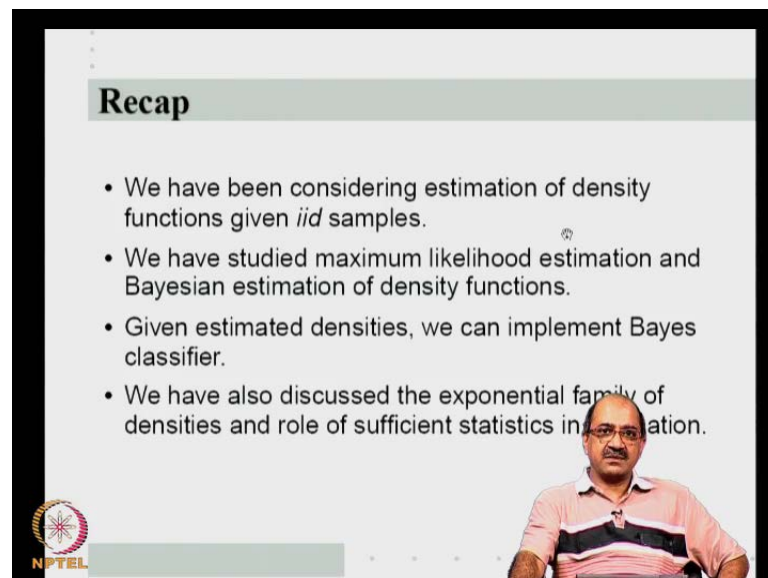


Pattern Recognition
Prof. P. S. Sastry
Department of Electronics and Communication Engineering
Indian Institute of Science, Bangalore

Lecture - 10
Mixture Densities, ML estimation and EM algorithm

Hello and welcome to the next talk in Pattern Recognition. This would be a last topic we look at parametric estimation and then, we will move on to non-parametric estimation. So, to briefly recall what we have been doing in the last few classes, we will consider estimation of density functions, given IID samples from the density. We studied maximum likelihood estimation, Bayesian estimation, density functions.

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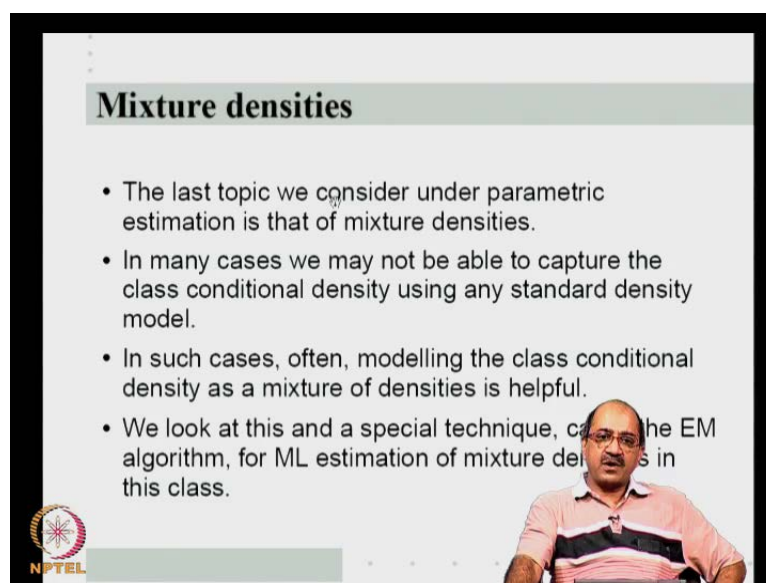
Recap

- We have been considering estimation of density functions given *iid* samples.
- We have studied maximum likelihood estimation and Bayesian estimation of density functions.
- Given estimated densities, we can implement Bayes classifier.
- We have also discussed the exponential family of densities and role of sufficient statistics in estimation.

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For all the standard density functions, we seen how to compute the ML estimates as well as the Bayesian estimates. The idea is that, given the estimate densities, we can implement the Bayes classifier with the estimated densities; while considering ML estimation and so on. We had also looked at the issue of exponential family of densities, as we have seen that is a very good generic density model, all the standard densities are captured there. We looked at exponential family of densities and we also studied the role of sufficient statistics in estimation, in the last class.

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Mixture densities

- The last topic we consider under parametric estimation is that of mixture densities.
- In many cases we may not be able to capture the class conditional density using any standard density model.
- In such cases, often, modelling the class conditional density as a mixture of densities is helpful.
- We look at this and a special technique, called the EM algorithm, for ML estimation of mixture densities in this class.

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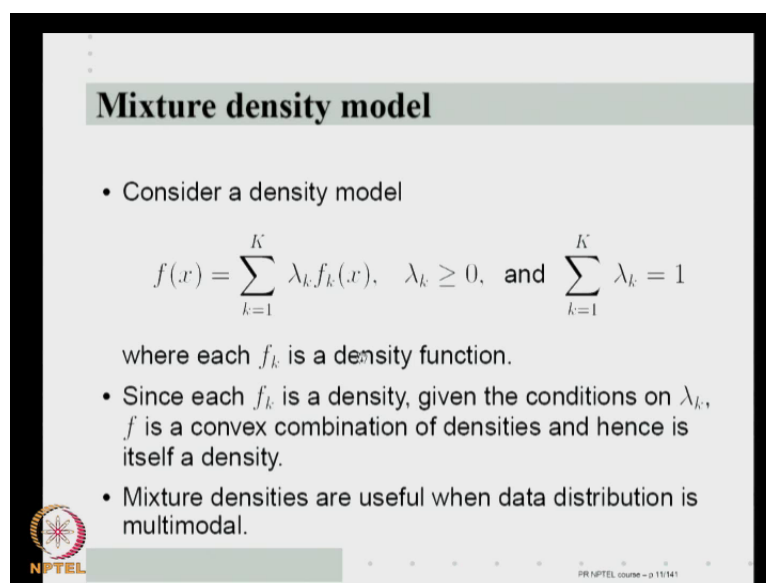
A small inset video shows a man with glasses and a pink shirt speaking.

So, as I said, we are going to look at the last topic namely mixture densities, in the parametric estimation. So, today we will consider estimation of mixture of densities, the basic idea is that, in many cases, the standard density model such as exponential or normal or gamma whatever, do not necessarily capture the the underlying data distribution.

One reason could be for example, most densities are unimodal and you know, data distribution may not be unimodal model. In such cases, it is often very helpful to consider a mixture of densities as the class conditional density models. That is, instead of thinking of a class conditional density a single normal, we may think of it as a mixture of normal's or mixture of exponentials and so on.

So, that is where, mixture densities come and in this class, we are going to look at, how one estimates mixture densities. Our main reason for looking at mixture densities is that, through this problem, we will introduce a very important algorithm in estimation, which is called the EM algorithm. EM stands for Expectation and Maximization, we will see the algorithm later so, this EM algorithm is a is a very important algorithm estimation, useful in many probabilistic models including things like HMM models, hidden Markov models and graphical models and so on. While many of those things we may not consider in this class, this since this algorithm is important, we look at it from the point of view of estimating mixture of densities.

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Mixture density model

- Consider a density model

$$f(x) = \sum_{k=1}^K \lambda_k f_k(x), \quad \lambda_k \geq 0, \quad \text{and} \quad \sum_{k=1}^K \lambda_k = 1$$

where each f_k is a density function.

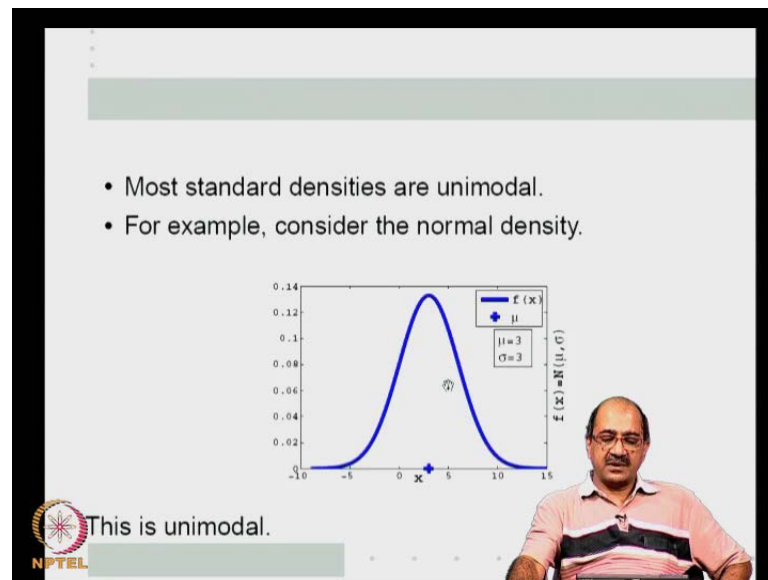
- Since each f_k is a density, given the conditions on λ_k , f is a convex combination of densities and hence is itself a density.
- Mixture densities are useful when data distribution is multimodal.

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So, this is the mixture density model, consider a density model where, the density of x is given by summation over k , k going from 1 to capital K , $\lambda_k f_k(x)$ where, λ_k is greater than or equal to 0 and λ_k sum to 1. And each of the f_k 's is a density of course, may be same kind of density or different kind of densities, that does not matter but, each of f_k 's is a density.

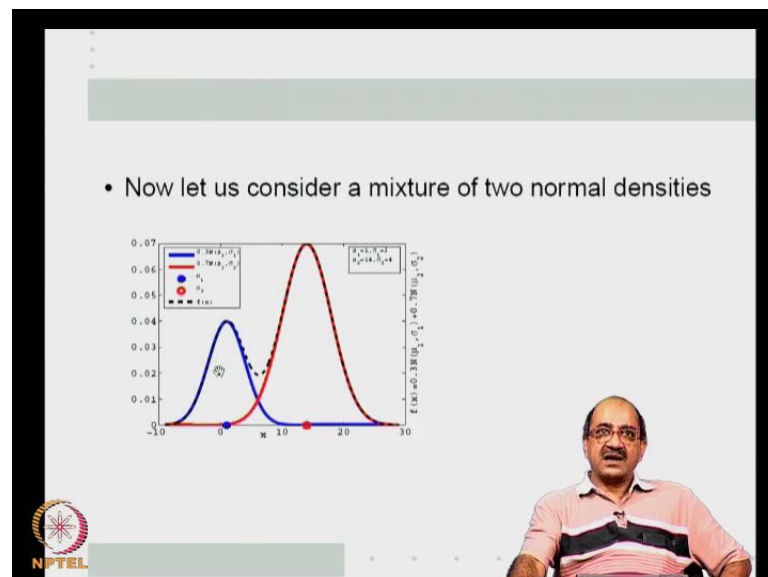
Since each of f_k is a density and all the λ_k 's are positive, the summation λ_k of k will be positive, also if you integrate this over x , each of f_k will integrate to 1. And since summation λ_k is equal to 1, $f(x)$ will itself integrate to 1; so, essentially because, f is a convex combination of densities, it will itself be a density. So, this is a well formed density model, if λ_k satisfy these conditions for convex combination, and f_k 's are densities. We often call λ_k as the mixing coefficients and f_k as the component densities. Mixture density are very useful especially, when data distribution is multimodal, that instead of being having only one maximum, it may have many many maxima.

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For example, if you consider most standard densities are unimodal for example, normal, there is a normal density curve, which has exactly one maximum right. Everything falls off monotonically on either side of the maximum, exponential density is a similar thing, more standard density is Poisson binomial, all of them are unimodal.

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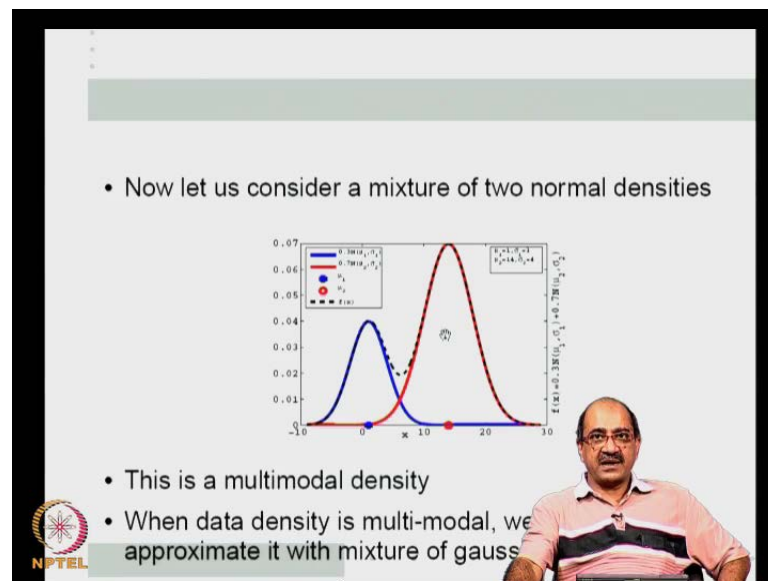


But, mixture densities allow us to capture densities, that are multimodal so, here is a mixture of two normal densities. The blue is one normal density, the red is another normal density and the black one, the the that is going like like that is a mixture of the

two, here, I just taken 0.3 and 0.7 as the mixing coefficients. Essentially, if I take the two means of the normal, sufficiently far off, on one side the sum is completely dominated by one density, and the other side the sum is completely dominated by other density.


