

Stochastic Calculus: Lecture Notes

Contents

1	σ-Algebras	2
2	Measures, Probability	2
3	Measurable Functions, Random Variables	2
4	Expectation, Indicator Functions	3
5	Independence, Covariance	3
6	Conditional Expectation	3
7	Stochastic Process	4
8	Martingale	4
9	Brownian Motion	5
10	Itô Integral and Isometry	6
11	Stochastic Integral	6
12	Itô's Lemma	7
13	Itô Process	9
14	Quadratic Variation	9
15	Itô's Isometry	10
16	Integral Martingale	10
17	Geometric Brownian Motion	10
18	Change of Measure (Randon-Nikodym)	11
19	Girsanov's Theorem	11
20	Stopping Times	13
20.1	Doob's Optional Stopping Theorem	13

1 σ -Algebras

Definition 1.1. Let Ω be a nonempty set. A σ -algebra \mathcal{F} on Ω is a collection of subsets of Ω such that:

1. $\Omega \in \mathcal{F}$;
2. If $A \in \mathcal{F}$, then its complement $A^c = \Omega \setminus A \in \mathcal{F}$;
3. If $\{A_n\}_{n=1}^\infty \subseteq \mathcal{F}$, then the union $\bigcup_{n=1}^\infty A_n \in \mathcal{F}$.

Exercise 1.1. Let \mathcal{F} be a σ -algebra on Ω . Show that:

1. $\emptyset \in \mathcal{F}$.
2. For any finite collection $A_1, \dots, A_n \in \mathcal{F}$, also $\bigcup_{i=1}^n A_i \in \mathcal{F}$ and $\bigcap_{i=1}^n A_i \in \mathcal{F}$.
3. For $A, B \in \mathcal{F}$, the difference $A \setminus B \in \mathcal{F}$.
4. The intersection of an arbitrary family $\{\mathcal{F}_\alpha\}_{\alpha \in I}$ of σ -algebras is itself a σ -algebra.

2 Measures, Probability

Definition 2.1. Let Ω be a set and \mathcal{F} a σ -algebra over Ω . A function $\mu : \mathcal{F} \rightarrow \mathbb{R}$ is called a measure if it satisfies the following properties:

1. Non-negativity: $\forall A \in \mathcal{F}, \mu(A) \geq 0$;
2. Null empty set: $\mu(\emptyset) = 0$;
3. Countable additivity: For every sequence $\{E_k\}_{k=1}^\infty$ of pairwise disjoint sets in \mathcal{F} ,

$$\mu\left(\bigcup_{k=1}^\infty E_k\right) = \sum_{k=1}^\infty \mu(E_k).$$

A probability measure P is a measure with $P(\Omega) = 1$.

3 Measurable Functions, Random Variables

Definition 3.1. Let (Ω, \mathcal{F}) and (Y, \mathcal{G}) be measurable spaces, meaning that Ω and Y are sets equipped with respective σ -algebras \mathcal{F} and \mathcal{G} . A function $f : \Omega \rightarrow Y$ is said to be measurable if for every $E \in \mathcal{G}$ the pre-image of E under f is in \mathcal{F} :

$$f^{-1}(E) = \{x \in \Omega \mid f(x) \in E\} \in \mathcal{F}.$$

Definition 3.2. Let (Ω, \mathcal{F}, P) be a probability space and (Y, \mathcal{G}) a measurable space. Then an (Y, \mathcal{G}) -valued random variable is a measurable function

$$X : \Omega \rightarrow Y.$$

X is \mathcal{F} -measurable. The notation $\sigma(X)$ denotes the σ -algebra generated by X .

