## Neural Networks: Tensorflow model operation

#### Andrzej Kordecki

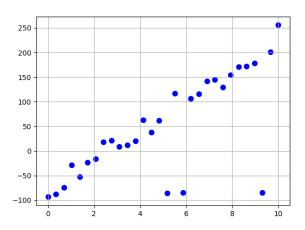
Neural Networks for Classification and Identification (ML.EM05): Exercise 11
Division of Theory of Machines and Robots
Institute of Aeronautics and Applied Mechanics
Faculty of Power and Aeronautical Engineering
Warsaw University of Technology

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### Examples of network models

#### Linear regression task:



Dataset generation and standardization:

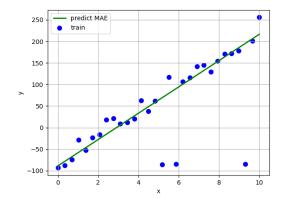
```
# Generate regression dataset
X = np.linspace(0, 10, 30)
Y = 2 * X + 4*np.random.rand(np.size(X))-2
X = X.reshape(-1, 1)
Y = Y.reshape(-1, 1)
# Data scaling
Y = (Y - np.mean(Y))/np.std(Y)
```

Building and training of neural network model:

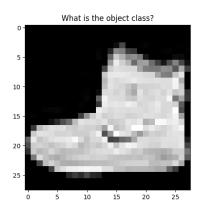
```
# Define model
model = tf.keras.Sequential([
    tf.keras.layers.Dense(1, activation='linear',
                           input_shape=(1, ))
])
# Set training parameters
model.compile(optimizer='SGD',
              loss=tf.keras.losses.MAE)
# Train model
model.fit(X, Y, epochs=1000)
```

Predicting model results:

```
predX1 = np.linspace(min(X), max(X), 100)
predY1 = model.predict(predX1)
```



#### Image classification task:



#### Image dataset - MNIST dataset:



Dataset loading and normalization:

```
train_images = train_images / 255.0
test_images = test_images / 255.0
```

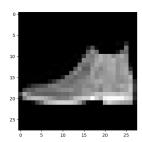
```
Building and training of neural network model:
model = tf.keras.Sequential([
    tf.keras.layers.Flatten(input_shape=(28, 28)),
    tf.keras.layers.Dense(128, activation='relu'),
    tf.keras.layers.Dense(10, activation=None)
1)
model.summary()
model.compile(optimizer='adam',
              loss=tf.keras.losses
                     .SparseCategoricalCrossentropy(
                         from_logits=True),
              metrics=['accuracy'])
```

Model evaluation on train and test dataset:

```
test_loss, test_acc = model.evaluate(test_images,
                           test_labels, verbose=2)
print('\nTest accuracy:', test_acc)
# Prints:
Test accuracy: 0.8813999891281128
# But, the training accuracy is:
Epoch 10/10
1875/1875 [============ ] - 3s 1ms/step
- loss: 0.2388 - accuracy: 0.9109
```

#### Model predictions:

```
# Input size of image must mach input size of model
# t_image.shape = (1,28,28) and image size = (28,28)
t_image = np.expand_dims(test_images[0, :, :], axis=0)
t_label = test_labels[0]
```



Model predictions with logits:

```
prediction = model.predict(t_image)
print(f"Logits: Prediction = {prediction},
      Label = {t label}")
print(f"Prediction = {class_names[np.argmax(prediction)]
      label = {class names[t label]}")
# Prints:
Logits: Prediction = [[-8.693618 -10.190063]
-11.337278 -11.141912 -9.663246 -2.8053892
-8.676396 2.8095415 -10.380032
                                    6.2661247]],
Label = 9
Prediction = Ankle boot, label = Ankle boot
```

Attach a softmax layer to convert the logits to probabilities:

Do we need to train model again?

