - bone101
 - examples
 - extras
 - analog.js
 - analog2.js
 - Blink.ino
 - blink.py
 - blinkled.js
 - blinky.rb
 - fade.js
 - input.js
 - input2.js
 - shiftout.js
 - minidisplay-example
 - pruspeak
 - doc_and_examples
 - 1_example.sh
 - beaglebone_headers
 - pinmux.pdf
 - README.md
 - src
 - driver
 - dts

Cloud9 File Edit Find View Goto Run Tools Window Help Preview Run DISK MEMORY +

FAVORITES

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FILE SYSTEM

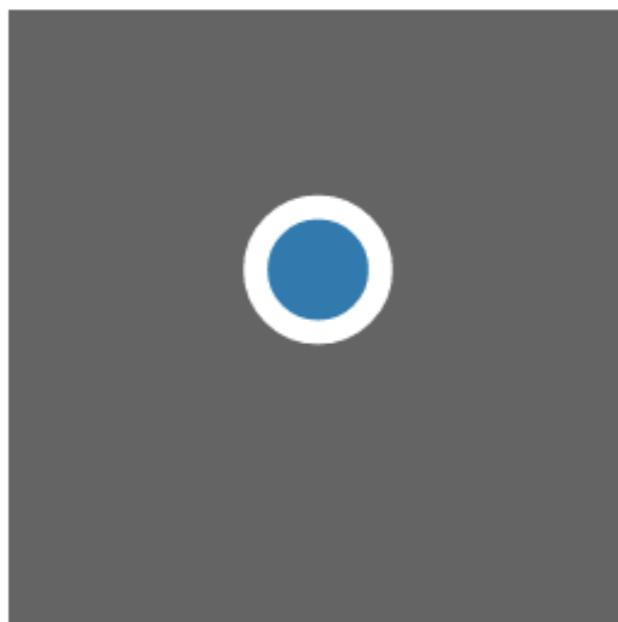
- cloud9
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 - 1_example.sh
 - beaglebone_headers
 - pinmux.pdf
 - README.md
 - src
 - driver
 - dts

```
root@beaglebone:/var/lib/cloud9# uname -r  
3.8.13-bone69  
root@beaglebone:/var/lib/cloud9# cat /etc/dogtag  
BeagleBoard.org Debian Image 2015-01-19  
root@beaglebone:/var/lib/cloud9#
```

