Jaeseok Park

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Summary

My main interest lies at SLAM(visual, sensor fusion,), visual localization and robotics mathmetics.

My favourite applications are autonomous driving and logistics.

I am a self motivated person.

EMPLOYMENT

• Motion2AI Seoul, South Korea 2021.02.08 - Present

Robotics Researcher (Full-time)

- o Development server side graph optimization application using Ceres.
- Development lidar mapping backpack.
- FAST feature extractor and FAST feature tracker using CUDA
- Development firmware and device management application

• Helper Robotics

Intern (Full-time)

Seoul, South Korea 2020.12.01 - 2021.02.05

• Development multi robot path planning using Dijkstra algorithm.

Projects

• Drowsiness Recognition Smart Stand

AI Makerthon 3rd Place

o Drowsiness Recognition

Key achievements:

- 1. Face Detection Based on haar cascade classifier
- 2. Eye Detection Based on DNN Model
- 3. Drowsiness Detection Based on eye edge detected result
- LED brightness control using photo resistor

• Mobile Robot Control

Mobile Robot Control uisng joy stick

- BLDC Motor Control using MODBUS protocol based motor driver
- Development joy stick controller
- o Development External PID Contoller for unstable driving of mobile robot
- o Mobile Robot Control Algorithm

• Wheel Detection for parking robot

Key Technology Development Project for Robot Industry in Korea

SKILLS

- **Programming** C/C++, Firmware side C, CUDA, Python, php
- Libraries ROS, GTSAM, Ceres, Qt, HAL(Firmware)
- Some skills SLAM(Visual-Inertial, Lidar-Inertial), Visual Localization, Firmware, Robotics mathmetics

EDUCATION

• Tech University Of Korea(TUK)

Electrical Engineering [B.A] 3.04/4.5

Siheung, South Korea 2016.03.01 - Present

o 2020 Second Semester Grade Scholarship D-1

RESEARCH EXPERIENCES

• Inteligence Healthcare LAB(IH LAB), Tech University Of Korea(TUK)

Undergraduate research student (Advisor: Eung-Hyuk Lee)

Siheung, South Korea 2019.01 - 2020.10