

Model Merging & Editing

EECE695D: Efficient ML Systems

Spring 2025

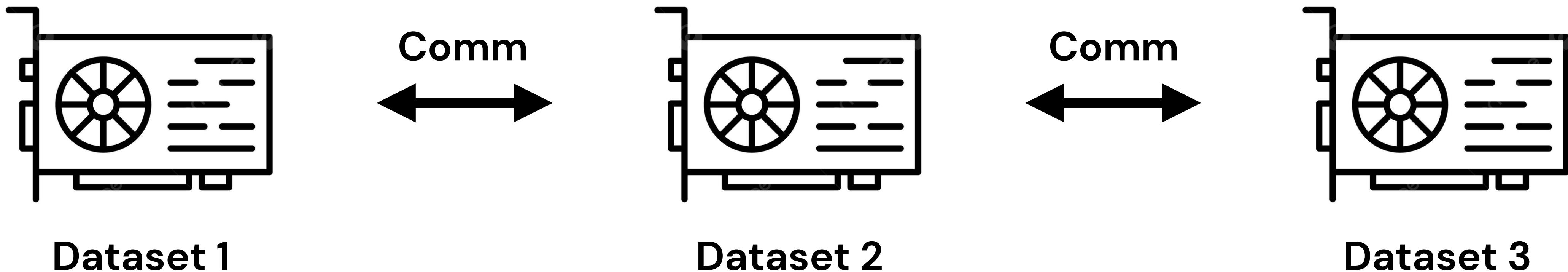
Recap

- **Last week.** Train a model, using knowledge transferred from other training runs
 - Continual Learning
 - Meta-Learning
- **Today.** Post-training methods
 - Merging. Transfer experience
 - Editing. Pinpoint fixes

Merging

Model Merging

- Goal. Want to **aggregate** the knowledge of concurrent training runs
 - Decentralize, due to privacy or computational cost
 - Depends critically on how often we can **communicate**
 - High. SGD (w/ parallelism)
 - Medium. Federated Learning
 - Low. Merging



High Comm.: SGD

- Every step, aggregating experiences of B clients (B: batch size)

- Initialize the parameter θ_0
- In each step $t = 0, 1, \dots$

- For each client $i \in \{1, \dots, B\}$

Local Training

- Draw a single sample (x_i, y_i)

- Generate a local update $\theta_t^{(i)} = \theta_t - \eta \cdot \nabla_{\theta} \ell(y_i, f_{\theta_t}(x_i))$

- Aggregate the experiences:

Aggregate

$$\theta_{t+1} = \frac{1}{B} \sum_{i=1}^B \theta_t^{(i)}$$

Medium Comm.: Federated Learning

- FedAvg (2017). Aggregate every **E steps**

- Initialize the parameter θ_0
- In each round $t = 0, 1, \dots$
- For each client $i \in \{1, \dots, B\}$

- Initialize the local checkpoint $\theta_{t,0}^{(i)} = \theta_t$

- For each **local step** $j = 1, \dots, E$

- Draw a batch of samples

- Update the local checkpoint

$$\theta_{t,j}^{(i)} = \theta_{t,j-1}^{(i)} - \eta \sum_k \nabla_{\theta} \ell(y_k, f_{\theta_{t,j-1}^{(i)}}(x_k))$$

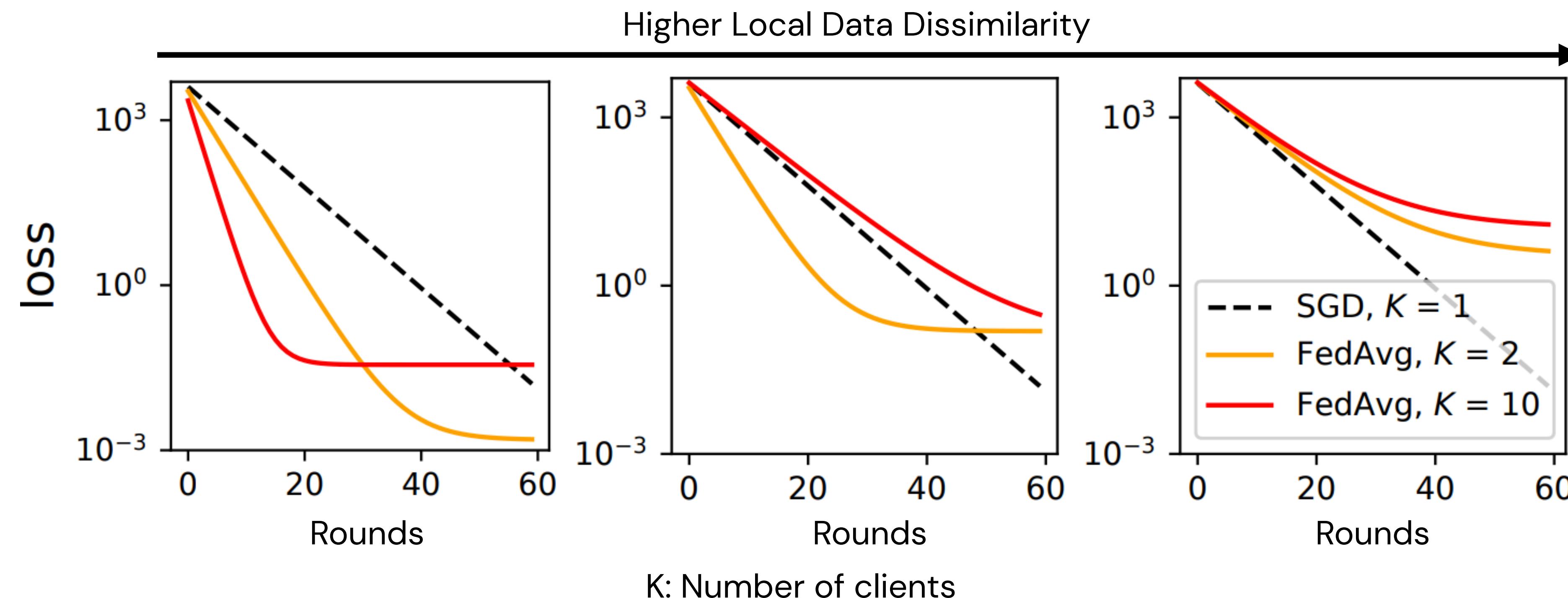
**Local Training
with E steps**

- Aggregate the experiences:

$$\theta_{t+1} = \frac{1}{B} \sum_{i=1}^B \theta_{t,E}^{(i)}$$

Medium Comm.: Federated Learning

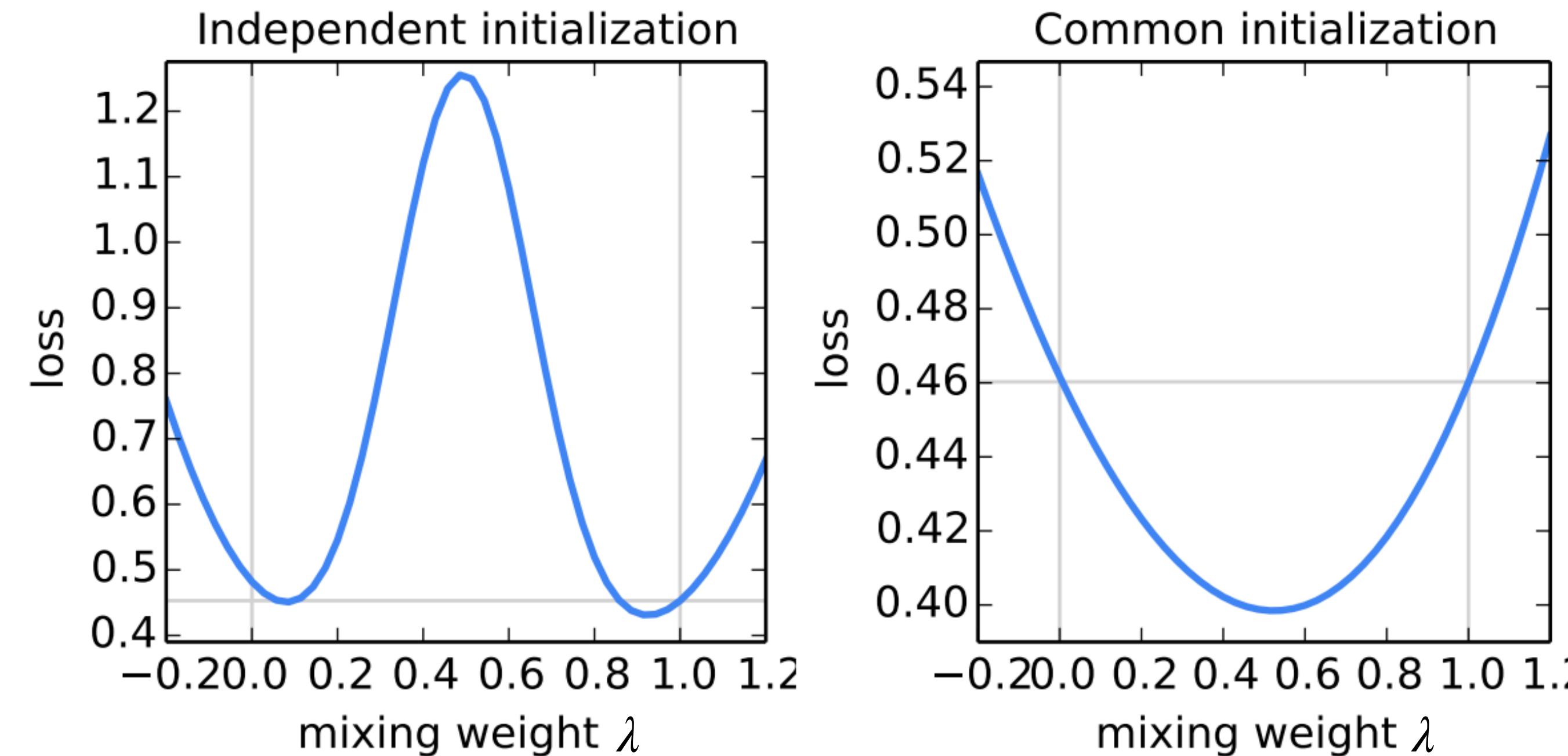
- Two factors critically affect the performance:
- **(1) Frequency.** The number of local steps should be small
 - Especially when local data are dissimilar



Medium Comm.: Federated Learning

- (2) Shared init. The initial parameter θ_0 should be identical
 - Otherwise, high **loss barrier** between weights

$$\lambda \cdot \theta_1 + (1 - \lambda) \cdot \theta_2$$



Low Comm.: Merging

- **Challenge.** Can we merge two independently trained models, with a **single aggregation after training?**
 - Ideally, we would want:
 - If trained on a same dataset, achieve the accuracy of model ensemble (with cheaper inference)
 - If trained on different datasets, achieve good accuracy in both domains