Outline Debugger

Easy to extend with other visualizations

Processing.js Demo



BeagleBone Black

1 GHz performance, ready to use

Truly flexible open hardware and software development platform

All you need is in the box

Proven ecosystem from prototype to product

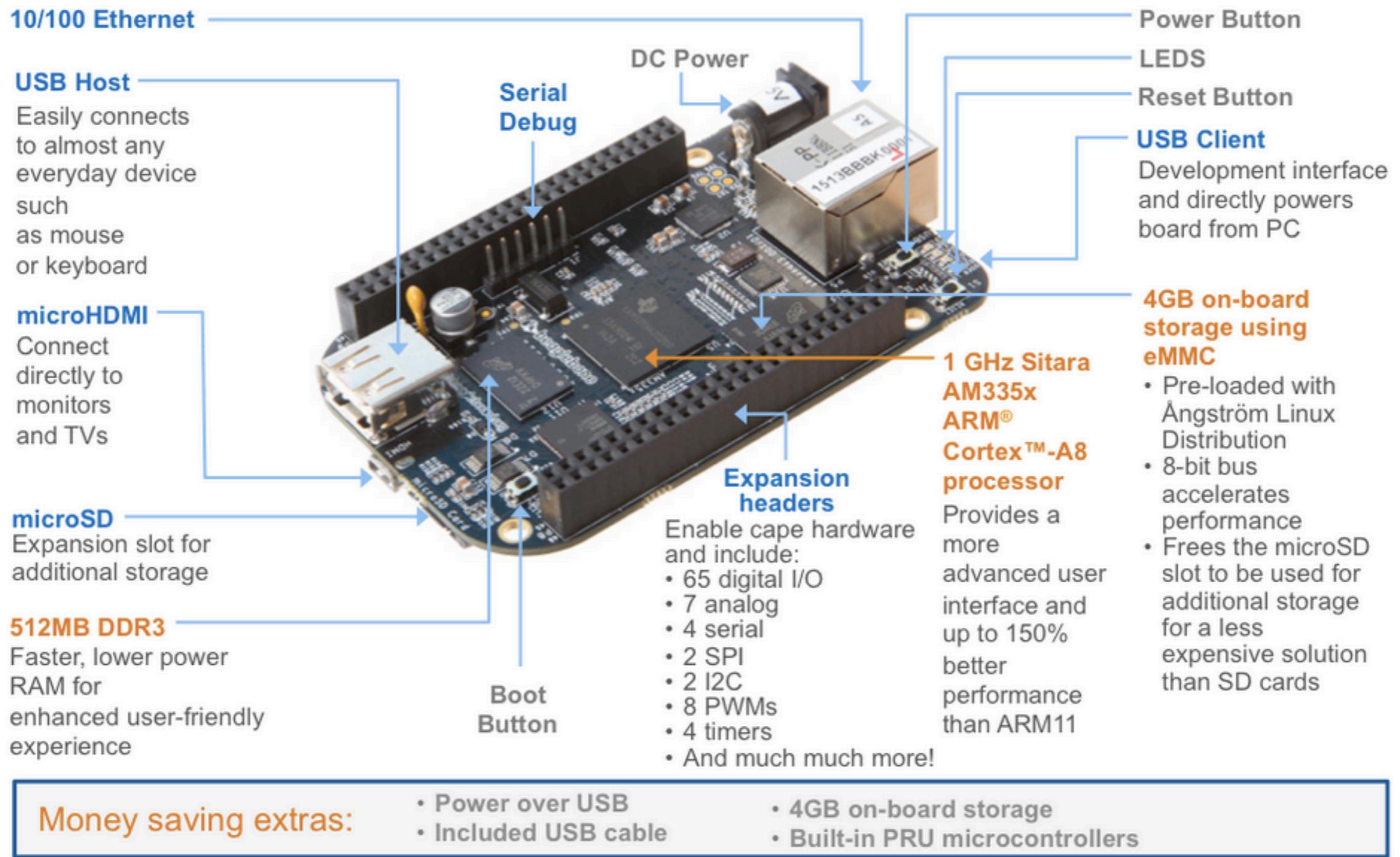


BeagleBone Black

- Ready to use: ~\$50
- 1 GHz performance and embedded microcontrollers
- On-board HDMI to connect directly to TVs and monitors
- 512MB DDR3-800 RAM
- On-board 4GB flash storage with Debian frees up the microSD card slot
- Support for existing Cape plug-in boards:
<http://beaglebonecapes.com>

Most affordable and proven open hardware Linux platform available

BeagleBone Black board features



Huge base of existing projects

Making it fun and easy to bring ideas to life



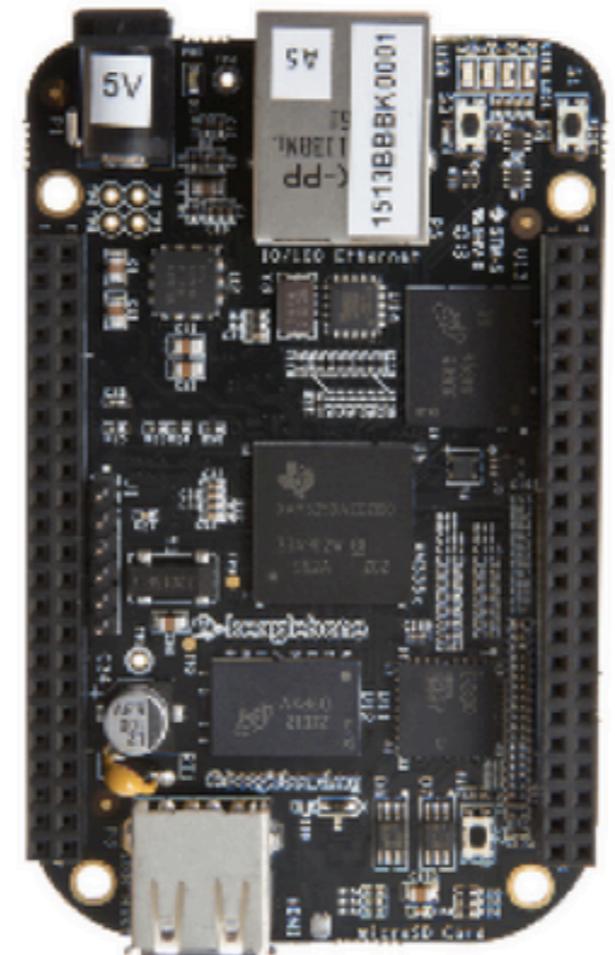
- Medical analysis, assistance and information management
- Home information, automation and security systems
- Home and mobile entertainment and educational systems
- New types of communications systems
- Personal robotic devices for cleaning, upkeep and manufacturing
- Remote presence and monitoring
- Automotive information management and control systems
- Personal environmental exploration and monitoring

<http://beagleboard.org/project>

 beagleboard.org

Cape Expansion Headers

DGND	1	2	DGND
VDD_3V3	3	4	VDD_3V3
VDD_5V	5	6	VDD_5V
SYS_5V	7	8	SYS_5V
PWR_BUT	9	10	SYS_RESETN
UART4_RXD	11	12	GPIO_60
UART4_TXD	13	14	EHRPWM1A
GPIO_48	15	16	EHRPWM1B
SPI0_CS0	17	18	SPI0_D1
I2C2_SCL	19	20	I2C2_SDA
SPI0_DO	21	22	SPI0_SCLK
GPIO_49	23	24	UART1_TXD
GPIO_117	25	26	UART1_RXD
GPIO_115	27	28	SPI1_CS0
SPI1_DO	29	30	GPIO_122
SPI1_SCLK	31	32	VDD_ADC
AIN4	33	34	GNDA_ADC
AIN6	35	36	AIN5
AIN2	37	38	AIN3
AIN0	39	40	AIN1
GPIO_20	41	42	ECAAPPWMO
DGND	43	44	DGND
DGND	45	46	DGND



LEGEND			
POWER/GROUND/RESET	1	2	DGND
AVAILABLE DIGITAL	3	4	MMC1_DAT6
AVAILABLE PWM	5	6	MMC1_DAT2
SHARED I2C BUS	7	8	GPIO_66
RECONFIGURABLE DIGITAL	9	10	GPIO_69
ANALOG INPUTS (1.8V)	11	12	GPIO_45