In between, I get a smooth transition from one maximum to another. So, many data distributions, which have such multimodal characteristic right can be easily captured using mixture of normal.

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So, these are multimodal densities, the mixture is a multimodal density and when data density is multimodal, we can often approximate it with sum of normal's like this. So, as a matter of fact, what I call Gaussian mixtures, mixture density modal is a very often used density modal, for class conditional densities in pattern recognition problems.

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ML estimation of mixture models

- Consider a mixture of normal densities

$$f(x | \theta) = \sum_{k=1}^K \lambda_k f_k(x)$$


where each f_k is $\mathcal{N}(\mu_k, \Sigma_k)$.

- The parameter vector, θ , consists of all λ_k , which are called mixing coefficients, and all the parameters of the constituent densities, namely, $\mu_k, \Sigma_k, k = 1, \dots, K$.




So, let us say, we have a mixture of K normal densities, $f(x | \theta)$ where θ is equal to 1 to K $\lambda_k f_k(x)$ where, each f_k is normal with mean vector μ_k and covariance matrix Σ_k right. So, the parameter vector θ consists of all the λ_k case, which are called mixing coefficients and the parameters of all the constituent densities namely, all μ_k 's and all Σ_k 's. The f_k 's are sometimes called component densities or constituent densities, let us say, λ_k are called the mixing coefficients.


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- Let $\mathcal{D} = \{x_1, \dots, x_n\}$ be a sample of n iid data from this density.
- Then the likelihood function is

$$L(\theta | \mathcal{D}) = \prod_{i=1}^n \left[\sum_{k=1}^K \lambda_k f_k(x_i) \right]$$



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• The log likelihood is given by


$$l(\theta | \mathcal{D}) = \sum_{i=1}^n \ln \left[\sum_{k=1}^K \lambda_k f_k(x_i) \right]$$


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• Let $\mathcal{D} = \{x_1, \dots, x_n\}$ be a sample of n iid data from this density.

• Then the likelihood function is

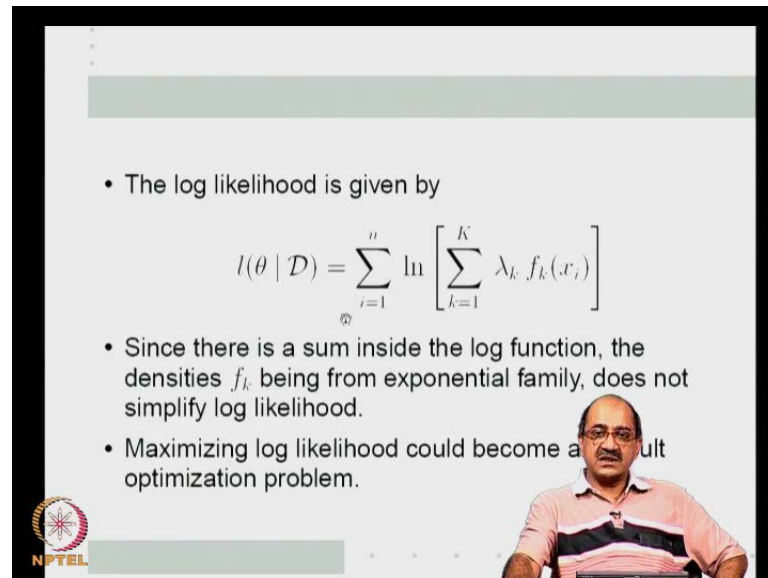
$$L(\theta | \mathcal{D}) = \prod_{i=1}^n \left[\sum_{k=1}^K \lambda_k f_k(x_i) \right]$$


Now, let us say, we we have this density model and let us say, we have a sample of n iid data from this density model that is, the standard scenario in any maximum likelihood estimation. We have a density model and we have data and then, we form the likelihood and maximize the likelihood to estimate the parameters. So, the likelihood would be what $l(\theta | \mathcal{D})$ is simply product of this density model right.

So, if I do product of this density model, this is what I get, product i is equal to 1 to n of the density model, which k is equal to 1 to K $\lambda_k f_k(x_i)$. As you have seen, we often

take log likelihood, in all our earlier examples taking log simplified the problem. So, let us take the log likelihood, if I take log likelihood, this product of course, will certainly become sum when I take a log.

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• The log likelihood is given by

$$l(\theta | \mathcal{D}) = \sum_{i=1}^n \ln \left[\sum_{k=1}^K \lambda_k f_k(x_i) \right]$$

• Since there is a sum inside the log function, the densities f_k being from exponential family, does not simplify log likelihood.

• Maximizing log likelihood could become a difficult optimization problem.

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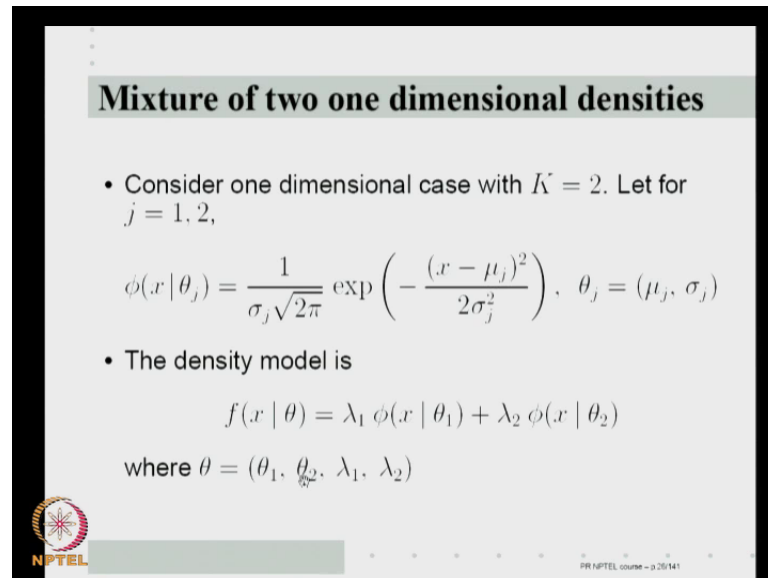
So, I get sum of \ln of this now, this kind of tells you, why mixture density model estimation is difficult, see what we have here is the sum inside the log function. Earlier, we got sum log of directly the f_k , and f_k being from the exponential family for example, Gaussian. Because, f itself will be exponential something, if I take log, I get a very nice expression and that is, how we have solved analytically for the ML estimation, of all the standard densities.

But here, because, there is a sum inside the log and we cannot simplify it, the fact that f_k is from an exponential family, does not give us any analytical simplification. So, this means, that maximizing log likelihood can become a difficult optimization problem earlier because, as directly got \ln suppose, capital k is 1 then, you have to simply get $\ln \lambda + \ln f$.

And if f is exponential that, what is inside the exponent comes out and as we have seen through sufficient statistics, that immediately gives rise to very simplified ML analytical expressions for ML estimates. But here, we have a sum inside a log and hence, those simplifications do not occur then, we may have to solve it numerically and it can become a difficult optimization problem.

What we will see in this class is, we will take a specific example of this and try to solve it by explicitly calculating the partial derivatives and out of that, we will try and formulate a general procedure for all such densities.

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Mixture of two one dimensional densities


- Consider one dimensional case with $K = 2$. Let for $j = 1, 2$,

$$\phi(x | \theta_j) = \frac{1}{\sigma_j \sqrt{2\pi}} \exp \left(-\frac{(x - \mu_j)^2}{2\sigma_j^2} \right), \quad \theta_j = (\mu_j, \sigma_j)$$

- The density model is

$$f(x | \theta) = \lambda_1 \phi(x | \theta_1) + \lambda_2 \phi(x | \theta_2)$$


where $\theta = (\theta_1, \theta_2, \lambda_1, \lambda_2)$

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So, for our simplification, we will consider one dimensional problem with only two component densities, we want both component densities to be normal. So, let us put a special symbol for it, let us say, ϕ of x given θ_j is normal with parameters μ_j and σ_j . So, θ_j consists of μ_j σ_j so, ϕ of x given θ_j is normal with mean μ_j and variance σ_j^2 right, this is the ϕ of x given θ_j .

And let us say, our density model is mixture of two such normals so, f of x given θ is λ_1 times ϕ of x given θ_1 plus λ_2 times ϕ of x given θ_2 . So, this is ϕ of x given θ_1 is normal with parameters θ_1 namely, μ_1 and σ_1 , ϕ of x given θ_2 is normal with parameter θ_2 namely, μ_2 and σ_2 . So, f itself will have parameters given by θ , as θ_1 parameters of this density, the θ_2 parameters of this density and the two mixing coefficients, that will be the parameter vector.

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- The log likelihood is

$$l(\mathcal{D} | \theta) = \sum_{i=1}^n \ln(\lambda_1 \phi(x_i | \theta_1) + \lambda_2 \phi(x_i | \theta_2))$$

- We need to maximize this with respect to θ .
- Let us calculate the partial derivatives of l .
- First note that

$$\frac{\partial \phi(x | \theta_j)}{\partial \mu_s} = \frac{\partial \phi(x | \theta_j)}{\partial \sigma_s} = 0, \text{ if } j \neq s.$$

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Now, what is the log likelihood, as we have just now seen is, summation i is equal to 1 to n , \ln of $\lambda_1 \phi(x_i | \theta_1) + \lambda_2 \phi(x_i | \theta_2)$. So, this is what, I have to differentiate with respect to various components of θ , what are the components of θ $\mu_1, \mu_2, \sigma_1, \sigma_2, \lambda_1, \lambda_2$. So, I have to differentiate this, with respect to the components to maximize so, to obtain the ML estimate of θ , given this log likelihood, we have to maximize this with respect to θ .

To maximize this with respect to θ , we have to calculate partial derivatives of l and equate it to 0 and see, if we can solve for it. So, if I want partial derivatives let us say, with respect to μ or σ of this, essentially this \ln will give me 1 by that $\lambda_1 \phi(x_i | \theta_1) + \lambda_2 \phi(x_i | \theta_2)$, into derivative of $\phi(x_i | \theta_1)$ with respect to μ_1 or σ_1 or whatever similarly, derivative of $\phi(x_i | \theta_2)$ with respect to μ_1 σ_1 .

So, first, let us calculate this partial of these these derivatives of ϕ , with respect to μ and σ . The way we put this θ_1 and θ_2 , let us first notice that, partial derivative of $\phi(x_i | \theta_j)$ with respect to μ_s or $\phi(x_i | \theta_j)$ with respect to σ_s is 0, if j is not equal to s . So, if I want $\phi(x_i | \theta_1)$ with respect to μ_2 because, $\phi(x_i | \theta_1)$ depends only on μ_1 and σ_1 , is derivative with respect to μ_2 would be 0.

Similarly, the derivative with respect to sigma 2 will also be 0 right so, only phi x given theta 1 will have non-zero derivative with respect to mu 1 and sigma 1 only. And phi x given theta 2 will have non-zero derivatives with with respect to mu 2 and sigma 2 only. So, we do not have to calculate the crossed derivatives so, we have to only calculate derivatives of phi x, given theta j with respect to mu j and sigma j.

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Mixture of two one dimensional densities

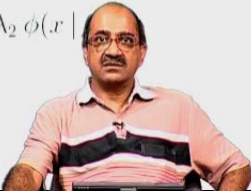
- Consider one dimensional case with $K = 2$. Let for $j = 1, 2$,

$$\phi(x | \theta_j) = \frac{1}{\sigma_j \sqrt{2\pi}} \exp \left(-\frac{(x - \mu_j)^2}{2\sigma_j^2} \right), \quad \theta_j = (\mu_j, \sigma_j)$$

- The density model is

$$f(x | \theta) = \lambda_1 \phi(x | \theta_1) + \lambda_2 \phi(x | \theta_2)$$


where $\theta = (\theta_1, \theta_2, \lambda_1, \lambda_2)$



That is easily done simple differentiation of this, if I want derivative of this let us say, with respect to mu j, I get this factor as it is, into exponential of this as it is, multiplied by, the 2 will come out, we will cancel with this 2, x minus mu j by sigma j square, and another minus will cancel this minus. So, essentially what I get is the same phi x, given theta j multiplied by x minus mu j by sigma j square right.

