

We can now perform the elementary integral:

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$$\int \frac{c \, du}{\sqrt{u^2 - c^2}} = x + \delta = c \cosh^{-1}\left(\frac{u}{c}\right)$$

$$\Rightarrow u(x) = c \cosh\left(\frac{x+\delta}{c}\right), \sim \text{"Catenary"}$$

We can fix c & δ by $u(a) = \alpha$ and $u(b) = \beta$

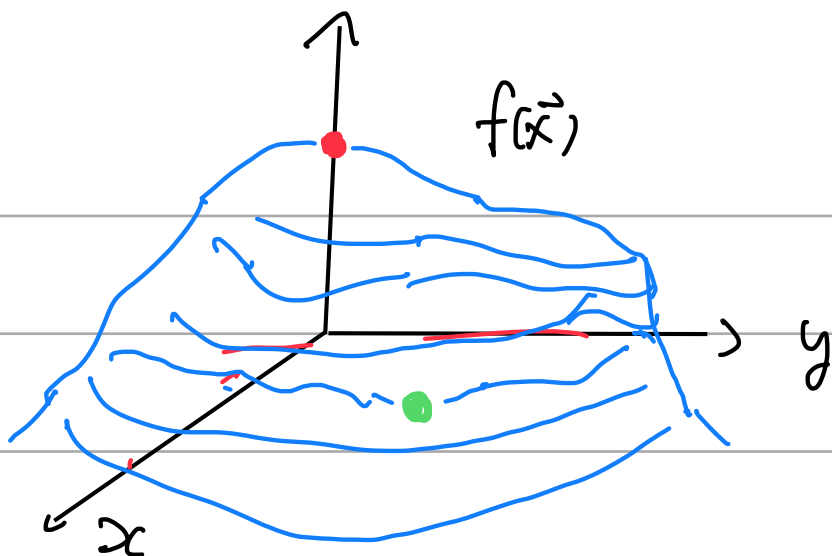
Variation with Constraints and Lagrangian Multiplier

We also mentioned earlier in isoperimetric problem that we sometimes need to consider variational problem subjected to certain constraints. To deal with these, we can introduce "Lagrangian Multiplier".

Before functional, think about extremizing a function

$$\begin{array}{l} f(\vec{x}) \\ \vec{x} \in \mathbb{R}^n \end{array} \quad \text{subjected to some constraint. } g(\vec{x}) = C$$

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e.g. Both red & green dots are extrema, but if we impose constraint $x^2 - y^2 = 0$ only red is allowed.

At extrema, we have $df = d\vec{x} \cdot \vec{\nabla} f(\vec{x}) = 0$

Now with constraint $g(\vec{x}) = C$ which defines a surface, only $d\vec{x}$ on such a surface is allowed.

$\Rightarrow \vec{\nabla} f(\vec{x})$ is perpendicular \perp to $g(\vec{x}) = C$

equivalently parallel \parallel to its normal vector $\vec{\nabla} g(\vec{x})$

For extrema we need

$$\vec{\nabla}(f(\vec{x}) - \lambda g(\vec{x})) = \vec{0} \quad \sim n \text{ equations}$$

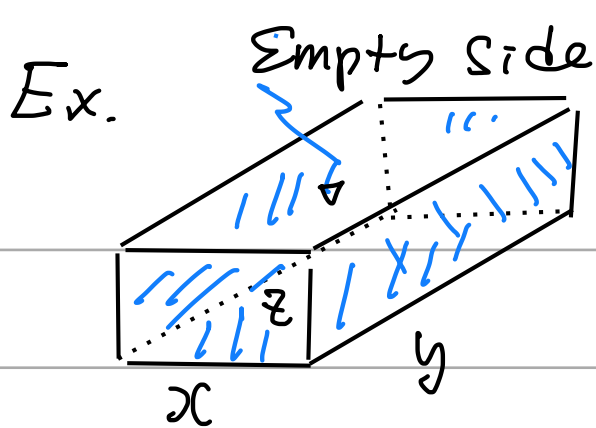
λ some undetermined real number

With one more constraint equation: $g(\vec{x}) = C$

\Rightarrow We can view this as imposed by treating also as a variable, extremizing with respect to λ in