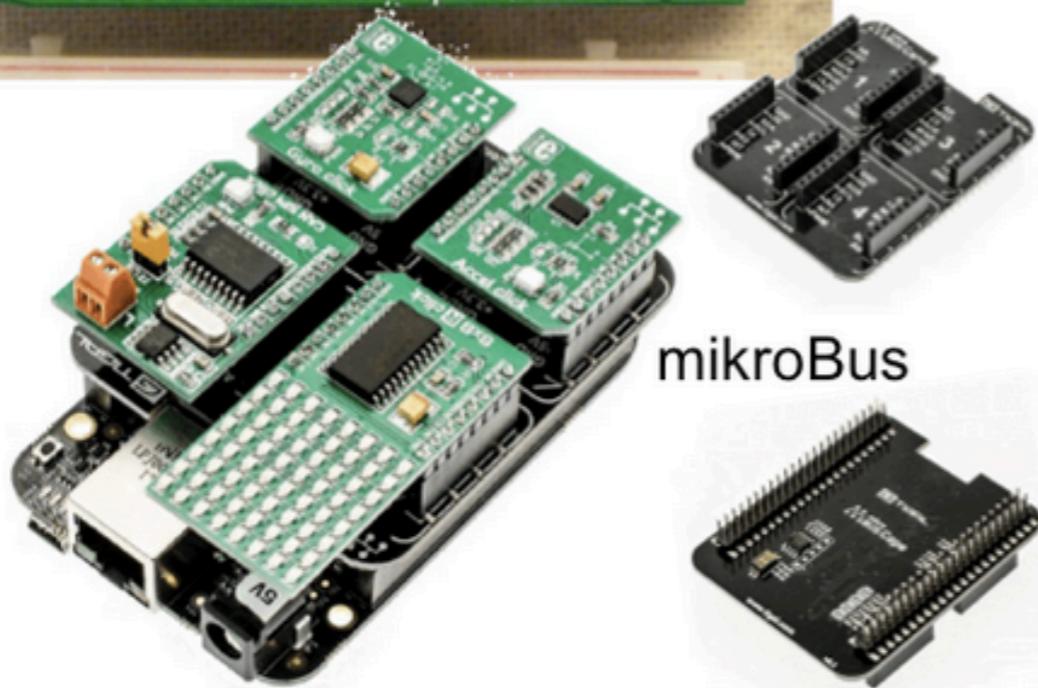
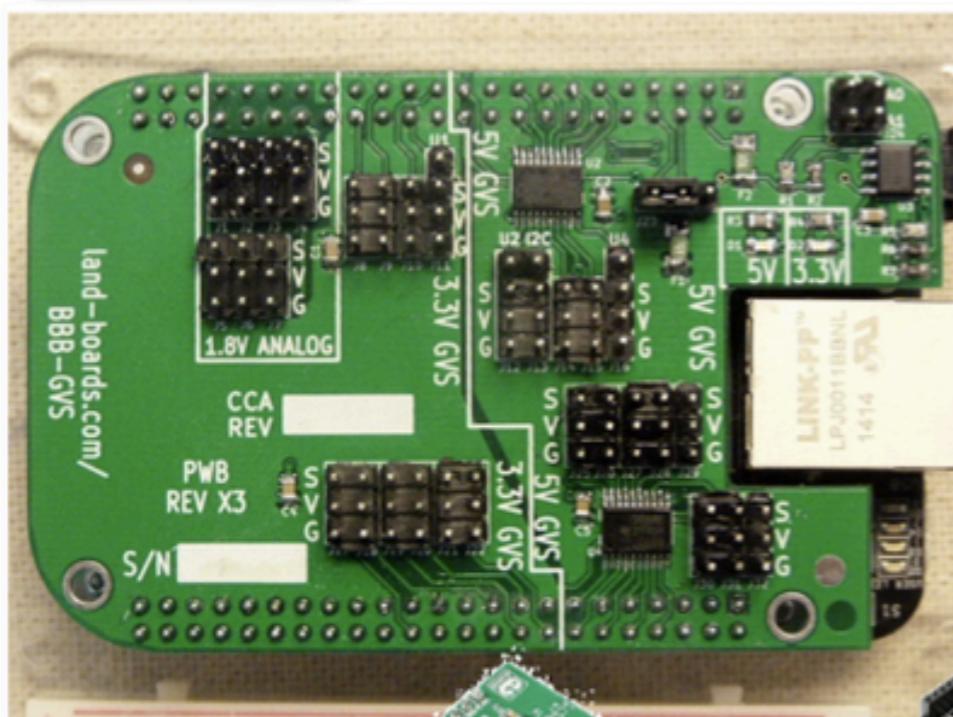
DGND	1	2	DGND
MMC1_DAT6	3	4	MMC1_DAT7
MMC1_DAT2	5	6	MMC1_DAT3
GPIO_66	7	8	GPIO_67
GPIO_69	9	10	GPIO_68
GPIO_45	11	12	GPIO_44
EHRPWM2B	13	14	GPIO_26
GPIO_47	15	16	GPIO_46
GPIO_27	17	18	GPIO_65
EHRPWM2A	19	20	MMC1_CMD
MMC1_CLK	21	22	MMC1_DAT5
MMC1_DAT4	23	24	MMC1_DAT1
MMC1_DATA0	25	26	GPIO_61
LCD_VSYNC	27	28	LCD_PCLK
LCD_HSYNC	29	30	LCD_AC_BIAS
LCD_DATA14	31	32	LCD_DATA15
LCD_DATA13	33	34	LCD_DATA11
LCD_DATA12	35	36	LCD_DATA10
LCD_DATA8	37	38	LCD_DATA9
LCD_DATA6	39	40	LCD_DATA7
LCD_DATA4	41	42	LCD_DATA5
LCD_DATA2	43	44	LCD_DATA3
LCD_DATA0	45	46	LCD_DATA1