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By differentiation we get, for $j = 1, 2$,


$$\frac{\partial \phi(x | \theta_j)}{\partial \mu_j} = \phi(x | \theta_j) \frac{(x - \mu_j)}{\sigma_j^2}$$
$$\frac{\partial \phi(x | \theta_j)}{\partial \sigma_j} = \phi(x | \theta_j) \left[\frac{(x - \mu_j)^2}{\sigma_j^3} - \frac{1}{\sigma_j} \right]$$


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So, that is what I will get, $\frac{\partial \phi(x | \theta_j)}{\partial \mu_j}$ is $\phi(x | \theta_j)$ into $x - \mu_j$ by σ_j^2 . Similarly, differentiating the normal function with respect to σ_j , we get $\phi(x | \theta_j)$ into $\frac{(x - \mu_j)^2}{\sigma_j^3} - \frac{1}{\sigma_j}$. So, in both of them the $\phi(x | \theta_j)$ there will be a common factor.

So, with that algebra, one can show that, $\frac{\partial \phi(x | \theta_j)}{\partial \sigma_j}$ will once again be $\phi(x | \theta_j)$ multiplied by $\frac{(x - \mu_j)^2}{\sigma_j^3} - \frac{1}{\sigma_j}$.


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- The log likelihood is

$$l(\mathcal{D} | \theta) = \sum_{i=1}^n \ln(\lambda_1 \phi(x_i | \theta_1) + \lambda_2 \phi(x_i | \theta_2))$$


- We need to maximize this with respect to θ .
- Let us calculate the partial derivatives of l .
- First note that

$$\frac{\partial \phi(x | \theta_j)}{\partial \mu_s} = \frac{\partial \phi(x | \theta_j)}{\partial \sigma_s} = 0, \text{ if } j \neq s.$$


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Given this now, we know how to calculate derivative with respect to this, if I want derivative of this with respect to μ_1 , that will be because, this \ln , this derivative will go inside the sum. \ln will give me 1 by $\lambda_1 \phi(x_i | \theta_1) + \lambda_2 \phi(x_i | \theta_2)$ into derivative of this with respect to μ_1 . Derivative of this second term with respect to μ_1 will be 0 and thereby, the first term with respect to μ_1 , we already know.

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By differentiation we get, for $j = 1, 2$,

$$\frac{\partial \phi(x | \theta_j)}{\partial \mu_j} = \phi(x | \theta_j) \frac{(x - \mu_j)}{\sigma_j^2}$$

$$\frac{\partial \phi(x | \theta_j)}{\partial \sigma_j} = \phi(x | \theta_j) \left[\frac{(x - \mu_j)^2}{\sigma_j^3} - \frac{1}{\sigma_j} \right]$$

Now we have

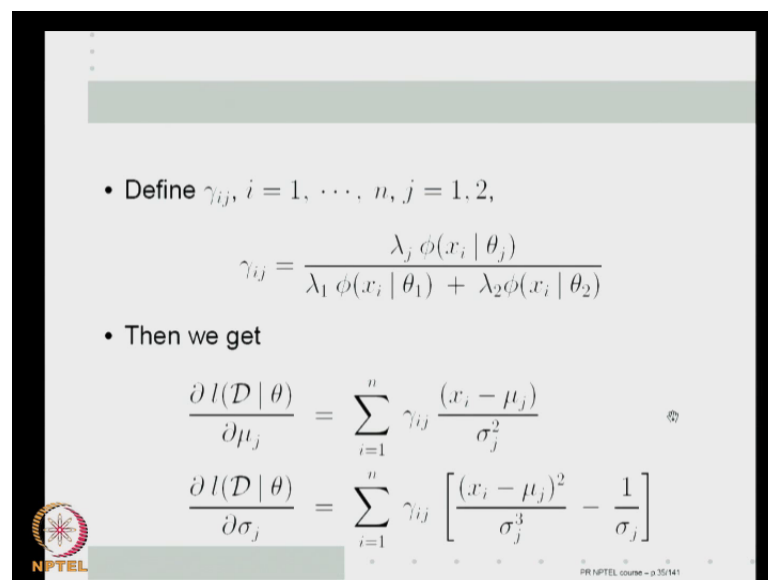
$$\frac{\partial l(\mathcal{D} | \theta)}{\partial \mu_j} = \sum_{i=1}^n \frac{\lambda_j \phi(x_i | \theta_j) \frac{(x_i - \mu_j)}{\sigma_j^2}}{\lambda_1 \phi(x_i | \theta_1) + \lambda_2 \phi(x_i | \theta_2)}$$


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So, doing all that, we get derivative of l with respect to μ_j , will be $\lambda_j \phi(x_i | \theta_j)$ given θ_j that comes from here into $x_i - \mu_j$ by σ_j^2 , this is the $\frac{\partial \phi}{\partial \mu_j}$, this comes because of the log. So, this is the partial derivative with respect to μ_j similarly, we will get this has to be σ_j , if you want with respect to σ_j once again this 1 by the λ_1 plus λ_2 term will be there.

And with respect to σ_j , I once again get that $\lambda_j \phi(x_i | \theta_j)$ given θ_j that term and instead of this $x_i - \mu_j$ by σ_j^2 , I will get this term right. So, in all these terms, as you can see, we have this factor $\lambda_j \phi(x_i | \theta_j)$ by λ_1 of x_i , given θ_1 by $\lambda_2 \phi(x_i | \theta_2)$ plus given name to that term.

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• Define $\gamma_{ij}, i = 1, \dots, n, j = 1, 2,$

$$\gamma_{ij} = \frac{\lambda_j \phi(x_i | \theta_j)}{\lambda_1 \phi(x_i | \theta_1) + \lambda_2 \phi(x_i | \theta_2)}$$

• Then we get

$$\frac{\partial l(\mathcal{D} | \theta)}{\partial \mu_j} = \sum_{i=1}^n \gamma_{ij} \frac{(x_i - \mu_j)}{\sigma_j^2}$$

$$\frac{\partial l(\mathcal{D} | \theta)}{\partial \sigma_j} = \sum_{i=1}^n \gamma_{ij} \left[\frac{(x_i - \mu_j)^2}{\sigma_j^3} - \frac{1}{\sigma_j} \right]$$

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Let us call it γ_{ij} , γ_{ij} is $\lambda_j \phi(x_i | \theta_j)$ by the sum of the two densities then, the earlier equation can be written as $\frac{\partial l}{\partial \mu_j}$ is summation i is equal to 1 to n , γ_{ij} into $x_i - \mu_j$ by σ_j^2 right. Just by taking that factor out, we got a very simple equation, as I said derivative with respect to σ_j will also be same so, let us write that also.

So, once again, it will be summation over i γ_{ij} instead of this term, the derivative the σ_j derivative term will come there. So, if I want to solve for these, I have to just equate them to 0 so, for example, if I equate them to 0 , what do I get, summation γ_{ij}

$\sum_{i=1}^n \gamma_{ij} (x_i - \mu_j) = 0$. By multiplying by σ_j^2 right, that will give me $\sum_{i=1}^n \gamma_{ij} x_i = \mu_j \sum_{i=1}^n \gamma_{ij}$.

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• Hence the ML estimates satisfy, for $j = 1, 2$,


$$\hat{\mu}_j = \frac{\sum_{i=1}^n \gamma_{ij} x_i}{\sum_{i=1}^n \gamma_{ij}}$$

$$\hat{\sigma}_j^2 = \frac{\sum_{i=1}^n \gamma_{ij} (x_i - \hat{\mu}_j)^2}{\sum_{i=1}^n \gamma_{ij}}$$

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So, I can easily solve for μ_j that is, what I get so, I know the ML estimates satisfy μ_j , if $\sum_{i=1}^n \gamma_{ij} x_i = \mu_j \sum_{i=1}^n \gamma_{ij}$. Similarly, if I equate this to 0, take σ_j^2 to the other side, it becomes $\sigma_j^2 \sum_{i=1}^n \gamma_{ij} (x_i - \mu_j) = 0$. So, $\sigma_j^2 \sum_{i=1}^n \gamma_{ij} x_i = \mu_j \sum_{i=1}^n \gamma_{ij}$. So, σ_j^2 will be $\sum_{i=1}^n \gamma_{ij} (x_i - \mu_j)^2$ by $\sum_{i=1}^n \gamma_{ij}$ right.


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• Hence the ML estimates satisfy, for $j = 1, 2$,

$$\hat{\mu}_j = \frac{\sum_{i=1}^n \gamma_{ij} x_i}{\sum_{i=1}^n \gamma_{ij}}$$
$$\hat{\sigma}_j^2 = \frac{\sum_{i=1}^n \gamma_{ij} (x_i - \mu_j)^2}{\sum_{i=1}^n \gamma_{ij}}$$


• First, we like to note that these are not re estimates. The RHS in the above equation depends on the unknown parameter values.



That is the term, first let us understand that, we have not solved the problem at all, the γ_{ij} right depend on θ_j . That means, they need to calculate γ_{ij} , I need to know μ_j σ_j for j is equal to 1 to 2. So, even though this looks like an estimate, it is not an estimate because, the RHS depends on the parameters we want to estimate.

But, if I put the same μ_j σ_j in the RHS, this is some equations that, the μ_j σ_j have to satisfy that is why, I wrote here ML estimate satisfy this equation. The inside, these are the ML estimates given by the equation right because, both sides I will have the μ 's and σ 's right. But, on the other hand, this is very interesting structure here right say, for example, if γ_{ij} is equal to 1 for all i , it will be simply summation x_i by n , which is the old sample mean estimate.

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- Hence the ML estimates satisfy, for $j = 1, 2$,


$$\hat{\mu}_j = \frac{\sum_{i=1}^n \gamma_{ij} x_i}{\sum_{i=1}^n \gamma_{ij}}$$

$$\hat{\sigma}_j^2 = \frac{\sum_{i=1}^n \gamma_{ij} (x_i - \hat{\mu}_j)^2}{\sum_{i=1}^n \gamma_{ij}}$$

- First, we like to note that these are not real estimates. The RHS in the above equations depends on the unknown parameter values.
- However, there is an interesting structure here.

So, there is a lot of structure here so, let us look at the structure more closely.

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$$\hat{\mu}_j = \frac{\sum_{i=1}^n \gamma_{ij} x_i}{\sum_{i=1}^n \gamma_{ij}}$$

$$\hat{\sigma}_j^2 = \frac{\sum_{i=1}^n \gamma_{ij} (x_i - \hat{\mu}_j)^2}{\sum_{i=1}^n \gamma_{ij}}$$

- These are similar to the 'sample mean estimates'.
- It is a sample mean with 'weight' γ_{ij} for x_i . γ_{ij} are sometimes called responsibility coefficients.
- If there is only one component in the mixture, these become the usual ML estimates.

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These are my estimates so, first thing is, if they are they are like sample mean estimates, if I look at the μ_j estimate, it is summation something into x_i plus summation the same thing right. The sample mean would have taken this gamma $i j$'s to be 1 instead of getting 1, I am getting some other numbers so, I can same thing about sigma $j i i j$ square estimate. So, I can think of this, as it is a sample mean where, all samples are not


weighted equally, it is a sample mean but, the sample x_i is weighted with γ_{ij} right.

So, if I think of if I think of giving separate weight to each sample so, when I am estimating μ_j , I give the weight γ_{ij} to sample x_i . So, you can think of γ_{ij} as how much responsibility x_i has, for estimation of the j -th component density. So, if I think of γ_{ij} as weights then, this is essentially a weighted sample mean. See somehow, if γ_{ij} 's are 1 and 0 so that, I know this exercise are from the μ_j density then, this should have an exactly the sample mean.


But, instead of that, this it has become a weighted sample mean with weights γ_{ij} and the γ_{ij} sometimes called the responsibility coefficients. Of course, if there is only one component then, j will instead of being one, to do j is 1 then, γ_{ij} 's are all 1 then, this has the same sample mean estimates, we got earlier for ML estimation of mean and variance, of a single normal density.

So, they are kind of, in the limiting case of only one component the in the density, they go back to the single density estimates. They still retain the nice sample mean structure, with γ_{ij} is being the weights associated with the i th sample and if I think of these these as weights then, these are essentially weighted sample mean estimates. Of course, they are not really estimates, as they are said because, the γ_{ij} is a dependent μ_i μ_j . So, let us come back to this but, let us remember that, μ_j and σ_j are not the only parameters, λ_1 λ_2 , the mixing coefficients are also to be estimated.

