

mas651 exercises

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Problem (5.1.1).

Let (S, \mathcal{S}) be a state space of X_n where $S = \{1, 2, \dots, N\}$ and $\mathcal{S} = 2^S$. Note that N is an absorbing state. And $X_1 = 1$ with probability 1. For fixed k such that $1 \leq k < N$, $k \leq n$,

$$P(X_{n+1} = k + 1 | X_n = k) = \frac{N - k}{N}$$

and

$$P(X_{n+1} = k | X_n = k) = \frac{k}{N}.$$

If $k > n$, then the above are all 0. So it is a temporally inhomogeneous. The Markov property is trivial since the very next state only depends on the current state.

□

Problem (5.1.2).

$$P(X_4 = 2 | X_3 = 1, X_2 = 1, X_1 = 1, X_0 = 0) = (1/16)/(1/4) = 1/4$$

but

$$P(X_4 = 2 | X_3 = 1, X_2 = 0, X_1 = 0, X_0 = 0) = (1/16)/(1/8) = 1/2.$$

Thus X_n is not a Markov chain.

□

Problem (5.1.5).

$$P(X_{n+1} = k + 1 | X_n = k) = \frac{m - k}{m} \frac{b - k}{m}$$

because we must choose a white ball in the left urn and a black ball in the right urn.

$$P(X_{n+1} = k | X_n = k) = \frac{k}{m} \frac{b - k}{m} + \frac{m - k}{m} \frac{m + k - b}{m}$$

since there are two cases, choosing both black or both white.

$$P(X_{n+1} = k - 1 | X_n = k) = \frac{k}{m} \frac{m + k - b}{m}$$

since we must choose a black ball in the left urn and a white ball in the right urn. Note that the sum of the above is 1, so there is no other transition probability.

□

Problem (5.1.6).

$$P(S_{n+1} = k + 1 | S_n = k) = \frac{P(X_{n+1} = 1, S_n = k)}{P(S_n = k)}$$

where the denominator is

$$\int_{\theta \in (0,1)} P(S_n = k|\theta) dP = \binom{n}{x} \frac{x!y!}{(n+1)!} = \frac{1}{n+1}$$

for $x =$ the number of i such that $U_i \leq \theta$ and $y = n - x$. Note that $x = (n+k)/2$ and $y = (n-k)/2$ since $x + y = n$ and $x - y = k$. The numerator is

$$\int_{\theta \in (0,1)} P(X_{n+1} = 1, S_n = k|\theta) dP = \binom{n}{x} \frac{(x+1)!y!}{(n+2)!}$$

These are because $P(S_n = k|\theta) = \theta^x(1-\theta)^y \binom{n}{x}$ and $P(X_{n+1} = 1, S_n = k|\theta) = P(X_{n+1} = 1|\theta)P(S_n = k|\theta) = \binom{n}{x} \theta^{x+1}(1-\theta)^y$ and using the kernel of beta distribution.

Thus, the probability what we want is $(n+k+2)/(2n+4)$ which depends on n . So X_n is temporally inhomogeneous.

$$P(S_{n+1} = k+1 | S_1 = t_1, \dots, S_n = k) = P(X_{n+1} = 1 | X_1 = t_1, \dots, X_n = t_n)$$

where $\sum_{i=1}^n t_i = k$. We can show the above is equal to $P(S_{n+1} = k+1 | S_n = k) = (n+k+2)/(2n+4)$ similarly, by omitting the $\binom{n}{x}$ term of both denominator and numerator.

□

Problem (5.2.1).

By the given hint,

$$E(1_A 1_B | \mathcal{F}_n) = E(1_A E(1_B | \mathcal{F}_n) | X_n)$$

so it suffices to show that $E(1_B | \mathcal{F}_n) = E(1_B | X_n)$.

Let $Y = 1_{B_n}(\omega_0) \cdots 1_{B_{n+k}}(\omega_k)$. Then $Y \circ \theta_n =$ the indicator function of $\{X_n \in B_n, \dots, X_{n+k} \in B_{n+k}\} = B$. By the markov property,

$$P(B | \mathcal{F}_n) = E_{X_n} Y.$$

Let $\varphi(x) = E_x Y$ then $\varphi(X_n)$ is $\sigma(X_n)$ -measurable mapping. Thus, when B has a form of $\{X_n \in B_n, \dots, X_{n+k} \in B_{n+k}\}$ for some nonnegative integer k ,

$$P(B | \mathcal{F}_n) = P(B | X_n).$$

Note that a collection of such B generates $\sigma(X_n, X_{n+1}, \dots)$.