Capes to make wiring even easier

BBB-GVS



GVS



mikroBus

Grove Cape for BeagleBone Series

SKU: 811001001

USD ▾ \$19.90

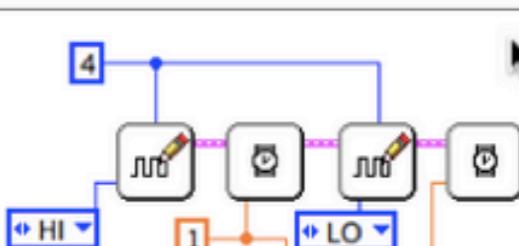
Grove

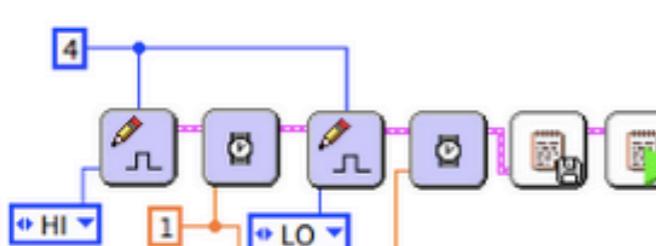


<http://botspeak.org/>

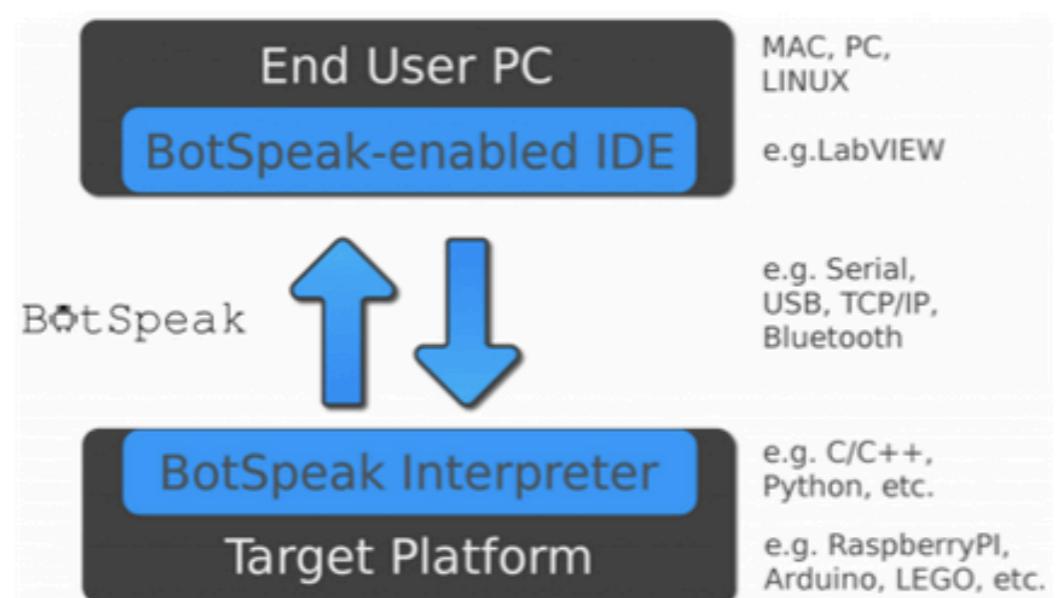
Blink

This code will blink DIO[4] on the device once.

Blink Direct Mode			
LabVIEW	BotSpeak	TinySpeak	
	SET DIO[4],1	CA04 0001	
	WAIT 1	0357 03E8*	
	SET DIO[4],0	CA04 0000	
	WAIT 1	0357 03E8*	

Blink Scripting Mode			
LabVIEW	BotSpeak	TinySpeak	
	SCRIPT	0173	
	SET DIO[4],1	CA04 0001	
	WAIT 1	0357 03E8*	
	SET DIO[4],0	CA04 0000	
	WAIT 1	0357 03E8*	
	ENDSCRIPT	0145	
	RUN 0	0372 0000	

*one second is converted to 1000 ms on the arduino since it does not support floating point



What are PRUs

- “Programmable Real-time Units”
- 32-bit RISC processors at 200MHz with single-cycle pin access for hard real-time
- Optimized for packet processing/switching and software implementations of peripherals
- Part of the PRU-ICSS, “Industrial Communications SubSystem”

PRU: Programmable Real-time Unit

Architecture

- Two 32-bit RISC cores for real-time functions each running at 200MHz
- 8KB IRAM, 8KB DRAM, 12KB Shared RAM
- **Single-cycle execution**
- **Direct I/O interface sampling at ~5ns**
- Logic, Control and arithmetic instructions
- 32-bit MULT and Interrupt controller
- Efficient bit/byte/word manipulations