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- Let us also find maximizers of log likelihood with respect to λ_j .
- Since we have a constraint $\lambda_1 + \lambda_2 = 1$, this is a constrained optimization.
- So, we need to equate to zero, the partial derivatives of
$$l(\mathcal{D} | \theta) + \eta(\lambda_1 + \lambda_2 - 1)$$
where η is the Lagrange multiplier.
- By equating to zero the partial derivative of the above with respect to λ_1 , we get

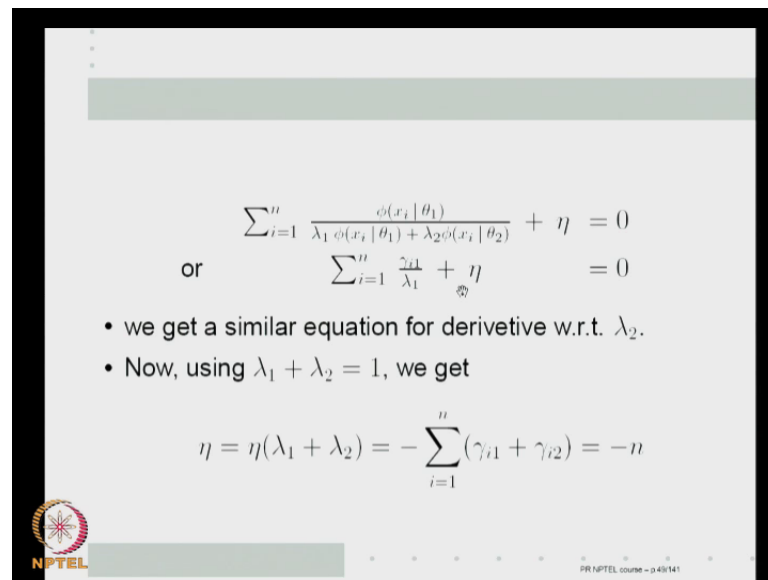


So, let us complete our estimation so, we have to maximize the log likelihood with respect to the lambda j's also but, maximization with respect to lambda j's is not straight forward. Because, lambda j's have a constraint lambda 1 plus lambda 2 is equal to 1 of course, they also have a constraint that, lambda 1 lambda 2 greater than 0. But, we have to certainly, satisfy the constraint lambda 1 plus lambda 2 is equal to 1 and hence, it is a constraint optimization problem.

No problem, we already seen this when we estimated Bernoulli multinomial density. We had similar constraint and we used constraint optimization for it. So, what do we do, we form the Lagrangian so, which means, instead of equating to 0, the partial derivatives of the log likelihood, we take the log likelihood plus a Lagrange multiplier times the constraint lambda 1 plus lambda 2 minus 1.

Take the derivative of this and equate that to 0 so, if you do that let us say, we take derivative of this with respect to lambda 1. So, the second term only gives me eta, the first term I wanted to differentiate with respect to lambda 1 that is, fairly straight forward, we will get this. Let us look at l, if I differentiate with respect to lambda 1, I get 1 by this into d by d lambda 1 of this, will give me phi x i given theta 1 right.

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$$\sum_{i=1}^n \frac{\phi(x_i | \theta_1)}{\lambda_1 \phi(x_i | \theta_1) + \lambda_2 \phi(x_i | \theta_2)} + \eta = 0$$

or
$$\sum_{i=1}^n \frac{\gamma_{i1}}{\lambda_1} + \eta = 0$$

- we get a similar equation for derivative w.r.t. λ_2 .
- Now, using $\lambda_1 + \lambda_2 = 1$, we get

$$\eta = \eta(\lambda_1 + \lambda_2) = - \sum_{i=1}^n (\gamma_{i1} + \gamma_{i2}) = -n$$


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So, this is $\phi(x_i | \theta_1)$ given θ_1 by $\lambda_1 \phi(x_i | \theta_1) + \lambda_2 \phi(x_i | \theta_2)$ given θ_2 plus η equal to 0. Since we already defined the γ 's, this term is nothing but, γ_{i1} because, this is $\phi(x_i | \theta_1)$. So, if there is a λ_1 , here this term would have been γ_{i1} because, there is no λ_1 , we will write it as γ_{i1} by λ_1 plus η equal to 0.

That means, summation γ_{i1} is equal to minus $\eta \lambda_1$ so, we get a similar equation for λ_2 meaning, summation γ_{i2} will be equal to minus $\eta \lambda_2$. Now, using $\lambda_1 + \lambda_2 = 1$, we get η is equal to $\eta(\lambda_1 + \lambda_2)$. Now, $\eta \lambda_1$ is summation γ_{i1} , $\eta \lambda_2$ is summation γ_{i2} so, that is what, we get and by definition, $\gamma_{i1} + \gamma_{i2}$ is equal to 1 so, this gives me n so, if I substitute that in this equation, I get my λ_1 estimate.


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- Hence, the ML estimates for λ_j satisfy


$$\hat{\lambda}_j = \frac{1}{n} \sum_{i=1}^n \gamma_{ij}$$

- Putting all these together we get



My lambda 1 estimate is 1 by n summation gamma i j but, both for lambda 1 lambda 2 I written one equation for lambda j right so, we now obtained estimates for mu's mu j's sigma j's and lambda j's.

(Refer Slide Time: 23:23)



- The ML estimates for $\mu_j, \sigma_j, \lambda_j, j = 1, 2$, satisfy

$$\hat{\mu}_j = \frac{\sum_{i=1}^n \gamma_{ij} x_i}{\sum_{i=1}^n \gamma_{ij}}, \quad \hat{\lambda}_j = \frac{1}{n} \sum_{i=1}^n \gamma_{ij}$$

$$\hat{\sigma}_j^2 = \frac{\sum_{i=1}^n \gamma_{ij} (x_i - \mu_j)^2}{\sum_{i=1}^n \gamma_{ij}}$$

- The structure of equations is interesting.
- These are not expressions for estimates.
- However, we can solve for estimates using, e.g., Gauss-Siedel iteration.

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So, we can put all of them together into like this, mu j hat is summation gamma i j x i by summation gamma i j, sigma j square hat is summation gamma i j x i minus mu j whole square by summation gamma i j and lambda j is 1 by n summation gamma i j. As I said of course, these are not estimates because, both sides involve the unknown mu's and

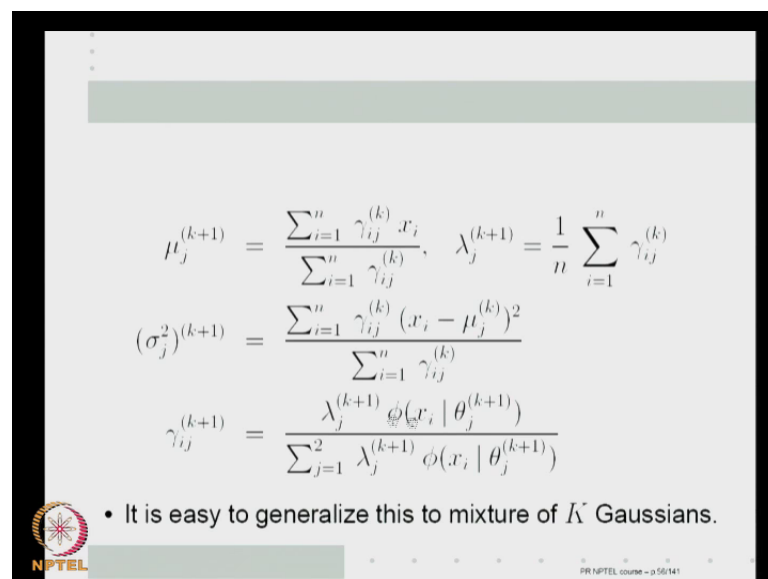
sigma's. But, we know that, the final estimates for mu sigma and lambda's have to satisfy this set of simultaneous non-linear equations.

This first note that, as I said this structure is very interesting see, lambda j you are asking what what is the chance that, a given x i, a random x i comes from the j th component density, for for each i, if x i is responsibility to j is gamma i j then, gamma i is summation gamma i j by n, should be the chance of a random x i coming from the j th component density right.

Similarly, we have already seen that, these are simple sample mean estimators somehow, this gamma i j, the responsible coefficients seem to give us some weight of, how much of x i should I assign, while estimating things for j th component density. So, this structure is interesting even though, they are not expressions for estimates because, both sides involve.

But then, we know, that the estimates mu mu j sigma j lambda j satisfy these simultaneous equations, given any set of simultaneous non-linear equations, we can solve them iteratively using let us say, Gauss-Siedel iteration. What is Gauss-Siedel iteration do, at each iteration I use the values of the previous iteration, put them in the RHS of the equations and then, the LHS will give me my new equations.

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The slide displays the following equations for the EM algorithm:

$$\mu_j^{(k+1)} = \frac{\sum_{i=1}^n \gamma_{ij}^{(k)} x_i}{\sum_{i=1}^n \gamma_{ij}^{(k)}}, \quad \lambda_j^{(k+1)} = \frac{1}{n} \sum_{i=1}^n \gamma_{ij}^{(k)}$$

$$(\sigma_j^2)^{(k+1)} = \frac{\sum_{i=1}^n \gamma_{ij}^{(k)} (x_i - \mu_j^{(k)})^2}{\sum_{i=1}^n \gamma_{ij}^{(k)}}$$

$$\gamma_{ij}^{(k+1)} = \frac{\lambda_j^{(k+1)} \phi(x_i | \theta_j^{(k+1)})}{\sum_{j=1}^K \lambda_j^{(k+1)} \phi(x_i | \theta_j^{(k+1)})}$$

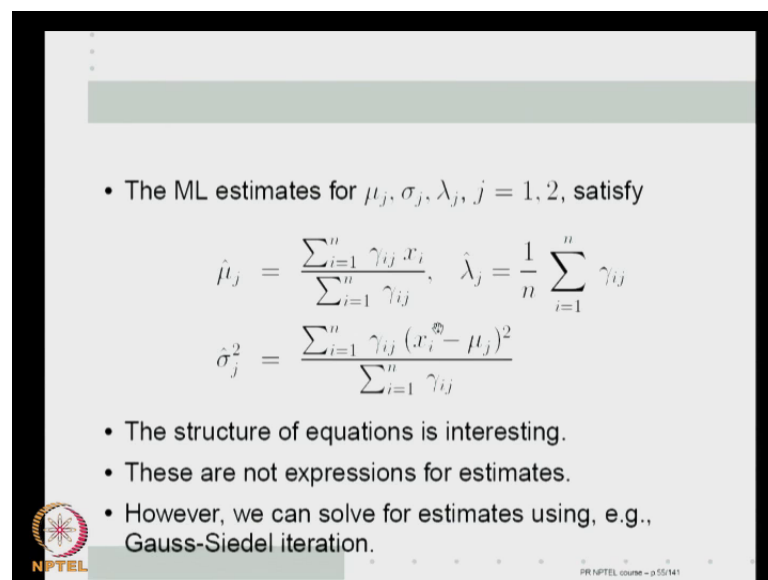
Below the equations, there is a bullet point: "It is easy to generalize this to mixture of K Gaussians."

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So, if I did that, I get these iterates so, if I want the new μ_j that is, the value of the k plus first iteration, for my estimate for μ_j , that will be $\gamma_{ij} x_i$ by summation $\gamma_{ij} k$ where, I am using the previous iteration values of γ_{ij} right. Similarly, for λ_j similarly, for σ^2_j and $\gamma_{ij} k$ plus 1 is always given the current values of θ_j 's and λ_j 's, I can calculate γ as k plus 1.

So, this is an iterative procedure, I start with some initial guesses then, given the initial $\theta_1 0$, $\theta_2 0$ and $\lambda_1 0$ and $\lambda_2 0$, I can calculate $\gamma_{ij} 1$. Once I know $\gamma_{ij} 1$, I can calculate $\mu_j 1$, $\sigma_j 1$, $\lambda_j 1$ using that, I will calculate $\gamma_{ij} 2$ and so on. So, this is a nice iterative method, which is essentially the Gauss-Siedel iteration for solving the previous set of simultaneous equations right.

(Refer Slide Time: 23:32)



• The ML estimates for $\mu_j, \sigma_j, \lambda_j, j = 1, 2$, satisfy

$$\hat{\mu}_j = \frac{\sum_{i=1}^n \gamma_{ij} x_i}{\sum_{i=1}^n \gamma_{ij}}, \quad \hat{\lambda}_j = \frac{1}{n} \sum_{i=1}^n \gamma_{ij}$$

$$\hat{\sigma}_j^2 = \frac{\sum_{i=1}^n \gamma_{ij} (x_i - \mu_j)^2}{\sum_{i=1}^n \gamma_{ij}}$$

• The structure of equations is interesting.
 • These are not expressions for estimates.
 • However, we can solve for estimates using, e.g., Gauss-Siedel iteration.

