B.E E&C FIFTH SEMESTER SYLLABUS

MANAGEMENT AND ENTREPRENEURSHIP DEVELOPMENT

B.E., V Semester, EC/TC/EI/BM/ML

[As per Choice Based Credit System (CBCS) scheme]

Subject Code	15ES51	IA Marks	20
Number of Lecture	04	Exam Marks	80
Hours/Week			
Total Number of	50 (10 Hours / Module)	Exam Hours	03
Lecture Hours			
CDEDITC 04			

CREDITS - 04

Course Objectives: This course will enable students to:

- Understand basic skills of Management
- Understand the need for Entrepreneurs and their skills
- Understand Project identification and Selection
- Identify the Management functions and Social responsibilities
- Distinguish between management and administration

Module-1	RBT Level
Management: Nature and Functions of Management – Importance, Definition, Management Functions, Levels of Management, Roles of Manager, Managerial Skills, Management & Administration, Management as a Science, Art & Profession (Selected topics of Chapter 1, Text 1).	L1, L2
Planning: Planning-Nature, Importance, Types, Steps and Limitations of Planning; Decision Making – Meaning, Types and Steps in Decision Making(Selected topics from Chapters 4 & 5, Text 1).	
Module-2	
Organizing and Staffing: Organization -Meaning, Characteristics, Process of Organizing, Principles of Organizing, Span of Management (meaning and importance only), Departmentalisation, Committees–Meaning, Types of Committees; Centralization Vs Decentralization of Authority and Responsibility; Staffing -Need and Importance, Recruitment and Selection Process (Selected topics from Chapters 7, 8 & 11,Text 1).	L1, L2
Directing and Controlling: Meaning and Requirements of Effective Direction, Giving Orders; Motivation-Nature of Motivation, Motivation Theories (Maslow's Need-Hierarchy Theory and Herzberg's Two Factor Theory); Communication – Meaning, Importance and Purposes of Communication; Leadership-Meaning, Characteristics, Behavioural Approach of Leadership; Coordination-Meaning, Types, Techniques of Coordination; Controlling – Meaning, Need for Control System, Benefits of Control, Essentials of Effective Control System, Steps in Control Process (Selected topics from Chapters 15 to 18 and 9, Text 1).	
Module-3	
Social Responsibilities of Business: Meaning of Social Responsibility, Social Responsibilities of Business towards Different Groups, Social Audit, Business Ethics and Corporate Governance (Selected topics from Chapter 3, Text 1).	L1, L2

Entrepreneurship : Definition of Entrepreneur, Importance of Entrepreneurship, concepts of Entrepreneurship, Characteristics of successful Entrepreneur, Classification of Entrepreneurs, Myths of Entrepreneurship, Entrepreneurial Development models, Entrepreneurial development cycle, Problems faced by Entrepreneurs and capacity building for Entrepreneurship (Selected topics from Chapter 2, Text 2).	
Module-4	
Modern Small Business Enterprises: Role of Small Scale Industries, Impact of Globalization and WTO on SSIs, Concepts and definitions of SSI Enterprises, Government policy and development of the Small Scale sector in India, Growth and Performance of Small Scale Industries in India, Sickness in SSI sector, Problems for Small Scale Industries, Ancillary Industry and Tiny Industry (Definition only)(Selected topics from Chapter 1, Text 2).	L1, L2
Institutional Support for Business Enterprises: Introduction, Policies & Schemes of Central Level Institutions, State Level Institutions (Selected topics from Chapter 4, Text 2).	
Module-5	
Projects Management: AProject. Search for a Business idea: Introduction, Choosing an Idea, Selection of product, The Adoption process, Product Innovation, Product Planning and Development Strategy, Product Planning and Development Process. Concepts of Projects and Classification: Introduction, Meaning of Projects, Characteristics of a Project, Project Levels, Project Classification, Aspects of a Project, The project Cycle, Features and Phases of Project management, Project Management Processes. Project Identification: Feasibility Report, Project Feasibility Analysis. Project Formulation: Meaning, Steps in Project formulation, Sequential Stages of Project Formulation, Project Evaluation.	L1, L2, L3
Project Design and Network Analysis: Introduction, Importance of Network Analysis, Origin of PERT and CPM, Network, Network Techniques, Need for Network Techniques, Steps in PERT, CPM, Advantages, Limitations and Differences.	
(Selected topics from Chapters 16 to 20 of Unit 3, Text 3).	