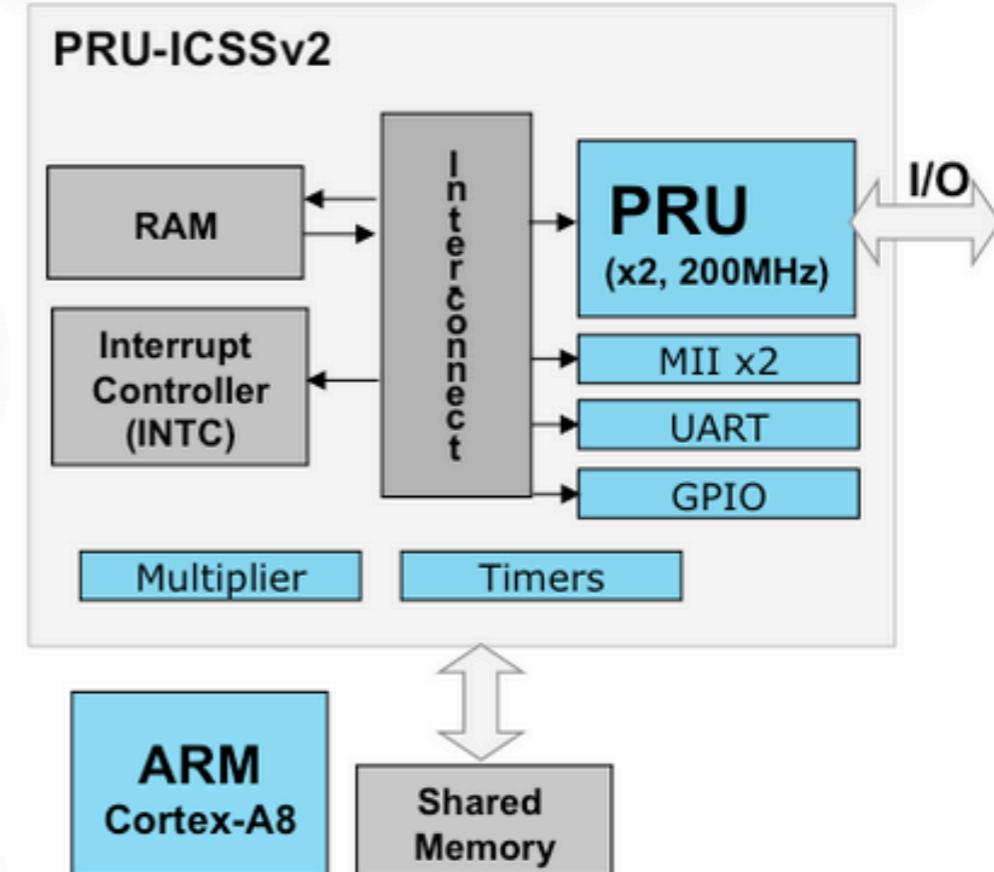
Capabilities

- Implement **Real-time communication interfaces** : PROFIBUS, EtherCAT, PROFINET & Ethernet/IP
- Implement **custom IP** (such as EnDAT 2.2, SINC3 decimation, PWMs, DP Memory, Manchester Coding, 9 bit UART or a Backplane bus)

Advantages

- Completely programmable & Flexible
- Reduce system cost & complexity

AM335x SoC: ARM + PRU



25 PRU low-latency I/Os

P9		
DGND	1	2
VDD_3V3	3	4
VDD_5V	5	6
SYS_5V	7	8
PWR_BUT	9	10
GPIO_30	11	12
GPIO_31	13	14
GPIO_48	15	16
GPIO_5	17	18
I2C2_SCL	19	20
GPIO_3	21	22
GPIO_49	23	24
PRUO_7	25	26
PRUO_5	27	28
PRUO_1	29	30
PRUO_0	31	32
AIN4	33	34
AIN6	35	36
AIN2	37	38
AIN0	39	40
PRUO_6	41	42
DGND	43	44
DGND	45	46

P8		
DGND	1	2
GPIO_38	3	4
GPIO_34	5	6
GPIO_66	7	8
GPIO_69	9	10
PRUO_15 OUT	11	12
GPIO_23	13	14
GPIO_47	15	16
GPIO_27	17	18
GPIO_22	19	20
PRU1_12	21	22
GPIO_36	23	24
GPIO_32	25	26
PRU1_8	27	28
PRU1_9	29	30
GPIO_10	31	32
GPIO_9	33	34
GPIO_8	35	36
GPIO_78	37	38
PRU1_6	39	40
PRU1_4	41	42
PRU1_2	43	44
PRU1_0	45	46
PRU1_7		
PRU1_5		
PRU1_3		
PRU1_1		