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We know, that the ML estimates satisfy these simultaneous equations, these are only equations because, as I said the γ_{ij} 's on the right hand side themselves involves μ_j 's σ_j 's and λ_j 's. So, this is the set of simultaneous equations satisfied by μ_j σ_j λ_j . So, we are iteratively solving it, each iteration we use the previous values in the RHS and that value, we assign as the new value for the corresponding variable in the on the LHS, that is the standard Gauss-Siedel iteration.

So, if I did that, get these iterative equations of course, these simultaneous equations have to be well behaved for the Gauss-Siedel iteration to properly converge, what rate it converges, depends on the nature of these equations and so on. These are of course, non-

linear equation, they are not linear equations but, generally for most well behaved non-linear equations, the Gauss-Siedel iteration converges.

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$$\mu_j^{(k+1)} = \frac{\sum_{i=1}^n \gamma_{ij}^{(k)} x_i}{\sum_{i=1}^n \gamma_{ij}^{(k)}}, \quad \lambda_j^{(k+1)} = \frac{1}{n} \sum_{i=1}^n \gamma_{ij}^{(k)}$$

$$(\sigma_j^2)^{(k+1)} = \frac{\sum_{i=1}^n \gamma_{ij}^{(k)} (x_i - \mu_j^{(k)})^2}{\sum_{i=1}^n \gamma_{ij}^{(k)}}$$

$$\gamma_{ij}^{(k+1)} = \frac{\lambda_j^{(k+1)} \phi(x_i | \theta_j^{(k+1)})}{\sum_{j=1}^2 \lambda_j^{(k+1)} \phi(x_i | \theta_j^{(k+1)})}$$

- It is easy to generalize this to mixture of K Gaussians.


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So, we can say that, this iterative procedure is the optimization procedure to optimize log likelihood and hence, find the ML estimates of a mixture density, which in this specific example of mixture of two Gaussians. By the way, my component index is j we have taken care to always write sum over j is equal to 1 to 2 like here so that, whatever we have done easily extends to a k component mixture too. Of course, because all our these derivatives have come from Gaussian, these specific set of equations are particular to Gaussian mixtures.


But, even that, they are not specific to only two components, is easily generalises to k components, we use it two only so that, my equations do not overflow out of the slide otherwise, even if you have k component mixtures, we can still do this. So, this we obtained by simply differentiating the log likelihood function and equating to 0. And since we cannot analytically solve it, we used a Gauss-Siedel iteration to solve the resulting simultaneous equation, that the estimates have to satisfy, that is what gave us this iterative procedure.

Now, we will of course, there must be something nice about it because, as I said, this is an essentially sample mean estimates right. So, there is some structure here, something interesting happening here so, let us try to take a look at that.

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- What we have done so far is a special case of general procedure.
- In many cases the ML estimation of mixture of densities gives rise to such an iterative optimization procedure.
- We now look at this general procedure.



So, as it turns out, what we have done is a special case of a very general procedure, that allows you to do the ML estimation of any k component mixture, not necessarily Gaussian. In many case of ML estimation of mixture on densities, it gives rise to the same kind of iterative optimization procedures and we will now look at this general procedure. As I said in the beginning, this general procedure, is what will lead us to the so called EM algorithm, expectation maximization algorithm.

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- Our density model was

$$f(x | \theta) = \sum_{j=1}^2 \lambda_j \phi(x | \theta_j)$$

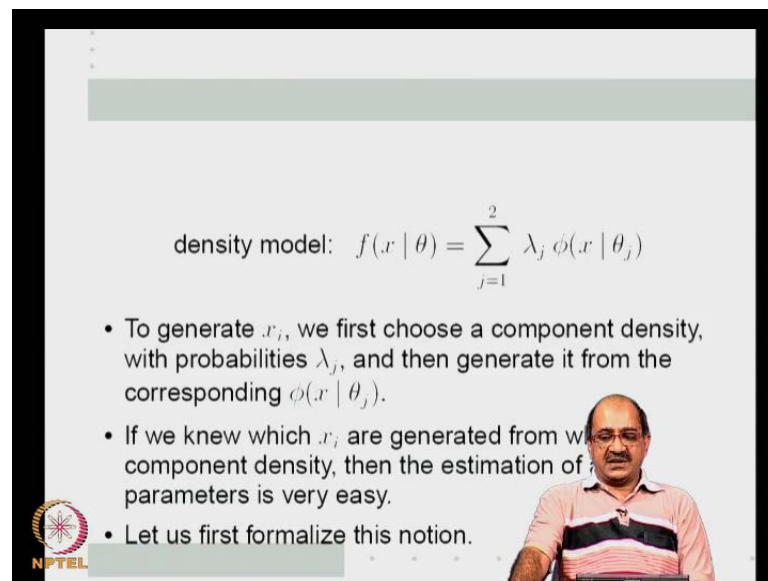
(while we stick to 2-component mixture, it is easily generalized to K components).

- In our sample each x_i is drawn *iid* according to this distribution.



So, let us go back, our original density model is $f(x | \theta)$ given θ_j is equal to 1 to 2, $\lambda_j \phi(x | \theta_j)$, I still put j is equal to 1 to 2 so, I am sticking to my example of two components. But, as I said, is only because, it is easier to write the expressions as you will see wherever, I put the summation up to 2, if you put summation up to k it is easily generalizes to k component mixtures so, when we have our samples, each excised on iid, according to this density.

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density model:
$$f(x | \theta) = \sum_{j=1}^2 \lambda_j \phi(x | \theta_j)$$

- To generate x_i , we first choose a component density, with probabilities λ_j , and then generate it from the corresponding $\phi(x | \theta_j)$.
- If we knew which x_i are generated from which component density, then the estimation of parameters is very easy.
- Let us first formalize this notion.

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So, I can ask, how would I draw such samples if this is my density model, how would I draw samples from it because, they have different densities, from which you draw. We are assuming that, if ϕ 's are normals, we can always generate random numbers with respect to a particular normal density. So, given any density, there are ways to generate random numbers, how do I generate with respect to mixture density, one way of thinking about it is, what I will do is, to generate each x_i , I will first choose a component density.


I have to decide, whether the next x_i say, x_1, x_2 whatever, the next x comes from $\phi(x | \theta_1)$ or $\phi(x | \theta_2)$, this decision I have to make with probability λ_1 or λ_2 . That is, with probability of λ_1 , I choose the first density, probability of λ_2 , I choose the second density that is why, λ 's are positive and sum to 1. So, using λ_1, λ_2 so on, as the probabilities for choice, I choose a component density and then, I generate it from the component density.

So, each x_i , is the finally what I get, is generated either from one of this $\phi(x|\theta_1)$ or $\phi(x|\theta_2)$. When you think, as I do not know, which x_i is generated from which density right because, that I am not told probabilistically some x_i are generated from $\phi(x|\theta_1)$, some x_i are generated $\phi(x|\theta_2)$. And this is this probabilistic or stochastic choice is controlled by λ_1 and λ_2 that is how, I am going to generate my sample that is how, iid samples come from such a mixture density estimation.

However, I am only given x_1, x_2, \dots, x_n so, I do not know, whether x_1 is come from the first component density or second component density. But, just for a moment pretend that, somebody tells us this, if somebody tells us this then, the estimation is absolutely trivial. Then, given my full data, I can separate it out into data of x_i , that have come from a $\phi(x|\theta_1)$ now, that is simply estimating a single normal density.

So, I know how to do it so, if I can separate data, as data that come from the first component density, $\phi(x|\theta_1)$ and data that comes from the second component density, $\phi(x|\theta_2)$ then, estimation of the parameters is very simple. Now, this is a very interesting characteristic so, we have a situation here where, essentially I have a mixture density and to actually estimate it, I have to go through a complicated iterative, complicate otherwise, I have go through an iterative procedure. Whereas, if somebody tells me, which x_i are come from, which component density, the estimation is trivial so, let us try to formalize this.

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Missing Information

- Let random variables Z_{ij} , $i = 1, \dots, n$, $j = 1, 2$, denote the information of which component density each sample comes from.
- For each i , $Z_{ij} = 1$ if x_i came from j^{th} component density.
- We would have $\sum_j Z_{ij} = 1$, $\forall i$.
- Also, we have

$$P[Z_{ij} = 1] = \lambda_j, \forall i; \quad \text{and} \quad f(x_i | Z_{ij} = 1) = \phi(x_i | \theta_j)$$

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Let us say, we define random variables Z_{ij} , i going from 1 to n and j going from 1 to 2 recall that, n is the number of data samples we have. So, you define random variable Z_{ij} , the idea is Z_{ij} gives me information about, which component density i has come from. So, if I look at Z_{i1} and Z_{i2} I can tell, whether x_i has come from first density or second density.


How am I doing this, for each i , I will make $Z_{ij} = 1$ if x_i came from j^{th} component that is, if x_i came from the first component then, I will make Z_{i1} equal to 1 and Z_{i2} is equal to 0. And if x_i came from the second component density then, I will make Z_{i1} equal to 0 and Z_{i2} is equal to 1 right. So, each Z_{ij} is binary like that and we have summation $\sum_j Z_{ij}$ is equal to 1 of course, it looks needlessly complicated, I have only two numbers Z_{i1} and Z_{i2} .

And from way, the way I have defined it because, each x_i , if x_i has come from the first component is, it is not coming from the second component. So, I might as well use only one number Z_i right the reason why I have used two numbers is that, this naturally generalizes to k components, if I had k components then, I would have Z_{i1} , Z_{i2} , Z_{ik} , only one of them is 1.

So, this is this is a representation of a binary vector, much like what we saw in the multinomial density estimation. So, even though the two, only there are only two components and I know $Z_{i1} + Z_{i2}$ is equal to 1, let us still stick with the notation of

Z_{ij} for our indicators. So, Z_{ij} is 1 if x_i came from the j th component, for j is equal to 1 to 2 and $Z_{i1} + Z_{i2}$ is equal to 1.

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Missing Information

- Let random variables $Z_{ij}, i = 1, \dots, n, j = 1, 2$, denote the information of which component density each sample comes from.
- For each i , $Z_{ij} = 1$ if x_i came from j^{th} component density.
- We would have $\sum_j Z_{ij} = 1, \forall i$.
- Also, we have

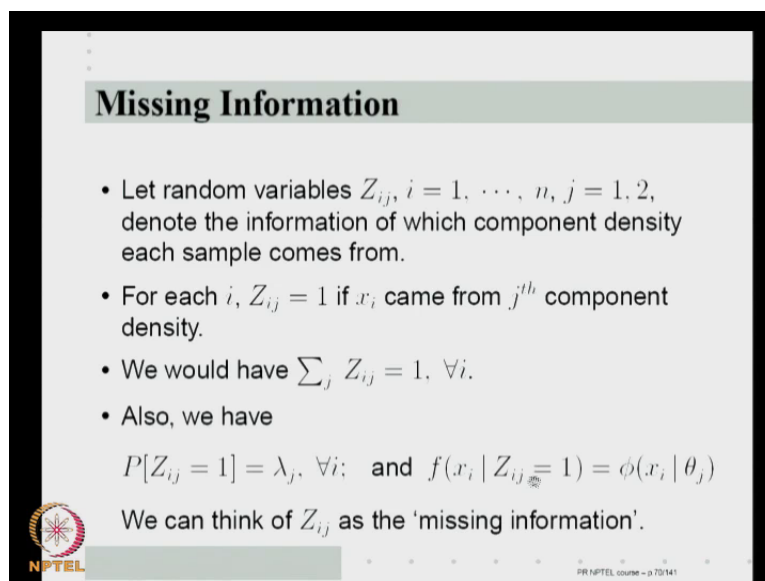
$$P[Z_{ij} = 1] = \lambda_j, \forall i; \quad \text{and} \quad f(x_i | Z_{ij} = 1) = \phi(x_i | \theta_j)$$

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Now, by definition, when probability Z_{ij} is equal to 1 Z_{ij} is equal to 1, the even z_{ij} is equal to 1 is that, the x_i comes from the first from the j th component, component density. Now, because each x_i are iid, irrespective of what the remaining samples are doing, for that x_i with probability λ_j , I choose the j th component density. So, probably Z_{ij} is equal to 1 is λ_j that, this probably Z_{i1} is equal to 1 is λ_1 , probably Z_{i2} is equal to 1 is λ_2 .