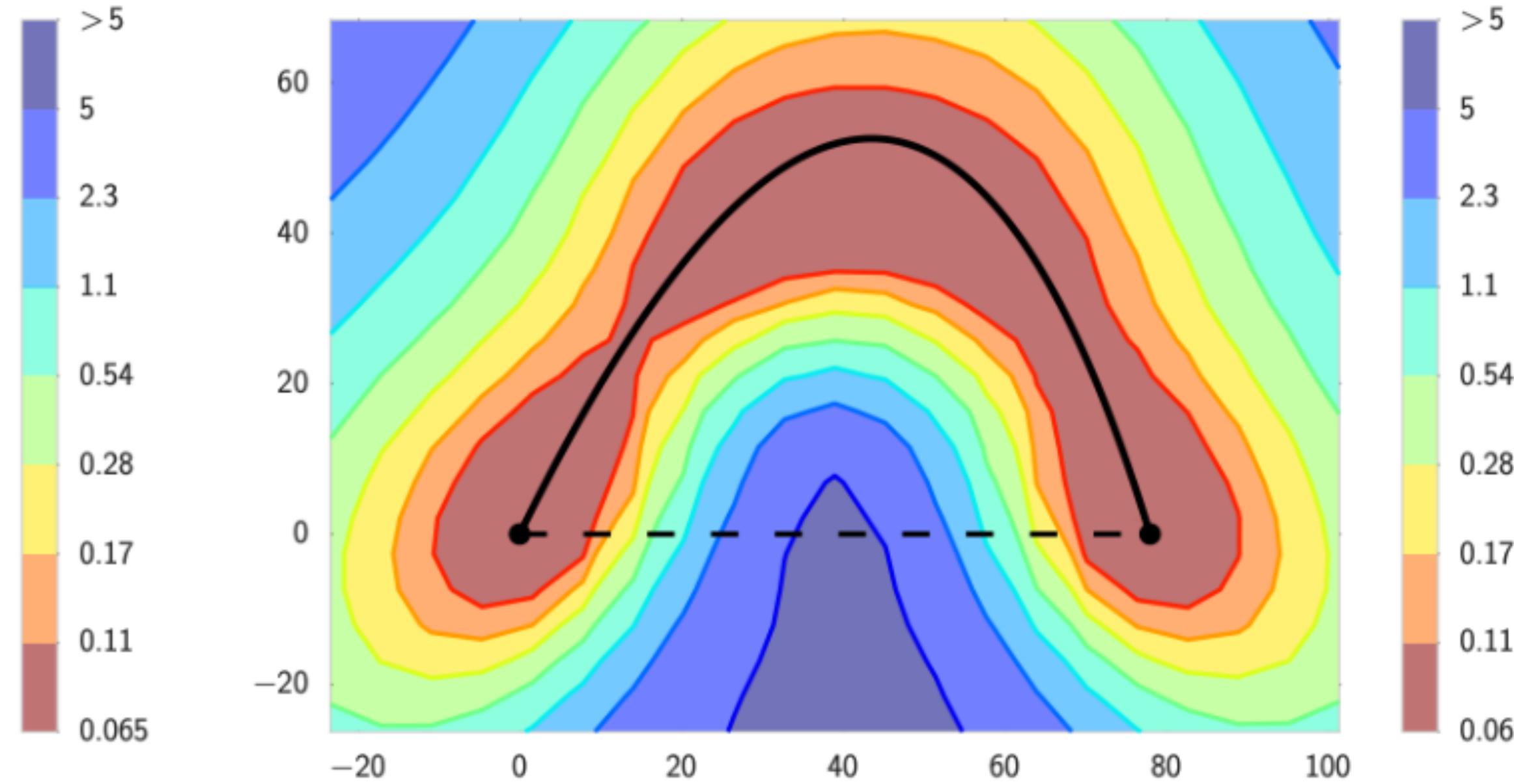
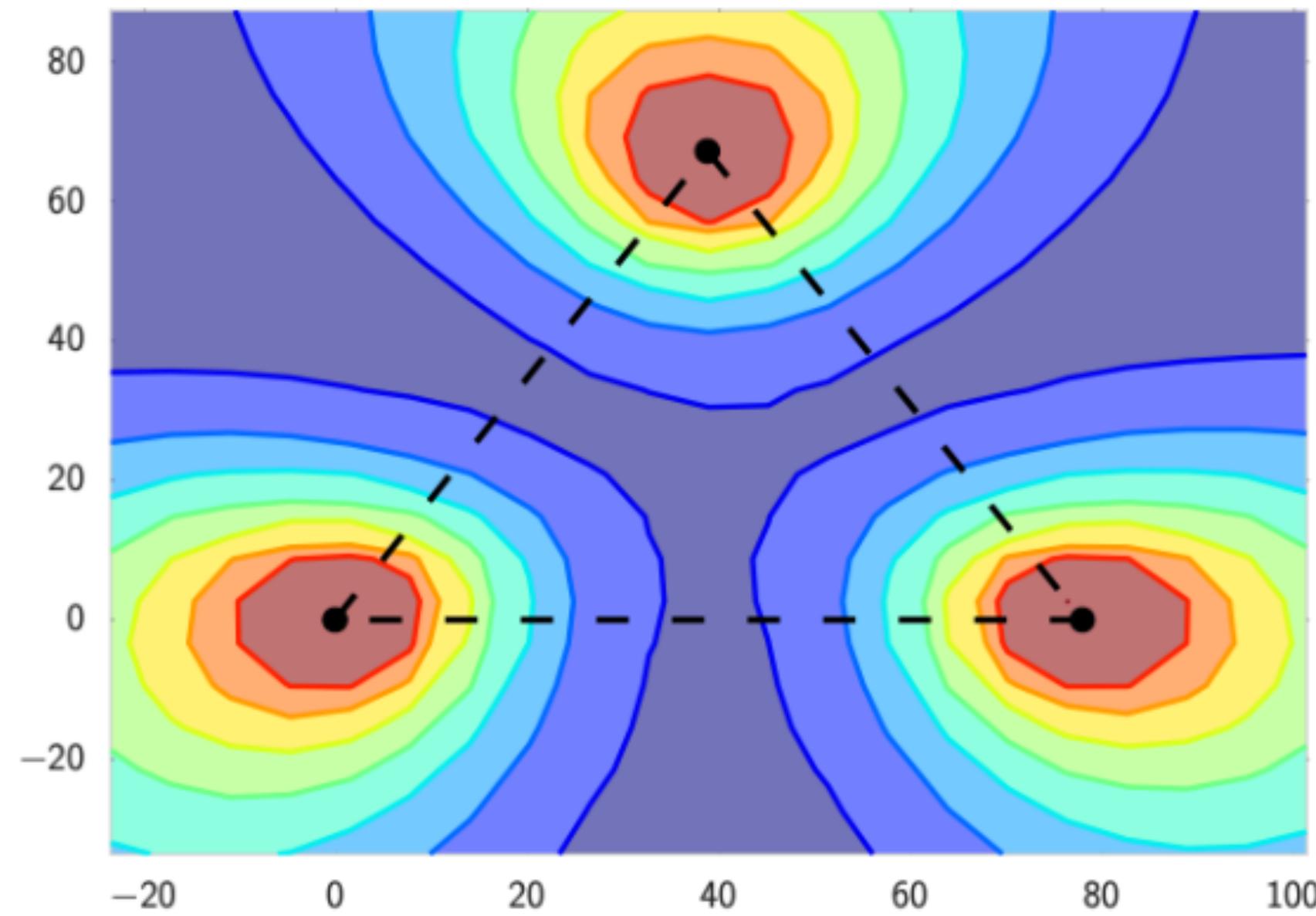
Low Comm.: Merging

- **Scenarios.** Roughly two categories:
 - Independent initialization:
 - Git Re-Basin, REPAIR, Ziplt!
 - Pre-trained model as initialization:
 - Model Soup

Merging: Independent init.