Cloud9 File Edit Find View Goto Run Tools Window Help Preview Run DISK MEMORY +

FAVORITES

- ~ .
 - am335x_starterware
 - LEDscape
 - openpixelcontrol

FILE SYSTEM

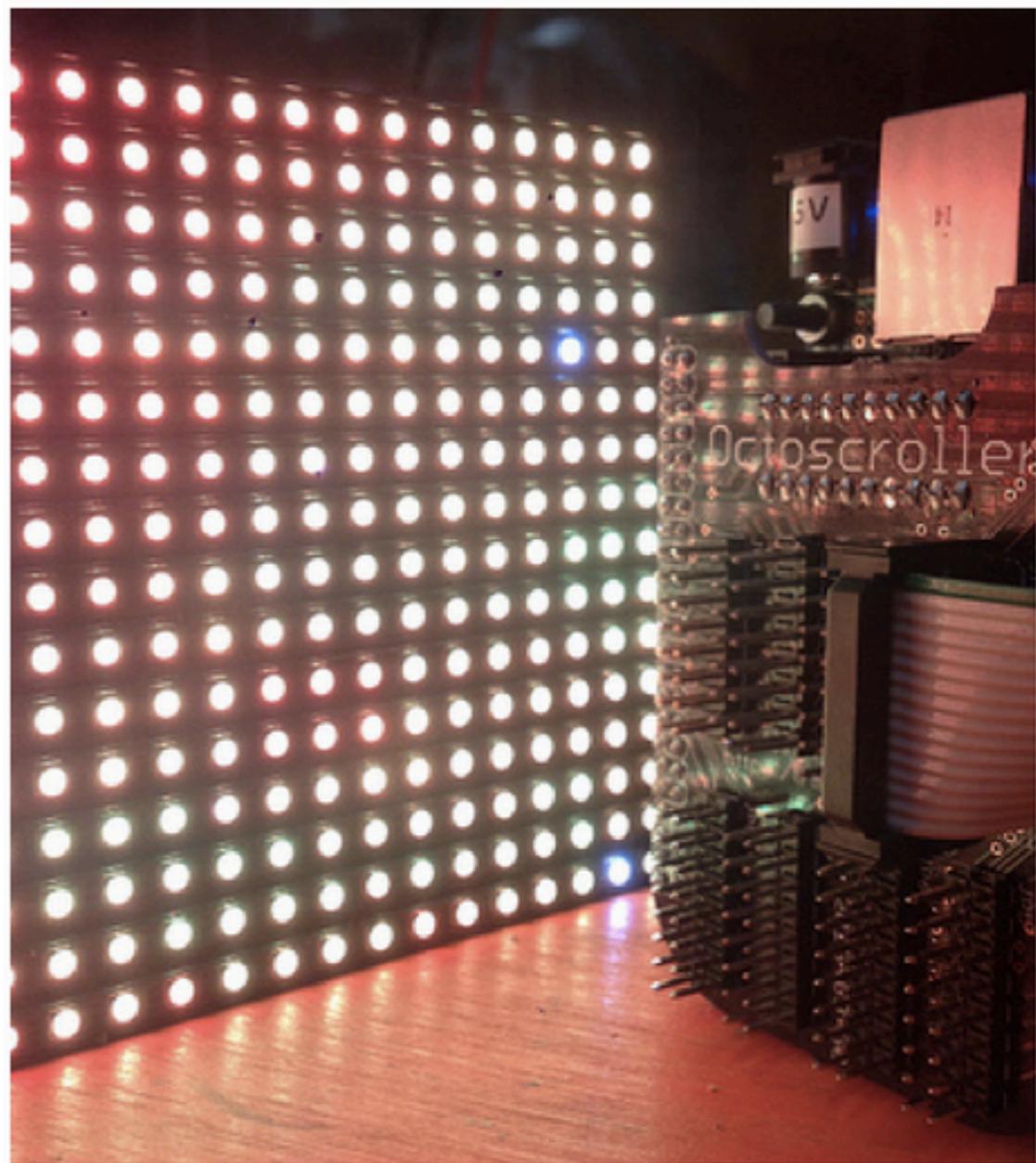
- cloud9
 - _includes
 - _layouts
 - autorun
 - sensortag.js
 - bone101
 - examples
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 - analog.js
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 - Blink.ino
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 - minidisplay-example
 - pruspeak
 - doc_and_examples
 - 1_example.sh
 - beaglebone_headers
 - pinmux.pdf
 - README.md
 - src
 - driver
 - dts

```
root@beaglebone:/var/lib/cloud9# uname -r  
3.8.13-bone69  
root@beaglebone:/var/lib/cloud9# cat /etc/dogtag  
BeagleBoard.org Debian Image 2015-01-19  
root@beaglebone:/var/lib/cloud9# nc localhost 6060  
SCRIPT  
SET DIO[4], 1  
WAIT 1000  
SET DIO[4], 0  
WAIT 1000  
GOTO 0  
ENDSCRIPT  
RUN
```

Outline Debugger

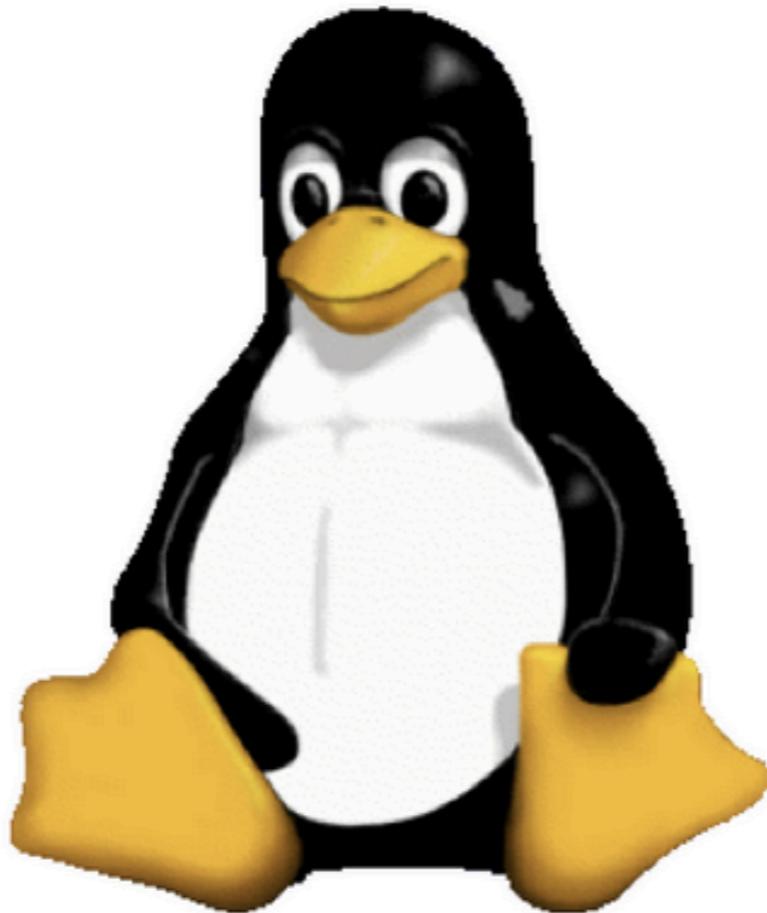
LEDscape and Octoscroller

- Works with Adafruit 32x16 LED panels
- 12-bit color supported through PRU-based pulse-width modulation
- Open source software and hardware
- Content delivered using network packets (Python)
- Supports 64 panels each



Must teach operating systems concepts

- Where are my bits?
- What is a command line and why do I care?
- In Linux, everything is a file