4 Expectation, Indicator Functions

$$X \in L^1(\Omega) \quad \text{if} \quad E[|X|] < \infty.$$

$$E[X] = \int_{\Omega} X(\omega) dP(\omega).$$

For any event $A \in \mathcal{F}$, the *indicator function* is

$$\mathbf{1}_A(\omega) = \begin{cases} 1, & \omega \in A, \\ 0, & \omega \notin A. \end{cases}$$

One then has

$$P(A) = \int_{\Omega} \mathbf{1}_A dP = \mathbf{E}[\mathbf{1}_A].$$

5 Independence, Covariance

Two events $A, B \in \mathcal{F}$ are *independent* if

$$P(A \cap B) = P(A)P(B).$$

Random variables X and Y are independent if for all $A, B \in \mathcal{G}$:

$$P(X \in A \cap Y \in B) = P(X \in A)P(Y \in B).$$

$$\begin{aligned} E[XY] &= E[X]E[Y], \\ \text{Cov}(X, Y) &= E[XY] - E[X]E[Y], \\ \rho(X, Y) &= \frac{\text{Cov}(X, Y)}{\sigma_X \sigma_Y}. \end{aligned}$$

A random variable X and a σ -algebra \mathcal{F} are independent if $\sigma(X)$ and \mathcal{F} are independent. This means:

$$P(X \in I \mid A) = P(X \in I), \quad \forall A \in \mathcal{F}, \text{ interval } I.$$

6 Conditional Expectation

Definition 6.1. Let (Ω, \mathcal{F}, P) be a probability space, $X : \Omega \rightarrow \mathbb{R}^n$ a random variable, and let $\mathcal{G} \subseteq \mathcal{F}$ be a sub- σ -algebra. A conditional expectation of X given \mathcal{G} , denoted $E[X \mid \mathcal{G}]$, is any \mathcal{G} -measurable function such that

$$\int_A E[X \mid \mathcal{G}] dP = \int_A X dP, \quad \forall A \in \mathcal{G}.$$

Properties:

1. Linearity: $E[aX + bY \mid \mathcal{G}] = aE[X \mid \mathcal{G}] + bE[Y \mid \mathcal{G}]$
2. If X is \mathcal{G} -measurable:
$$\begin{aligned} E[XY \mid \mathcal{G}] &= XE[Y \mid \mathcal{G}], \\ E[X \mid \mathcal{G}] &= X \end{aligned}$$
3. Tower rule: $E[E[X \mid \mathcal{G}] \mid \mathcal{H}] = E[X \mid \mathcal{H}]$ if $\mathcal{H} \subset \mathcal{G}$
4. If X is independent of \mathcal{G} : $E[X \mid \mathcal{G}] = E[X]$
5. Total expectation: $E[E[X \mid \mathcal{G}]] = E[X]$

7 Stochastic Process

Definition 7.1. Let T be a set of times. A stochastic process $\{X_t\}_{t \in T}$ is a collection of random variables on (Ω, \mathcal{F}, P) .

Definition 7.2. A filtration is a family $\{\mathcal{F}_t\}$ of sub- σ -algebras of \mathcal{F} with the property that $\mathcal{F}_s \subseteq \mathcal{F}_t$ for $0 \leq s < t$.

A stochastic process $\{X_t\}$ is adapted to filtration $\{\mathcal{F}_t\}$ if X_t is \mathcal{F}_t -measurable for all t .

Example 7.1. If T is discrete:

- X_0 is \mathcal{F}_0 -measurable
- (X_0, X_1) is \mathcal{F}_1 -measurable
- (X_0, X_1, X_2) is \mathcal{F}_2 -measurable

8 Martingale

Definition 8.1. A process $\{X_t\}_{t \in T}$ is a martingale with respect to the filtration $\{\mathcal{F}_t\}$ if:

1. X_t is integrable for all t ,
2. X_t is adapted to the filtration \mathcal{F}_t ,
3. For all $s \leq t$, $E[X_t | \mathcal{F}_s] = X_s$.

This implies:

$$E[X_t - X_s | \mathcal{F}_s] = 0$$

$$E[X_s] = E[X_t] = E[X_0], \quad \text{so the expectation is constant.}$$

Example 8.1. $X_t = B_t^2 - t$.

$$d(B_t^2) = 2B_t dB_t + dt \implies dX_t = 2B_t dB_t.$$

Mean:

$$E[X_t] = E[B_t^2] - t = t - t = 0.$$

Martingale property: for $s < t$,

$$X_t - X_s = \int_s^t 2B_u dB_u,$$

so by independence $E[X_t - X_s | \mathcal{F}_s] = 0$ and hence

$$E[X_t | \mathcal{F}_s] = X_s.$$

Example 8.2. $X_t = B_t^3 - 3 \int_0^t B_u du$.

$$d(B_t^3) = 3B_t^2 dB_t + 3B_t dt \implies dX_t = 3B_t^2 dB_t.$$

Mean: *by Itô isometry*,

$$E[X_t] = 0.$$

Martingale property: *for* $s < t$,

$$X_t - X_s = \int_s^t 3B_u^2 dB_u,$$

so $E[X_t | \mathcal{F}_s] = X_s$.

