Machine Learning from Data CSCI 4100

Assignment 6

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Exercise 3.4

a) Given $y = w^{*T}X + \epsilon$, and from LFD pg.86, $\hat{y} = X(X^TX)^{-1}X^Ty$. Substituting y, we get

$$\hat{y} = X(X^T X)^{-1} X^T (w^{*T} X + \epsilon)$$

$$= X(X^T X)^{-1} X^T (X w^* + \epsilon)$$

$$= X(X^T X)^{-1} (X^T X) w^* + X(X^T X)^{-1} X^T \epsilon$$

$$= X w^* + X(X^T X)^{-1} X^T \epsilon$$
and we know $H = X(X^T X)^{-1} X^T$ from LFD (3.6), so
$$= X w^* + H \epsilon$$

b) $\hat{y} - y = (Xw^* + H\epsilon) - (Xw^* + \epsilon) = H\epsilon - \epsilon = (H - I)\epsilon$ So, the matrix of interest is (H - I)

c)

$$E_{in}(w_{lin}) = \frac{1}{N} ||\hat{y} - y||^2$$
$$= \frac{1}{N} ||(H - I)\epsilon||^2$$
$$= \frac{1}{N} \epsilon^T (H - I)^T \cdot (H - I)\epsilon$$

From Exercise 3.3 a and c, we can take a couple of facts; $H = X(X^TX)^{-1}X^T$ and it is symmetric, also $(I - H)^K = I - H$. With these in mind,

$$= \frac{1}{N} \epsilon^{T} (H - I)^{T} (H - I) \epsilon$$

$$= \frac{1}{N} \epsilon^{T} (H - I)^{T} (H - I) \epsilon$$

$$= \frac{1}{N} \epsilon^{T} (H - I)^{2} \epsilon$$

$$= \frac{1}{N} \epsilon^{T} (I - H)^{2} \epsilon$$

$$= \frac{1}{N} \epsilon^{T} (I - H) \epsilon$$

d)

$$\mathbb{E}_{\mathcal{D}}[E_{in}(w_{lin})] = \mathbb{E}_{D} \left[\frac{1}{N} \epsilon^{T} (I - H) \epsilon \right]$$

$$= \mathbb{E}_{D} \left[\frac{1}{N} \epsilon^{T} \epsilon - \frac{1}{N} \epsilon^{T} H \epsilon \right]$$

$$= \mathbb{E}_{D} \left[\frac{1}{N} \epsilon^{T} \epsilon \right] - \mathbb{E}_{D} \left[\frac{1}{N} \epsilon^{T} H \epsilon \right]$$

$$= \frac{1}{N} \mathbb{E}_{D}[\epsilon^{T} \epsilon] - \frac{1}{N} \mathbb{E}_{D}[\epsilon^{T} H \epsilon]$$

 ϵ is a noise term with zero mean and σ^2 variance, defined by the problem. We know that $\mathbb{E}_{\mathcal{D}}\left[\epsilon^T\epsilon\right]$ term is equal to $N\sigma^2$.

 $\mathbb{E}_{\mathcal{D}}\left[\epsilon^T H \epsilon\right] = \sigma^2 \cdot tr(H)$. $\epsilon^T H \epsilon$ forms a diagonal matrix composed of σ^2 's and H, since ϵ is independent with zero mean and σ^2 variance.

Trace of H is given as (d+1) from **Exercise 3.3** (c)

$$\therefore \mathbb{E}_{\mathcal{D}}\left[\epsilon^T H \epsilon\right] = \sigma^2 (d+1).$$

