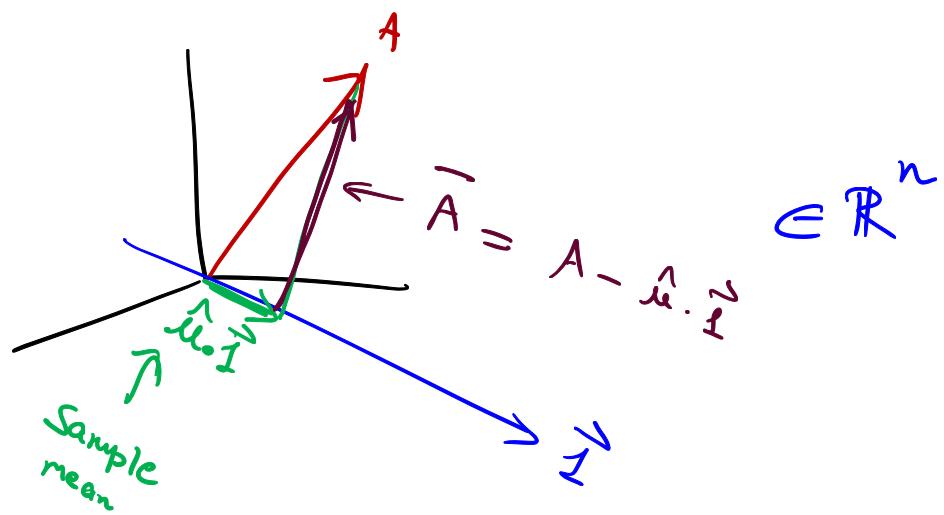


$$\begin{array}{|c} \hline A \\ \hline x_1 \\ x_2 \\ \vdots \\ \vdots \\ x_n \\ \hline \end{array}$$



True Unknown

$$\text{Variance} = \sigma^2 = E[(A - \mu)^2]$$

$$E[g(x)] \rightarrow \int_x g(x) f(x) dx$$

$$\sum_x g(x) P(A=x)$$

mean  
 $g(x) = x$

Variance  
 $g(x) = (x - \mu)^2$

Sqrlk  $\equiv$  standard deviation ( $\sigma$ )

Sample Variance :

$$\hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \hat{\mu})^2$$

(biased estimate)

$$E[\hat{\sigma}^2] \neq \sigma^2$$

$$\text{Unbiased } \hat{\sigma}_u^2 = \frac{1}{n-1} \sum_{i=1}^n (x_i - \hat{\mu})^2 \quad E[\hat{\sigma}_u^2] = \sigma^2$$