$$\phi(\vec{x}, \lambda) = f(\vec{x}) - \lambda(g(\vec{x}) - C) \quad (\sim n+1 \text{ variables})$$

$$\frac{\partial \phi}{\partial \lambda} = g(\vec{x}) - C = 0$$



Open
 A box with width & length and height (x, y, z) , its volume is fixed at $\frac{L^3}{2}$, find (x, y, z) which Minimise its surface area?

$$V = xyz = \frac{L^3}{2}, \quad A(x, y, z) = xy + 2xz + 2yz$$

\int volume \nearrow fixed \int surface area \searrow only one bottom no top

So we need consider

$$\phi(x, y, z, \lambda) = A(x, y, z) - \lambda \left(xyz - \frac{L^3}{2} \right)$$

Constraint

$$= 2z(x+y) + xy - \lambda \left(xyz - \frac{L^3}{2} \right)$$

Extremizing w.r.t z : $0 = 2(x+y) - \lambda xy \Rightarrow \lambda = \frac{2(x+y)}{xy}$

\therefore w.r.t. x : $0 = 2z + y - \lambda yz = \frac{y}{x} (x - 2z) \Rightarrow x = 2z$

\therefore w.r.t. y : $0 = 2z + x - \lambda xz = \frac{x}{y} (y - 2z) \Rightarrow y = 2z$

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Now we have $(x, y, z) = (2z, 2z, z)$

Finally, varying with respect to λ :

$$xyz = 4z^3 = \frac{L^3}{2} \Rightarrow \frac{L}{2} = z$$

\Rightarrow This can be checked by directly solving the constraint $z = \frac{L^3}{2} \frac{1}{xy}$ and perform minimization.

Now if we extend our analysis to functionals, so we like to extremize some functional $J[u]$, subjected to constraint $P[u] = C$ Functional also

So we construct:

$$\Phi[u, \lambda] = J[u] - \lambda(P[u] - C)$$

and extremize w.r.t λ & $u(x) \Rightarrow \lambda$ imposes

(w.r.t = With respect to) $P[u] = C$

Consider isoperimetric problem :

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$$A[u] = \oint_C x(s) \frac{dy}{ds} ds, \quad P[u] = \oint_C ds \sqrt{\left(\frac{dx}{ds}\right)^2 + \left(\frac{dy}{ds}\right)^2}$$

$$\Rightarrow \Phi[u, \lambda] = \oint_C ds \left(x(s) \frac{dy}{ds} - \lambda \left(\sqrt{\left(\frac{dx}{ds}\right)^2 + \left(\frac{dy}{ds}\right)^2} - 1 \right) \right)$$

$$= \oint dy \left(\underbrace{x(y) - \lambda \sqrt{1 + \left(\frac{dx}{dy}\right)^2}}_{L} \right) + \lambda l$$

$L \sim$ No explicit y dependence

$$x' = \frac{dx}{dy}$$

From 1st integral earlier, we can deduce

$$\text{Constant} = -\left(x - \lambda \sqrt{1 + (x')^2}\right) + x' \frac{\partial L}{\partial x'}$$

$$= \frac{\lambda}{\sqrt{1 + (x')^2}} - x(y) \Rightarrow (x')^2 = \frac{\lambda^2}{(x - x_0)^2} - 1$$

Some Constant

$$\Rightarrow \frac{dx}{dy} = \frac{\lambda^2 - (x - x_0)^2}{(x - x_0)^2} \Rightarrow x = x_0 \pm \sqrt{\lambda^2 - (y - y_0)^2}$$

Some other Constant

$$\text{We get } (x - x_0)^2 + (y - y_0)^2 = \lambda^2 = L^2 \quad \leftarrow \text{obtained from } \lambda - \text{E.O.M.}$$