# JAE-EUN (ESTHER) LIM

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#### **EDUCATION**

## **RELEVANT EXPERIENCE**

## Carnegie Mellon University

Pittsburgh, PA GPA 3.79/4.00

Bachelor of Science in Mechanical Engineering Additional Major in Robotics Spring 2018

## **SKILLS**

## Programming/Software

Python C/C++ Java Javascript/React.js MATLAB/Simulink SQL

#### Frameworks/Applications

OpenCV TensorFlow Scikit-Learn Django OpenGL AWS Git

## Languages

Computer Vision

Fluent in Korean & English

## **RELEVANT COURSES**

Machine Learning
Feedback Controls System
Robotics Systems Engineering
Robot Kinematics and
Dynamics
Fundamentals of Programming
and Computer Science
Principles of Imperative
Programming
Engineering Statistics and Quality
Control

Research & Development Engineer – Diamond Kinetics, Inc. September 2018-present (Pittsburgh, PA)

- Own entire physics engine for a new feature called Swing Fingerprint from start to its successful launch in November 2019.
- Develop computer vision algorithms using object detection and tracking, image processing, and machine learning to facilitate baseball/softball motion analyses and validate calculations from sensors.
- Design and implement algorithms for sensor calibration (IMU and magnetometer) and event points detection for pitch and swing using signal processing, optimization, and machine learning.
- Design and develop automated testing framework and labeling tools for physics engine.
- Diagnose causes of physics engine errors and implement fixes. Optimize physics engine algorithmically and using cProfile and Cython.

#### CAD Design Automation Intern - Kennametal, Inc. Summer 2018 (Latrobe, PA)

- Developed application in C++ to automate tray loading for milling inserts.
- Created algorithm for arranging different shapes of milling inserts and optimized peg pitch on tray for space efficiency.

## Research Assistant - Computer Vision Group, Robomechanics Lab, Fall 2017-Spring 2018

- Conducted research in visual odometry for bounding legged robots to explore the effect of pitch motion in visual odometry estimation.
- Created MATLAB simulation of the camera view of a bounding robot.

## Software Engineer Intern – Verify Apply, Summer 2017

- Designed and implemented frontend and backend of website from scratch using Python and Django framework.
- Designed and built web pages using HTML, CSS, and JavaScript.

## **PROJECTS**

## Computer Vision, Spring 2018

 Implemented in MATLAB: Hough transform, bag of visual words, OCR using neural networks, image matching, stitching and homographies, 3D reconstruction, image alignment and tracking.

## Machine Learning, Spring 2018

• Implemented in C++ and Java: decision tree, logistic regression, neural network, Hidden Markov Model, reinforcement learning.

#### Physical Pac-Man Game - Capstone, Fall 2017-Spring 2018

- Developed UI for the game using Python Kivy library.
- Designed and manufactured autonomous Pac-Man, tele-operated Ghost, and game board.

## Robotics Projects – Introduction to Robotics, Spring 2016

 Designed nine robots with Lego Mindstorms and programmed them to implement PID control, dead reckoning, motion planning, localization, and forward/inverse kinematics.

#### GeaRace, Spring 2015

 Created educational car game in Python and Tkinter that teaches students the physics of gear trains.

# **LEADERSHIP AND ACTIVITIES**

## Teaching Assistant – Introduction to Robotics, Spring 2017, Spring 2018

• Organized and led labs. Helped students in office hours. Assessed students for the labs.

## Outreach Chair, WoMEn@CMU (Senior Leadership Recognition), Fall 2016 - Spring 2018

• Organized outreach events to expose engineering to local middle/high school female students through in-class sessions composed of a lecture and a hands-on experiment.