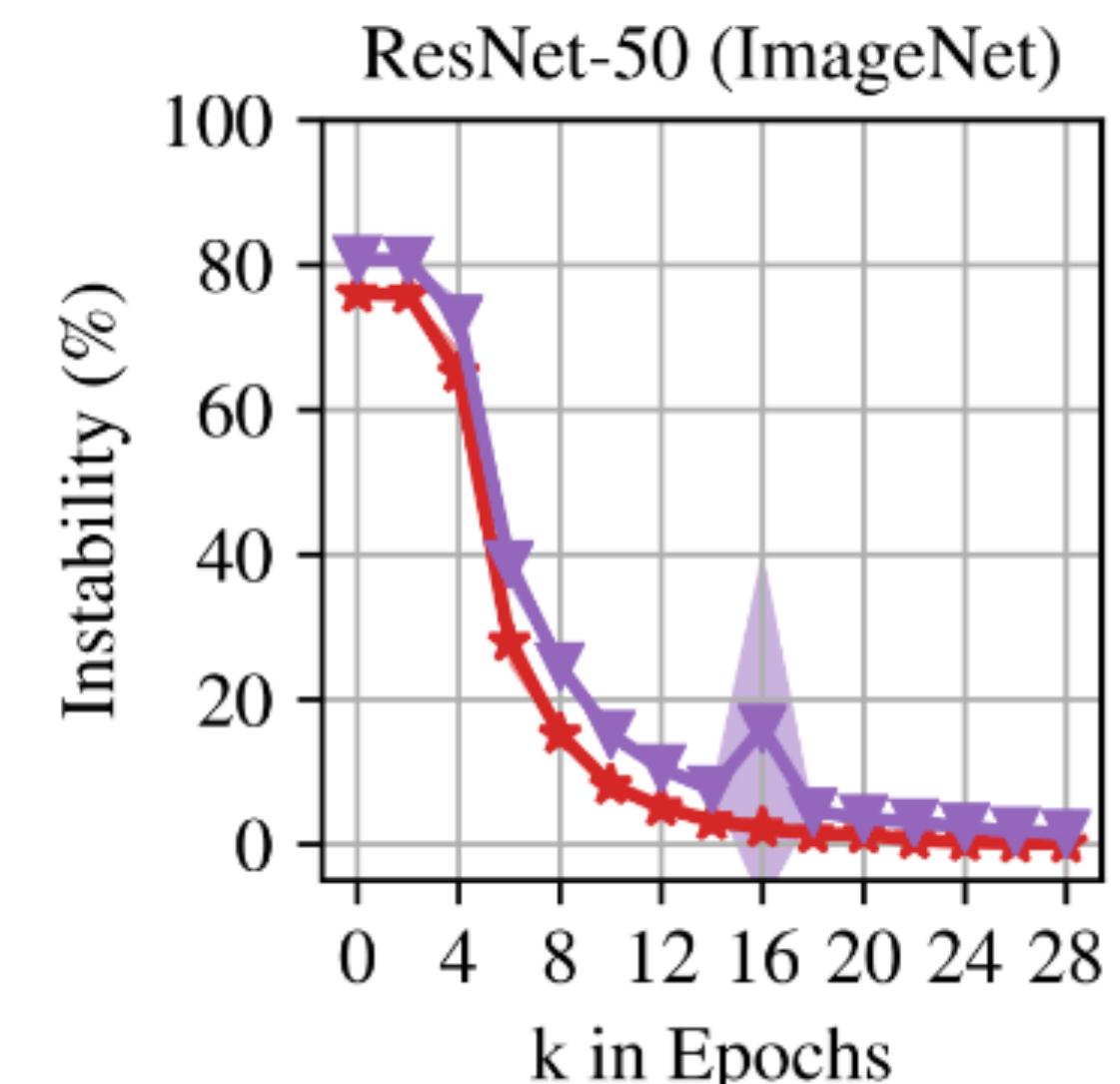
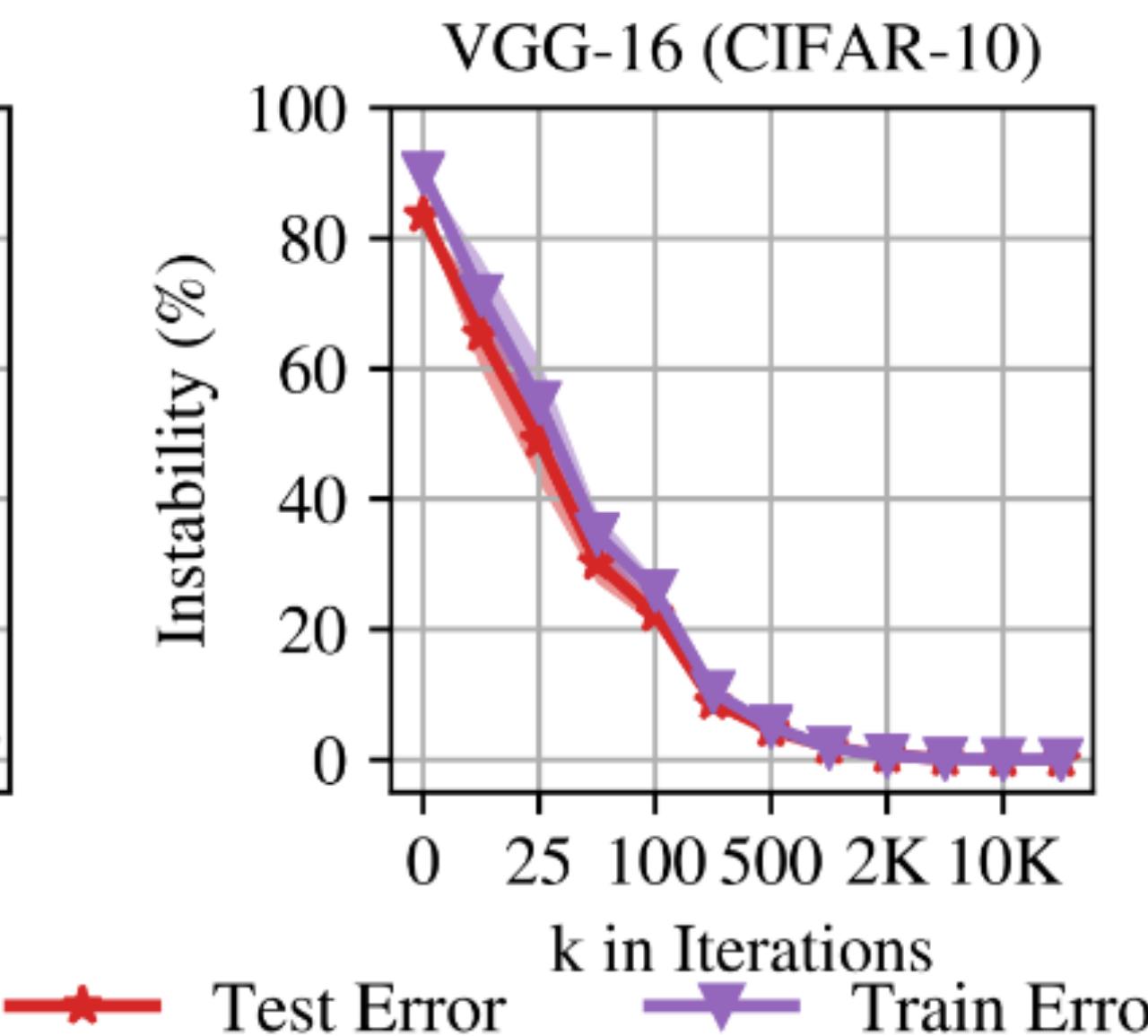
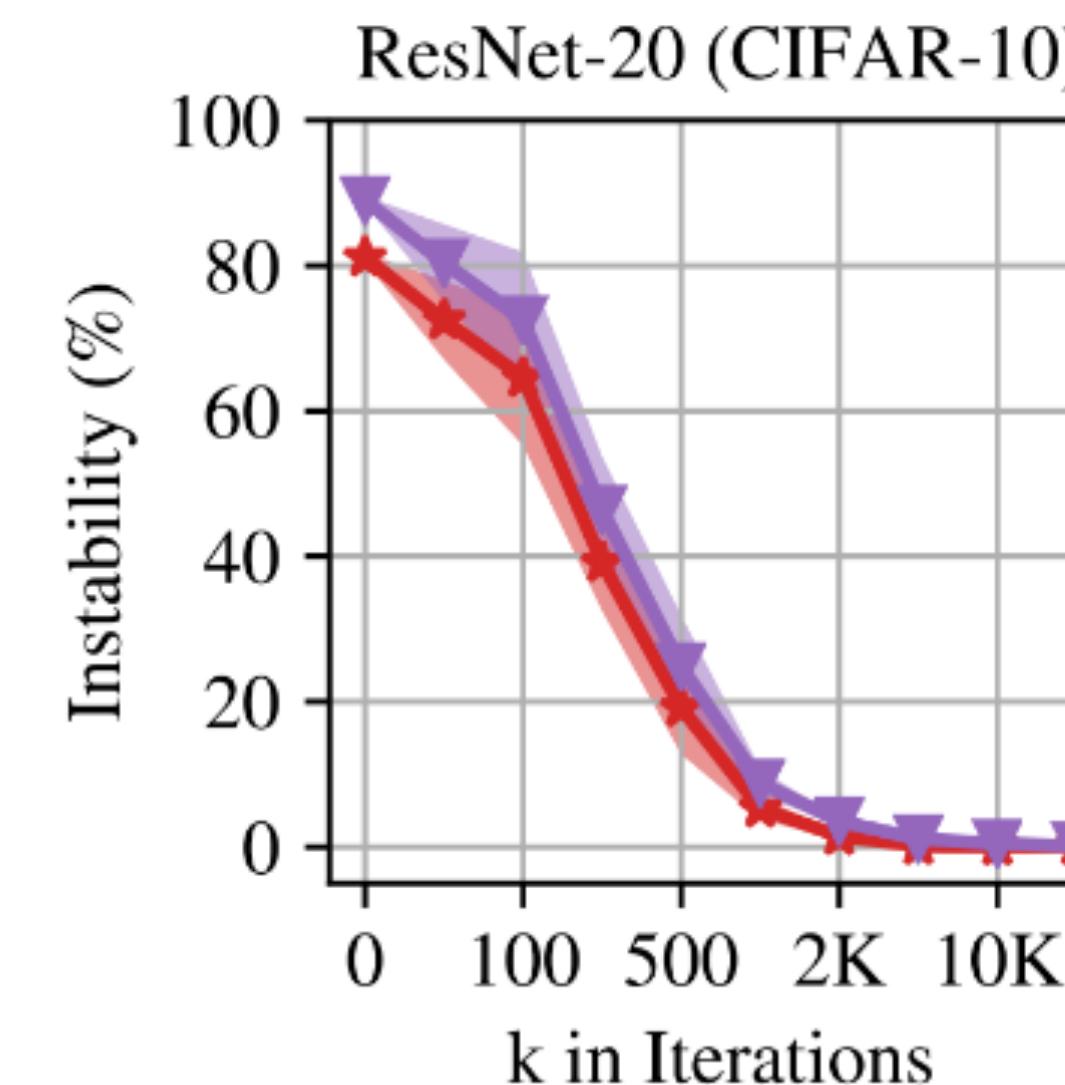
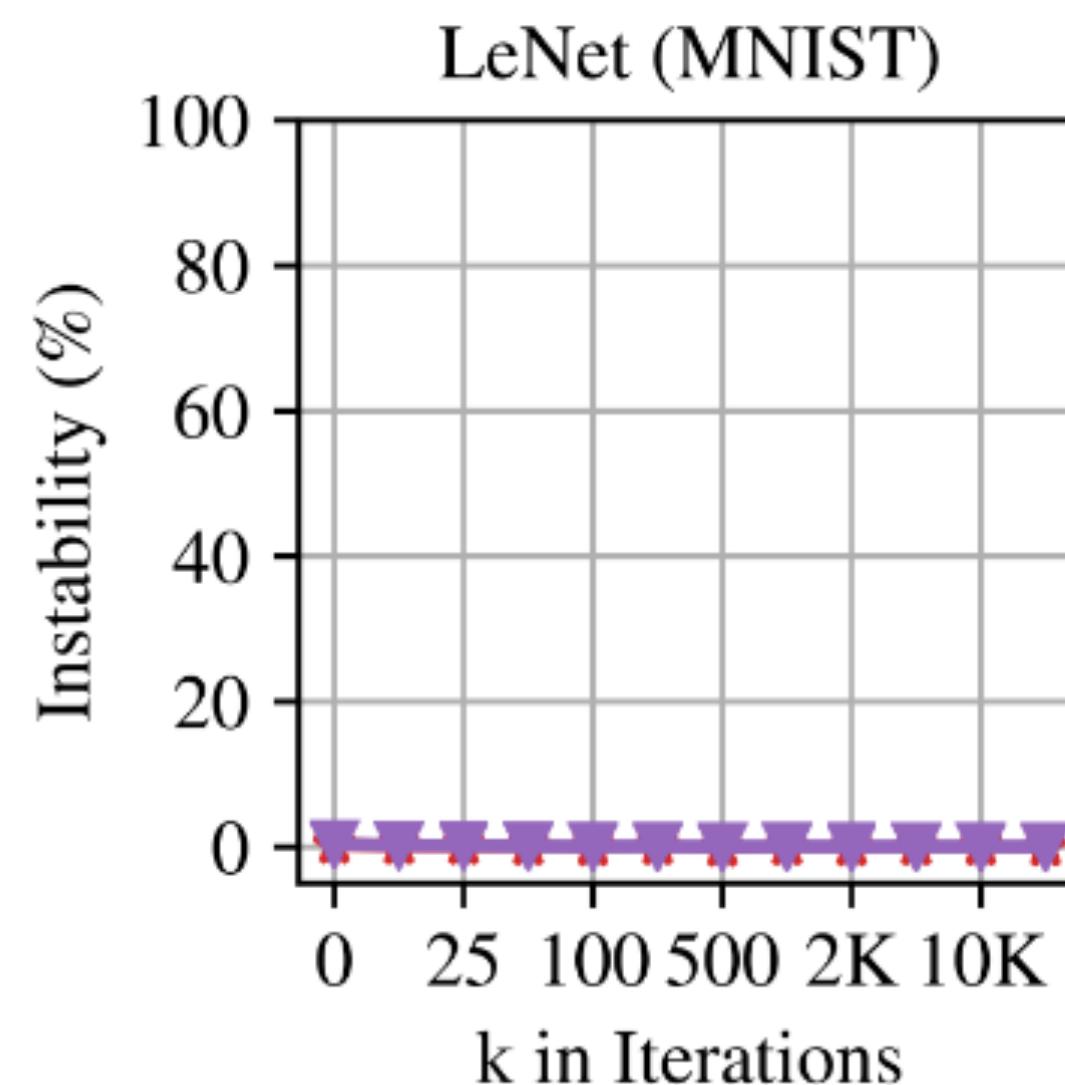
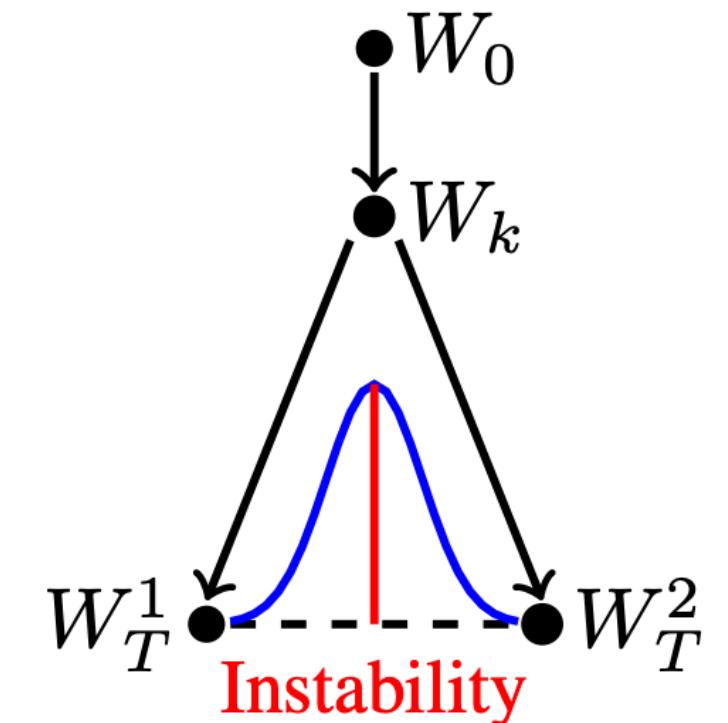
Mode connectivity

- By 2017, people realized that there exists a **nonlinear low-loss curve** in the parameter space between two independently trained models (w/ same data)
 - Note. Two sources of randomness; init & SGD ordering
- **Problem.** Nonlinear, so requires an extensive search for interpolation



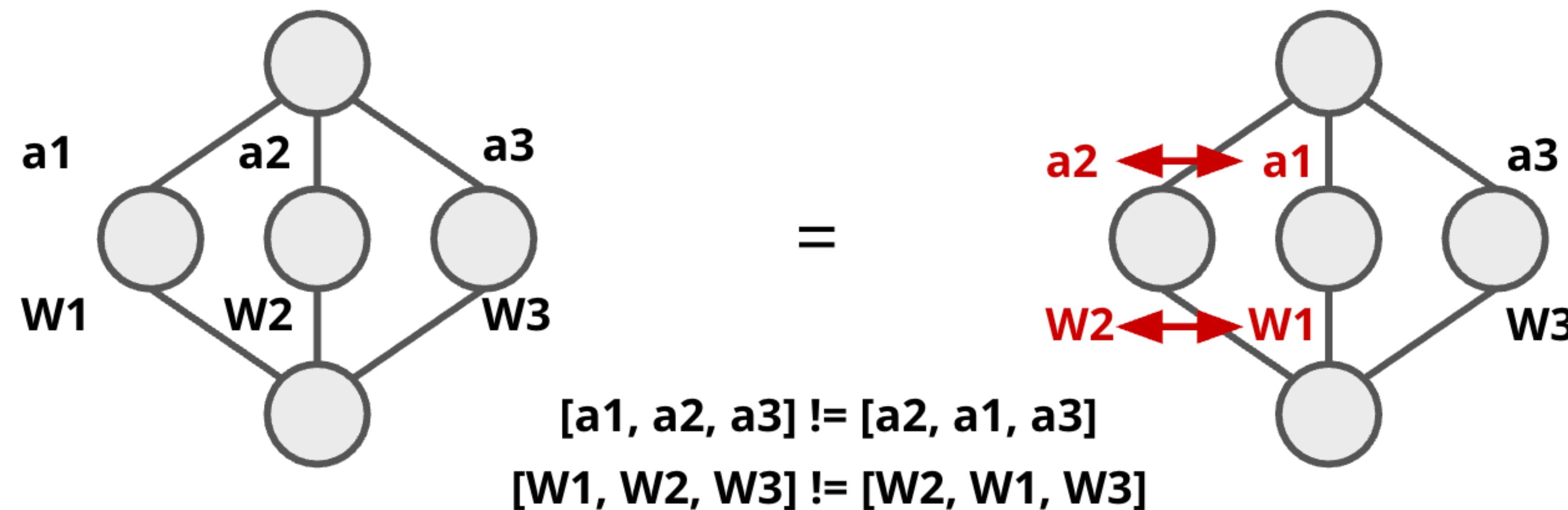
“Linear” mode connectivity

- If two models share the **initialization & first k SGD iterations**, then the **linear** interpolation suddenly works
 - i.e., converge to a linearly connected basin
- **Question.** Can we do a similar thing without much shared randomness?