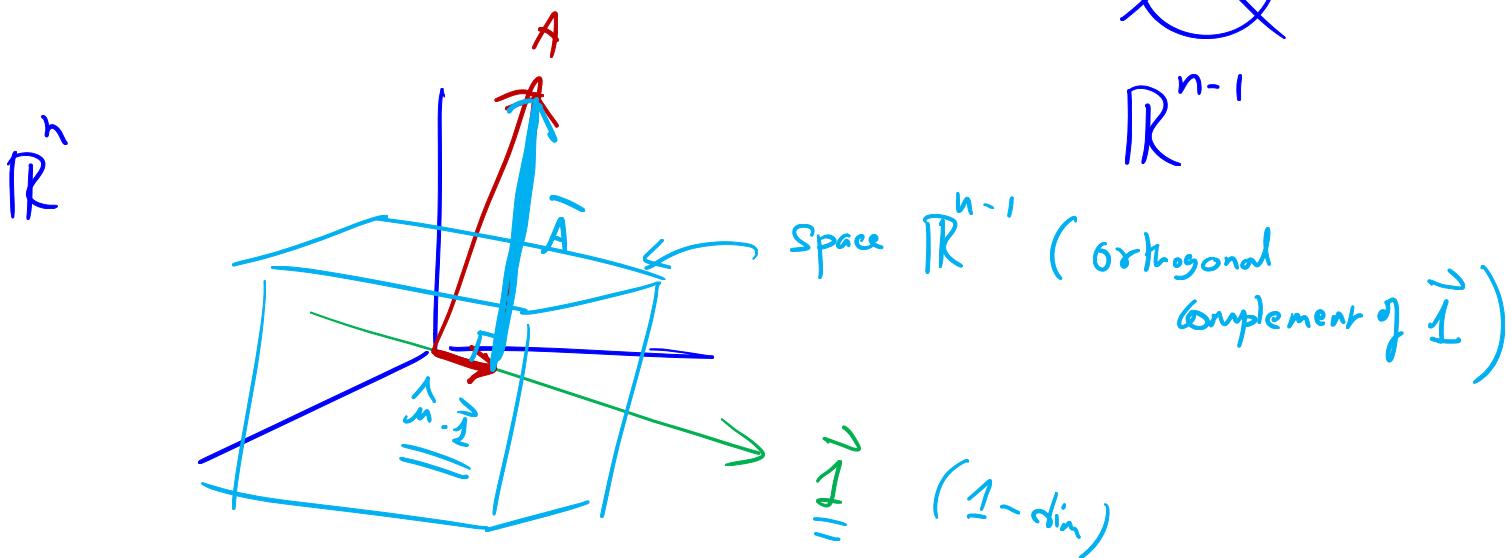
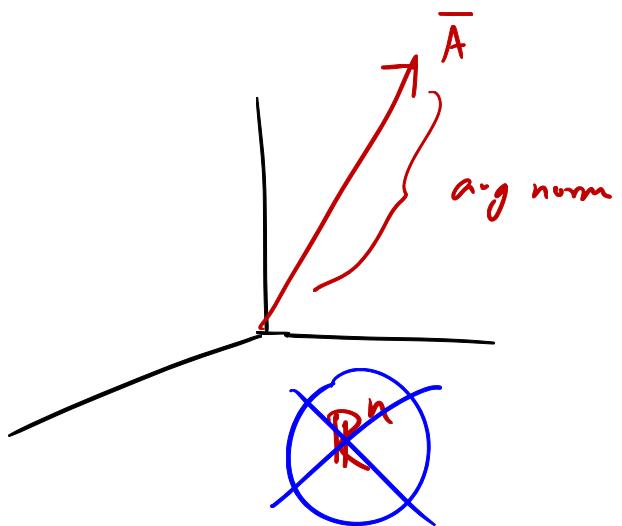
why !!! degrees of freedom

$$\bar{A} = \begin{pmatrix} x_1 - \hat{\mu} \\ x_2 - \hat{\mu} \\ \vdots \\ x_n - \hat{\mu} \end{pmatrix}$$

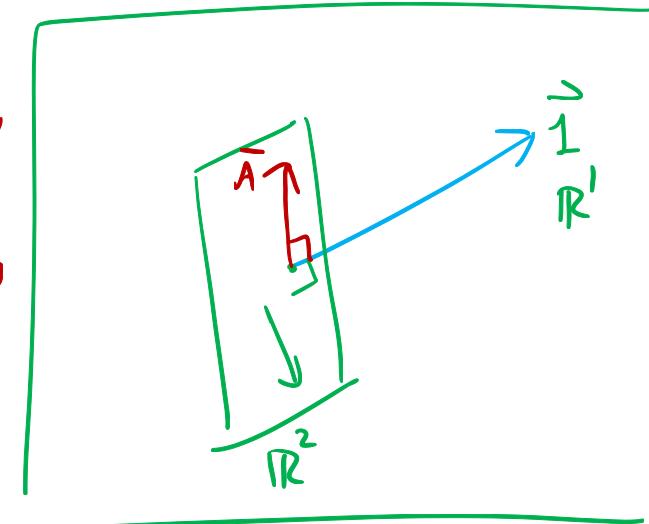
$$\hat{\sigma}^2 = \frac{1}{n} \bar{A}^T \bar{A} = \frac{\bar{A} \cdot \bar{A}}{n}$$

=  $\frac{1}{n} \|\bar{A}\|^2$

norm squared per dim



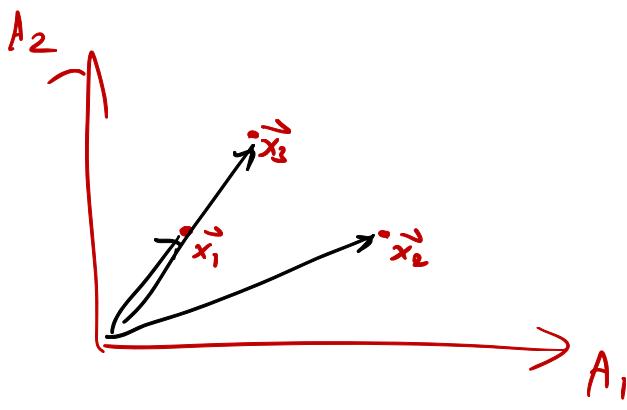
df = degrees of freedom  
≡ dimensionality of the subspace where the r.v. lies



$$\mathbb{R}^3 \equiv \mathbb{R}^n$$

	$A_1$	$A_2$
$\vec{x}_1$	$x_{11}$	$x_{12}$
$\vec{x}_2$	$x_{21}$	$x_{12}$
:	:	
:	:	
$\vec{x}_n$		