The softmax layer rescales the outputs, so that the activations sum to 1 and all of them lie between 0 and 1:

$$y_k = \frac{\exp(v_k)}{\sum_k \exp(v_k)}$$

Model predictions with Softmax layer:

```
# Prints:

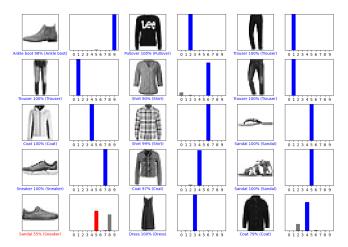
Logits: Prediction = [[3.0869717e-07 6.9124908e-08 2.1948530e-08 2.6684052e-08 1.1706536e-07 1.1136732e-04 3.1405943e-07 3.0569704e-02 5.7165298e-08 9.6931803e-01]], Label = 9 Prediction = Ankle boot, label = Ankle boot
```

predictions = probability\_model.predict(test\_images)

print(f"Softmax: Prediction = {prediction},

Label = {t label}")

Evaluation of model on test dataset.



# Improving model evaluation and training

Results evaluation general approach:

- Test model after training on new data (at least validation data)
- Checking loss/measures value training history.

To evaluate the inference-mode loss and metrics for the data provided with use tensorflow function:

```
eval_model = model.evaluate(test_images, test_labels)
print(f"Model evaluation = {eval_model}")
```

- # Prints information about loss and accuracy
- # measures used in training:
- # Model evaluation =
  - **‡** [0.41732025146484375, 0.8860999941825867]

Results evaluation from training history - Part 1. We will include information about validation data:

If we have one set we can use on of function arguments to split dataset into training and validation set.

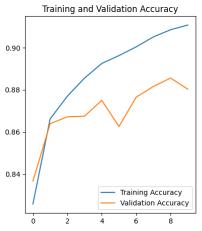
The validation data is selected from the last samples in the x and y data provided, before shuffling.

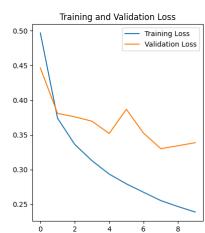
Results evaluation from training history - Part 2. We will use default measures names.

```
acc = history.history['accuracy']
val_acc = history.history['val_accuracy']
loss = history.history['loss']
val_loss = history.history['val_loss']
epochs_range = range(len(loss))
```

plt.show()

```
Results evaluation from training history - Part 3:
plt.figure(figsize=(8, 8))
plt.subplot(1, 2, 1)
plt.plot(epochs_range, acc, label='Training Accuracy')
plt.plot(epochs_range, val_acc,
            label='Validation Accuracy')
plt.legend(loc='lower right')
plt.title('Training and Validation Accuracy')
plt.subplot(1, 2, 2)
plt.plot(epochs_range, loss, label='Training Loss')
plt.plot(epochs_range, val_loss,
            label='Validation Loss')
plt.legend(loc='upper right')
plt.title('Training and Validation Loss')
```





TensorBoard is a tool for providing the measurements and visualizations needed during the machine learning workflow.

Start TensorBoard through the command line:

Open address in internet browser.

#### Save and load models

#### Model progress can be saved:

- after training,
- during training (e.g. after each epoch),
- before training.

This means a model can resume where it left off and avoid long training times. You can save:

- model structure,
- model structure and weights.

#### Save and load models

Before and after training:

Load model or weights:

```
# Loads the weights
model.load_weights(checkpoint_path)
# Load the entire model from a HDF5 file.
models.load_model('my_model.h5')
```

Save model or weights:

```
# Save the weights
model.save_weights(path)
# Save the entire model to a HDF5 file.
model.save('my_model.h5')
```

#### Save and load models

Saving during training with use of Checkpoint callback:

```
checkpoint_path = "c:/saves/cp_model.h5"
checkpoint_dir = os.path.dirname(checkpoint_path)
# Create a callback that saves the model's weights
cp_callback = tf.keras.callbacks.ModelCheckpoint(
                        filepath=checkpoint_path,
                        save_weights_only=True,
                        verbose=1)
# Train the model with callback
model.fit(train_images, train_labels, epochs=10,
          validation_data=(test_images,test_labels),
          callbacks=[cp_callback]) # Pass callback
```

#### Overfit and underfit in model training:

- Overfitting occurs when the accuracy of our model on the validation data would peak after training for a number of epochs, and would then stagnate or start decreasing.
- Underfitting occurs when there is still room for improvement on the train data. In can happen due to: too simple model or too short training time.

