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Part1

```
dp=0.01;ds=0.01;
```

```
Rp=-20*log(1-dp);
```

```
Rp = 0.2010;
```

```
Rs=-20*log10(ds);
```

```
Rs = 40;
```

```
wp=0.4;
```

```
N=3; % 3th order
```

```
figure (1)
```

```
[b,a]=ellip(N,Rp,Rs,wp);
```

```
w=linspace(-pi,pi,1000);
```

```
H=freqz(b,a,w);
```

```
%Magnitude response in linear scale
```

```
subplot(221)
```

```
plot(w/pi,abs(H),'m');grid;
```

```
xlabel('w X pi');ylabel('|H|')
```

```
title('Magnitude response in linear scale')
```

```
%Magnitude response in db
```

```
subplot(222)
```

```
plot(w/pi,20*log10(abs(H)));grid;
```

```
xlabel('w X pi');ylabel('|H|')
```

```
ylim([-100,5])
```

```
title('Magnitude response in db')
```

```
%Impulse response
```

```
h=impz(b,a,50);
```

```
subplot(223)
```

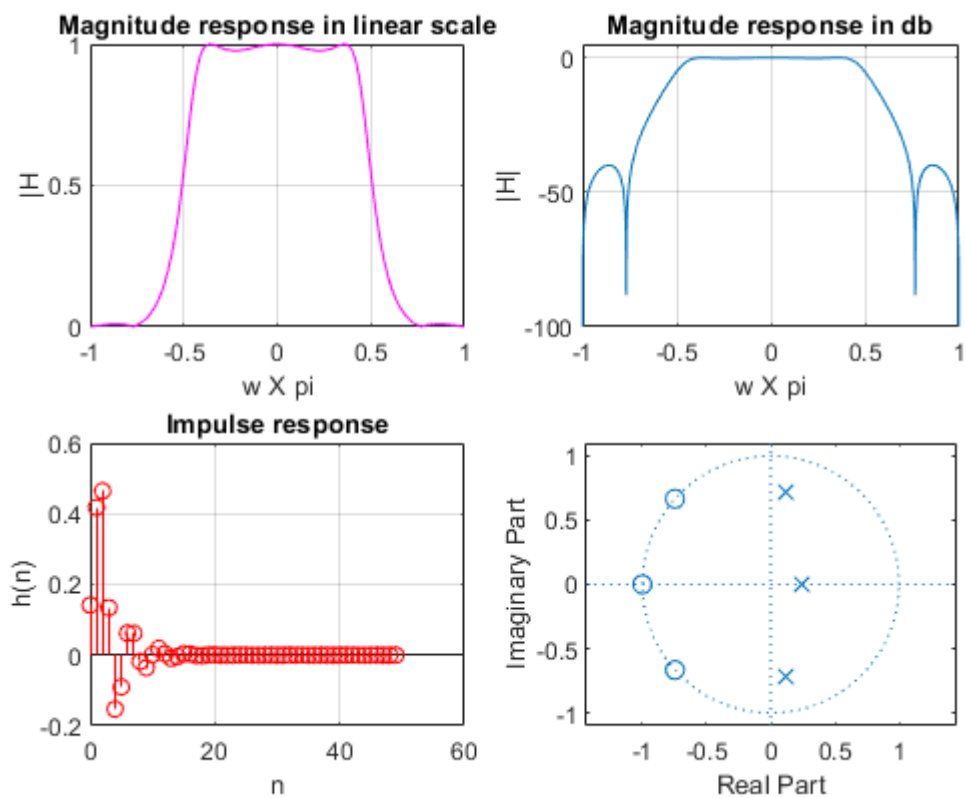
```
stem([0:49],h,'r');grid;xlabel('n');ylabel('h(n)')
```

```
title('Impulse response')
```

```
%pole zero plot
```

```
subplot(224)
```

```
zplane(b,a)
```



part 2

```
dp=0.01;ds=0.01;
```

```
Rp=-20*log(1-dp);
```

```
Rp = 0.2010;
```

```
Rs=-20*log10(ds);
```

```
Rs = 40;
```

```
wp=0.4;
```

```
N=4;% 4th order
```

```
figure (2)
```

```
[b,a]=ellip(N,Rp,Rs,wp);
```

```
w=linspace(-pi,pi,1000);
```

```
H=freqz(b,a,w);
```

```
%Magnitude response in linear scale
```

```
subplot(221)
```

```
plot(w/pi,abs(H),'m');grid;
```

```
xlabel('w X pi');ylabel('|H|')
```

```
title('Magnitude response in linear scale')
```

```
%Magnitude response in db
```

```
subplot(222)
```

```
plot(w/pi,20*log10(abs(H)));grid;
```

```
xlabel('w X pi');ylabel('|H|')
```

```
ylim([-100,5])
```

```
title('Magnitude response in db')
```

```
%impulse response
```

```
h=impz(b,a,50);
```

```
subplot(223)
```