Permutation Invariance

- Turned out that **permutation-invariance** of neural nets play a role:
 - If we permute some neurons of a net:
 - Function does not change
 - Parameter does change
 - That is, there are “**equivalent params**”



Permutation Invariance

- More generally, consider an MLP

$$f_{\theta}(x) = W_L \sigma(W_{L-1} \sigma(\dots \sigma(W_1 x) \dots))$$

- Suppose that we construct another MLP using the same parameters, except

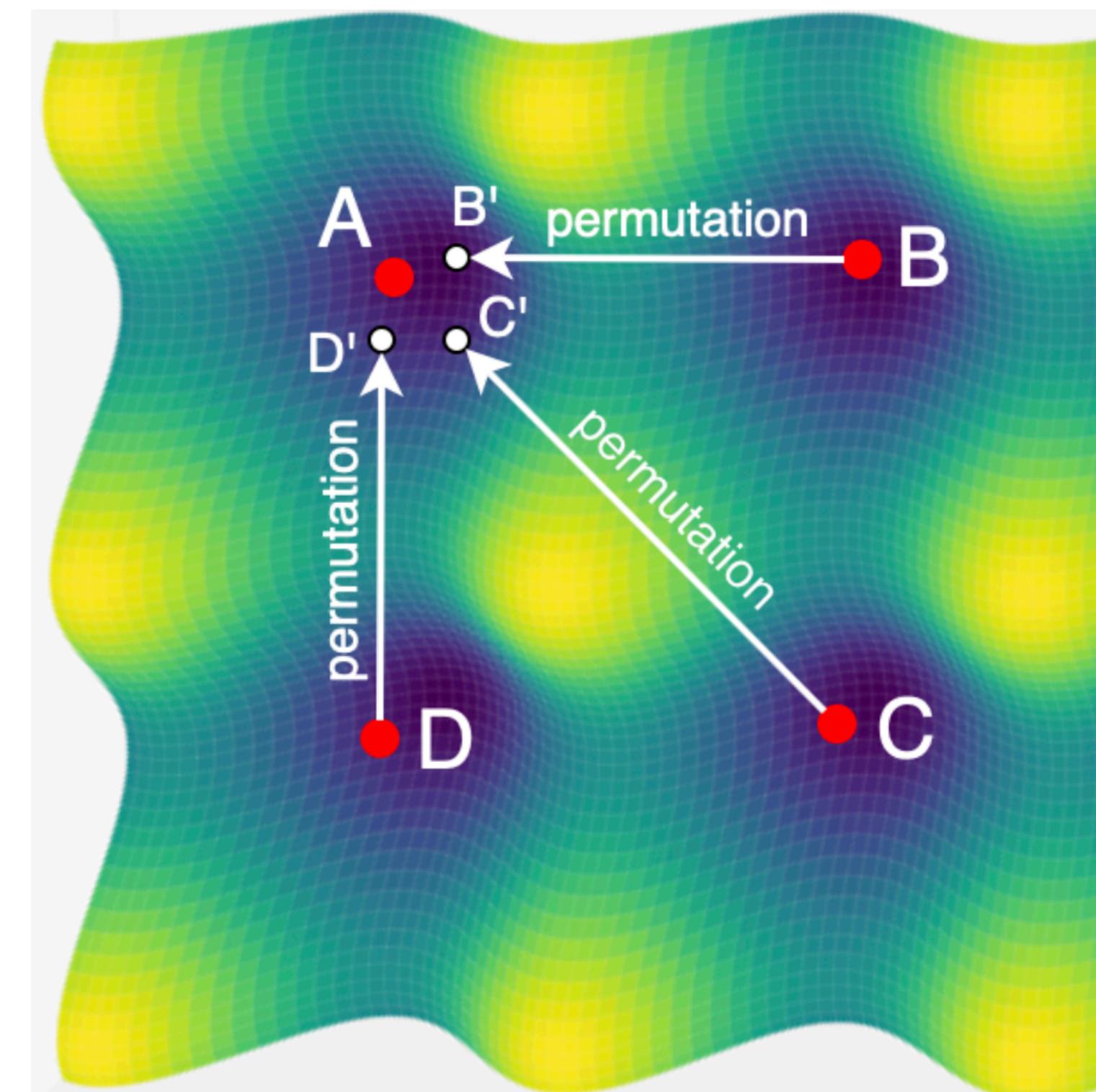
$$\tilde{W}_i = PW_i, \quad \tilde{W}_{i+1} = W_{i+1}P^{\top}$$

- Here, P is a **permutation matrix**
(binary matrix with only one 1 in each col/row)
- Then, we have

$$f_{\theta}(x) = f_{\tilde{\theta}}(x)$$

Permutation Invariance

- **Conjecture.** If we **permute neurons in a correct way**, any two modes are linearly connected with each other
 - To merge the knowledge, simply permute & linearly interpolate



Matching the neurons

- **Question.** Given two nets, how can we find the best permutation?
- **Naïve.** Try all permutations, interpolate, find the best one.
 - Challenge. The solution space is too large
 - For a two-layer MLP with d neurons, exists $d!$ permutations

ARCHITECTURE	NUM. PERMUTATION SYMMETRIES
MLP (3 layers, 512 width)	$10 \wedge 3498$
VGG16	$10 \wedge 35160$
ResNet50	$10 \wedge 55109$
Atoms in the observable universe	$10 \wedge 82$

Matching the neurons

- Many solutions, but the **activation matching** is popular
- **Idea.** Match the neurons with the most similar activations
 - Suppose that we have one sample.
 - Let $\mathbf{z}^{(A)}, \mathbf{z}^{(B)} \in \mathbb{R}^d$ be the layer i input activation of model A&B, resp.
 - Solve the ℓ^2 minimization
$$\min_P \|\mathbf{z}^{(A)} - P\mathbf{z}^{(B)}\|^2$$
 - If we do extend this multiple samples, becomes equivalent to:

$$\max_P \langle P, \mathbf{Z}^{(A)}(\mathbf{Z}^{(B)})^\top \rangle_F, \quad \mathbf{Z}^{(A)}, \mathbf{Z}^{(B)} \in \mathbb{R}^{d \times n}$$

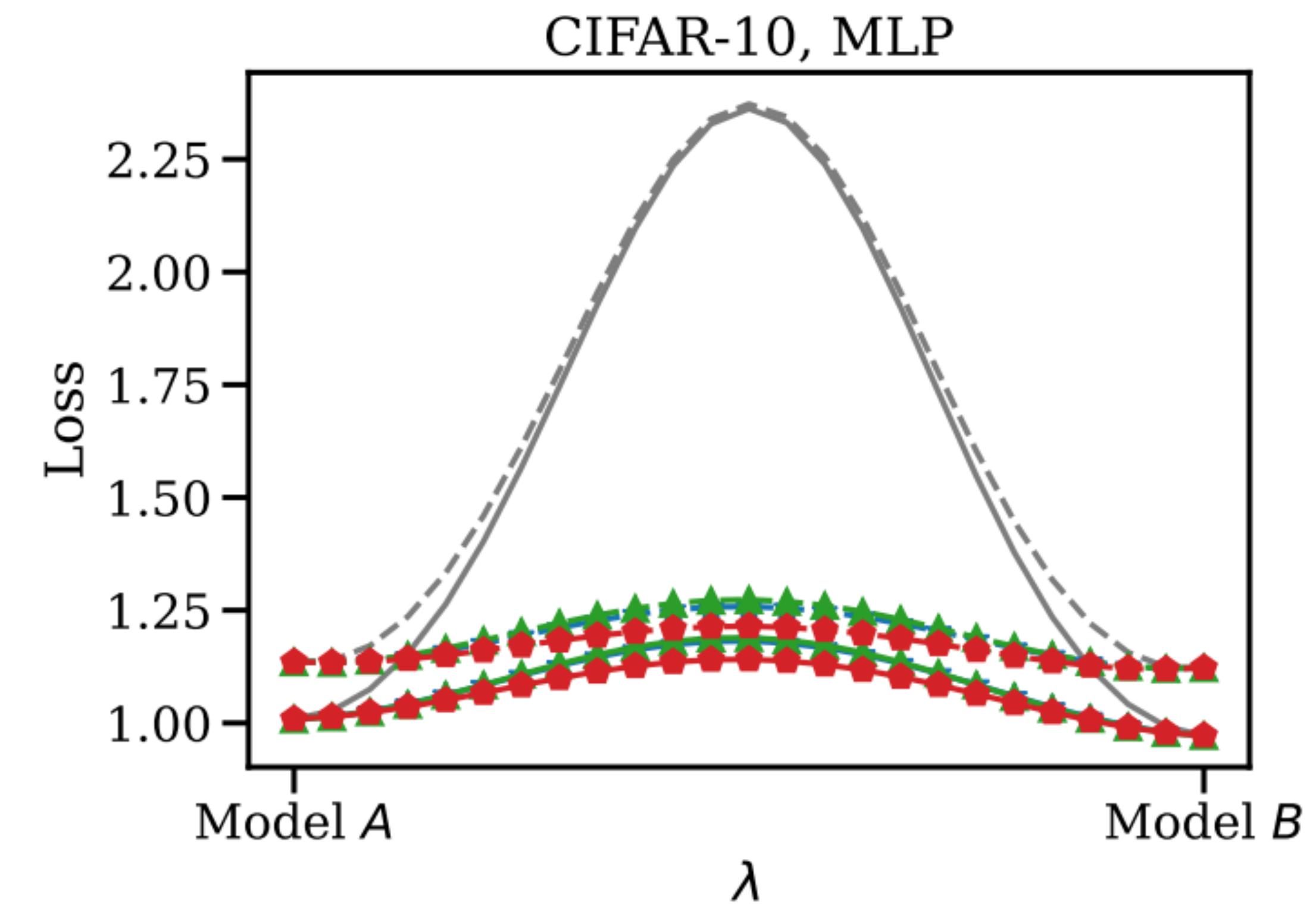
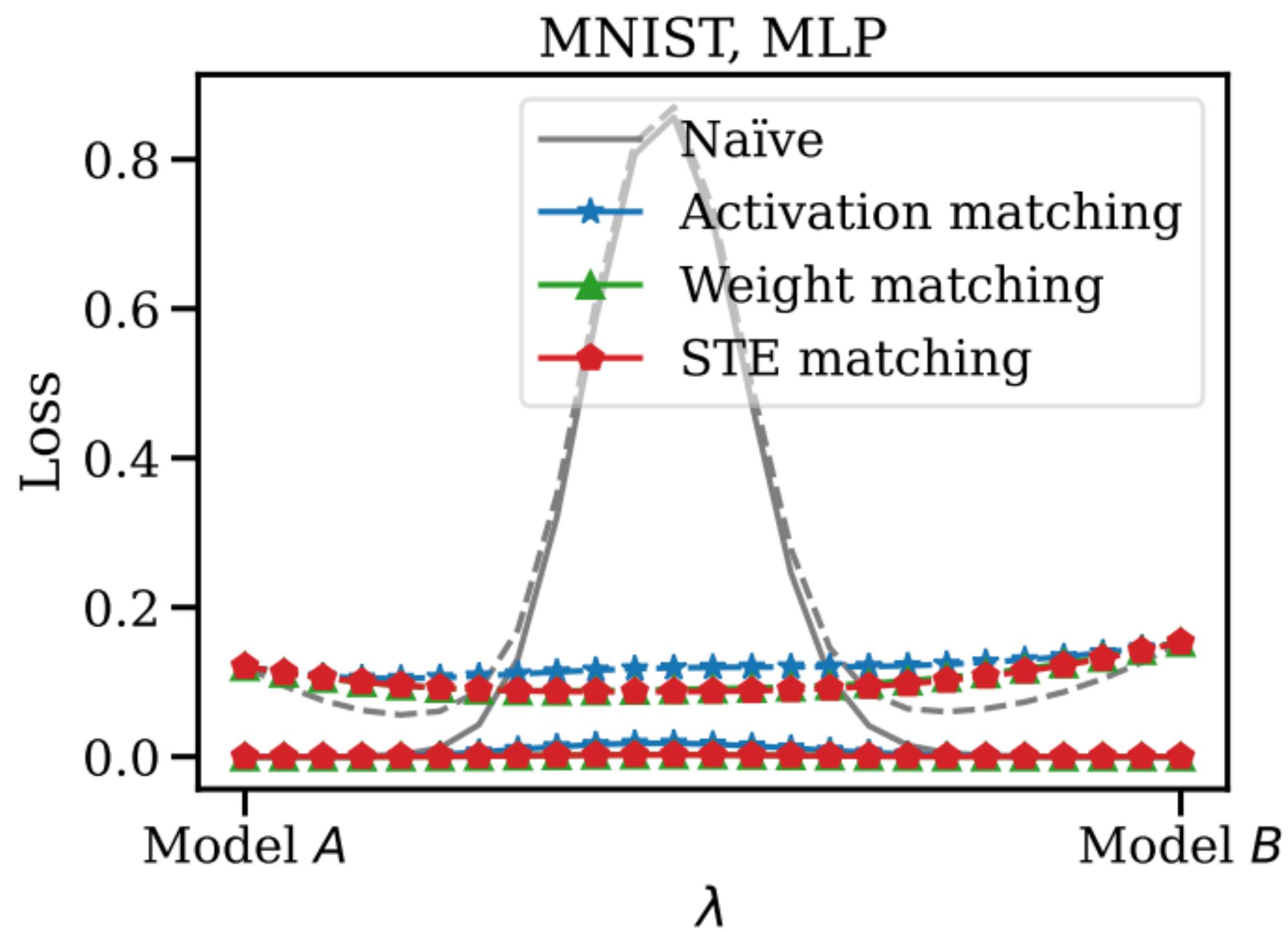
Matching the neurons