Example 8.3. $X_t = \exp(B_t - \frac{1}{2}t)$.

$$dX_t = X_t dB_t \quad (\text{since } d(B_t - \frac{1}{2}t) = dB_t - \frac{1}{2}dt).$$

Mean:

$$E[X_t] = e^{-\frac{1}{2}t} E[e^{B_t}] = e^{-\frac{1}{2}t} e^{\frac{1}{2}t} = 1.$$

Martingale property: *for* $s < t$,

$$X_t - X_s = \int_s^t X_u dB_u,$$

so $E[X_t | \mathcal{F}_s] = X_s$.

Example 8.4. $X_t = \sin(B_t)$, *define*

$$M_t = \sin(B_t) + \frac{1}{2} \int_0^t \sin(B_u) du.$$

By Itô,

$$d \sin(B_t) = \cos(B_t) dB_t - \frac{1}{2} \sin(B_t) dt \implies dM_t = \cos(B_t) dB_t.$$

Mean: $E[M_t] = 0$. Martingale property: *for* $s < t$,

$$M_t - M_s = \int_s^t \cos(B_u) dB_u \implies E[M_t | \mathcal{F}_s] = M_s.$$

Equivalently,

$$\sin(B_t) + \frac{1}{2} \int_0^t \sin(B_u) du$$

is a martingale.

9 Brownian Motion

Definition 9.1. *The process B_t is a Brownian motion if:*

1. $B_0 = 0$,
2. B_t is almost surely continuous,

3. B_t has independent increments,
4. $B_t - B_s \sim N(0, t - s)$ for $0 \leq s < t$.

$$F_{\mu, \sigma}(x) = \frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{1}{2} \left(\frac{x - \mu}{\sigma} \right)^2}$$

Properties:

- $E[B_t] = 0$
- $E[B_t^2] = t = \text{Var}(B_t)$
- B_t is a martingale
- $E[B_t \mid B_s] = B_s$

10 Itô Integral and Isometry

Given a simple adapted process $h_t = \sum_{i=0}^{n-1} h_i \mathbf{1}_{(t_i, t_{i+1}]}(t)$, define the Itô integral:

$$\int_0^T h_s dB_s = \sum_{i=0}^{n-1} h_i (B_{t_{i+1}} - B_{t_i}).$$

Itô isometry:

$$\mathbb{E} \left[\left(\int_0^T h_s dB_s \right)^2 \right] = \mathbb{E} \left[\int_0^T h_s^2 ds \right].$$

11 Stochastic Integral

$$\int_0^T W_s dW_s \quad (\text{not Riemann-Stieltjes})$$

Elementary process:

$$\int_0^T h_t(\omega) dW_t(\omega) := \sum_{i=0}^{n-1} e_i(\omega) (W_{t_{i+1}} - W_{t_i})$$

General process:

$$\int_0^T X_t(\omega) dW_t(\omega) := \lim_{n \rightarrow \infty} \sum_{t_i} X_t^{(n)} (W_{t_{i+1}} - W_{t_i})$$