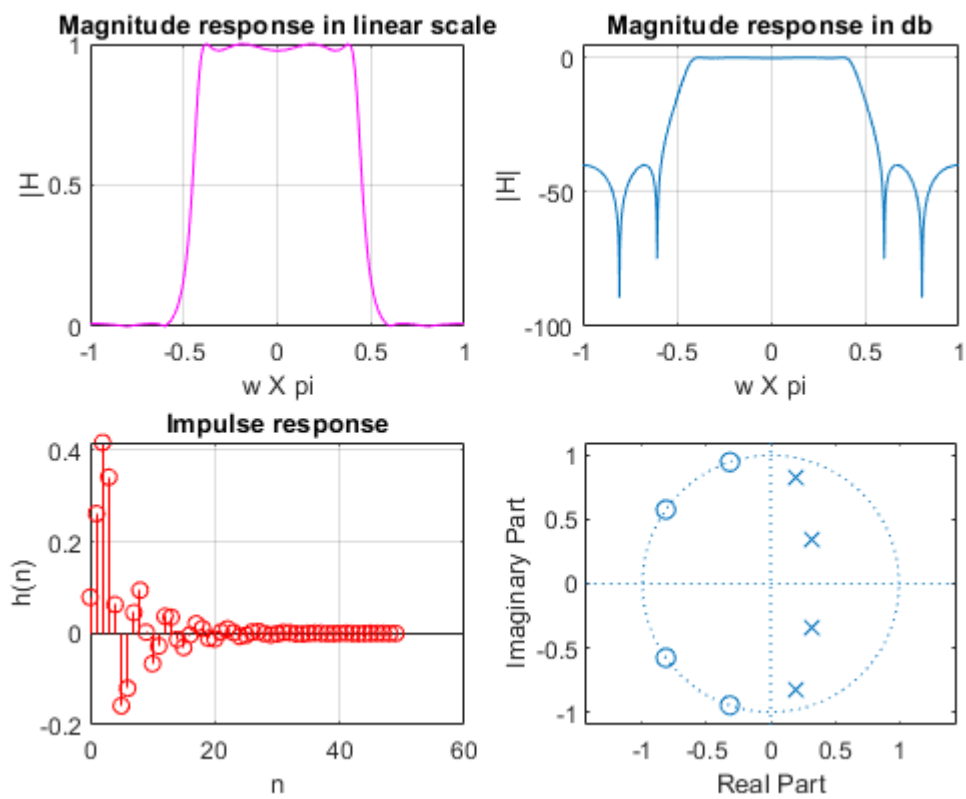
```
stem([0:49],h,'r');grid;xlabel('n');ylabel('h(n)')
```

```
title('Impulse response')
```

```
%pole zero plot
```

```
subplot(2,2,4)
```

```
zplane(b,a)
```



part 3

```
dp=0.01; ds=0.01;
```

```
Rp=-20*log(1-dp);
```

```
Rp = 0.2010;
```

```
Rs=-20*log10(ds);
```

```
Rs = 40;
```

```
wp=0.4;
```

```
% 6th order
```

```
N=6;
```

```
figure (3)
```

```
[b,a]=ellip(N,Rp,Rs,wp);
```

```
w=linspace(-pi,pi,1000);
```

```
H=freqz(b,a,w);
```

```
%Magnitude response in linear scale
```

```
subplot(221)
```

```
plot(w/pi,abs(H),'m');grid;
```



```
xlabel('w X pi');ylabel('|H|')
```

```
title('Magnitude response in linear scale')
```

```
%Magnitude response in db
```

```
subplot(222)
```

```
plot(w/pi,20*log10(abs(H)));grid;
```

```
xlabel('w X pi');ylabel('|H|')
```

```
ylim([-100,5])
```

```
title('Magnitude response in db')
```

```
%Impulse response
```

```
h=impz(b,a,50);
```

```
subplot(223)
```