Course Outcomes: After studying this course, students will be able to:

- Understand the fundamental concepts of Management and Entrepreneurship
- Select a best Entrepreneurship model for the required domain of establishment
- Describe the functions of Managers, Entrepreneurs and their social responsibilities
- Compare various types of Entrepreneurs
- Analyze the Institutional support by various state and central government agencies

Question paper pattern

- The question paper will have TEN questions.
- Each full question carries 16 marks.
- There will be two full questions (with a maximum of Three sub questions) from each module.
- Each full question will have sub questions covering all topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1. Principles of Management P.C Tripathi, P.N Reddy, McGraw Hill Education, 6th Edition, 2017. ISBN-13:978-93-5260-535-4.
- **2.** Entrepreneurship Development Small Business Enterprises- Poornima M Charantimath, Pearson Education 2008, ISBN 978-81-7758-260-4.
- **3.** Dynamics of Entrepreneurial Development and Management by Vasant Desai. HPH 2007, ISBN: 978-81-8488-801-2.

Reference Book:

Essentials of Management: An International, Innovation and Leadership perspective by Harold Koontz, Heinz Weihrich McGraw Hill Education, 10th Edition 2016. ISBN- 978-93-392-2286-4.

DIGITAL SIGNAL PROCESSING

B.E., V Semester, Electronics & Communication Engineering / **Telecommunication Engineering**

[As per Choice Based Credit System (CBCS) scheme]

Subject Code	15EC52	IA Marks	20
Number of Lecture	04	Exam Marks	80
Hours/Week			
Total Number of	50 (10 Hours / Module)	Exam Hours	03
Lecture Hours			
CDEDITS 04			

Course objectives: This course will enable students to

- Understand the frequency domain sampling and reconstruction of discrete time signals.
- Study the properties and the development of efficient algorithms for the computation of DFT.
- Realization of FIR and IIR filters in different structural forms.
- Learn the procedures to design of IIR filters from the analog filters using impulse invariance and bilinear transformation.
- Study the different windows used in the design of FIR filters and design appropriate filters based on the specifications.

Modules				
Module-1	RBT			
Discrete Fourier Transforms (DFT): Frequency domain sampling and	Level L1, L2			
reconstruction of discrete time signals. DFT as a linear transformation, its	L1, L2			
relationship with other transforms. Properties of DFT, multiplication of two				
DFTs- the circular convolution.				
Module-2				
Additional DFT properties, use of DFT in linear filtering, overlap-save and	L1, L2,			
overlap-add method. Fast-Fourier-Transform (FFT) algorithms: Direct	L3			
computation of DFT, need for efficient computation of the DFT (FFT				
algorithms).				
Module-3				
Radix-2 FFT algorithm for the computation of DFT and IDFT-decimation-in-time				
and decimation-in-frequency algorithms. Goertzel algorithm, and chirp-z	L3			
transform.				
Module-4				
Structure for IIR Systems: Direct form, Cascade form, Parallel form structures.	L1, L2,			
IIR filter design: Characteristics of commonly used analog filter - Butterworth	L3			
and Chebyshev filters, analog to analog frequency transformations.				
Design of IIR Filters from analog filter using Butterworth filter: Impulse				
invariance, Bilinear transformation.				
Module-5				
Structure for FIR Systems: Direct form, Linear Phase, Frequency sampling	L1, L2,			

structure, Lattice structure.
FIR filter design: Introduction to FIR filters, design of FIR filters us

FIR filter design: Introduction to FIR filters, design of FIR filters using - Rectangular, Hamming, Hanning and Bartlett windows.