#### To prevent overfitting we performe:

- Add more data or new different dataset to complete our original training dataset. The dataset should cover the full range of inputs that the model is expected to handle. Additional data may only be useful if it covers new and uncommon cases.
- Use regularization methods. These methods place constraints on the quantity and type of information your model can store. If a network can only afford to memorize a small number of patterns, the optimization process will force it to focus on the most prominent patterns, which have a better chance of generalizing well.

The simplest way to prevent overfitting is to start with a small model with a small number of learnable parameters (small model capacity):

- Large model with more parameters will have more "memorization capacity" and therefore will be able to easily learn a perfect dictionary-like mapping between training samples and their targets.
- Deep learning models tend to be good at fitting to the training data, but the real challenge is generalization, not fitting.

Unfortunately, there is no magical formula to determine the right size or architecture/structure of your model. You will have to experiment using a series of different architectures.

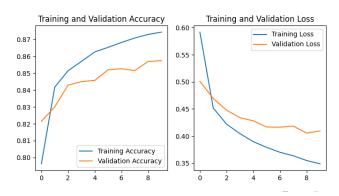
To find an appropriate model size, it's best to start with relatively few layers and parameters, then begin increasing the size of the layers or adding new layers until you see diminishing returns on the validation loss.

The obtained results:

```
Epoch 10/10
```

loss: 0.3489 - accuracy: 0.8743

- val\_loss: 0.4093 - val\_accuracy: 0.8574



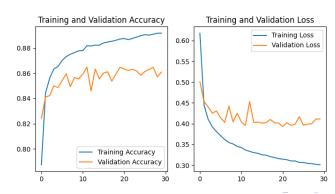
We increase total number of epochs to 30.

The obtained results:

Epoch 30/30

loss: 0.3012 - accuracy: 0.8917

- val\_loss: 0.4113 - val\_accuracy: 0.8609



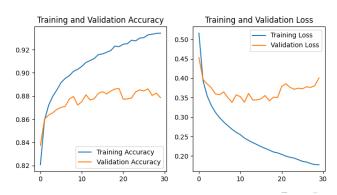
We increase total number of neurons in hidden layer to 64.

The obtained results:

Epoch 30/30

loss: 0.1774 - accuracy: 0.9343

- val\_loss: 0.4009 - val\_accuracy: 0.8786



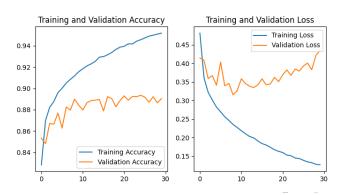
What happen if we further increase number of neurons to 256.

The obtained results:

```
Epoch 30/30
```

```
loss: 0.1774 - accuracy: 0.9343 \
```

- val\_loss: 0.4009 - val\_accuracy: 0.8786



Conclusions for avoiding overfiting and underfitting:

- Compare the validation metrics to the training metrics.
- If both metrics are moving in the same direction, the model is too small or too small number epochs.
- If the validation metric begins to stagnate while the training metric continues to improve, you are probably close to overfitting. There is a small difference between training and validation metrics. We have found a good model structure.
- If the validation metric is going in the wrong direction, the model is clearly overfitting.

If we check the big model loss and accuracy, these models have as good values as simple model at some epoch. The big model have also better capacity to improve results. How can we improve big models?

We can also avoiding overfiting and underfitting in case of big model:

- Early stopping criterion.
- Dynamic learning rate and momentum methods.
- Weight regularization.
- Adding generalization layers: dropout and batch normalization.