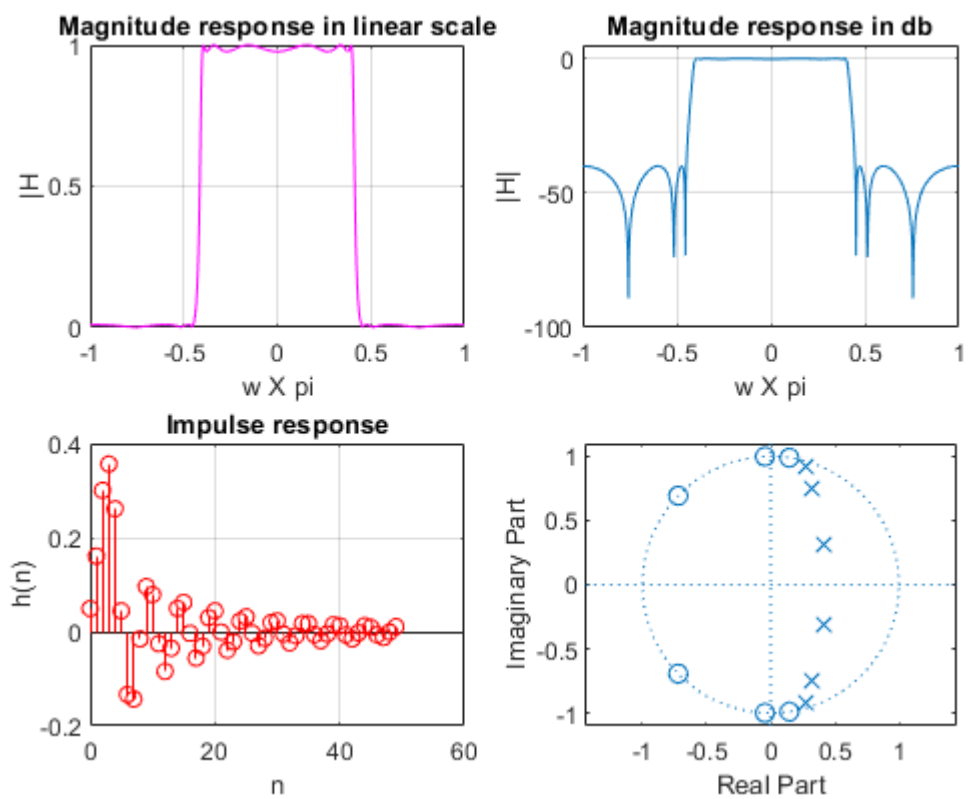
```
stem([0:49],h,'r');grid;xlabel('n');ylabel('h(n)')
```

```
title('Impulse response')
```

```
%pole zero plot
```

```
subplot(224)
```

```
zplane(b,a)
```



part 4

```
% define sampling frequency

fs = 400; % 400 Hz


% define fc, cutoff frequency

fc = 100; % 100 Hz


% define the filter characteristics

Wp = fc/(fs/2);

Rp = 1;% passband ripple

Rs = 40;% stopband attenuation

N = 5;

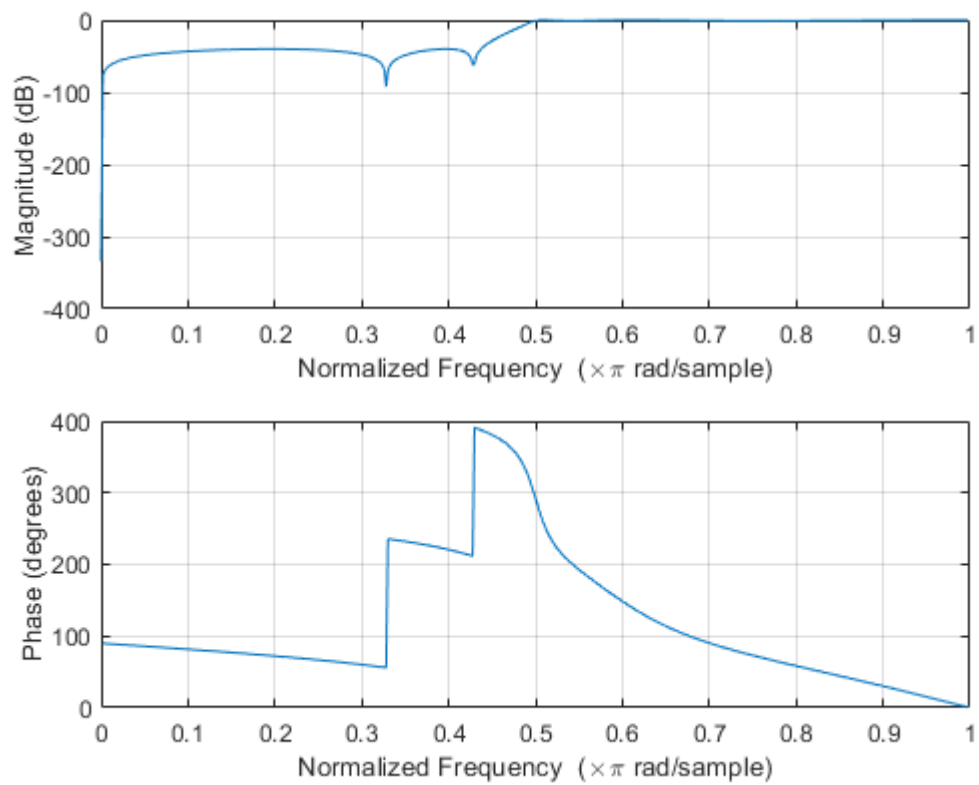

% obtain the filter coefficients

[B,A] = ellip(N,Rp,Rs,Wp,'high');


% plot the frequency response

figure;

freqz(B,A);grid on;
```



part 7

N=20;