And the second thing, that is interesting here is the density of x_i unconditional density of x_i , I know what it is here is my density model. But, if you give me Z_{ij} 's, conditioned on Z_{ij} is equal to 1, what is the density of x_i , Z_{ij} is equal to 1 means, x_i is coming from the j th component density. So, conditioned on z_{ij} is equal to 1, the density of x_i is simply $\phi(x_i | \theta_j)$ so, conditioned on Z_{i1} is equal to 1, density of x_i is $\phi(x_i | \theta_1)$. And condition on Z_{i2} is equal to 1, density of x_i is $\phi(x_i | \theta_2)$ that is that is how, this Z_{ij} 's can also be equivalently specified.

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Missing Information

- Let random variables Z_{ij} , $i = 1, \dots, n$, $j = 1, 2$, denote the information of which component density each sample comes from.
- For each i , $Z_{ij} = 1$ if x_i came from j^{th} component density.
- We would have $\sum_j Z_{ij} = 1$, $\forall i$.
- Also, we have

$$P[Z_{ij} = 1] = \lambda_j, \forall i; \quad \text{and} \quad f(x_i | Z_{ij} = 1) = \phi(x_i | \theta_j)$$

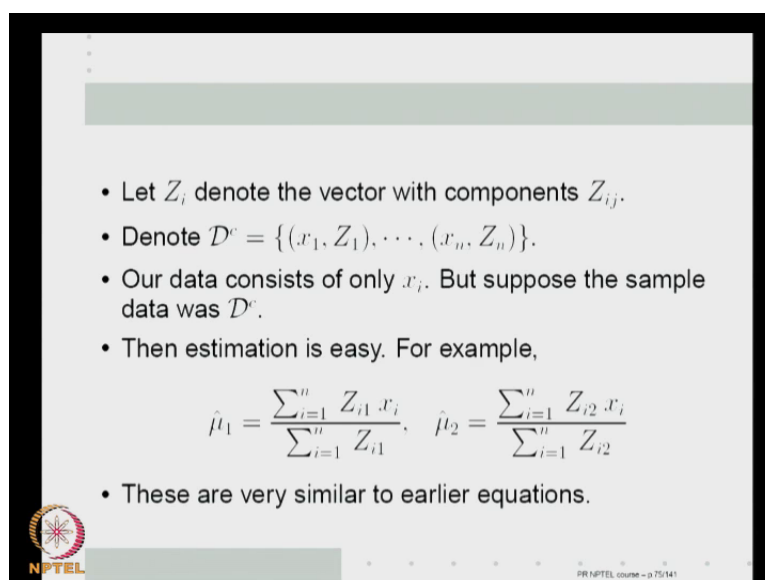
We can think of Z_{ij} as the 'missing information'.

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We can think of Z_{ij} 's as the missing information essentially, the density estimation problem for the mixture densities has become difficult because, I am not given the Z_{ij} information, I am only given x_i 's. If I am also given the random variable Z_{ij} , for i is equal to 1 to n and j is equal to 1 to 2 here or in general, 1 to k then, as we can see, the the estimation we see so, we can think of Z_{ij} as the missing information.

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- Let Z_i denote the vector with components Z_{ij} .
- Denote $\mathcal{D}^c = \{(x_1, Z_1), \dots, (x_n, Z_n)\}$.
- Our data consists of only x_i . But suppose the sample data was \mathcal{D}^c .
- Then estimation is easy. For example,

$$\hat{\mu}_1 = \frac{\sum_{i=1}^n Z_{i1} x_i}{\sum_{i=1}^n Z_{i1}}, \quad \hat{\mu}_2 = \frac{\sum_{i=1}^n Z_{i2} x_i}{\sum_{i=1}^n Z_{i2}}$$
- These are very similar to earlier equations.

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Let Z_i denote the vector of component z_{ij} in our case, Z_i will be Z_{i1} , Z_{i2} and let us say, \mathcal{D}^c denote the data written as $x_1 Z_1, x_n Z_n$, this c means complete.


So, I am I am thinking of $x_1 \dots x_n$ is the data I am given but, there are some missing components there, if you put in the missing components then, my new data is become D^c , c for complete.

We will see complete again later, our data consists of only x_i but, suppose for a minute, that the sample data that we are given is actually $x_1 Z_1, \dots, x_n Z_n$. then obviously, estimation is trivial. What will be μ_1 hat, $\sum_{i=1}^n Z_i x_i$ by $\sum_{i=1}^n Z_i$. Only if Z_i is 1, the x_i has come from the first component so, I will pick all the all all my sample that have come from the first component and take their sample mean, that is the mean of the first component, that is the ML estimation for the mean of the first component.

Similarly, mean of the second component right, this is very straight forward by the definition of Z_i 's so, if the Z_i 's are given, the estimation is trivial. More importantly, as you can see, these equations are exactly like the equations we saw earlier, except that wherever, I am getting Z_{ij} , there I am getting γ_{ij} . Because, I did not have Z_{ij} , I am kind of using the ratio of likelihoods as so, to say the probability, that i th one comes from component one or component two that is what, γ_{ij} 's are giving me.

So, these equations tell me that, if the missing information Z_i is given to me then, I can trivially finish my estimation of all the component densities. Of course, I have written only for μ 's but similarly, I can write for everything σ 's as well as λ 's, if Z_i 's are known.

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Complete and incomplete data

- The general situation is as follows.
- The data that we have is 'incomplete'
- This is because of some 'hidden' or 'missing' data.
- If we are given the complete data then ML estimation is easy.
- In our example, x_i is the incomplete data.
- (x_i, Z_i) constitutes the complete data and Z_i constitute the missing or hidden data/variables.

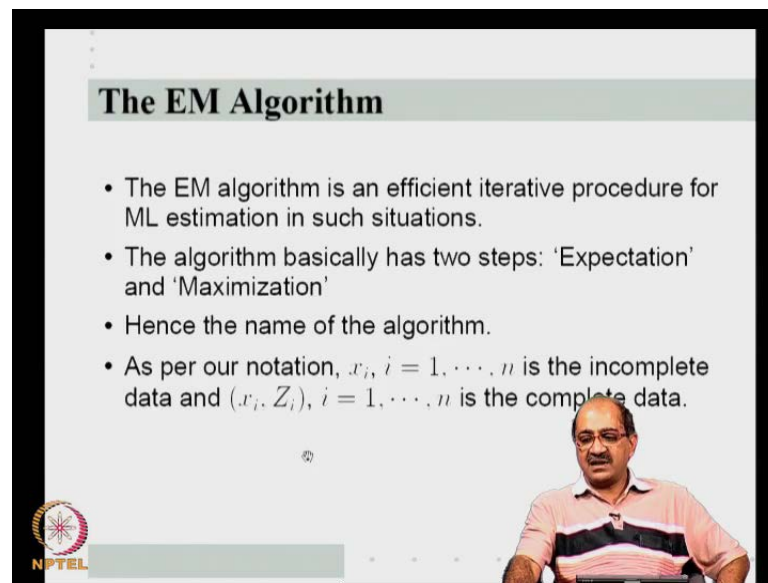
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Now, let us put all this intuition together into characterize the general situation that we have, the data that we have is somehow, what we call incomplete right. That that does not have all the information, that we would ideally like to have to make our job of estimation easy. So, the data we have is incomplete, it is incomplete because, there are some hidden or missing data, or hidden or missing variables right.

If we are given the complete data, what we call D_c in the previous slide namely, the original incomplete data plus the missing data then, ML estimation is very easy, this is the general situation. In our example, x_i 's are x_i 's all the x_i 's together come constitute the incomplete data and if I have given $x_i Z_i$, that constitutes the complete data so, Z_i are the missing or hidden data or hidden variables so, that is the general situation.

So, we are given incomplete data, we can hypothesize some missing data, like the Z_i variables here such that, if I have given $x_i Z_i$ as my actual complete data then, the estimation is simple right, this kind of thing is true for all mixture density estimation right. Now, we have, we are seeking a general method whereby, if I can hypothesize some variables Z_i at the missing variables in such a way that, if I am given $x_i Z_i$ together, my estimation is very simple. But, I am only given x_i , what can I do about estimation, that is the question we would like to ask.

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The EM Algorithm

- The EM algorithm is an efficient iterative procedure for ML estimation in such situations.
- The algorithm basically has two steps: 'Expectation' and 'Maximization'
- Hence the name of the algorithm.
- As per our notation, $x_i, i = 1, \dots, n$ is the incomplete data and $(x_i, Z_i), i = 1, \dots, n$ is the complete data.


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And the algorithm that specifically addresses this question is called the EM algorithm, is an efficient iterative procedure for maximum likelihood estimation, in such situations. The algorithm basically has two steps, so called expectation step and maximization step and that is the reason, for the name EM, expectation maximization, is called expectation maximization algorithm or EM algorithm.

The notation is that, $x_i, i = 1, \dots, n$ is the incomplete data, $(x_i, Z_i), i = 1, \dots, n$ is the complete data so, the EM algorithm is like this. So, we have a notion of incomplete data, which is the actual observed data and we have notion of complete data by hypothesizing some variables, some extra random variables Z_i , we define what is called complete data.

So, an EM algorithm starts with deciding what is my complete data so obviously, the incomplete data is whatever data I am given, my complete data consists of incomplete data plus the missing variables. So, I design the missing variables to in such a way that, if the complete data is given then, my estimation become simple.

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- Let $f(x, Z | \theta)$ be the density for the complete data. That is, the complete data is n iid samples from this density model.
- Thus, the complete data log likelihood is

$$l(\theta | \mathcal{D}^c) = \ln \left(\prod_{i=1}^n f(x_i, Z_i | \theta) \right)$$

- As earlier, we would also denote \mathcal{D}^c by (\mathbf{x}, \mathbf{Z}) .
- Hence the complete data loglikelihood is also denoted by $\ln(f(\mathbf{x}, \mathbf{Z} | \theta))$.

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Say, let $f(x, Z | \theta)$ be the density for the complete data, what do I mean, that the complete data that is, x_i, Z_i , i is equal to 1 to n or n iid samples from this density. So, the way we hypothesize z , we should because, we already know the density for a $f(x | \theta)$ given θ and we are hypothesizing z so, we should be able calculate the density model for the complete data. Once we get the density model of a complete data, this is the density model for the, the the log likelihood for the complete data. i is equal to, product i is equal to 1 to n of x_i, Z_i given θ , is the likelihood for the a complete data and putting a log, I get a log likelihood for the complete data.

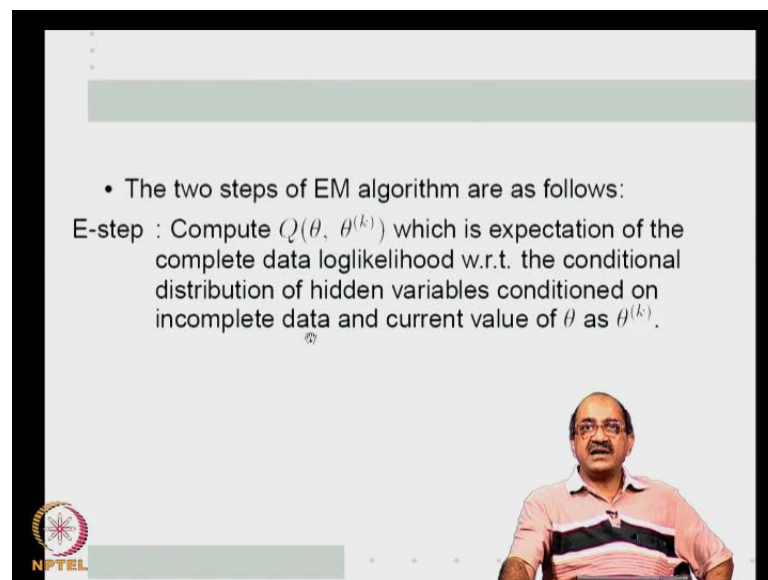
Recall that earlier, we have been, we said that the data x_1 to x_n can also be represented by a bold \mathbf{X} similarly, the data \mathcal{D}^c , which consists of $X_1, Z_1, X_2, Z_2, \dots, X_n, Z_n$ this is a complete data, will represented by bold \mathbf{X}, \mathbf{Z} . So, in the in that sense, the complete data log likelihood can also be written as log of this product will now become \ln of bold \mathbf{X}, \mathbf{Z} given θ .

So, we will use this notation also wherever, mostly we will use this notation for the complete data log likelihood and similarly, all the other log likelihoods. So, the the EM algorithm set up is, we have incomplete data \mathbf{x} , x_1, x_2, \dots, x_n and we have the model $f(x | \theta)$ given θ , that is the density model. We hypothesize some missing variables \mathbf{Z} then, we compute we the complete data density model affects given $\mathbf{Z}, f(\mathbf{X}, \mathbf{Z} | \theta)$ given θ .