$d = 2$



$$A = \begin{pmatrix} A_1 \\ A_2 \end{pmatrix} \text{ bivariate r.v.}$$

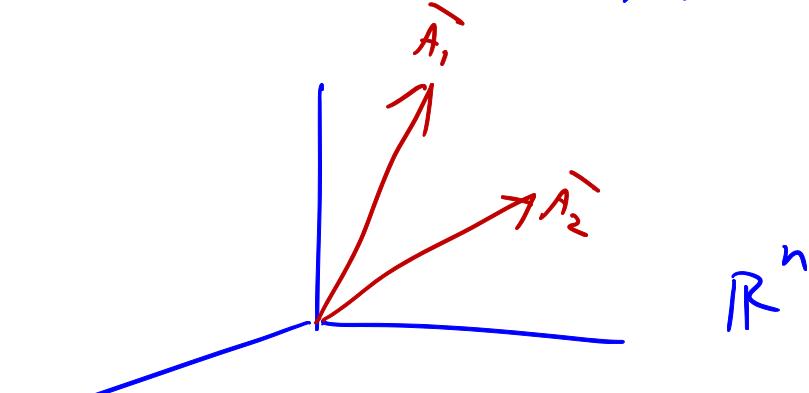
$$E[A] = \begin{pmatrix} E[A_1] \\ E[A_2] \end{pmatrix}$$

Covariance matrix  
2x2 square  
symmetric

$$\Sigma = \begin{pmatrix} \sigma_1^2 & \sigma_{12} \\ \sigma_{12} & \sigma_2^2 \end{pmatrix}$$

Population

$$\hat{\sigma}_{12} = \frac{1}{n} \sum_{i=1}^n (x_{i1} - \hat{\mu}_1)(x_{i2} - \hat{\mu}_2)$$



$$\hat{\tau}_{12} = \frac{1}{n} \bar{A}_1^T \bar{A}_2$$

Sample =

$$\hat{\Sigma} = \begin{pmatrix} \hat{\sigma}_1^2 & \hat{\sigma}_{12} \\ \hat{\sigma}_{12} & \hat{\sigma}_2^2 \end{pmatrix}$$

$\rho_{12}$  = Correlation between  $A_1$  &  $A_2$

$$= \sum_{i=1}^n (x_{i1} - \hat{x}_1)(x_{i2} - \hat{x}_2)$$

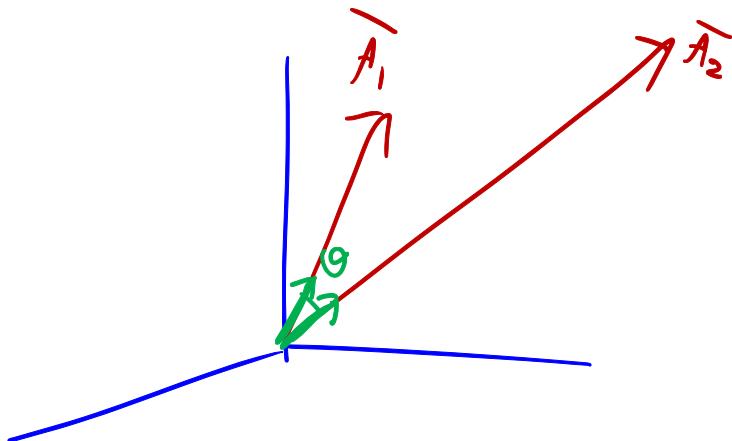
Row-view

$$\frac{\sqrt{\sum_{i=1}^n (x_{i1} - \hat{x}_1)^2}}{\sqrt{\sum_{i=1}^n (x_{i2} - \hat{x}_2)^2}}$$