Course Outcomes: After studying this course, students will be able to:

- Determine response of LTI systems using time domain and DFT techniques.
- Compute DFT of real and complex discrete time signals.
- Computation of DFT using FFT algorithms and linear filtering approach.
- Solve problems on digital filter design and realize using digital computations.

Question paper pattern:

- The question paper will have ten questions
- Each full question consists of 16 marks.
- There will be 2 full questions (with a maximum of three sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Book:

Digital signal processing – Principles Algorithms & Applications, Proakis & Monalakis, Pearson education, 4th Edition, New Delhi, 2007.

Reference Books:

- 1. Discrete Time Signal Processing, Oppenheim & Schaffer, PHI, 2003.
- 2. Digital Signal Processing, S. K. Mitra, Tata Mc-Graw Hill, 3rd Edition, 2010.
- 3. Digital Signal Processing, Lee Tan: Elsevier publications, 2007.

L3

Verilog HDL

B.E., V Semester, Electronics & Communication Engineering/ Telecommunication Engineering

[As per Choice Based Credit System (CBCS) scheme]

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Subject Code	15EC53	IA Marks	20
Number of Lecture	04	Exam Marks	80
Hours/Week			
Total Number of	50 (10 Hours / Module)	Exam Hours	03
Lecture Hours			

CREDITS - 04

Course objectives: This course will enable students to:

- Differentiate between Verilog and VHDL descriptions.
- Learn different Verilog HDL and VHDL constructs.
- Familiarize the different levels of abstraction in Verilog.
- Understand Verilog Tasks and Directives.
- Understand timing and delay Simulation.
- Learn VHDL at design levels of data flow, behavioral and structural for effective modeling of digital circuits.

Module-1	RBT Level
Overview of Digital Design with Verilog HDL	L1, L2,
Evolution of CAD, emergence of HDLs, typical HDL-flow, why Verilog HDL?, trends in HDLs. (Text1)	L3
Hierarchical Modeling Concepts	
Top-down and bottom-up design methodology, differences between	
modules and module instances, parts of a simulation, design block,	
stimulus block. (Text1)	
Module-2	
Basic Concepts	L1, L2,
Lexical conventions, data types, system tasks, compiler directives. (Text1)	L3
Modules and Ports	
Module definition, port declaration, connecting ports, hierarchical name referencing. (Text1)	
Module-3	
Gate-Level Modeling	L1, L2,
Modeling using basic Verilog gate primitives, description of and/or and	L3
buf/not type gates, rise, fall and turn-off delays, min, max, and typical	
delays. (Text1)	
Dataflow Modeling	
Continuous assignments, delay specification, expressions, operators, operands, operator types. (Text1)	
Module-4	
Behavioral Modeling	L1, L2,
Structured procedures, initial and always, blocking and non-blocking	L3

statements, delay control, generate statement, event control, conditional statements, Multiway branching, loops, sequential and parallel blocks.	
(Text1)	
Module-5	
Introduction to VHDL	L1, L2,
Introduction: Why use VHDL?, Shortcomings, Using VHDL for Design	L3
Synthesis, Design tool flow, Font conventions.	
Entities and Architectures: Introduction, A simple design, Design	
entities, Identifiers, Data objects, Data types, and Attributes. (Text 2)	

Course Outcomes: At the end of this course, students should be able to

- Write Verilog programs in gate, dataflow (RTL), behavioral and switch modeling levels of Abstraction.
- Write simple programs in VHDL in different styles.
- Design and verify the functionality of digital circuit/system using test benches.
- Identify the suitable Abstraction level for a particular digital design.
- Write the programs more effectively using Verilog tasks and directives.
- Perform timing and delay Simulation.

Question paper pattern:

- The question paper will have ten questions
- Each full question consists of 16 marks.
- There will be 2 full questions (with a maximum of three sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module
- The students will have to answer 5 full questions, selecting one full question from each module

Text Books:

- 1. Samir Palnitkar, "Verilog HDL: A Guide to Digital Design and Synthesis", Pearson Education, Second Edition.
- 2. Kevin Skahill, "VHDL for Programmable Logic", PHI/Pearson education, 2006.