12 Itô's Lemma

Theorem 12.1 (Itô's Lemma). *Let f be twice differentiable. Then for Brownian motion W_t :*

$$f(W_t) = f(0) + \frac{1}{2} \int_0^t f''(W_s) ds + \int_0^t f'(W_s) dW_s$$

Proof. Partition $[0, t]$ with $0 = t_0 < \dots < t_n = t$:

$$f(W_t) = f(0) + \sum_{i=0}^{n-1} (f(W_{t_{i+1}}) - f(W_{t_i}))$$

Using Taylor's Theorem:

$$f(W_{t_{i+1}}) - f(W_{t_i}) = f'(W_{t_i})(W_{t_{i+1}} - W_{t_i}) + \frac{1}{2} f''(\theta_i)(W_{t_{i+1}} - W_{t_i})^2$$

with θ_i between W_{t_i} and $W_{t_{i+1}}$. □

Example 12.1. Problem. *Let*

$$X_t = B_t^2.$$

Find the process $a(s, \omega)$ such that

$$X_t = E[X_t] + \int_0^t a(s, \omega) dB_s.$$

Solution. By Itô's formula,

$$dX_t = d(B_t^2) = 2B_t dB_t + dt,$$

so

$$X_t = X_0 + \int_0^t (2B_s dB_s + ds) = 0 + t + \int_0^t 2B_s dB_s.$$

Hence

$$E[X_t] = t, \quad a(s, \omega) = 2B_s.$$

Example 12.2. Problem. *Let*

$$X_t = B_t^3.$$

Find the process $a(s, \omega)$ such that

$$X_t = E[X_t] + \int_0^t a(s, \omega) dB_s.$$

Hint: introduce $Y_t = t B_t$.

Solution. By Itô's formula,

$$dX_t = d(B_t^3) = 3B_t^2 dB_t + 3B_t dt.$$

Set

$$Y_t = t B_t, \quad dY_t = B_t dt + t dB_t \implies \int_0^t B_s ds = t B_t - \int_0^t s dB_s.$$

Thus

$$\int_0^t 3B_s ds = 3\left(tB_t - \int_0^t s dB_s\right),$$

and

$$X_t = \int_0^t (3B_s^2 dB_s + 3B_s ds) = \int_0^t 3B_s^2 dB_s + 3\left(tB_t - \int_0^t s dB_s\right).$$

Rearranging,

$$X_t = 3 \int_0^t B_s^2 dB_s + 3tB_t - 3 \int_0^t s dB_s = 0 + \int_0^t (3B_s^2 + 3(t-s)) dB_s.$$

Therefore

$$E[X_t] = 0, \quad a(s, \omega) = 3B_s^2 + 3(t-s).$$

Example 12.3. Problem. Let

$$X_t = e^{B_t}.$$

Find the process $a(s, \omega)$ such that

$$X_t = E[X_t] + \int_0^t a(s, \omega) dB_s.$$

Hint: consider $Y_t = e^{B_t - \frac{1}{2}t}$.

Solution. By Itô's formula,

$$d(e^{B_t}) = e^{B_t} dB_t + \frac{1}{2}e^{B_t} dt.$$

Let

$$Y_t = e^{B_t - \frac{1}{2}t},$$

then

$$dY_t = e^{B_t - \frac{1}{2}t} dB_t,$$

so

$$Y_t = 1 + \int_0^t e^{B_s - \frac{1}{2}s} dB_s.$$

Hence

$$e^{B_t} = e^{\frac{1}{2}t} Y_t = E[e^{B_t}] + \int_0^t e^{\frac{1}{2}t} e^{B_s - \frac{1}{2}s} dB_s.$$

Therefore

$$E[X_t] = e^{\frac{1}{2}t}, \quad a(s, \omega) = e^{\frac{1}{2}t} e^{B_s - \frac{1}{2}s} = e^{B_s + \frac{1}{2}(t-s)}.$$

Example 12.4. Problem. Let

$$X_t = \sin(B_t).$$

Find the process $a(s, \omega)$ such that

$$X_t = E[X_t] + \int_0^t a(s, \omega) dB_s.$$

Hint: consider $Y_t = e^{\frac{1}{2}t} \sin(B_t)$.

Solution. By Itô's formula,

$$d \sin(B_t) = \cos(B_t) dB_t - \frac{1}{2} \sin(B_t) dt.$$

Set

$$Y_t = e^{\frac{1}{2}t} \sin(B_t), \quad dY_t = e^{\frac{1}{2}t} \cos(B_t) dB_t.$$

Thus

$$Y_t = \int_0^t e^{\frac{1}{2}s} \cos(B_s) dB_s,$$

and

$$\sin(B_t) = e^{-\frac{1}{2}t} Y_t = \int_0^t e^{-\frac{1}{2}(t-s)} \cos(B_s) dB_s.$$

Hence

$$E[X_t] = 0, \quad a(s, \omega) = e^{-\frac{1}{2}(t-s)} \cos(B_s).$$

13 Itô Process

Definition 13.1. A process satisfying

$$dX_t = \mu_t dt + \sigma_t dW_t$$

is called an Itô process.

