EDUCATION

RELEVANT EXPERIENCES

Carnegie Mellon University

Pittsburgh, PA GPA 3.84/4.00

Bachelor of Science in Mechanical Engineering Additional Major in Robotics Spring 2018

Master of Science in Robotics
Fall 2019

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Software

SKILLS

SolidWorks Autodesk Inventor MS Office Arduino Weka/LightSide

Machines

CNC Lathe Drill Press Band Saw Milling Machine Laser Cutter 3D Printer

Programming

C/C++ Python MATLAB/Simulink HTML/CSS/Django (self taught)

Languages

Fluent in Korean & English

RELEVANT COURSES

Mechanical Engineering

Engineering Design I
Feedback Control Systems
Dynamic Systems and Controls
Statics, Stress Analysis, Dynamics
Mechanical Systems Experimentation
Thermal-Fluids Experimentation
Thermodynamics
Fluid Mechanics
Heat Transfer

Robotics

Soft Robotics Computer Vision Machine Learning Robotics Systems Engineering Robot Kinematics and Dynamics

Others

Eng. Stats and Quality Control Business Communications

Research Assistant - Robomechanics Lab, Fall 2017-Spring 2018

- Conducted research in visual odometry for legged robots.
- Created simulations of bounding gait vision.

Engineering Intern - Verify Apply, Summer 2017

- Designed and implemented frontend and backend of website from scratch.
- Used Django framework.

Engineering Intern – Perception Robotics, Summer 2016 (Los Angeles, CA)

- Designed test rig for gecko gripper to test scaling effect on adhesion pressure.
- Manufactured molds for touch sensors using 3D printer.
- Conducted risk assessment for touch sensors on FANUC robotic arm.
- Operated Kawasaki RS06L using AS Language.

MECHANICAL ENGINEERING PROJECTS

Heat Sink, Spring 2017

 Investigated and analyzed a commercial CPU heat sink to determine if it will meet required performance.

Atlas, Auto-Steering Buggy – Project Lead for IMU Suspension System, Spring 2017

• Designed and built suspension system for IMU mount.

Smart Ball - Build 18 Annual Engineering Festival, Spring 2017

• Designed and built a remote-controlled ball that bounces around. Won Media Magician Award.

Pokeball Gripper - Second Lightest Gripper, Fall 2016

• Designed the second lightest gripper to hold and swing 3-lb Pokeball.

Motor & Gearbox, Wheel Design – Engineering Design I, Fall 2016

- Designed and selected the most efficient manufacturing process for mass production of a wheel that would roll in a barrel to climb up a ramp.
- Selected motor and gearbox combination for the wheel that would optimize a cost function of roll time, energy, and price.

ROBOTICS PROJECTS

Smart Dog Toy - Capstone, Spring 2018

Designed and built semi-autonomous dog toy that interacts with the dog and feeds the dog.

Physical Pac-Man Game - Capstone, Fall 2017-Spring 2018

- Designed and built autonomous Pac-Man and tele-operated Ghost robots.
- Designed and built portable and easy to assemble game board.

Feeding Robot, Fall 2017

 Programmed a 5 degree-of-freedom robotic arm to scoop up beads and drop them into a hole to simulate feeding a person.

Motion Sensing Glove, Spring 2017

• Modeled bending of finger and error in mapping of resistance and bend angle.

Machine Learning-Sentiment Analysis, Spring 2017

• Optimized machine learning algorithm via error analysis and parameter tuning.

Robotics Projects - Weekly Labs for Introduction to Robotics, Spring 2016

 Designed nine robots using Lego Mindstorms and wrote code in robotc to complete projects with the following topics: Computer vision, PID control, dead reckoning, motion planning, localization, urban search and rescue, and forward/inverse kinematics.

LEADERSHIP AND ACTIVITIES

Co-VP of Outreach Committee, WoMEn@CMU, Fall 2016 - present

• Organize outreach events to expose Mechanical Engineering to local middle/high school female students through in-class sessions composed of a lecture and a hands-on experiment.

Teaching Assistant – Introduction to Robotics, Spring 2017 – present

• Organize and lead labs. Help students in office hours. Assess students for the labs.

Sunday School Leader, Los Angeles Hope Church, Fall 2013-Summer 2015

- Coordinated and led Bible guizzes and activities (incorporated science and technology).
- Designed and decorated new Sunday school building.