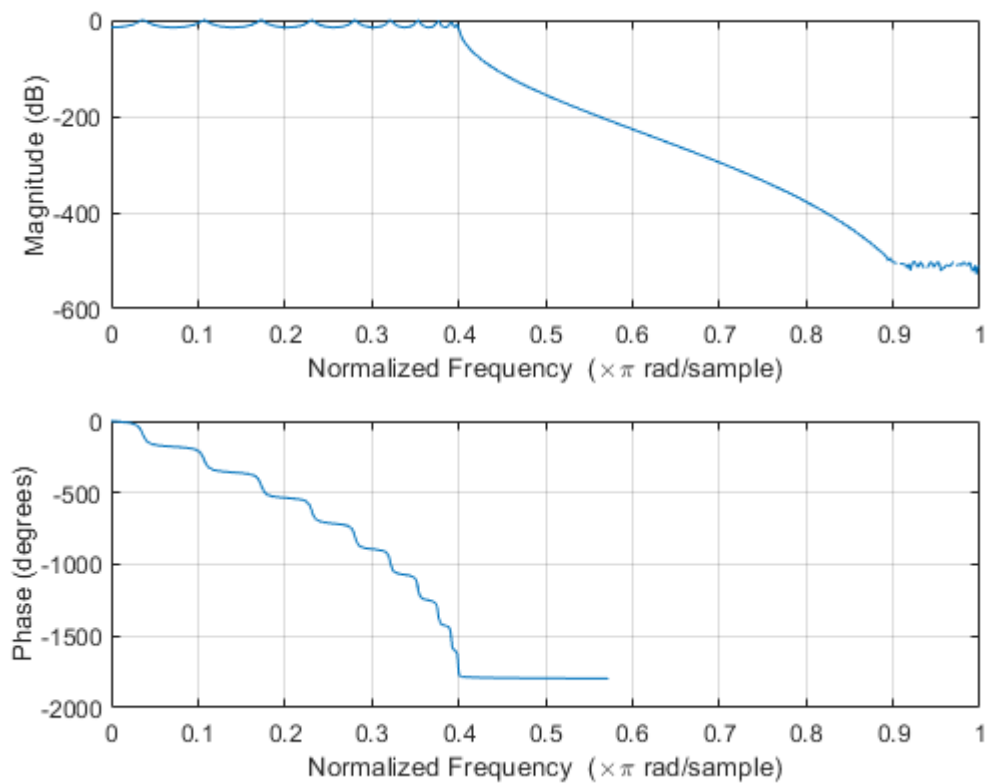
Rp=15;

Wp=0.4;

```
[b,a] = cheby1(N,Rp,Wp,'low');
```

```
freqz(b,a); % Frequency Response
```

```
[z,p,k] =cheby1(N,Rp,Wp,'low'); % To know zeros (z) position ,poles position (p) and gain k
```



part 8

```
Order = 4;

SB_ate = 30; % in dB (stopband attenuation)

SB_fre = 200; % Hz (Stop-band edge frequency)

SamFre = 1000; % in Hz (sampling rate)

PB_val = (SB_fre/SamFre)*2; % rad/sec (peak pass-band value)

[n,d] = cheby2(Order,SB_ate,PB_val);

freqz(n,d)

dt = 1/SamFre; % seconds per sample

StopTime = 0.2; % seconds

time = (0:dt:StopTime-dt)'; % Time step (seconds)
```

```

% Sine wave generation

Fre = 100;      % Hz Frequency of the signal

% generate the signal

Sig = sin(2*pi*Fre*time);

% adding noise

noi = 0.5*randn(size(time));

RS = Sig + noi;

figure

plot(time,RS)

grid on

xlabel('Time (sec)')

ylabel('Amplitude')

title('input signal')

ResOut = filter(n,d,RS);

%plot the signal

figure

plot(time,ResOut)

grid on

xlabel('Time (sec)')

```

```
ylabel('Amplitude')
```

```
title('Filtered signal')
```