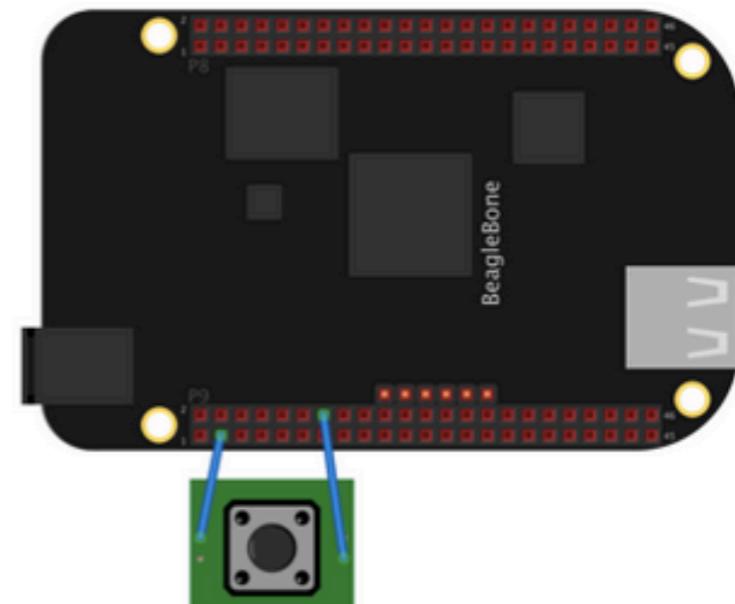
Some quick interfaces to hack

- LEDs

```
root@beaglebone:~# cd /sys/class/leds/beaglebone\:green\:usr0
root@beaglebone:/sys/class/leds/beaglebone:green:usr0# cat trigger
none nand-disk mmc0 mmc1 timer oneshot [heartbeat] backlight gpio cpu0 default-on transient
root@beaglebone:/sys/class/leds/beaglebone:green:usr0# echo none > trigger
root@beaglebone:/sys/class/leds/beaglebone:green:usr0# echo 1 > brightness
root@beaglebone:/sys/class/leds/beaglebone:green:usr0# echo 0 > brightness
```

- GPIOs

```
root@beaglebone:~# config-pin overlay cape-universalm
Loading cape-universalm overlay
root@beaglebone:~# config-pin p9.14 gpio_pd
root@beaglebone:~# config-pin -q p9.14
P9_14 Mode: gpio_pd Direction: in Value: 0
root@beaglebone:~# cd /sys/class/gpio
root@beaglebone:/sys/class/gpio# cat gpio50/direction
in
root@beaglebone:/sys/class/gpio# cat gpio50/value
0
```



Hacking with the ADC

- Don't forget it is only **1.8V**
- The overlay will load an ADC driver

- Steps

```
root@beaglebone:~# config-pin overlay BB-ADC
```

Loading BB-ADC overlay

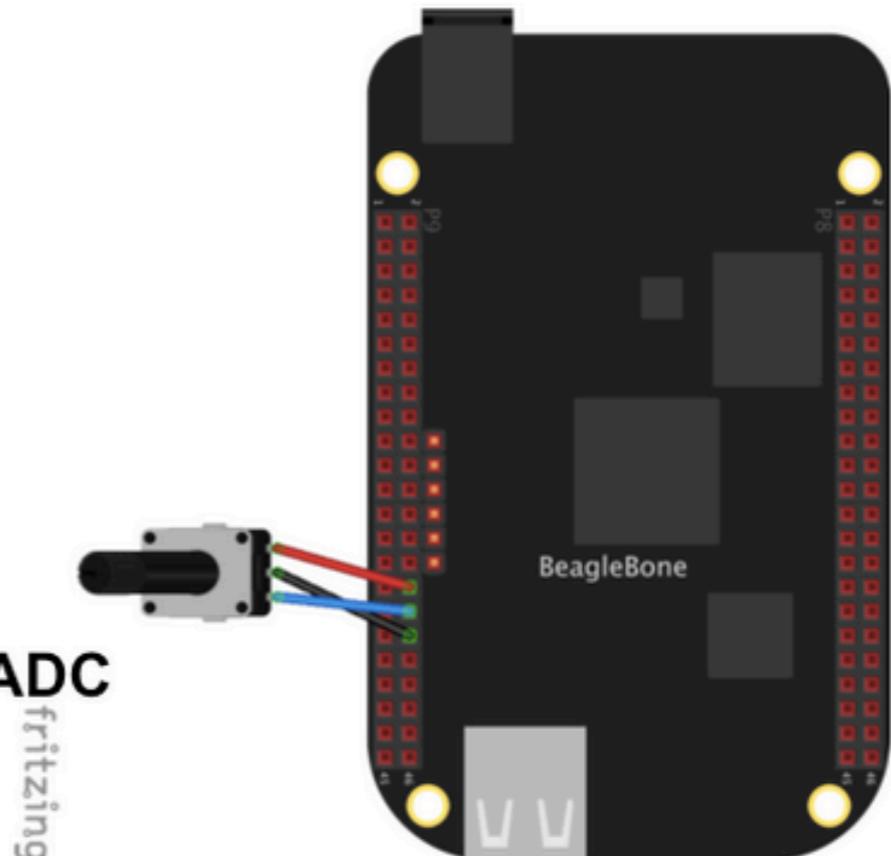
```
root@beaglebone:~# config-pin -q p9.36
```