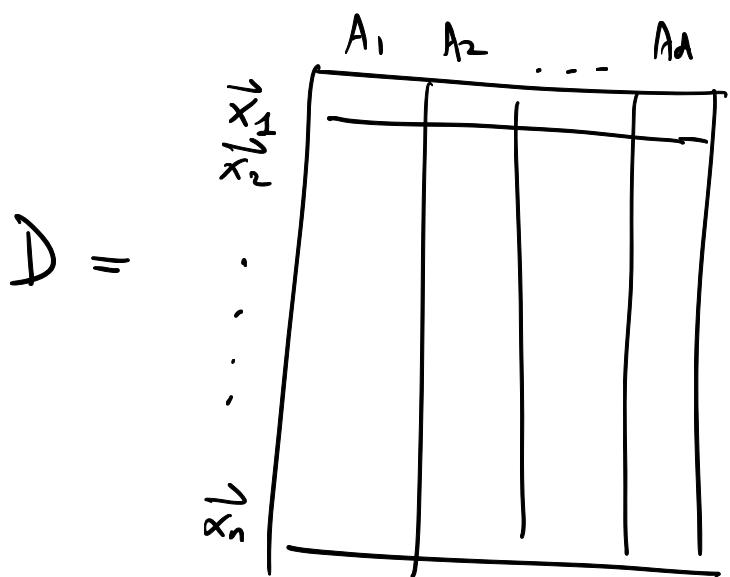
$$= \frac{\sigma_{12}}{\sqrt{\sigma_1^2} \sqrt{\sigma_2^2}} = \frac{\sigma_{12}}{\sigma_1 \cdot \sigma_2} \in [-1, 1]$$

Column-view

$$\rho_{12} = \frac{\cancel{\frac{1}{n}} \bar{A}_1^T \bar{A}_2}{\cancel{\left( \frac{1}{\sqrt{n}} \|\bar{A}_1\| \right)} \cancel{\left( \frac{1}{\sqrt{n}} \|\bar{A}_2\| \right)}} = \underbrace{\left( \frac{\bar{A}_1}{\|\bar{A}_1\|} \right)^T}_{\text{Column vector}} \underbrace{\left( \frac{\bar{A}_2}{\|\bar{A}_2\|} \right)}_{\text{Column vector}} = \cos \theta$$



## d-dimensions



$\vec{x}_i \in \mathbb{R}^d \leftarrow$  # of attributes  
 $A_j \in \mathbb{R}^n \leftarrow$  sample size

$$D \in \mathbb{R}^{n \times d}$$

$$\hat{\mu} \in \mathbb{R}^d$$

$$\boxed{\hat{\mu} = \frac{1}{n} D^T \vec{1}}$$

$$\vec{1} \in \mathbb{R}^n$$

$$\begin{aligned} & (d \times n) \quad (n \times 1) \\ & D^T \\ & \underbrace{\quad \quad \quad}_{d \times 1} \\ & = \frac{1}{n} \left[ \begin{array}{c} A_1^T \\ A_2^T \\ \vdots \\ A_d^T \end{array} \right] \left( \begin{array}{c} 1 \\ \vdots \\ 1 \end{array} \right) \end{aligned}$$

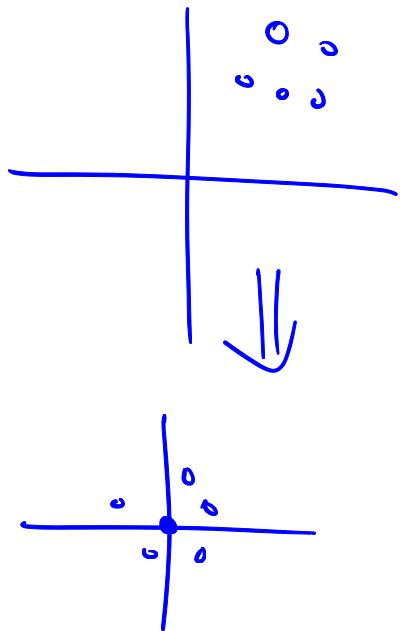
$$\hat{\Sigma} = \begin{pmatrix} \hat{\sigma}_{11}^2 & \hat{\sigma}_{12} & \hat{\sigma}_{13} & \cdots & \hat{\sigma}_{1d} \\ \hat{\sigma}_{21} & \hat{\sigma}_{22}^2 & \hat{\sigma}_{23} & \cdots & \hat{\sigma}_{2d} \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ \hat{\sigma}_{d1} & \hat{\sigma}_{d2} & \cdots & \hat{\sigma}_{d(d-1)} & \hat{\sigma}_{dd}^2 \end{pmatrix} = \left\{ \hat{\sigma}_{ij} \right\}_{i,j=1,\dots,d}$$