$$\max_P \langle P, \mathbf{Z}^{(A)}(\mathbf{Z}^{(B)})^\top \rangle_F, \quad \mathbf{Z}^{(A)}, \mathbf{Z}^{(B)} \in \mathbb{R}^{d \times n}$$

- The problem is the **linear assignment** problem:
 - Place exactly one 1 at row/col, so that the inner prod is maximized:
 - A well-known solver called “Hungarian method”:
 - https://en.wikipedia.org/wiki/Hungarian_algorithm
- Solve this, starting from layer 1 to layer L.

Matching the neurons

- The matching-based methods greatly improve interpolated performance
 - STE-based matching works better with models with BatchNorm



Matching the neurons

- Recent works use these techniques to merge models trained on different dataset
- Promise.**
 - Less inference cost than ensembling
 - No further training cost
- Limitation.**
 - Still far from the goal

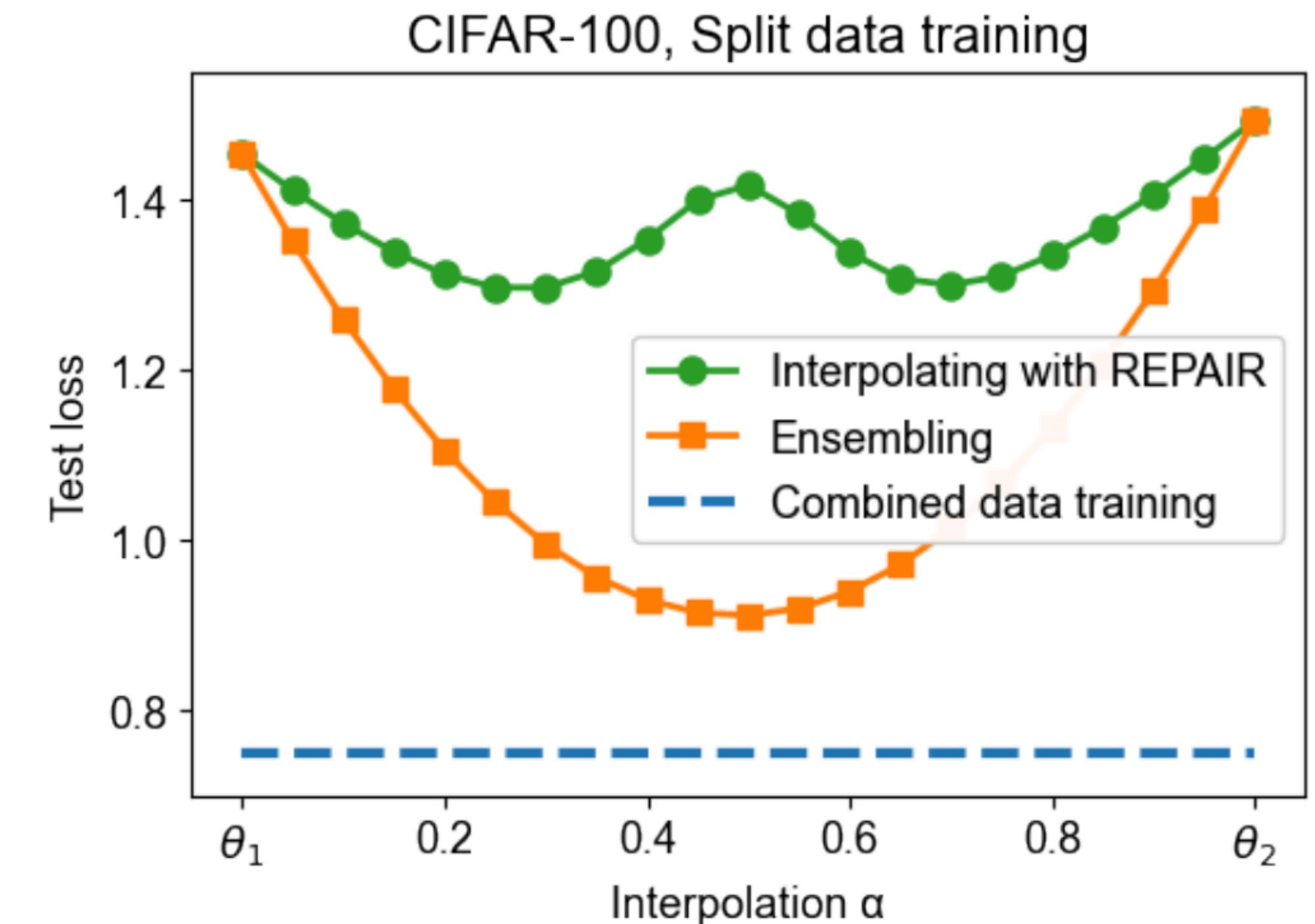
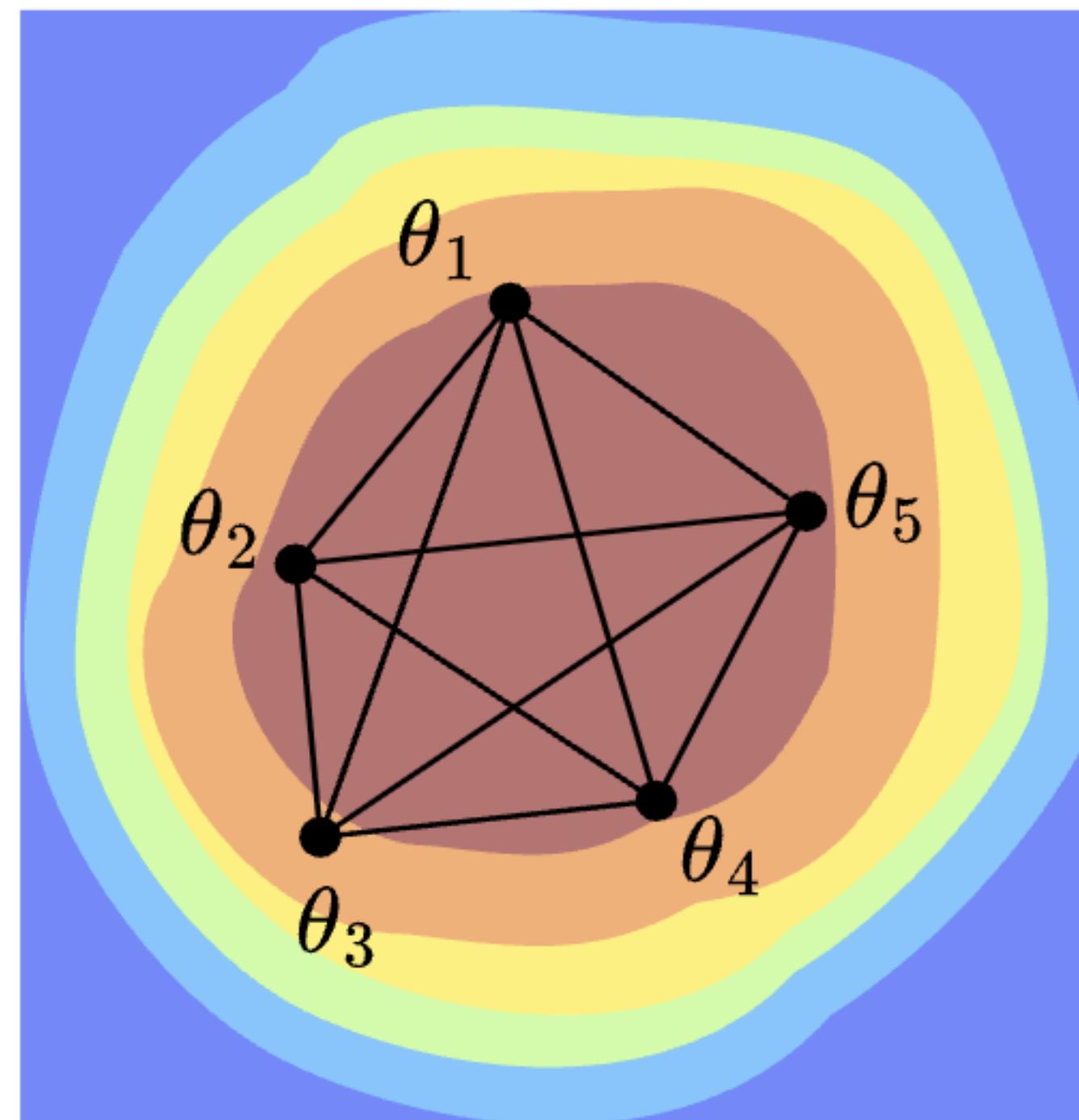


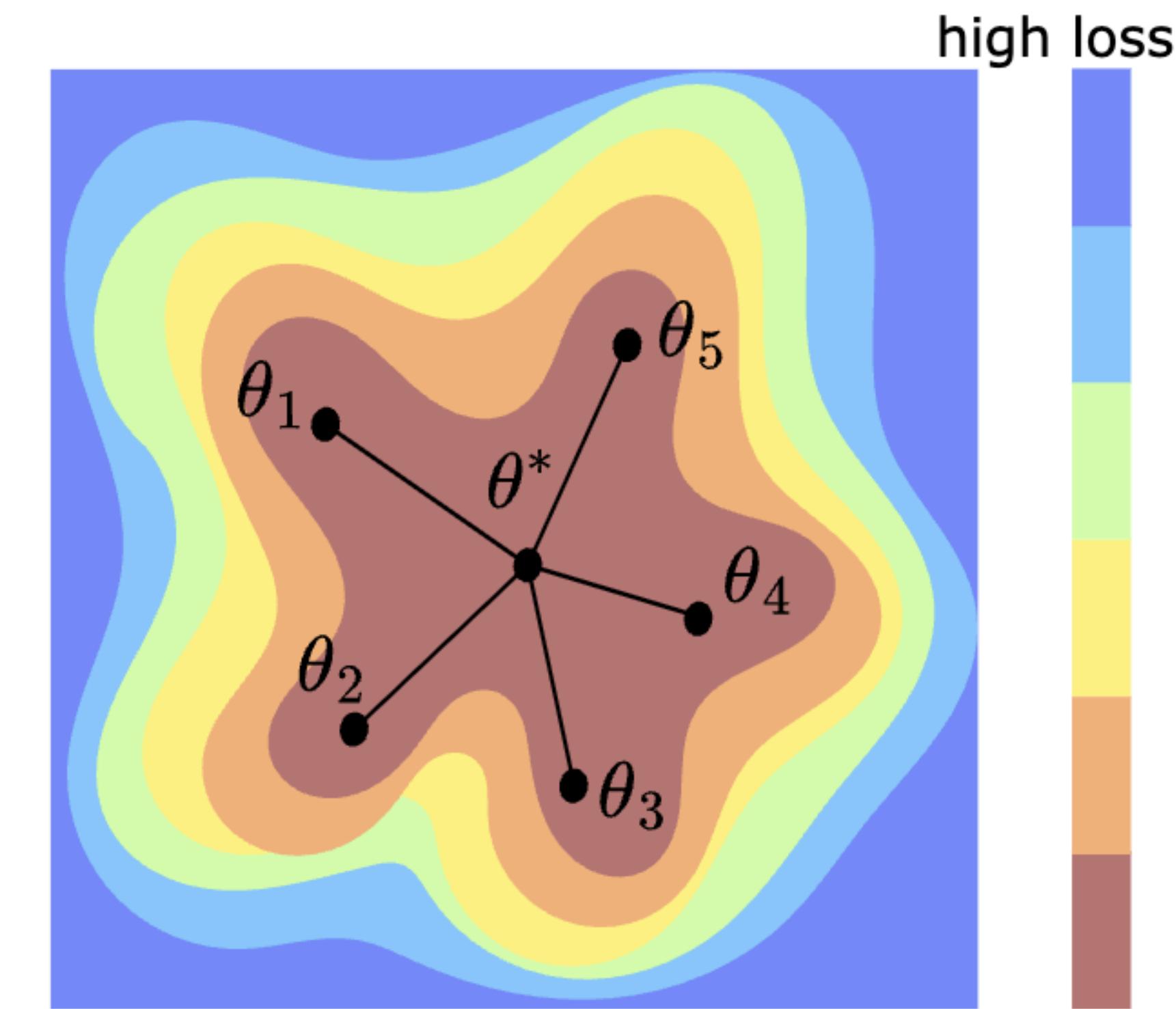
Figure 7: **Split data training.** When two networks are trained on disjoint, biased subsets of CIFAR-100, their REPAIRed interpolations outperform either endpoint with respect to the combined test set.