Reference Books:

- 1. Donald E. Thomas, Philip R. Moorby, "The Verilog Hardware Description Language", Springer Science+Business Media, LLC, Fifth edition.
- 2. Michael D. Ciletti, "Advanced Digital Design with the Verilog HDL" Pearson (Prentice Hall), Second edition.
- 3. Padmanabhan, Tripura Sundari, "Design through Verilog HDL", Wiley, 2016 or earlier.

INFORMATION THEORY AND CODING

B.E., V Semester, Electronics & Communication Engineering / Telecommunication Engineering

[As per Choice Based Credit System (CBCS) scheme]

Subject Code	15EC54	IA Marks	20	
Number of Lecture	04	Exam Marks	80	
Hours/Week				
Total Number of	50 (10 Hours / Module)	Exam Hours	03	
Lecture Hours				
CREDITS – 04				

Course Objectives: This course will enable students to:

- Understand the concept of Entropy, Rate of information and order of the source with reference to dependent and independent source.
- Study various source encoding algorithms.
- Model discrete & continuous communication channels.
- Study various error control coding algorithms.

Modules		
Module-1	RBT Level	
Information Theory: Introduction, Measure of information, Information	L1, L2,	
content of message, Average Information content of symbols in Long	L3	
Independent sequences, Average Information content of symbols in Long		
dependent sequences, Markov Statistical Model of Information Sources,		
Entropy and Information rate of Markoff Sources (Section 4.1, 4.2 of Text		
1).		
Module-2		
Source Coding : Source coding theorem, Prefix Codes, Kraft McMillan	L1, L2,	
Inequality property – KMI (Section 2.2 of Text 2).	L3	
Encoding of the Source Output, Shannon's Encoding Algorithm (Sections		
4.3, 4.3.1 of Text 1).		
Shannon Fano Encoding Algorithm, Huffman codes, Extended Huffman		
coding, Arithmetic Coding, Lempel - Ziv Algorithm (Sections 3.6, 3.7, 3.8,		
3.10 of Text 3).		
Module-3		
Information Channels: Communication Channels (Section 4.4 of Text 1).	L1, L2,	
Channel Models, Channel Matrix, Joint probabilty Matrix, Binary	L3	
Symmetric Channel, System Entropies, Mutual Information, Channel		
Capacity, Channel Capacity of : Binary Symmetric Channel, Binary Erasure Channel, Muroga, Theorem, Contineuos Channels (Sections 4.2,		
4.3, 4.4, 4.6, 4.7 of Text 3).		
Module-4		

Error Control Coding:	L1, L2,
Introduction, Examples of Error control coding, methods of Controlling	L3
Errors, Types of Errors, types of Codes, Linear Block Codes: matrix	
description of Linear Block Codes, Error Detection and Error Correction	
Capabilities of Linear Block Codes, Single Error Correcting hamming	
Codes, Table lookup Decoding using Standard Array.	
Binary Cyclic Codes: Algebraic Structure of Cyclic Codes, Encoding using	
an (n-k) Bit Shift register, Syndrome Calculation, Error Detection and	
Correction	
(Sections 9.1, 9.2, 9.3, 9.3.1, 9.3.2, 9.3.3 of Text 1).	
Module-5	
Some Important Cyclic Codes: Golay Codes, BCH Codes(Section 8.4 –	L1, L2,
Article 5 of Text 2).	L3
Convolution Codes : Convolution Encoder, Time domain approach, Transform domain approach, Code Tree, Trellis and State Diagram, The Viterbi Algorithm) (Section 8.5 – Articles 1,2 and 3, 8.6- Article 1 of Text 2).	
vice of rigorithm, (Section 5.5) rideles 1,2 and 5, 5.5 ridele 1 of text 2).	