So, now, we have the complete data model, that the joint density of X and Z because, Z is what we hypothesize, $f_{X|Z}$ given θ is the given density model. So, we have now, the density for X , the joint density for X and Z and of course, all the other conditional densities we can compute from there. For example, you can compute given this, we can compute the conditional density of Z given X and θ where, we are essentially hypothesizing the missing variables Z .

So, EM algorithm says that, if I have the notion of the complete data and the incomplete data, how do I actually estimate given that, I can only use the incomplete data, I do not know the values for Z .

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• The two steps of EM algorithm are as follows:

E-step : Compute $Q(\theta, \theta^{(k)})$ which is expectation of the complete data loglikelihood w.r.t. the conditional distribution of hidden variables conditioned on incomplete data and current value of θ as $\theta^{(k)}$.

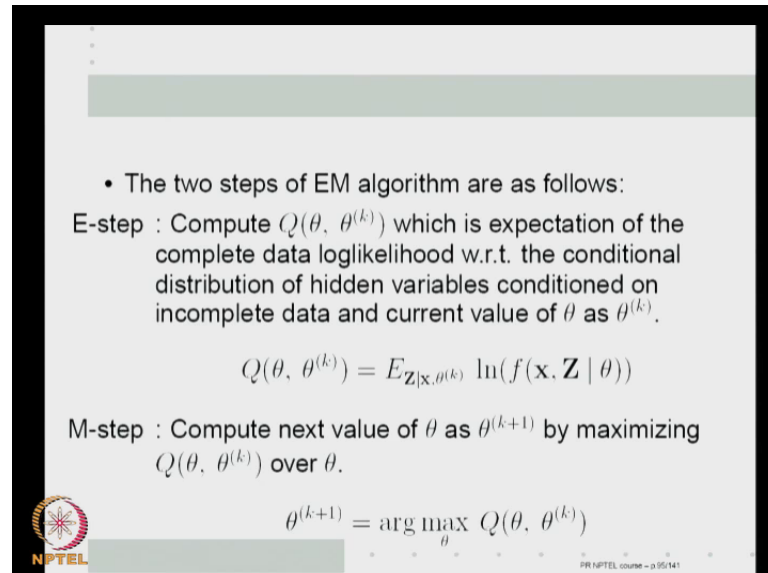
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So, this is how the EM algorithm works, there are two steps of the EM algorithm, the E-step and the M-step, E for expectation M for so, it is a iterative algorithm. So, at a given step, I I am in the k th iteration let us say, my current values for the estimated parameters are represented by $\theta^{(k)}$, this is the current estimated values. Given the current estimated values $\theta^{(k)}$, I compute a function of θ , which I call $Q(\theta, \theta^{(k)})$ because, while it is a function of θ , it also depends on the current estimated value.

So, I call the function $Q(\theta, \theta^{(k)})$ what is this function, it is the expectation of the complete data or log likelihood, as you take expectation of this quantity $\ln f_{X,Z}$ given θ right. It is the expectation of the complete data log likelihood with respect to the

conditional distribution of hidden variables, conditioned on the incomplete data and current value of theta is theta k.

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• The two steps of EM algorithm are as follows:

E-step : Compute $Q(\theta, \theta^{(k)})$ which is expectation of the complete data loglikelihood w.r.t. the conditional distribution of hidden variables conditioned on incomplete data and current value of θ as $\theta^{(k)}$.

$$Q(\theta, \theta^{(k)}) = E_{Z|X, \theta^{(k)}} \ln(f(X, Z | \theta))$$

M-step : Compute next value of θ as $\theta^{(k+1)}$ by maximizing $Q(\theta, \theta^{(k)})$ over θ .

$$\theta^{(k+1)} = \arg \max_{\theta} Q(\theta, \theta^{(k)})$$

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In symbols, what it means is, $Q(\theta, \theta^{(k)})$ is the expectation with respect to only Z but, using the distribution of Z , conditioned on X and $\theta^{(k)}$ of the complete data log likelihood. So, in this complete data log likelihood, all the terms involving Z are average wrote by the expectation and to average wrote, I use the conditional distribution of Z , given X and $\theta^{(k)}$. So, only in averaging over the Z terms here, I use this conditional distribution, the rest of the terms depend on this θ .

So, this this conditional expectation being ultimately by a function of both $\theta^{(k)}$ and θ that is why, it is called $Q(\theta, \theta^{(k)})$. So, to say it again, $Q(\theta, \theta^{(k)})$ is the conditional expectation of the complete data log likelihood, with respect to the conditional distribution of the missing variables or hidden variables, conditioned on the incomplete data and the this iteration values of the parameters. Once we got this, the M-step computes the next value of θ that is, $\theta^{(k+1)}$ by maximizing this function over θ .

So, $\theta^{(k+1)}$ is computed as maximizer of $Q(\theta, \theta^{(k)})$ over θ so, this is a argument of the max over θ of $Q(\theta, \theta^{(k)})$. So, I take this function as a function of θ , find which value of θ maximizes this function and that is, given at the next

iteration $\theta_k + 1$. These are that two steps E-step and M-step, it is a little complicated because of, this funny conditional expectation.

We will look at the example once again, we will go back to our two component Gaussian mixture example and compute these two steps so that, we understand how to compute these two steps.

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Example of EM


- Let us consider the example estimating a two component Gaussian density.

$$f(x | \theta) = \sum_{j=1}^2 \lambda_j \phi(x | \theta_j)$$

- The $x_i, i = 1, \dots, n$, is the given data which is the incomplete data here.
- The $Z_{ij}, i = 1, \dots, n, j = 1, 2$, that we defined earlier are the hidden variables or the missing data.
- Recall that Z_{ij} is the indicator whether or not x_i came from the j^{th} component of the mixture.

So, let us consider the example of estimating two component Gaussian densities, this is our given data model this is our incomplete data generator. So, x_i is the given data, which is the incomplete data, the Z_{ij} 's that we have defined earlier are the hidden variables or the missing variables, and $x_i Z_{ij}$ constitute the full data. Now, recall that, Z_{ij} is an indicator of, which of these j component densities, that x_i comes from.

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- By definition of Z_{ij} , we have

$$P[Z_{ij} = 1] = \lambda_j, \forall i; \quad \text{and} \quad f(x_i | Z_{ij} = 1) = \phi(x_i | \theta_j)$$
- Recall $Z_i = (Z_{i1}, Z_{i2})$. Hence

$$f(Z_i | \theta) = \prod_{j=1}^2 (\lambda_j)^{Z_{ij}}, \quad \text{and} \quad f(x_i | Z_i, \theta) = \prod_{j=1}^2 (\phi(x_i | \theta_j))^{Z_{ij}}$$


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So, as remember, by definition Z_{ij} , we have probability Z_{ij} equal to 1, is λ_j that is, x_i coming from j th component has probability λ_j and conditioned on Z_{ij} is equal to 1, x_i is the density, is the j th component density. Given these two, we can now write the marginal density of Z as follows, remember that, my complete data is $x_i | Z_i$, Z_i has two components Z_{i1}, Z_{i2} .

If you want to write marginal density then, $f(Z_i | \theta)$ is $\prod_{j=1}^2 \lambda_j^{Z_{ij}}$ this is, if I take away the product, it will be $\lambda_1^{Z_{i1}} \lambda_2^{Z_{i2}}$. Only one of Z_{i1} and Z_{i2} is 1, the other is 0 so, if Z_{i1} is 1, this becomes λ_1 , Z_{i1} is equal to 0, this becomes λ_2 that is, exactly this. So, I can think of this just like in the Bernoulli model, I can take the marginal of Z like this and conditional of x_i , conditioned on Z and θ , once again x_i conditioned at $Z_i | \theta$ is product $\phi(x_i | \theta_j)$ to the power Z_{ij} .

Once again $Z_i | Z_j$'s are 0 on 1, for each i only one j is 1 so, whichever 1 is 1, I get that particular component density. So, I have got conditioned conditional density of x given Z 's and has the marginal of Z 's.

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- Hence density of complete data is

$$f(x_i, Z_i | \theta) = \prod_{j=1}^2 (\lambda_j \phi(x_i | \theta_j))^{Z_{ij}}$$

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So, by multiplying, I get the joint right so, the joint density model is, I have to multiply these two, both the product. So, the lambda j also comes inside this so, that this is the density model for the complete data. So, this is how, I compute the density model complete data because, given the density model for the incomplete data. And because, I am I am hypothesizing, which are the missing variables that is how, I compute the density model for the complete data.

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- Hence density of complete data is

$$f(x_i, Z_i | \theta) = \prod_{j=1}^2 (\lambda_j \phi(x_i | \theta_j))^{Z_{ij}}$$

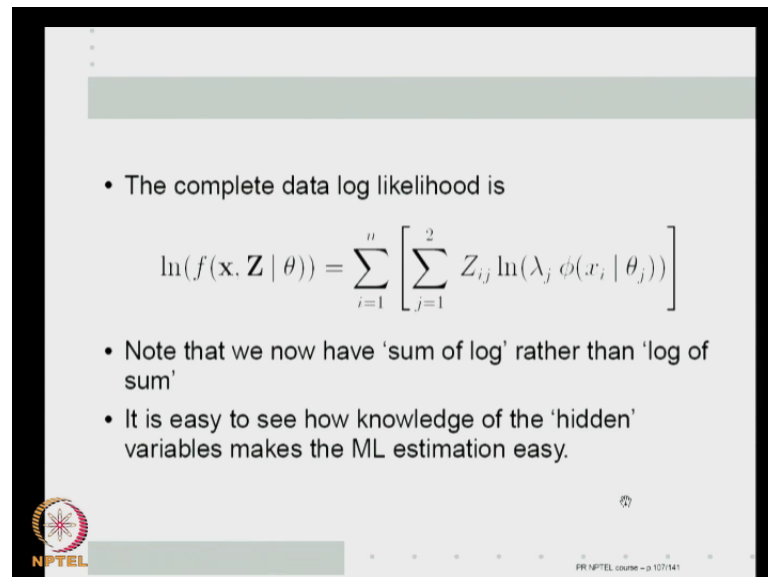
- Thus complete data likelihood is

$$f(\mathbf{x}, \mathbf{Z} | \theta) = \prod_{i=1}^n \left[\prod_{j=1}^2 (\lambda_j \phi(x_i | \theta_j))^{Z_{ij}} \right]$$

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So, the the complete data likelihood will be, this this symbol we are using for the complete data likelihood $f(\mathbf{X}, \mathbf{Z} | \theta)$, is product over i is equal to 1 to n of $f(\mathbf{X}_i, \mathbf{Z}_i | \theta)$ given θ , which is product over j is equal to 1 to 2 of this. So, this is my complete data likelihood.

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- The complete data log likelihood is


$$\ln(f(\mathbf{x}, \mathbf{Z} | \theta)) = \sum_{i=1}^n \left[\sum_{j=1}^2 Z_{ij} \ln(\lambda_j \phi(x_i | \theta_j)) \right]$$

- Note that we now have 'sum of log' rather than 'log of sum'
- It is easy to see how knowledge of the 'hidden' variables makes the ML estimation easy.

If I want complete data log likelihood, that is the complete data log likelihood now, before we will go to our E and M steps, let us look at this expression now, we have got rid of the sum of log. Instead of sum of log, we have got log of sum see now, log directly applies to ϕ 's so because, ϕ is exponential I can now, simplify this. The moment I hypothesize \mathbf{Z}_i , my complete data log likelihood is the old structure of sum of log rather than, log of sum, that I was getting, if I used only the mixture density.

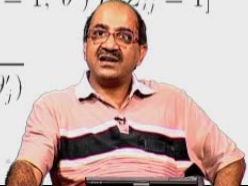
So, this is actually how, the knowledge of \mathbf{Z}_i has made the made the estimation simple because, the complete data log likelihood is the usual form of sum of log, and the way we have done n of examples of, how to maximize such things all right.

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Example: E-step

- For the E-step, we have to take expectation of Z w.r.t. distribution conditioned on x at a given value of θ .
- We have, for any θ' ,


$$\begin{aligned} E[Z_{ij} | x, \theta'] &= P[Z_{ij} = 1 | x, \theta'] = P[Z_{ij} = 1 | x_i, \theta'] \\ &= \frac{f(x_i | Z_{ij} = 1, \theta') P[Z_{ij} = 1]}{\sum_{j=1}^2 f(x_i | Z_{ij} = 1, \theta') P[Z_{ij} = 1]} \\ &= \frac{\lambda_j \phi(x_i | \theta'_j)}{\sum_{j=1}^2 \lambda_j \phi(x_i | \theta'_j)} \end{aligned}$$


So, now, let us do the E-step, in the E-step we have to take expectation of Z with respect to the distribution conditioned on X , at a given value of θ . So, what is the expected value of Z_{ij} conditioned on x and sum θ prime, Z_{ij} is a binary valued random variable so, its expectation will be probability it takes value 1. So, this is same as probability Z_i is equal to 1, conditioned on x and θ now, X 's are X_1, X_2, X_n they are iid and hence, Z_{ij} only depends on x_i , it does not depend on others.