Recent work: Star conjecture

- Recent work proposes a “star conjecture”:
 - Weaker than linear interpolation, stronger than simple mode connectivity



Convexity conjecture (Entezari et al.)
holds only for wide networks.



Star domain conjecture (ours)
holds even for narrower networks.

Further readings

- **REPAIR.** Fixed for models with BatchNorms
 - <https://arxiv.org/abs/2211.08403>
- **Ziplt.** Merges only several layers for better performance
 - <https://arxiv.org/abs/2305.03053>
- **Deep Weight Space Alignment.** Learn to predict the permutation
 - <https://arxiv.org/abs/2310.13397>
- **Star Domain.** Alternative conjecture
 - <https://arxiv.org/abs/2403.07968>

Pretrained model as initialization

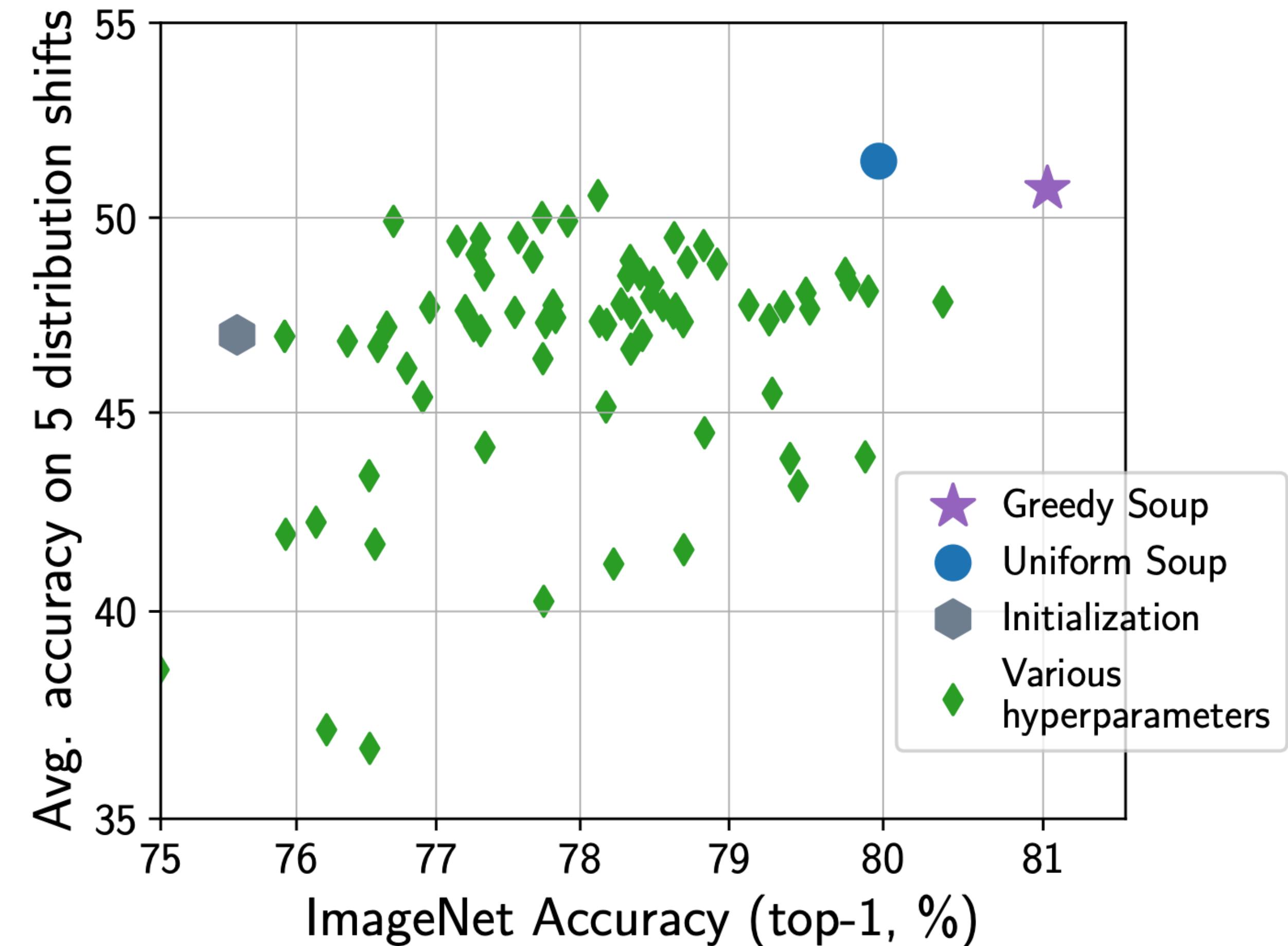
Model soup

- Idea. Use large pre-trained models as a shared init

- Generate multiple fine-tuned versions for a target task
 - Diverse hyperparameters
 - Average the fine-tuned weights

$$\theta = \sum_{i=1}^M w_i \theta_i$$

- Not as good as ensemble, but cheap



Model soup

- Selecting the nice ingredients is critical

- **Greedy Soup.**

- Sort each ingredient by validation acc.
- Add one and taste:
 - If tastes better, keep it
 - Otherwise, remove

Recipe 1 GreedySoup

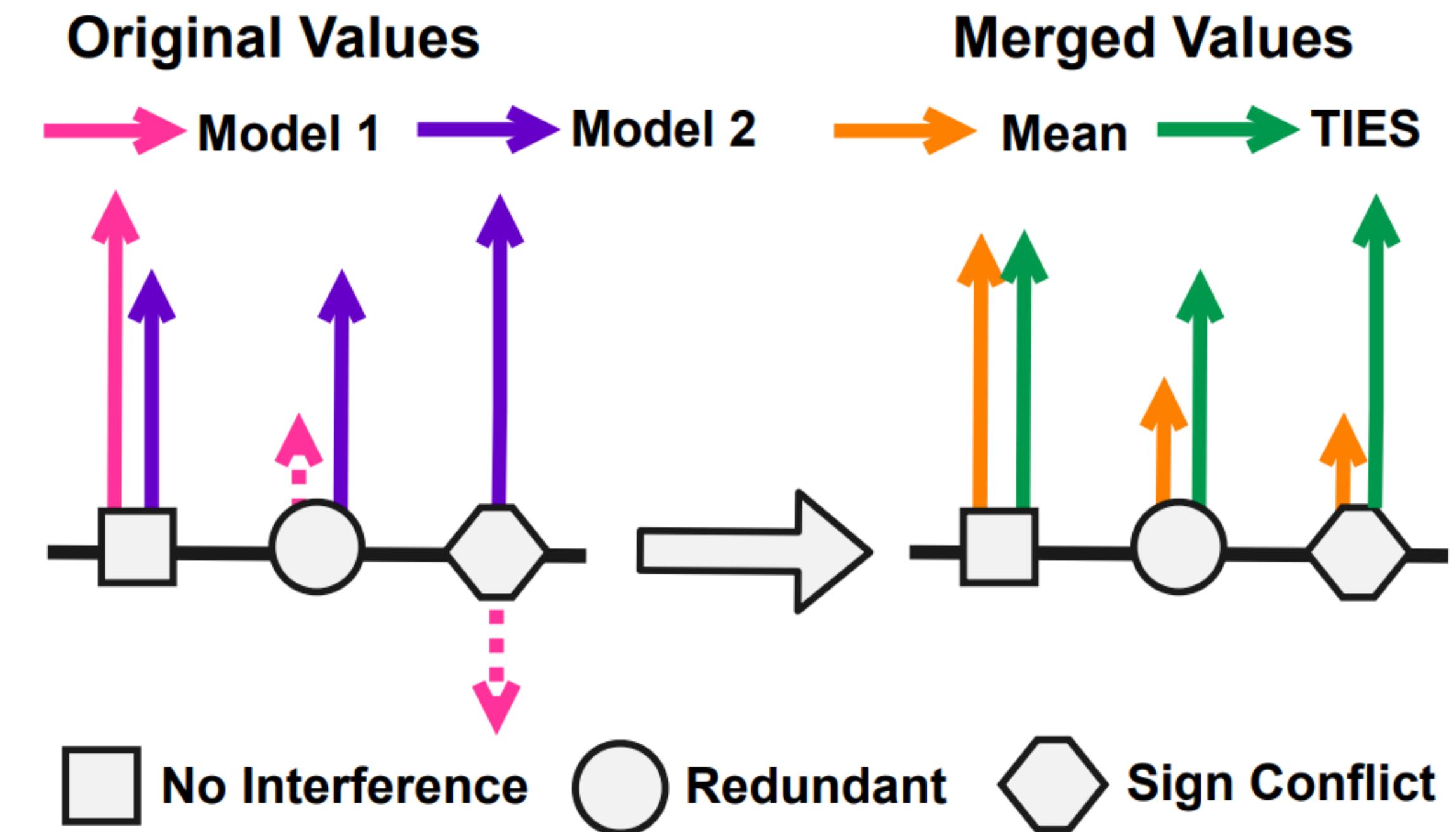
Input: Potential soup ingredients $\{\theta_1, \dots, \theta_k\}$ (sorted in decreasing order of $\text{ValAcc}(\theta_i)$).

```
ingredients ← {}
for i = 1 to k do
    if ValAcc(average(ingredients ∪ {θii}
return average(ingredients)
```

Removing the noise in parameter updates

- Turns out that these parameter updates are **quite noisy**:
- **TIES-merging (2023)**. Resolving conflicts between updates

- Sign conflict. Ignore a smaller one
- Redundant update. Ignore small one
- Others. Average out



Further readings

- **DARE.** Pruning-inspire version of TIES
 - <https://arxiv.org/abs/2311.03099>
- **Model Stock.** Layerwise merging & smaller ingredients for soup
 - <https://arxiv.org/abs/2403.19522>
- **Evolutionary Optimization.** Use EO to find the best weight combination
 - <https://arxiv.org/abs/2403.13187>

Editing

Motivation

- The knowledge of neural nets is not perfect
 - Factual mistake
 - Outdated information
 - Cannot access certain info

Who teaches EECE695D-01 at POSTECH right now?

As of March 24, 2025, the instructor for EECE695D-01 at POSTECH is not publicly listed. For the most accurate and current information, I recommend checking POSTECH's official course catalog or contacting the Electrical Engineering department directly.