So,

$$\mathbb{E}_{\mathcal{D}}[E_{in}(w_{lin})] = \frac{1}{N} \mathbb{E}_{\mathcal{D}}[\epsilon^{T} \epsilon] - \frac{1}{N} \mathbb{E}_{\mathcal{D}}[\epsilon^{T} H \epsilon]$$

$$= \frac{1}{N} (N\sigma^{2} - \sigma^{2}(d+1))$$

$$= \sigma^{2} - \frac{\sigma^{2}}{N}(d+1)$$

$$= \sigma^{2}(1 - \frac{d+1}{N}) \text{ for } N \ge d+1$$

e)

$$\mathbb{E}_{\mathcal{D},\epsilon'}[E_{test}(w_{lin})] = \mathbb{E}_{\mathcal{D},\epsilon'}\left[\frac{1}{N}\|H\epsilon - \epsilon'\|^{2}\right]$$

$$= \frac{1}{N}\mathbb{E}_{\mathcal{D},\epsilon'}\left[\|H\epsilon - \epsilon'\|^{2}\right]$$

$$= \frac{1}{N}\mathbb{E}_{\mathcal{D},\epsilon'}\left[(H\epsilon - \epsilon')^{T}(H\epsilon - \epsilon')\right]$$

$$= \frac{1}{N}\mathbb{E}_{\mathcal{D},\epsilon'}\left[((\epsilon^{T}H^{T})H\epsilon - (\epsilon^{T}H^{T})\epsilon' - (\epsilon')^{T}H\epsilon + (\epsilon')^{T}\epsilon'\right]$$

because H is symmetric, $H^TH = H^2 = H \dots$ according to **Exercise 3.3**(a), (b).

$$= \frac{1}{N} \mathbb{E}_{\mathcal{D},\epsilon'} \left[(\epsilon^T H^T H \epsilon - \epsilon^T H^T \epsilon' - (\epsilon')^T H \epsilon + (\epsilon')^T \epsilon' \right]$$

$$= \frac{1}{N} \mathbb{E}_{\mathcal{D},\epsilon'} \left[(\epsilon^T H \epsilon - \epsilon^T H^T \epsilon' - (\epsilon')^T H \epsilon + (\epsilon')^T \epsilon' \right]$$

$$= \frac{1}{N} \mathbb{E}_{\mathcal{D},\epsilon'} \left[(\epsilon^T H \epsilon - \epsilon^T H^T \epsilon' - (\epsilon^T H^T \epsilon')^T + (\epsilon')^T \epsilon' \right]$$

$$\dots$$

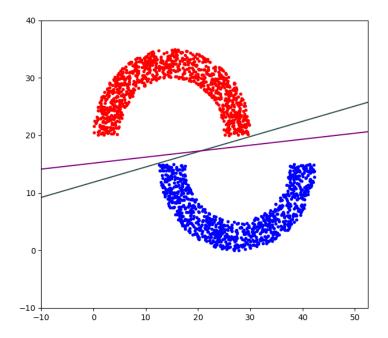
$$= \frac{1}{N} \times \left\{ \mathbb{E}_{\mathcal{D},\epsilon'} [\epsilon^T H \epsilon] + \mathbb{E}_{\mathcal{D},\epsilon'} [-\epsilon^T H^T \epsilon'] + \mathbb{E}_{\mathcal{D},\epsilon'} [-(\epsilon^T H^T \epsilon')^T] + \mathbb{E}_{\mathcal{D},\epsilon'} [(\epsilon')^T \epsilon'] \right\}$$

$$= \frac{1}{N} \times \left\{ \sigma^2 (d+1) + 0 + 0 + N \sigma^2 \right\}$$

$$= \sigma^2 \left(1 + \frac{d+1}{N} \right)$$

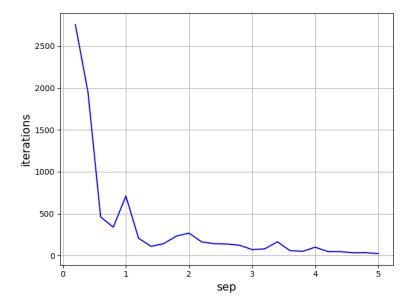
Problem 3.1

a) w = [-866, -19.31, 73.02]. PLA is shown in slate gray.



b) w = [-1.19182, -0.00816, 0.07856]. Linear regression is shown in purple. We can see that linear regression can be used for classification, like PLA. Both PLA and Linear regression separated all the data points. Also, w_{lin} could be a good approximation for the perceptron model.