Inner-product form

$$\bar{D} = D - \underbrace{\mathbf{1}}_{n \times d} \cdot \underbrace{\hat{\mu}^T}_{n \times 1} \quad \text{1} \times d$$

centered data matrix

$$\hat{\Sigma} = \frac{\bar{D}^T \bar{D}}{n} \quad \text{(all pairwise dot-product)}$$



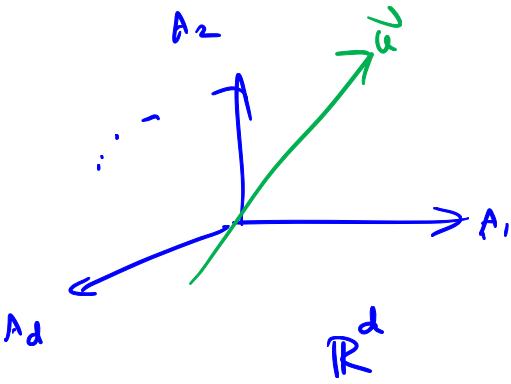
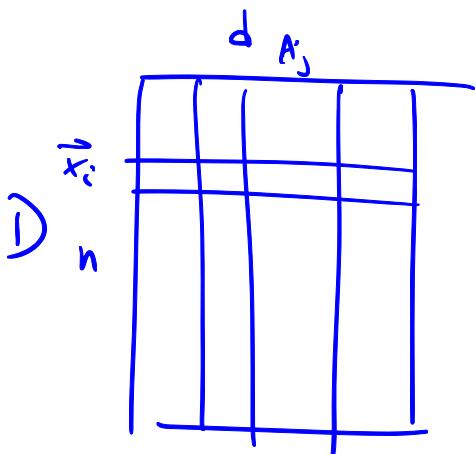
Outer-product form

$$\hat{\Sigma} = \frac{1}{n} \sum_{i=1}^n \underbrace{(\vec{x}_i)}_{d \times 1} \underbrace{(\vec{x}_i)^T}_{1 \times d} \quad \text{d \times d}$$

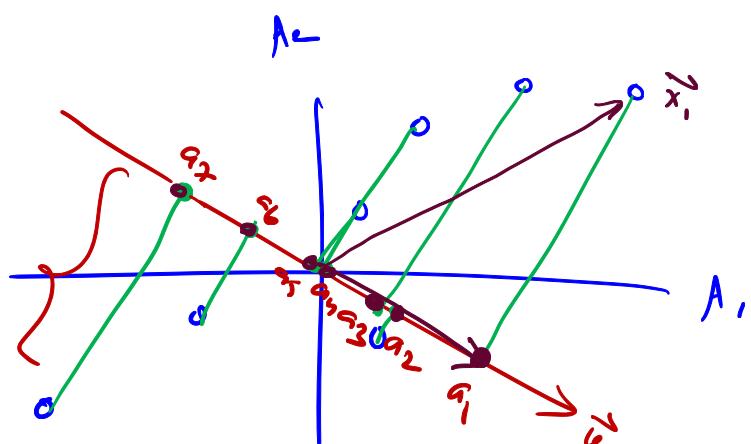
$$\vec{x}_i \rightarrow \vec{\bar{x}}_i = \vec{x}_i - \vec{\hat{\mu}}$$

↑  
(centered)  
point

$$\hat{\Sigma} = \boxed{\vec{x}_1 \vec{x}_1^T} + \boxed{\vec{x}_2 \vec{x}_2^T} + \boxed{\vec{x}_3 \vec{x}_3^T} + \cdots + \boxed{\vec{x}_d \vec{x}_d^T}$$



"good" direction / attribute (constructed)



1) Center data  
 $\bar{D}$

$$\text{Proj}_{\vec{u}} (\vec{x}_i) \cdot \vec{u} = \left( \frac{\vec{x}_i^T \vec{u}}{\vec{u}^T \vec{u}} \right) \vec{u}$$