Condition:

$$\int_0^t (\sigma_s^2 + |\mu_s|) ds < \infty$$

Chain rule:

$$d(f(t, X_t)) = f_t dt + f_X dX_t + \frac{1}{2} f_{XX} (dX_t)^2$$

Multivariate:

$$d(f(X_{1,t}, \dots, X_{d,t})) = \sum_i f_{X_i} dX_{i,t} + \frac{1}{2} \sum_{i,j} f_{X_i X_j} dX_{i,t} dX_{j,t}$$

14 Quadratic Variation

$$\langle X \rangle_t = \lim_{n \rightarrow \infty} \sum_{j=1}^n [X_{j/n} - X_{(j-1)/n}]^2$$

$$\langle X, Y \rangle_t = \lim_{n \rightarrow \infty} \sum_{j=1}^n [X_{j/n} - X_{(j-1)/n}] [Y_{j/n} - Y_{(j-1)/n}]$$

$$(dW_t)^2 = dt,$$

$$[dW_t, dW_t] = dt,$$

$$[W_t, W_t] = t,$$

$$[t, t] = 0, \quad [t, W_t] = 0$$

$$dX_t = \mu dt + \sigma_t dW_t \Rightarrow d\langle X_t \rangle = \sigma_t^2 dt$$

15 Itô's Isometry

Let $X_t \in L^2[0, T]$. Then:

$$E \left[\left(\int_0^T X_t dW_t \right)^2 \right] = E \left[\int_0^T X_t^2 dt \right]$$

Proof sketch.

$$E \left[\left(\int_0^T X_t dW_t \right)^2 \right] = E \left[\left(\sum_{i=0}^{n-1} e_i (W_{t_{i+1}} - W_{t_i}) \right)^2 \right]$$

Expanding the square:

$$= \sum_{i=0}^{n-1} E [e_i^2 (W_{t_{i+1}} - W_{t_i})^2] + 2 \sum_{0 \leq i < j \leq n-1} E [e_i e_j (W_{t_{i+1}} - W_{t_i})(W_{t_{j+1}} - W_{t_j})]$$

Because Brownian increments are independent and have mean zero, the cross terms vanish:

$$\mathbb{E}[(W_{t_{i+1}} - W_{t_i})(W_{t_{j+1}} - W_{t_j})] = 0 \quad \text{for } i \neq j$$

Therefore:

$$E \left[\left(\int_0^T X_t dW_t \right)^2 \right] = \sum_{i=0}^{n-1} E [e_i^2] (t_{i+1} - t_i) = E \left[\int_0^T X_t^2 dt \right]$$

For general $X_t \in L^2([0, T])$, we approximate using a sequence of such simple processes $X_t^{(n)} \rightarrow X_t$ in L^2 , and apply the isometry to the limit by dominated convergence.

16 Integral Martingale

$$Y_t := \int_0^t X_u dW_u$$

is a martingale if $X_t \in L^2[0, T]$.

Proof:

$$\begin{aligned} E[Y_t | \mathcal{F}_s] &= E \left[\int_0^s X_u dW_u + \int_s^t X_u dW_u \mid \mathcal{F}_s \right] \\ &= \int_0^s X_u dW_u = Y_s \end{aligned}$$

17 Geometric Brownian Motion

$$dX_t = \mu X_t dt + \sigma X_t dW_t \Rightarrow \frac{dX_t}{X_t} = \mu dt + \sigma dW_t$$

Apply Itô's Lemma to $\log(X_t)$, then integrate:

$$X_T = X_0 \exp \left(\left(\mu - \frac{\sigma^2}{2} \right) T + \sigma W_T \right)$$