Now let $\mathcal{G} = \{C : P(C | \mathcal{F}_n) = P(C | X_n)\}$. By putting $B_{n+i} = S$ for $0 \leq i \leq k$, we earn $\Omega_0 \in \mathcal{G}$. If $C, D \in \mathcal{G}$ and $C \subset D$, then by properties of conditional expectation, $D \setminus C \in \mathcal{G}$. If $C_i \in \mathcal{G}$ and $C_i \uparrow C$ then by monotone convergence theorem for conditional expectation, $C \in \mathcal{G}$. Thus \mathcal{G} is a lambda system containing a collection of B 's which generates $\sigma(X_n, \dots)$. Therefore, by Dynkin's theorem, the third equation is satisfied by any $B \in \sigma(X_n, \dots)$. By the first equation, we can derive the conclusion. □

Problem (5.2.4).

First, claim that

$$P_x(X_n = y | T_y = m) = P_y(X_{n-m} = y).$$

This is because

$$\begin{aligned} P_x(X_n = y | T_y = m) &= \frac{P_x(X_n = y, T_y = m)}{P_x(T_y = m)} \\ &= \frac{\int_{T_y=m} 1_{(X_n=y)} dP_x}{P_x(T_y = m)} \\ &= \frac{\int_{T_y=m} E(1_{(X_n=y)} | \mathcal{F}_m) dP_x}{P_x(T_y = m)} \\ &= \frac{\int_{T_y=m} E_{X_m} 1_{(X_{n-m}=y)} dP_x}{P_x(T_y = m)} \\ &= \frac{P_x(T_y = m) P_y(X_{n-m} = y)}{P_x(T_y = m)}. \end{aligned}$$

Now, note that $P_x(X_n = y) = \sum_{m=1}^n P_x(X_n = y, T_y = m)$. From this and

the above discussion,

$$\begin{aligned} p^n(x, y) &= P_x(X_n = y) = \sum_{m=1}^n P_x(X_n = y | T_y = m) P_x(T_y = m) \\ &= \sum_{m=1}^n P_y(X_{n-m} = y) P_x(T_y = m) = \sum_{m=1}^n P_x(T_y = m) p^{n-m}(y, y). \end{aligned}$$

□

Problem (5.2.6).

Fix $x \in S \setminus C$. Since $P_x(T_C = \infty) = \lim_{M \rightarrow \infty} P_x(T_C > M) < 1$, we can choose N_x and ε so that

$$P_x(T_C > M) \leq 1 - \varepsilon$$

whenever $M \geq N_x$. Note that we can choose N_x as an integer. Put $N = \max_{x \in S \setminus C} N_x$. Now we get

$$\begin{aligned} P_y(T_C > 2N) &= \sum_{x \in S \setminus C} P_y(T_C > 2N, T_C > N, X_N = x) \\ &= \sum_{x \in S \setminus C} P_y(T_C > 2N | X_N = x, T_C > N) P_y(X_N = x, T_C > N) \\ &\leq \sum_{x \in S \setminus C} P_x(T_C > N) P_y(X_N = x, T_C > N) \\ &\leq (1 - \varepsilon) \sum_{x \in S \setminus C} P_y(X_N = x, T_C > N) \\ &\leq (1 - \varepsilon)^2. \end{aligned}$$

By induction, the result follows.

Remark 1. By $k \rightarrow \infty$, we can say that $P_y(T_C = \infty) = 0$. That is, $P_y(T_C < \infty) = 1$.

□

Problem (5.2.7).

1. It is similar to the manipulation of problem 5.2.4:

$$\begin{aligned} P_x(V_A < V_B) &= \sum_y P_x(V_A < V_B, X_1 = y) = \sum_y P_x(V_A < V_B | X_1 = y) P_x(X_1 = y) \\ &= \sum_y p(x, y) P_x(V_A < V_B | X_1 = y) = \sum_y p(x, y) P_y(V_A < V_B) \end{aligned}$$

where the first term is $h(x)$ and the last term is $\sum_y p(x, y)h(y)$.

2. I think we must further assume that h is bounded and measurable. For convenience, let $\tau = V_A \wedge V_B = V_{A \cup B}$. By the equation (5.2.2) of our textbook, we get

$$\begin{aligned} E_x(h(X_{n+1})|\mathcal{F}_n) &= \sum_y p(X_n, y)h(y) \\ &= h(X_n) \end{aligned}$$

for $X_n \notin A \cup B$.