Scalar projection

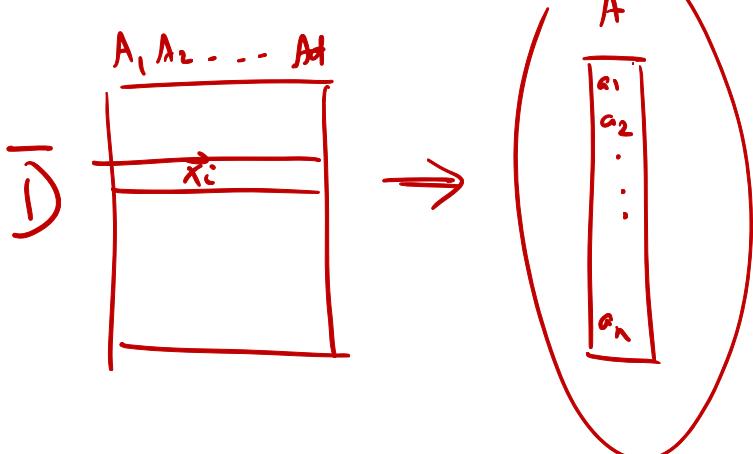
all centered already ( $\vec{x}_i \equiv \vec{x}_i^c$ )

$$a_i^c = \text{Proj}_{\vec{u}} (\vec{x}_i^c)$$

2)  $\vec{u}$  is unit vector

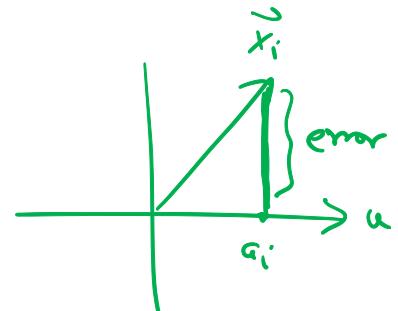
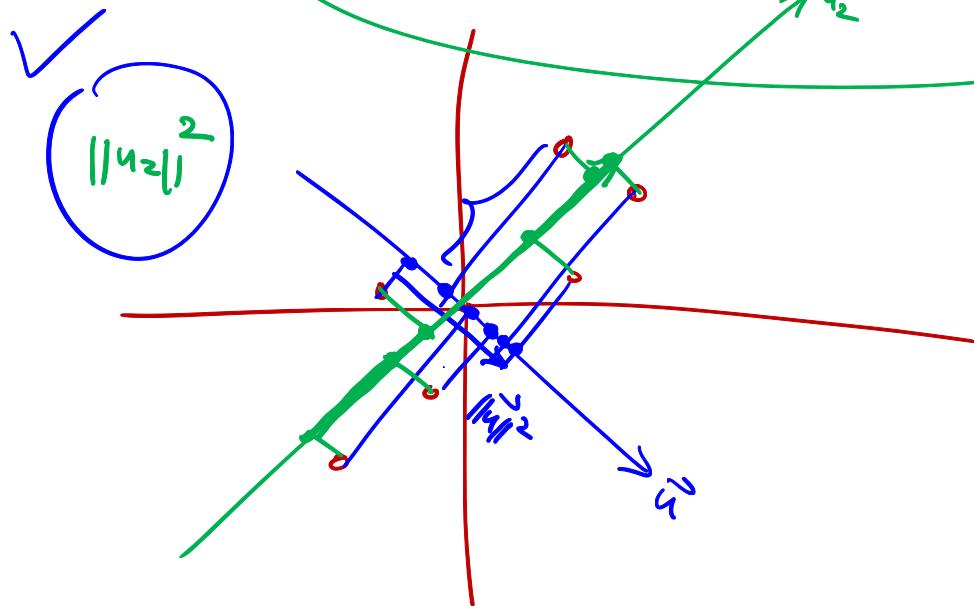
$$\|\vec{u}\|^2 = 1$$

$$\vec{u}^T \vec{u} = 1$$



Objective:

- 1) Maximize Variance
- 2) minimize the <sup>squared</sup> error (sum over all points)