Problem 3.2



With sep in the range of $\{0.2, 0.4, ..., 5\}$, we generate 2,000 examples and run the PLA starting with $\mathbf{w} = \mathbf{0}$. We can see that the number of iterations quickly converges to a certain level. This is in agreement with what we had shown from **Problem 1.3** (e) in homework 2, and that is

$$t \le \frac{R^2 ||\mathbf{w}^*||^2}{\rho^2}.$$

Here, ρ increases as sep increases, making the upper bound smaller. If sep gets bigger, it means that the distance between the double-semi-circle increases, which allows for less iterations to take place before PLA converges.

Problem 3.8

Given $E_{out}(h) = \mathbb{E}[h(x) - y)^2]$, we have

$$E_{out}(h) = \mathbb{E}[h(x) - y)^{2}]$$

$$= \mathbb{E}[(h(x) - y - h^{*}(x) + h^{*}(x))^{2}]$$

$$= \mathbb{E}[((h(x) - h^{*}(x)) + ((h^{*}(x) - y))^{2}]$$

$$= \mathbb{E}[(h(x) - h^{*}(x))^{2} + (h^{*}(x) - y)^{2} + 2(h(x) - h^{*}(x))(h^{*}(x) - y)]$$

$$= \mathbb{E}[(h(x) - h^{*}(x))^{2}] + \mathbb{E}[(h^{*}(x) - y)^{2}] + 2\mathbb{E}[(h(x) - h^{*}(x))(h^{*}(x) - y)]$$

Looking at the last term $2\mathbb{E}[(h(x) - h^*(x))(h^*(x) - y)]$, we can see that

$$2\mathbb{E}[(h(x) - h^*(x))(h^*(x) - y)] = 2 \times \mathbb{E}[(h(x) - h^*(x))] \times \mathbb{E}[(h^*(x) - y)|x]$$

The last term $\mathbb{E}[(h^*(x) - y)|x]$ can be rewritten as, and using $h^*(x) = \mathbb{E}[y|x]$ given by the problem

$$\mathbb{E}[(h^*(x) - y)|x] = \mathbb{E}[h^*(x)|x] - \mathbb{E}[y|x] = h^*(x) - h^*(x) = 0$$

So, we find that

$$E_{out}(h) = \mathbb{E}\left[\underbrace{(h(x) - h^*(x))^2}_{\text{non-negative}}\right] + \mathbb{E}\left[\underbrace{(\mathbf{h}^*(\mathbf{x}) - y)^2}_{\text{non-negative}}\right]$$

From this, we can see that out of all the hypotheses, $h^*(x)$ is the one that will minimize $E_{out}(h)$.

Given $y = h^*(x) + \epsilon(x)$,

$$y = h^*(x) + \epsilon(x)$$

$$\downarrow \downarrow$$

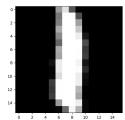
$$\mathbb{E}[y] = \mathbb{E}[h^*(x)] + \mathbb{E}[\epsilon(x)]$$

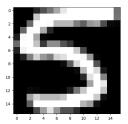
$$\mathbb{E}[y|x] = \mathbb{E}[h^*(x)|x] + \mathbb{E}[\epsilon(x)|x]$$

$$h^*(x) = h^*(x) + \mathbb{E}[\epsilon(x)|x]$$

$$0 = \mathbb{E}[\epsilon(x)]$$

Handwritten Digits a)





b)Let image[i][j] define the intensity of the pixel location in an image size of (16×16) . Then the average intensity is given as

$$intensity_val = \frac{1}{256} \sum_{i=0}^{15} \sum_{j=0}^{15} image[i][j]$$

Vertical symmetry is defined as

$$symmetry_val = \frac{1}{256} \sum_{i=0}^{7} \sum_{j=0}^{15} |image[i][j] - image[15 - i][j]|$$

c)