Pin is not modifiable: P9_36 AIN5

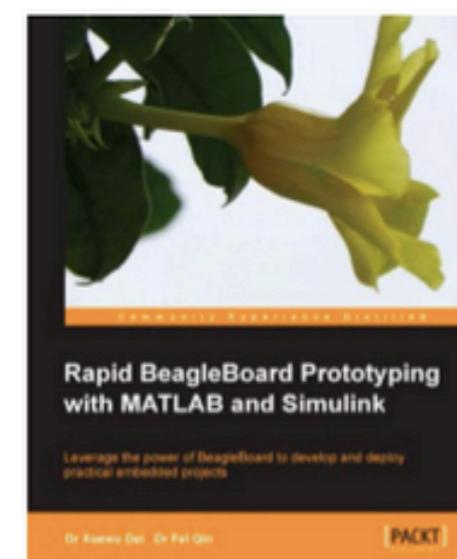
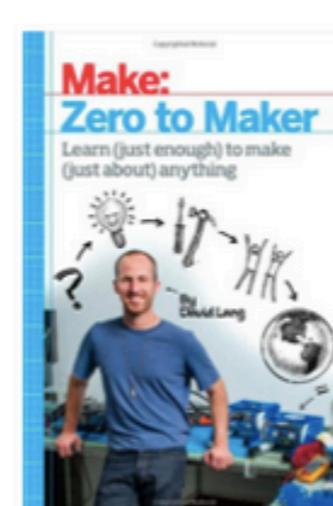
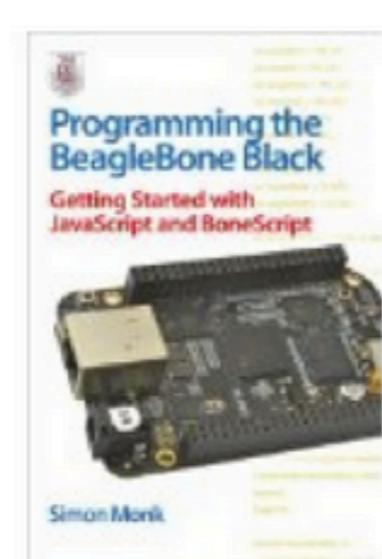
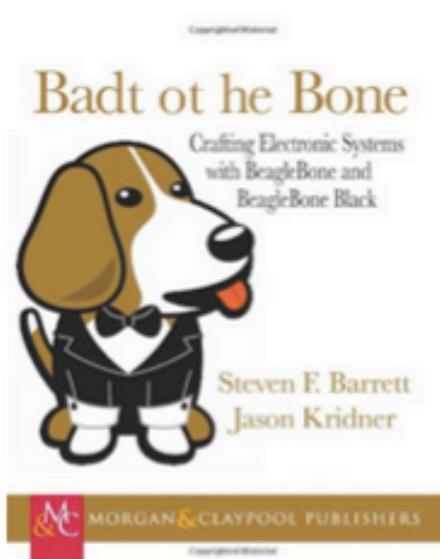
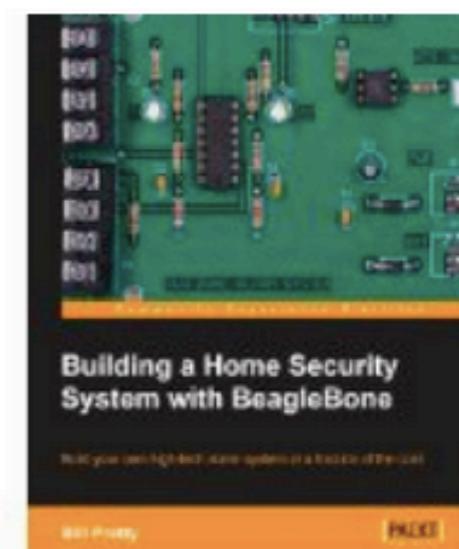
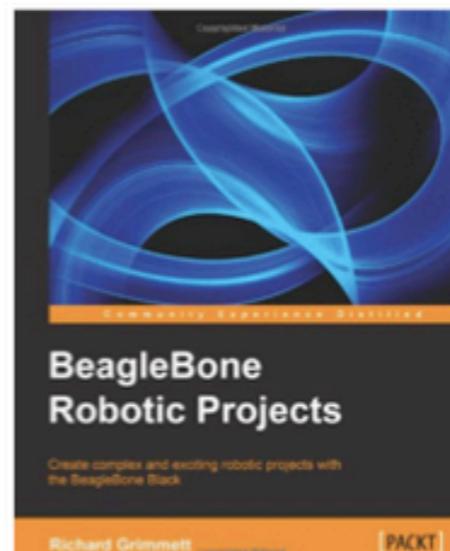
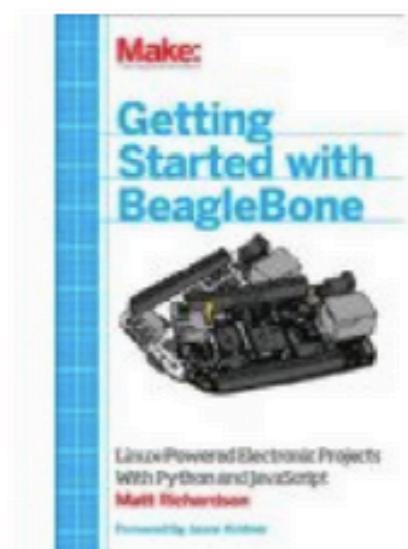
```
root@beaglebone:~# cd /sys/bus/iio/devices/iio\:device0
```

```
root@beaglebone:/sys/bus/iio/devices/iio\:device0# cat in_voltage5_raw
```

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Some BeagleBoard.org related books



<http://bit.ly/bbb-books>

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Stop