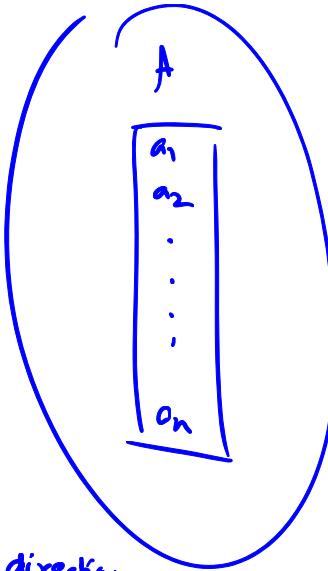
find  $\vec{u}$  that maximizes projected variance

$$1) \vec{u}^\top \vec{u} = 1$$

$$2) a_i = \text{Proj}_{\vec{u}} (\vec{x}_i) \\ = \frac{\vec{u}^\top \vec{x}_i}{\vec{u}^\top \vec{u}}$$

$$\sigma_u^2 = \frac{1}{n} \sum_{i=1}^n (a_i - \bar{a})^2$$

$\bar{a}$  along  $\vec{u}$  direction  
= zero



all projected points  
(along  $\vec{u}$ )

find  $\vec{u}$   $\sigma_u^2 = \frac{1}{n} \sum_{i=1}^n a_i^2 \rightarrow$  maximize

$J = \max_{\vec{u}} \sigma_u^2$

← scalar value

$$\hat{\sigma}_e^2 = \frac{1}{n} \sum_{i=1}^n a_i^2 = \frac{1}{n} \sum_{i=1}^n (\underline{\hat{u}}^T \underline{x}_i)^2$$

$$= \frac{1}{n} \sum_{i=1}^n (\underline{\hat{u}}^T \underline{x}_i) (\underline{\hat{u}}^T \underline{x}_i)^T$$

$$= \frac{1}{n} \sum_{i=1}^n (\underline{\hat{u}}^T \underline{x}_i) (\underline{x}_i^T \underline{\hat{u}})$$

$$= \underline{\hat{u}}^T \left( \underbrace{\frac{1}{n} \sum_{i=1}^n \underline{x}_i \underline{x}_i^T}_{\Sigma} \right) \underline{\hat{u}}$$

$$\hat{\sigma}_e^2 = \underline{\hat{u}}^T \underbrace{\Sigma}_{\text{quadratic form}} \underline{\hat{u}}$$

$\Sigma$  = covariance matrix of  $D$

$\underline{\hat{u}}$  is unknown  
infinite choices

"Random projections"

$$J = \max_{\underline{\hat{u}}} \underbrace{\underline{\hat{u}}^T \Sigma \underline{\hat{u}}}_{\text{quadratic form}}$$

$$\boxed{\text{Subject to } \underline{\hat{u}}^T \underline{\hat{u}} = 1}$$

$$\underline{\hat{u}} = \mathbb{R}^d = \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_d \end{pmatrix}$$

Constrained optimization

$$\nabla_{\underline{\hat{u}}} = \boxed{\frac{\partial J}{\partial \underline{\hat{u}}} = 0}$$

try to solve for  $\underline{\hat{u}}$   $\rightarrow$  closed form

iterative gradient method

$$\underset{\underline{\hat{u}}}{\text{Mg}} \quad J = \underline{\hat{u}}^T \Sigma \underline{\hat{u}} - \alpha (\underline{\hat{u}}^T \underline{\hat{u}} - 1) \quad \leftarrow \text{unconstrained}$$

Lagrange multiplier

$$\frac{\partial J}{\partial \vec{u}} = 2 \sum \vec{u} - \alpha \cdot 2 \vec{u} = 0$$

$$\Rightarrow \boxed{\sum \vec{u} = \alpha \vec{u}}$$

$$\left[ \begin{array}{l} \vec{u}^T \vec{u} = (\vec{u})^2 \\ \sum \vec{u}^T \vec{u} = \vec{u}^T \sum \vec{u} \\ \sum \vec{u}^2 \end{array} \right]$$

Special equation : eigenvalue & eigenvectors of  $\sum \vec{u}$   
 $\alpha$  &  $\vec{u}$

the direction that maximize the proj variance is  $\vec{u}$ ,  
 the eigenvector corresponding to the (largest) eigenvalue  $\alpha$  of  $\sum \vec{u}$

$$\vec{u}^T \sum \vec{u}$$

$$(u_1 u_2 \dots u_d) \begin{bmatrix} d \times d \\ \Sigma \end{bmatrix} \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_d \end{pmatrix} = \sum_{i=1}^d \sum_{j=1}^d u_i \sigma_{ij} u_j$$