Motivation

- **Option#1.** Retrain the model from scratch, with original dataset + patch data
 - Too Costly!
- **Option#2.** Fine-tune with patch
 - Costly, and can affect other predictions
- **Option#3.** Retrieval-augmented generation
 - Good, but sometimes conflict with the original model

Goal

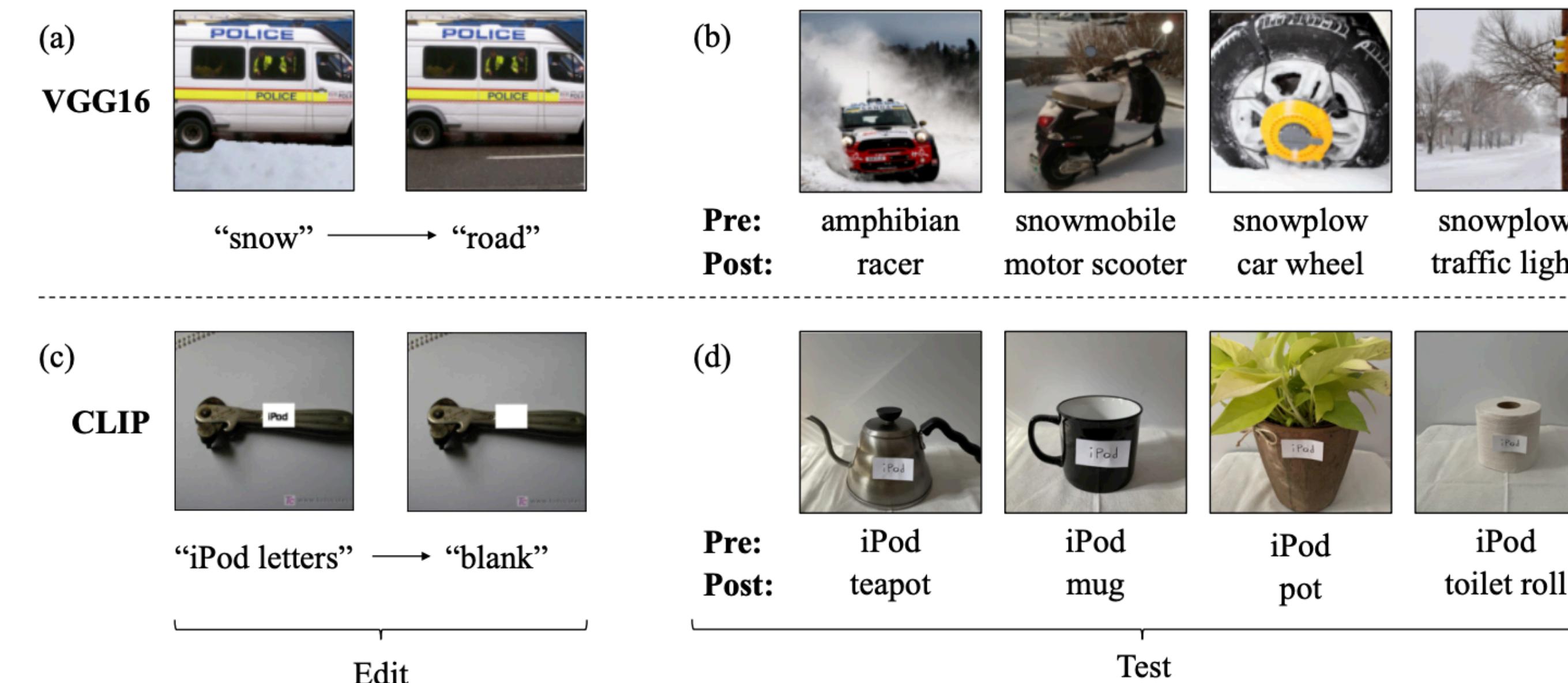
- Given a model $f_\theta(\cdot)$, **modify the prediction** on a sample \mathbf{x}^* to be y^*
- We want to find $\tilde{\theta}$ such that:
 - **Reliable.** Makes desired changes $f_{\tilde{\theta}}(\mathbf{x}^*) \approx y^*$
(e.g., “who’s the president of United States?”)
 - **Local.** Minimally affects unrelated info $f_{\tilde{\theta}}(\mathbf{x}) \approx f_\theta(\mathbf{x}), \quad \mathbf{x} \neq \mathbf{x}^*$
(e.g., “which team does Messi play for?”)
 - **Generalizes.** Corrects output for related input $f_{\tilde{\theta}}(\mathbf{x}) \approx y^*, \quad \mathbf{x} \approx \mathbf{x}^*$
(e.g., “who’s the US president?”)
- Plus, we want to minimize the computational cost of doing so

Approaches

- Many approaches:
 - Partial Retraining
 - Meta-Learning
 - Task Arithmetics

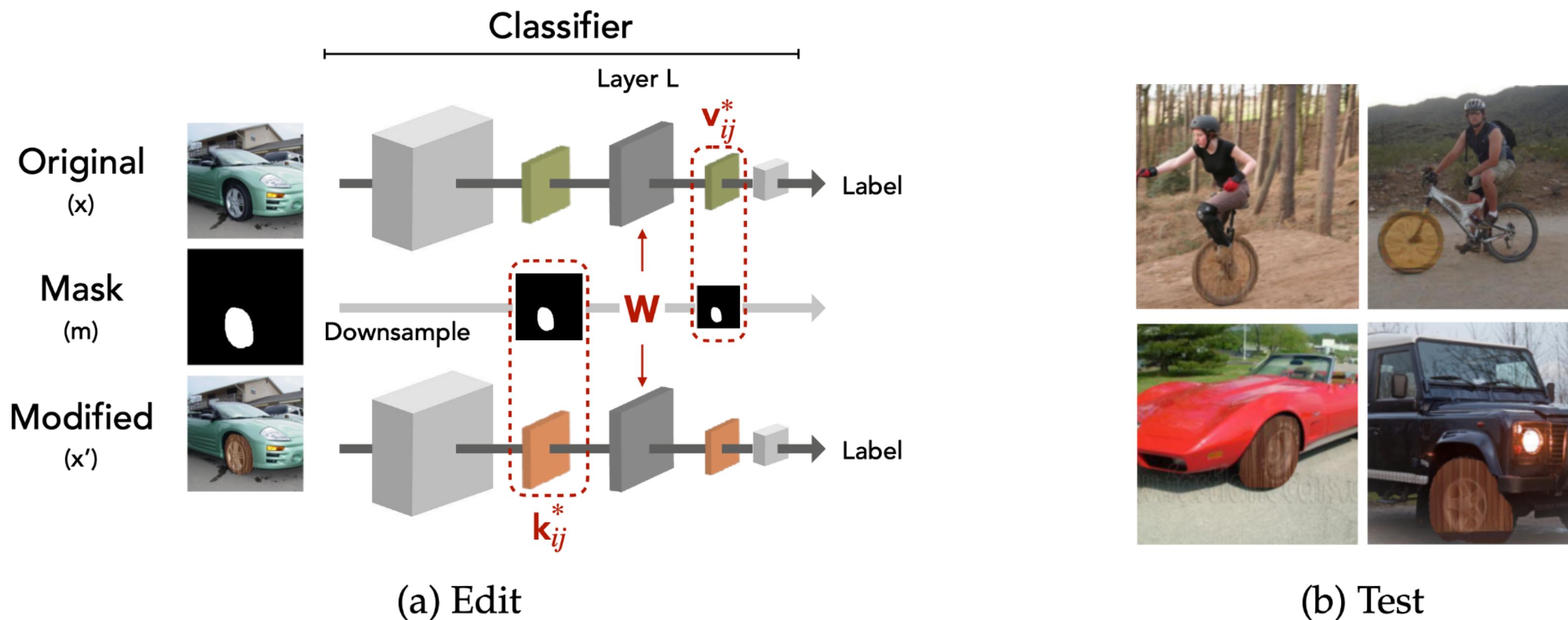
Partial Retraining

- Retrain only one (or few) layers
- We study the example of Santurkar et al., (2021)
 - Given a single pair of exemplar, edit prediction rules to equate them
 - e.g., replace certain concepts / robustness to attacks



Partial Retraining

- Update the layer i as follows:
 - **Input.** Layer $(i-1)$ activation of a model that sees **modified input** (called “keys” $k^* \in \mathbb{R}^m$)
 - **Output.** Layer i activation of a model that sees the **original input** (called “values” $v^* \in \mathbb{R}^n$)



Partial Retraining

- Find a matrix W' which solves

$$W' = \arg \min \|V - WK\|^2, \quad \text{subject to} \quad v^* = W'k^*$$

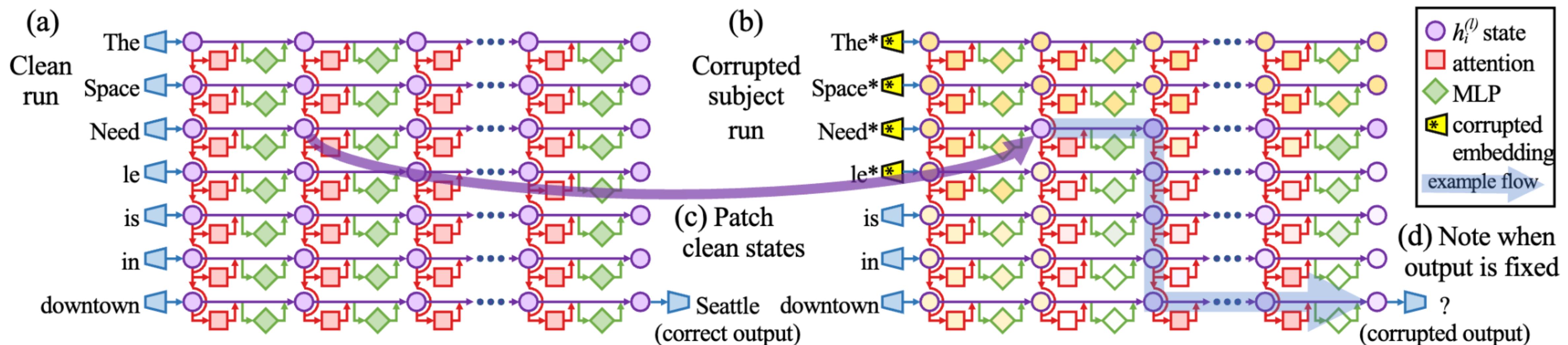
- V, K are values/keys for unmodified locations
- This is a least-squares with constraints, with solution expressed as:

$$W' = W + \Lambda(KK^\top)^{-1}k^*)^\top$$

- Λ can be found by gradient descent
- For updating a single concept, **rank-1 update** is enough!

Further ideas

- This approach requires pinpointing the **which-tensor-to-update**:
- **Idea.** Causality-based analysis (will not go into details)
 - i.e., corrupt-and-restore several tokens, and trace the corruptions
 - e.g., ROME (<https://arxiv.org/abs/2202.05262>)
MEMIT (<https://arxiv.org/abs/2210.07229>)

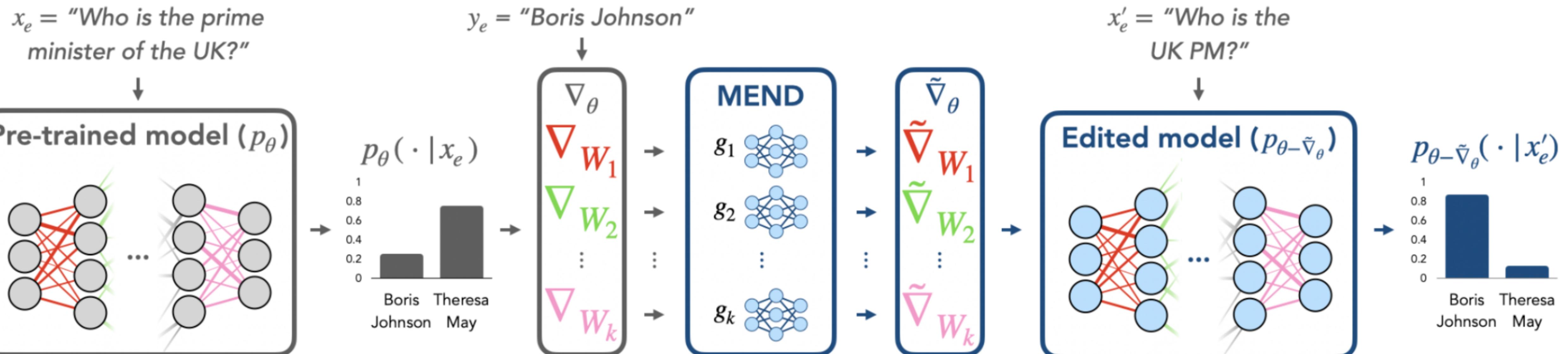


Meta-Learning

- Train a **model editor** which maps
 - “editing task” → weight updates
 - Super-fast editing
 - **Problem.** “Editing task” is difficult to formalize as a model input
- We study the example of Mitchell et al., (2022)