Now, put $Y_n = h(X_n)$. Then

$$Y_{n \wedge \tau} - Y_0 = h(X_{n \wedge \tau}) - h(X_0) = \sum_{k=1}^n 1_{(\tau \geq k)} (Y_k - Y_{k-1}).$$

By using the above,

$$\begin{aligned} E_x(Y_{n+1 \wedge \tau} - Y_0|\mathcal{F}_n) &= \sum_{k=1}^{n+1} 1_{(\tau \geq k)} E_x(Y_k - Y_{k-1}|\mathcal{F}_n) \\ &= 1_{(\tau \geq n+1)} (Y_n - Y_0) + 1_{(\tau < n+1)} (Y_\tau - Y_0) \\ &= 1_{(\tau > n)} (Y_n - Y_0) + 1_{(\tau \leq n)} (Y_\tau - Y_0) \\ &= Y_{n \wedge \tau} - Y_0. \end{aligned}$$

So $h(X_{n \wedge \tau})$ is a martingale. Note that the first equality is due to (5.2.2), and the last is due to optional stopping.

3. We assumed that h is bounded. Thus, our martingale is uniformly bounded, so the optional stopping theorem can be applied:

$$x = E_x h(X_0) = E_x h(X_\tau) = E_x [E_x(h(X_\tau)|\mathcal{F}_\tau)]$$

where the last term is equal to

$$E_x [E_{X_\tau} h(X_0)] = E_x [1_{(X_\tau \in A)} + 0 \cdot 1_{(X_\tau \in B)}] = E_x [1_{(X_\tau \in A)}].$$

The above is because $P_x(\tau < \infty) = 1$ and h is 1 on A and 0 on B . Note that this implies the result, since $X_\tau \in A$ is equivalent to $V_A < V_B$.

□

Problem (5.2.8).

Let $\tau = V_0 \wedge V_N$. Then $X_{n \wedge \tau}$ is an uniformly bounded martingale since the state space of X_n is finite. By the optional stopping theorem, we get

$$E_x X_0 = E_x X_\tau$$

where the LHS is equal to x . Note that, by the remark 1, we can say that $P_x(\tau < \infty) = 1$. Then the RHS of the above eqn is equal to $0P_x(V_0 < V_N) + NP_x(V_N < V_0)$. Thus,

$$x = NP_x(V_N < V_0).$$

□

Problem (5.2.11).

1. It is similar to the manipulation of problem 5.2.7:

$$\begin{aligned}
E_x V_A &= \sum_{k \geq 1} P_x(V_A \geq k) \\
&= P_x(V_A \geq 1) + \sum_{k \geq 2} P_x(V_A \geq k) \\
&= 1 + \sum_{k \geq 2} P_x(V_A \geq k) \\
&= 1 + \sum_{k \geq 2} \sum_y P_x(V_A \geq k | X_1 = y) P_x(X_1 = y) \\
&= 1 + \sum_y p(x, y) \sum_{k \geq 2} P_y(V_A \geq k - 1) = 1 + \sum_y p(x, y) E_y V_A
\end{aligned}$$

where $P_x(V_A \geq 1) = 1$ since x lies outside of A .

Also, $E_x V_A < \infty$ because

$$\begin{aligned}
E_x \frac{V_A}{N} &= \sum_{k \geq 1} P_x(V_A \geq kN) \\
&\leq \sum_{k \geq 1} (1 - \varepsilon)^k < \infty.
\end{aligned}$$

2. I think we should assume the measurability, and boundedness of g . By the manipulation used in problem 5.2.7, we get:

$$\begin{aligned}
E_x (g(X_{n+1}) + n + 1 | \mathcal{F}_n) &= n + 1 + \sum_y p(X_n, y) g(y) \\
&= n + g(X_n)
\end{aligned}$$

for $X_n \notin A$.

Now put $Y_n = g(X_n) + n$ and $\tau = V_A$ for convenience. Then

$$\begin{aligned}
E_x (Y_{n+1 \wedge \tau} - Y_0 | \mathcal{F}_n) &= \sum_{k=1}^{n+1} 1_{(\tau \geq k)} E_x (Y_k - Y_{k-1} | \mathcal{F}_n) \\
&= 1_{(\tau \geq n+1)} (Y_n - Y_0) + 1_{(\tau < n+1)} (Y_\tau - Y_0) \\
&= Y_{n \wedge \tau} - Y_0.
\end{aligned}$$

So $X_{n \wedge V_A} + n \wedge V_A$ is a martingale.

3. From the boundedness of g and the fact that V_A is L^1 function, our martingale is uniformly integrable. Thus we can apply optional stopping theorem:

$$E_x g(X_0) = E_x [V_A + g(X_{V_A})]$$

where the first term is $g(x)$ and the second term is $E_x V_A + E_x g(X_{V_A})$. But X_{V_A} lies in A and g is 0 on A . Thus the second term of the equation is $E_x V_A$.

□