Contents

- Part 1
- Part 2
- Part 3
- Part 4
- Part 5

Part 1

```
b=[1 -2.5]:%coefficients of numerator of H(z)

a=[1 -1 0.7]:%coefficients of denominator of H(z)

x=(n==0):%Impulse function

y = filter(b,a,x); % Impulse response

% It is same answer as my hand calculation.
```

Part 2

```
b=[1 =2.5];%coefficients of numerator of H(z)

a=[1 -1 0.7];%coefficients of denominator of H(z)

n=-5:30;

x=(n==0);%Impulse function
```

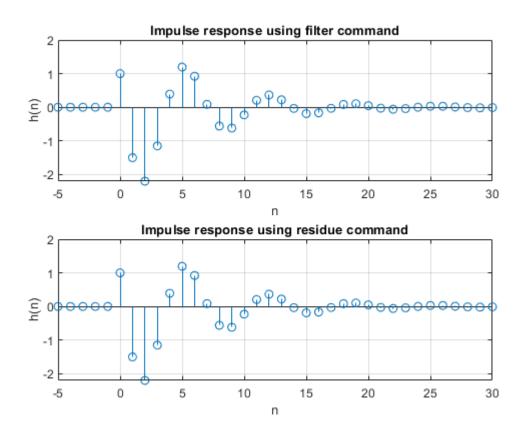
```
%using filter function
y=filter(b,a,x);%|mpulse response
figure(1);
subplot(2,1,1)
stem(n,y);grid;
title('Impulse response using filter command');
xlabel('n');ylabel('h(n)');
%using partial fraction method
[r p k]=residue(b,a); %residue function
h=((r(1)*(p(1).^n))+(r(2)*(p(2).^n))).*(n>=0);
subplot(2,1,2)
```

```
stem(n,h);grid;

title('Impulse response using residue command');

xlabel('n');

ylabel('h(n)');
```



Part 3

b=[1 -2.5];%coefficients of numerator of H(z)

```
a=[1 -1 0.7];%coefficients of denominator of H(z)
n=-5:30;
x=(n==0);%Impulse function
%using filter function
y=filter(b,a,x);%|mpulse response
figure(2);
subplot(3,1,1)
stem(n,y,'r');grid;
title('Impulse response using filter command');
xlabel('n');
ylabel('h(n)');
```

```
%using partial fraction method
[r p k]=residue(b,a); %residue function
h=((r(1)*(p(1).^n))+(r(2)*(p(2).^n))).*(n>=0);
subplot(3,1,2)
stem(n,h,'b');grid;
title('Impulse response using residue command');
xlabel('n');ylabel('h(n)');
%using equation(2)
[r p k]=residue(b,a); %residue function
R1=abs(r(1));
w0=angle(p(1));r=abs(p(1));alpha=angle(r(1));
```

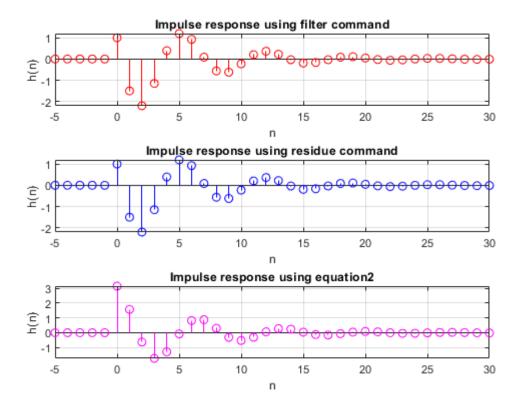
```
h=2*R1*(r.^n).*(cos((w0*n)+alpha)).*(n>=0);

subplot(3,1,3)

stem(n,h,'m'):grid;

title('Impulse response using equation2');

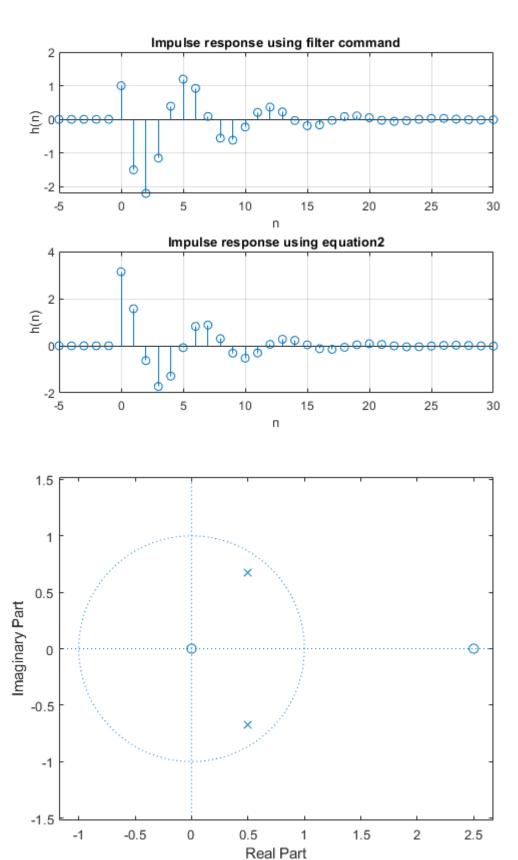
xlabel('n'):ylabel('h(n)');
```



Part 4

```
a=[1 -1 0.7];%coefficients of denominator of H(z)
n=-5:30;
x=(n==0);%Impulse function
y=filter(b,a,x);%|mpulse response
figure(3);
subplot(2,1,1)
stem(n,y);grid;
title('Impulse response using filter command');
xlabel('n');
ylabel('h(n)');
%using equation(2)
```

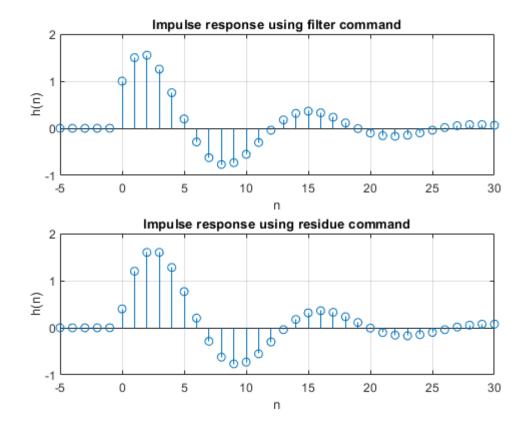
```
[r p k]=residue(b,a); %residue function
R1=abs(r(1));
w0=angle(p(1));r=abs(p(1));alpha=angle(r(1));
h=2*R1*(r.^n).*(cos((w0*n)+alpha)).*(n>=0);
subplot(2,1,2)
stem(n,h);grid;
title('Impulse response using equation2');
xlabel('n');
ylabel('h(n)');
figure(4);
zplane(b,a)
```



Part 5

```
a=[1 -2.1 1.6 -0.4];%coefficients of denominator of H(z)
n=-5:30;
x=(n==0);%Impulse function
y=filter(b,a,x);%|mpulse response
figure(5);
subplot(2,1,1)
stem(n,y);grid;
title('Impulse response using filter command');
xlabel('n');
ylabel('h(n)');
%using partial fraction method
```





Published with MATLAB® R2019b