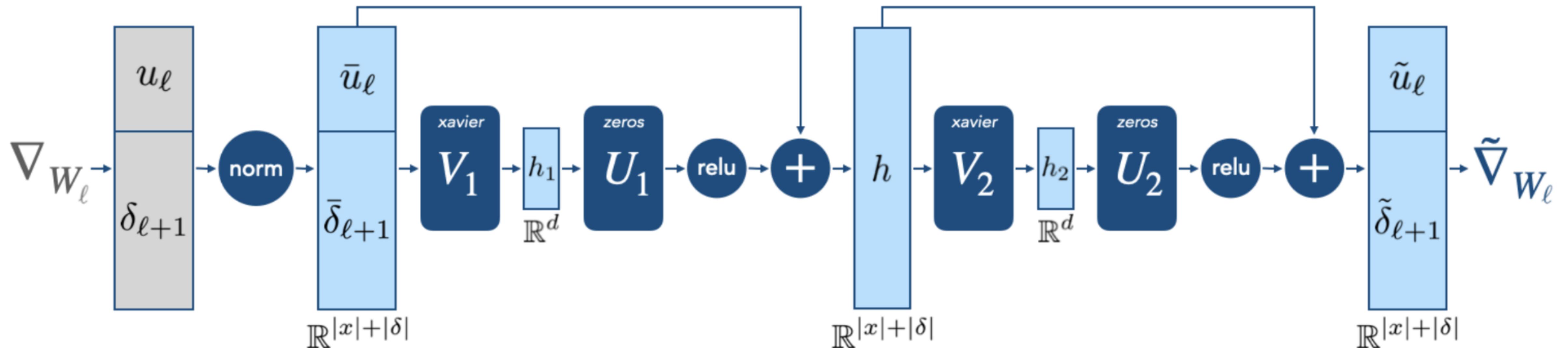
Meta-Learning

- **Idea.** Train a model that uses the **loss gradient** as an input, and the actual update as an output
 - Train separate predictors for each tensor (Reduced computational cost)



Meta-Learning

- Trick. Weight gradients for each sample are rank-1
 - Linear model: $\nabla_{\mathbf{W}} \|\mathbf{y} - \mathbf{Wx}\|^2 = 2(\mathbf{y} - \mathbf{Wx})\mathbf{x}^T$
 - Deeper model: (Handle similarly)
 - Thus, predict from/to concatenated rank-1 vectors



Meta-Learning

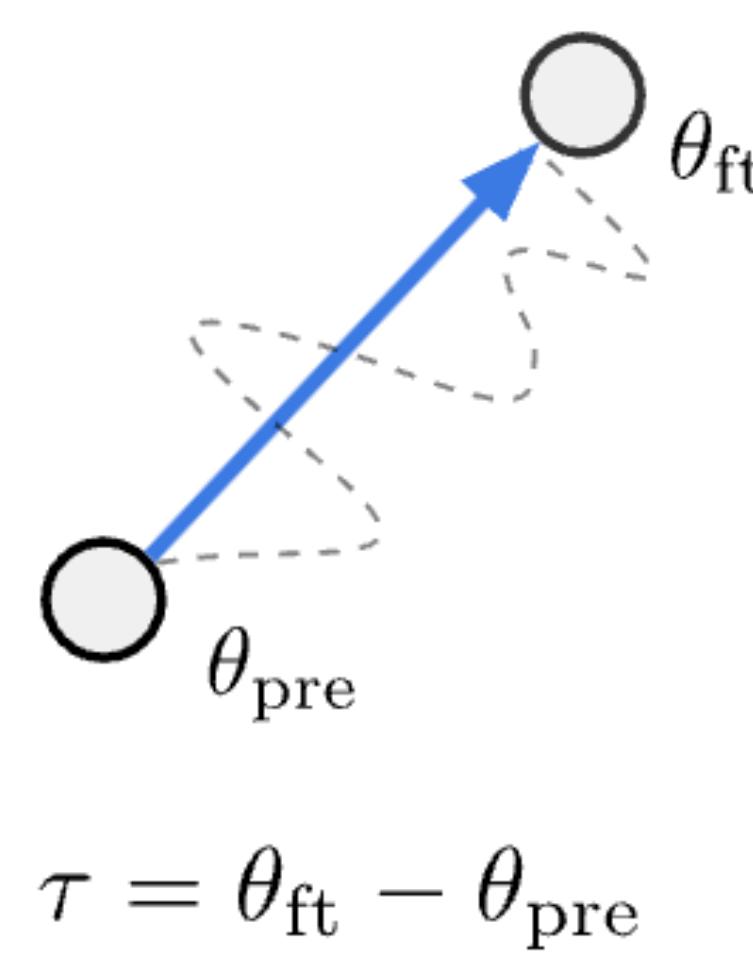
- **Meta-Training.**
 - At each step, sample:
 - Edit sample (\mathbf{x}_e, y_e)
 - Equivalence sample (\mathbf{x}'_e, y'_e)
 - Generated by removing some prefix tokens from edit
 - Locality example \mathbf{x}_{loc}
 - Then, train with the joint loss

MEND losses: $L_e = -\log p_{\theta_{\tilde{W}}}(y'_e | x'_e), \quad L_{\text{loc}} = \text{KL}(p_{\theta_W}(\cdot | x_{\text{loc}}) \| p_{\theta_{\tilde{W}}}(\cdot | x_{\text{loc}})). \quad (4a,b)$

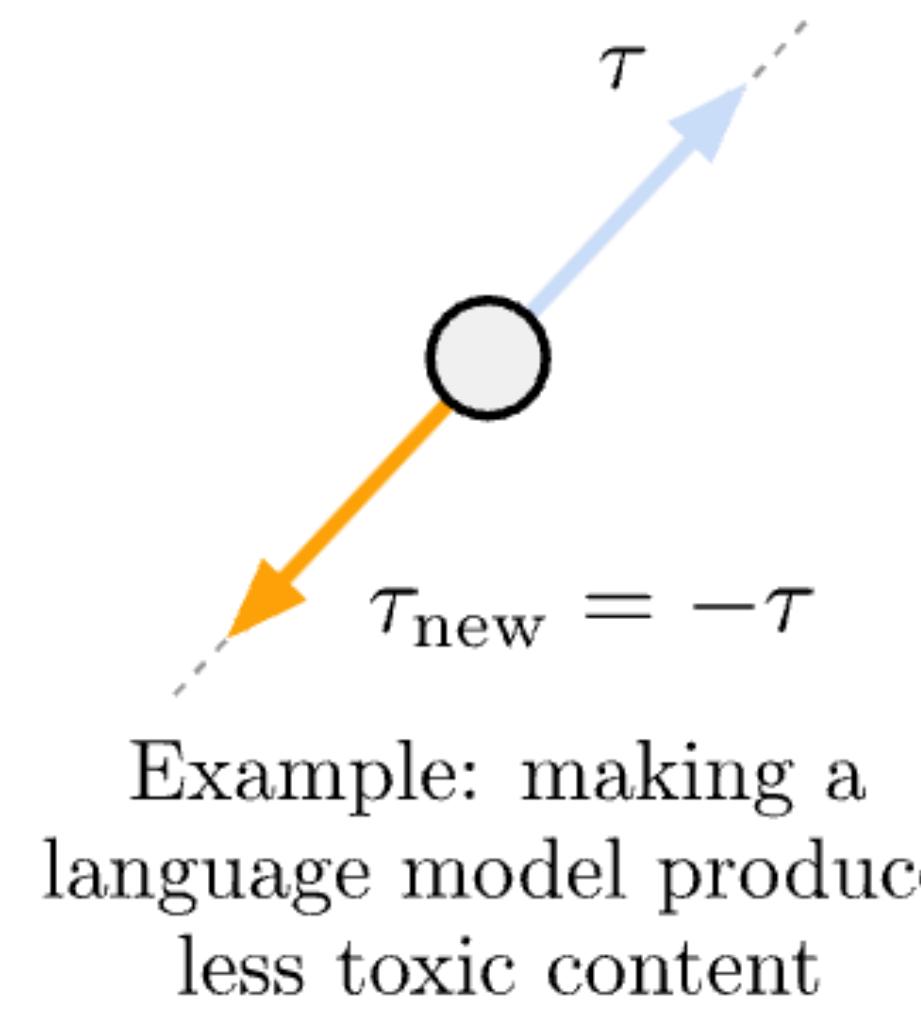
Task arithmetics

- Suppose that we have a large pre-trained base model
 - Then, we can do **arithmetics** with task-specific fine-tuned weight updates
 - Add knowledge: Fine-tune and add
 - Remove knowledge: Fine-tune and subtract

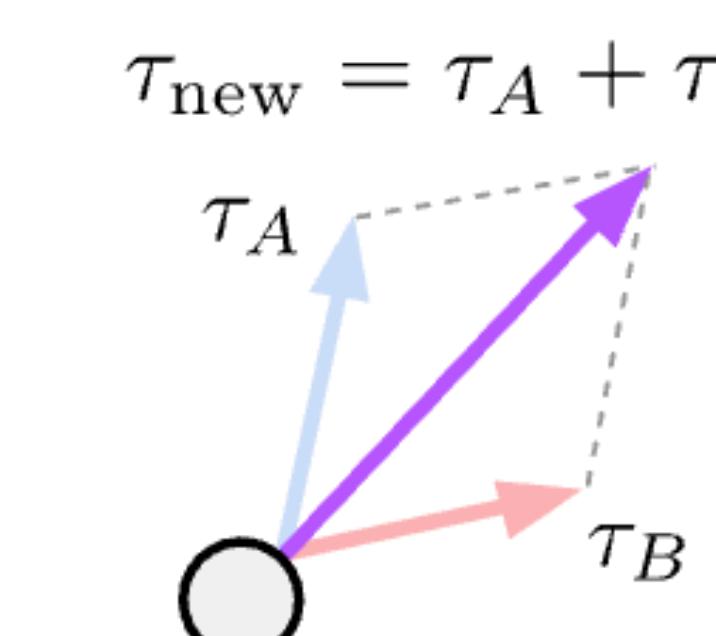
a) Task vectors



b) Forgetting via negation

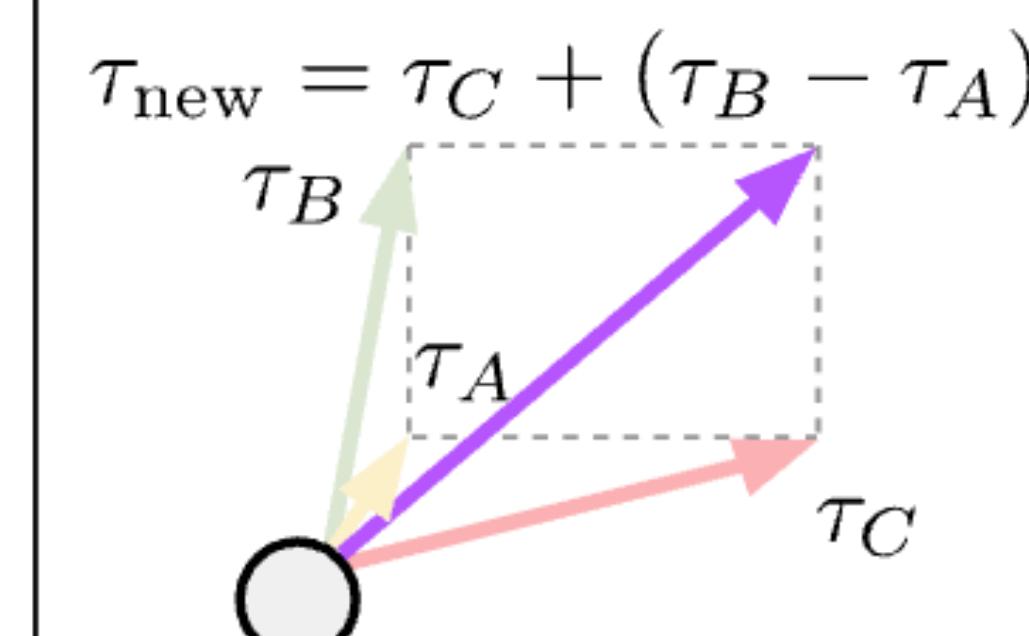


c) Learning via addition



Example: building a multi-task model

d) Task analogies



Example: improving domain generalization

Challenges

- Scaling up to trillion-scale models
- Editing black-box models:
 - <https://arxiv.org/abs/2211.03318>
- Applying massive edits in parallel
- Transferring edits from model to model

That's it for today