If $\mu = 0$, then:

$$X_T = X_0 \exp\left(\sigma W_T - \frac{\sigma^2}{2}T\right), \quad E[X_T] = X_0$$

Example 17.1. Problem. Let $X \sim N(\mu, \sigma^2)$. Using the fact that if

$$Y_t = \exp\left(-\frac{1}{2}\sigma^2 t + \sigma B_t\right)$$

is a martingale, compute

$$E[e^X].$$

Solution. Write $X = \mu + \sigma B_1$, so

$$e^X = \exp(\mu + \sigma B_1) = \exp\left(\mu + \frac{1}{2}\sigma^2\right) \exp\left(-\frac{1}{2}\sigma^2 + \sigma B_1\right).$$

Since $Y_1 = \exp(-\frac{1}{2}\sigma^2 + \sigma B_1)$ is a martingale with $E[Y_1] = 1$, it follows that

$$E[e^X] = \exp\left(\mu + \frac{1}{2}\sigma^2\right) E[Y_1] = \exp\left(\mu + \frac{1}{2}\sigma^2\right).$$

18 Change of Measure (Randon-Nikodym)

$$P(A) = \int_A dP, \quad Q(A) = \int_A f dP, \quad f = \frac{dQ}{dP}$$

Suppose p, q are measures on (Ω, \mathcal{F}) . q is absolutely continuous with respect to p , written $q \ll p$, if for every $E \in \mathcal{F}$, if $p(E) = 0$, then $q(E) = 0$. p and q are mutually absolutely continuous or equivalent if $p \ll q$ and $q \ll p$.

$$p(E) = 0 \quad \Longleftrightarrow \quad q(E) = 0$$

Theorem 18.1 (Randon-Nikodym). Suppose p, q are σ -finite measures on (Ω, \mathcal{F}) with $q \ll p$. Then there exists a function f such that for every E .

$$q(E) = \int_E f dp$$

The function f is called the Randon-Nikodym derivative of q with respect to p and is denoted

$$f = \frac{dq}{dp}$$

19 Girsanov's Theorem

Theorem 19.1 (Girsanov). Let $u \in L^2([0, T])$ be deterministic. Then the process:

$$X_t = \int_0^t \underbrace{u(s)}_{\text{drift}} ds + \underbrace{W_t}_{\text{Brownian motion}}, \quad 0 \leq t \leq T$$

is a Brownian motion with respect to the probability measure Q given by

$$dQ = \exp \left(\int_0^T u(s) ds - \frac{1}{2} \int_0^T u(s)^2 ds \right) dP$$

$X_t = at + W_t$	$X_t = at + W_t$
W_t is a P -Brownian motion	W_t is not a Q -Brownian motion
X_t is not a P -Brownian motion	X_t is a Q -Brownian motion

Table 1: Girsanov's Theorem

For constant $u(s)$,

$$dQ = \exp \left(-aW_t - \frac{1}{2}a^2t \right) dP$$

Example 19.1. Problem. Compute

$$E \left[(B_t + t^2) \exp \left(- \int_0^t s dB_s - \frac{1}{2} \int_0^t s^2 ds \right) \right].$$

Solution.

$$\frac{dQ}{dP} = \exp \left(- \int_0^t s dB_s - \frac{1}{2} \int_0^t s^2 ds \right).$$

By Girsanov, under Q the process

$$X_t = B_t + \int_0^t s ds = B_t + \frac{t^2}{2}$$

is a Q -Brownian motion. Hence

$$E \left[(B_t + t^2) \exp(\dots) \right] = \int_{\Omega} (B_t + t^2) dQ = E^Q(B_t + t^2) = E^Q \left(X_t + \frac{t^2}{2} \right) = \frac{t^2}{2}.$$

Example 19.2. Problem. Compute

$$E \left[(B_t + t^2) \exp \left(-2 \int_0^t s dB_s \right) \right].$$

Solution.

$$\frac{dQ}{dP} = \exp \left(-2 \int_0^t s dB_s - \frac{1}{2} \int_0^t (2s)^2 ds \right).$$

