JAE-EUN (ESTHER) LIM

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EDUCATION

Carnegie Mellon University
Pittsburgh, PA
GPA 3.84/4.00

Bachelor of Science in
Mechanical Engineering
Additional Major in Robotics
Spring 2018

Master of Science in Robotics
Fall 2019

SKILLS

Programming & Software
Java
C/C++
Python
MATLAB/Simulink
HTML/CSS/Django
SolidWorks
Weka

Languages
Fluent in Korean & English

RELEVANT COURSES

Computer Vision
Machine Learning
Feedback Controls System
Robotics Systems Engineering
Robot Kinematics and Dynamics
Fundamentals of Programming and Computer Science
Principles of Imperative Programming
Soft Robotics

RELEVANT EXPERIENCES

Research Assistant – Computer Vision Group, Robomechanics Lab, *Fall 2017-Spring 2018*
- Conducted research in visual odometry for bounding legged robots to explore the effect of pitch motion in visual odometry estimation.
- Created MATLAB simulation of the camera view of a bounding robot.

Software Engineer Intern – **Verify Apply**, *Summer 2017*
- Designed and implemented frontend and backend of website from scratch.
- Used Django framework.

Robotics Engineer Intern – **Perception Robotics**, *Summer 2016 (Los Angeles, CA)*
- Designed test rig for gecko gripper to test scaling effect on adhesion pressure.
- Manufactured molds for touch sensors using 3D printer.
- Conducted risk assessment for touch sensors on FANUC robotic arm.
- Operated Kawasaki RS06L using AS Language.

PROJECTS

Computer Vision, *Spring 2018*
- Implemented in MATLAB: Hough transform, bag of visual words, OCR using neural networks, image matching, stitching and homographies, 3D reconstruction, image alignment and tracking.

Machine Learning, *Spring 2018*
- Implemented in C++ and Java: decision tree, logistic regression, neural network, Hidden Markov Model, reinforcement learning.

Smart Dog Toy – Capstone (Most Innovative Award), *Spring 2018*
- Designed and built a treat-dispensing dog toy with a live stream camera that is remote-controlled via web app.

Physical Pac-Man Game – Capstone, *Fall 2017-Spring 2018*
- Designed and built autonomous Pac-Man and tele-operated Ghost robots.
- Designed and built portable and easy to assemble game board.

Feeding Robot, *Fall 2017*
- Programmed in MATLAB a 5 degree-of-freedom robotic arm to scoop up beads and drop them into a hole to simulate feeding a person.

Robotics Projects – Introduction to Robotics, *Spring 2016*
- Designed nine robots using Lego Mindstorms and wrote code in robotc to complete projects with the following topics: computer vision, PID control, dead reckoning, motion planning, localization, urban search and rescue, and forward/inverse kinematics.

LEADERSHIP AND ACTIVITIES

Outreach Chair, WoMEn@CMU, *Fall 2016 – Spring 2018*
- Organize outreach events to expose Mechanical Engineering to local middle/high school female students through in-class sessions composed of a lecture and a hands-on experiment.

Teaching Assistant – **Introduction to Robotics**, *Spring 2017, Spring 2018*
- Organize and lead labs. Help students in office hours. Assess students for the labs.