So, this is probably Z_{ij} is equal to 1, conditioned on x_i and θ prime now, this expression now, I can do what, using Bayes theorem. So, using Bayes theorem I can write this as, f of x_i given Z_i is equal to 1, probability Z_i is equal to 1 and summation over j of the same thing. f of x_i given Z_i is equal to 1 and at a θ primes is nothing but, $\phi(x_i)$ given because, Z_{ij} is equal to 1, θ_j prime and this is λ_j right.


So, what does this give me, λ_j from this term and this will give me $\phi(x_i)$ given θ_j prime and the denominator is sum of the same thing over j . This expression is very familiar right, this is exactly the γ s, that we defined earlier.

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- Thus, $E[Z_{ij} | \mathbf{x}, \theta'] = \gamma_{ij}(\theta')$ where

$$\gamma_{ij}(\theta') = \frac{\lambda_j \phi(x_i | \theta'_j)}{\sum_{j=1}^2 \lambda_j \phi(x_i | \theta'_j)}$$
- This is the same γ_{ij} that we defined earlier.
- This notation emphasizes the fact that the value of γ_{ij} depends on the parameter vector.
- Now we need to do this expectation on the complete data log likelihood which is



So, Z_{ij} conditioned on \mathbf{X} and θ' is γ_{ij} of θ' now, I will write it as a function of θ' where, γ_{ij} is a θ' , is $\lambda_j \phi(x_i | \theta'_j)$ given θ'_j by summation over j of the same thing right. First notice that, this is the same γ_{ij} 's that we defined earlier only thing is, earlier also a saying γ_{ij} 's are functions of the parameters, this time this our notation makes it absolutely clear that, they are functions of the θ 's right.

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$$\ln(f(\mathbf{x}, \mathbf{Z} | \theta)) = \sum_{i=1}^n \left[\sum_{j=1}^2 Z_{ij} \ln(\lambda_j \phi(x_i | \theta_j)) \right]$$

- Thus, under the E-step, we get

$$Q(\theta, \theta^{(k)}) = \sum_{i=1}^n \left[\sum_{j=1}^2 E[Z_{ij} | \mathbf{x}, \theta^{(k)}] \ln(\lambda_j \phi(x_i | \theta_j)) \right]$$

$$= \sum_{i=1}^n \left[\sum_{j=1}^2 \gamma_{ij}(\theta^{(k)}) \ln(\lambda_j \phi(x_i | \theta_j)) \right]$$

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Now, we need to do this expectation and the complete data log likelihood right, which is the complete data log likelihood, this. So, to take expectation of this, expectation only of Z's so, only this term will get into the expectation. So, in the Q step what will I get, if I take expectation of log likelihood that is, Q theta, theta k is, i is equal to 1 to n expectation goes in, j is equal to 1 to 2 expectation goes in, expectation of Z i j given X gamma theta k, rest of it is not function of Z i j.

So, that comes out of the expectation all right this is the, as you can see this is the conditional expectation of the log likelihood of the complete data, conditioned on X and theta k. That is how see, this term is dependent on theta k, what comes out of that expectation, still depends on whole theta j's, the the the the variable theta j that is why, this is a function of Q theta, theta k all right. So now, this I have already calculated I can substitute for it, if I substitute for it, I get this so, my E-step is complete, I have computed my Q theta, theta k.

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Example: the M-step

- In the M-step, we find $\theta^{(k+1)}$ that maximizes (over θ),

$$\begin{aligned}
 Q(\theta, \theta^{(k)}) &= \sum_{i=1}^n \left[\sum_{j=1}^2 \gamma_{ij}(\theta^{(k)}) \ln(\lambda_j \phi(x_i | \theta_j)) \right] \\
 &= \sum_{i=1}^n \sum_{j=1}^2 \gamma_{ij}(\theta^{(k)}) \left[\ln(\lambda_j) - \ln(\sigma_j \sqrt{2\pi}) - \frac{(x_i - \mu_j)^2}{2\sigma_j^2} \right]
 \end{aligned}$$

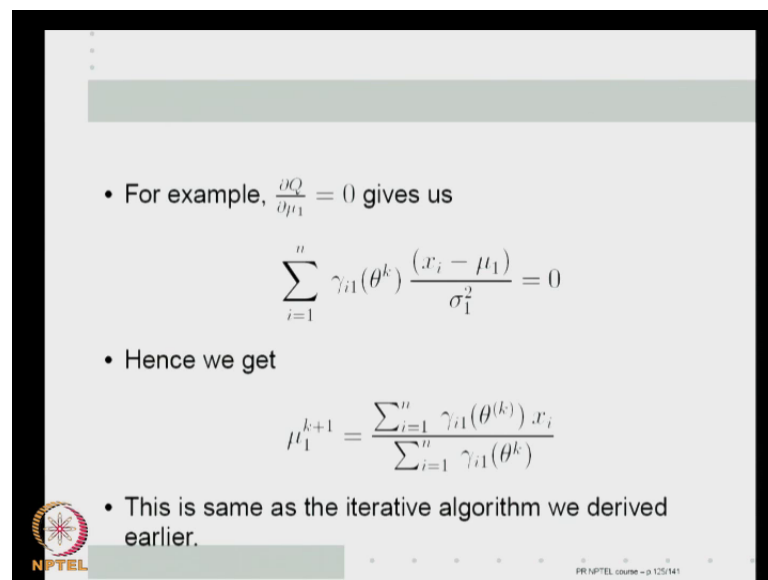
- This is now a simple optimization problem.

In the M-step, we have to find theta k plus 1, that maximizes Q theta, theta k over theta, this is my Q theta, theta k, as you can see this gamma i j's have now come in, at the expectation of those Z i j's conditioned on x and theta k. Now, if I substitute for my Gaussian, this will be ln lambda j minus, by the Gaussian this will be ln sigma j root 2 pi x x i minus mu j by sigma j square.

So, this is a very straight forward maximization note that, γ_{ij} 's are only a function of θ_k , they are not function of θ . When I am giving maximization with respect to θ , these are constant right so, if I want to maximize this subset to μ , only this term will contribute a derivative with respect to μ . So, if I did that, this is a very straight forward optimization problem simply because, these are no longer a functions of θ , this is like doing a single Gaussian estimation and we get that right.

Because, if I differentiate with respect to θ right I have say, with respect to μ , this 2 will come, this 2 will cancel, $x_i - \mu_j$ by σ_j^2 and this γ_{ij} θ_k , as coefficient all right.

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- For example, $\frac{\partial Q}{\partial \mu_1} = 0$ gives us

$$\sum_{i=1}^n \gamma_{i1}(\theta^k) \frac{(x_i - \mu_1)}{\sigma_1^2} = 0$$
- Hence we get

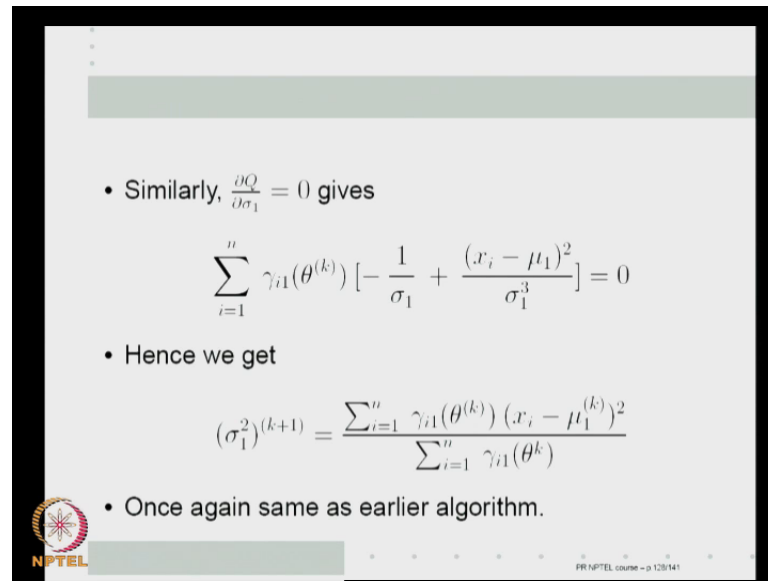
$$\mu_1^{k+1} = \frac{\sum_{i=1}^n \gamma_{i1}(\theta^{(k)}) x_i}{\sum_{i=1}^n \gamma_{i1}(\theta^k)}$$
- This is same as the iterative algorithm we derived earlier.

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So, that will give me μ_{1k+1} is this, is exactly like the expression we have got earlier right so, the earlier expressions we got are, what the EM algorithm gives us right.

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• Similarly, $\frac{\partial Q}{\partial \sigma_1} = 0$ gives

$$\sum_{i=1}^n \gamma_{i1}(\theta^{(k)}) \left[-\frac{1}{\sigma_1} + \frac{(x_i - \mu_1)^2}{\sigma_1^3} \right] = 0$$

• Hence we get

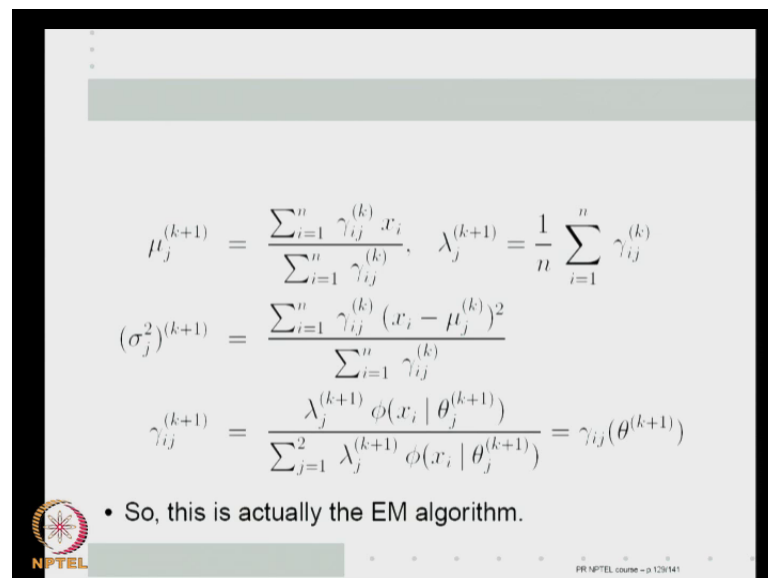
$$(\sigma_1^2)^{(k+1)} = \frac{\sum_{i=1}^n \gamma_{i1}(\theta^{(k)}) (x_i - \mu_1^{(k)})^2}{\sum_{i=1}^n \gamma_{i1}(\theta^{(k)})}$$

• Once again same as earlier algorithm.

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Similarly, if I had done with respect to sigma 1, I would have got the sigma 1 derivative and once again, I would have got the same expression as earlier.

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$$\mu_j^{(k+1)} = \frac{\sum_{i=1}^n \gamma_{ij}^{(k)} x_i}{\sum_{i=1}^n \gamma_{ij}^{(k)}}, \quad \lambda_j^{(k+1)} = \frac{1}{n} \sum_{i=1}^n \gamma_{ij}^{(k)}$$

$$(\sigma_j^2)^{(k+1)} = \frac{\sum_{i=1}^n \gamma_{ij}^{(k)} (x_i - \mu_j^{(k)})^2}{\sum_{i=1}^n \gamma_{ij}^{(k)}}$$

$$\gamma_{ij}^{(k+1)} = \frac{\lambda_j^{(k+1)} \phi(x_i | \theta_j^{(k+1)})}{\sum_{j=1}^2 \lambda_j^{(k+1)} \phi(x_i | \theta_j^{(k+1)})} = \gamma_{ij}(\theta^{(k+1)})$$

• So, this is actually the EM algorithm.

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So, now, I can go back and rewrite those equations right now, I will just wrote gamma i j k plus 1 as gamma i j theta k plus 1 right. This is the same slide, that we had earlier except the last line, this tells you, that the earlier iterative algorithm we got, is actually the EM algorithm for this particular example. So, I will stop here for this lecture, we completed this example so, next class, we will just briefly review this again and ask the

in general, what the EM algorithm is about. And then, briefly see, why the EM algorithm should converge and why, it gives us very nice way of doing mixture density estimation.

Thank you.