Under Q ,

$$X_t = B_t + \int_0^t 2s ds = B_t + t^2$$

is a Q -Brownian motion, so

$$E \left[(B_t + t^2) \exp \left(-2 \int_0^t s dB_s \right) \right] = \int_{\Omega} (B_t + t^2) dQ = E^Q(X_t) = 0.$$

Example 19.3. Problem. *Compute*

$$E\left[(B_t - t)^2 \exp\left(\int_0^t e^{-s} dB_s\right)\right].$$

Solution.

$$\frac{dQ}{dP} = \exp\left(-\frac{1}{2} \int_0^t e^{-2s} ds + \int_0^t e^{-s} dB_s\right).$$

Under Q ,

$$X_t = B_t - \int_0^t e^{-s} ds = B_t - 1 + e^{-t}$$

is a Q -Brownian motion. Hence

$$E\left[(B_t - t)^2 e^{\int_0^t e^{-s} dB_s}\right] = \int_{\Omega} (B_t - t)^2 e^{\frac{1}{2} \int_0^t e^{-2s} ds} dQ = e^{\frac{1}{2} \int_0^t e^{-2s} ds} E^Q\left[(B_t - t)^2\right].$$

Since

$$B_t - t = X_t + (1 - e^{-t} - t),$$

and $E^Q[X_t^2] = t$,

$$E^Q\left[(B_t - t)^2\right] = t + (1 - e^{-t} - t)^2.$$

Finally,

$$\int_0^t e^{-2s} ds = \frac{1}{2}(1 - e^{-2t}),$$

so the result is

$$\exp\left(\frac{1}{4}(1 - e^{-2t})\right) [t + (1 - e^{-t} - t)^2].$$

20 Stopping Times

Definition 20.1. Let (Ω, \mathcal{F}, P) be a probability space with a filtration $(\mathcal{F}_t)_{t \geq 0}$. A random time

$$\tau : \Omega \rightarrow [0, \infty]$$

is called a stopping time (with respect to (\mathcal{F}_t)) if for every $t \geq 0$ the event $\{\tau \leq t\} \in \mathcal{F}_t$.

20.1 Doob's Optional Stopping Theorem

Theorem 20.1 (Discrete-time OST). Let $(X_n)_{n \geq 0}$ be a martingale with respect to a filtration (\mathcal{F}_n) and let τ be a stopping time. If one of the following holds:

1. τ is bounded, i.e. there exists $N < \infty$ such that $\tau(\omega) \leq N$ for all $\omega \in \Omega$;
2. $\sup_n |X_n(\omega)| < K < \infty$ for all n, ω (i.e. the martingale is uniformly bounded) and $\tau < \infty$ a.s.;
3. $\tau < \infty$ a.s. and there is $K < \infty$ such that $|X_n - X_{n-1}| < K$ for all n, ω ,

then X_τ is integrable and

$$E[X_\tau] = E[X_0].$$

Theorem 20.2 (Continuous-time OST). *Let $(M_t)_{t \geq 0}$ be a right-continuous \mathcal{F}_t -martingale and τ a stopping time. If either*

- *τ is bounded, i.e. $\exists N < \infty$ such that $\tau \leq N$,*
- *or $\exists c > 0$ such that $\sup_{t \geq 0} E[|M_t|] \leq c$,*

then

$$E[M_\tau] = E[M_0].$$

Moreover, the stopped process $M_{t \wedge \tau}$ is itself a martingale.

Example 20.1 (Two-Barrier Hitting Probability for Brownian Motion). *Let $(B_t)_{t \geq 0}$ be standard Brownian motion and fix two barriers $+U$ and $-D$ (with $U, D > 0$). Define the stopping time*

$$\tau = \inf\{t \geq 0 : B_t = +U \text{ or } B_t = -D\}.$$

Since $B_{t \wedge \tau}$ is bounded by $\max\{U, D\}$, by the optional-stopping theorem

$$E[B_{t \wedge \tau}] = E[B_0] = 0.$$

But $B_{t \wedge \tau}$ takes the value $+U$ with probability p and $-D$ with probability $1 - p$, so

$$pU - (1 - p)D = 0 \implies p = \frac{D}{U + D}.$$

Thus the probability of hitting the upper barrier first is

$$\boxed{p = \frac{D}{U + D} .}$$