Course Outcomes: At the end of the course the students will be able to:

- Explain concept of Dependent & Independent Source, measure of information, Entropy, Rate of Information and Order of a source
- Represent the information using Shannon Encoding, Shannon Fano, Prefix and Huffman Encoding Algorithms
- Model the continuous and discrete communication channels using input, output and joint probabilities
- Determine a codeword comprising of the check bits computed using Linear Block codes, cyclic codes & convolutional codes
- Design the encoding and decoding circuits for Linear Block codes, cyclic codes, convolutional codes, BCH and Golay codes.

Question paper pattern:

- The question paper will have ten questions
- Each full question consists of 16 marks.
- There will be 2 full questions (with a maximum of three sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module
- The students will have to answer 5 full questions, selecting one full question from each module

Text Books:

- 1. Digital and analog communication systems, K. Sam Shanmugam, John Wiley India Pvt. Ltd, 1996.
- 2. Digital communication, Simon Haykin, John Wiley India Pvt. Ltd, 2008.
- 3. Information Theory and Coding, Muralidhar Kulkarni, K.S. Shivaprakasha, Wiley India Pvt. Ltd, 2015, ISBN:978-81-265-5305-1.

Reference Books:

- 1. ITC and Cryptography, Ranjan Bose, TMH, II edition, 2007
- 2. Principles of digital communication, J. Das, S. K. Mullick, P. K. Chatterjee, Wiley, 1986 Technology & Engineering

- 3. Digital Communications Fundamentals and Applications, Bernard Sklar, Second Edition, Pearson Education, 2016, ISBN: 9780134724058.
- 4. Information Theory and Coding, K.N.Haribhat, D.Ganesh Rao, Cengage Learning, 2017.

NANOELECTRONICS

B.E., V Semester, Electronics & Communication Engineering / Telecommunication Engineering

[As per Choice Based Credit System (CBCS) scheme]

Subject Code	15EC551	IA Marks	20
Number of Lecture	03	Exam Marks	80
Hours/Week			
Total Number of	40 (8 Hours / Module)	Exam Hours	03
Lecture Hours			

CREDITS - 03

Course Objectives: This course will enable students to:

- Enhance basic engineering science and technical knowledge of nanoelectronics.
- Explain basics of top-down and bottom-up fabrication process, devices and systems.
- Describe technologies involved in modern day electronic devices.
- Know various nanostructures of carbon and the nature of the carbon bond itself.
- Learn the photo physical properties of sensor used in generating a signal.

Module-1	RBT
Module 1	Level
Introduction: Overview of nanoscience and engineering. Development milestones in microfabrication and electronic industry. Moore's law and continued miniaturization, Classification of Nanostructures, Electronic properties of atoms and solids: Isolated atom, Bonding between atoms, Giant molecular solids, Free electron models and energy bands, crystalline solids, Periodicity of crystal lattices, Electronic conduction, effects of nanometerlength scale, Fabrication methods: Top down processes, Bottom up processes methods for templating the growth of nanomaterials, ordering of nanosystems (Text 1).	L1, L2
Module-2	
Characterization: Classification, Microscopic techniques, Field ion microscopy, scanning probe techniques, diffraction techniques: bulk and surface diffraction techniques (Text 1). Inorganic semiconductor nanostructures: overview of semiconductor physics. Quantum confinement in semiconductor nanostructures: quantum wells, quantum wires, quantum dots, super-lattices, band offsets, electronic density of states (Text 1).	L1, L2
Module-3	
Fabrication techniques: requirements of ideal semiconductor, epitaxial growth of quantum wells, lithography and etching, cleaved-edge over growth, growth of vicinal substrates, strain induced dots and wires, electrostatically induced dots and wires, Quantum well width fluctuations, thermally annealed quantum wells, semiconductor nanocrystals, collidal quantum dots, self-assembly techniques.(Text 1). Physical processes: modulation doping, quantum hall effect, resonant tunneling, charging effects, ballistic carrier transport, Inter band absorption, intraband absorption, Light emission processes, phonon bottleneck, quantum confined stark effect, nonlinear effects, coherence and dephasing, characterization of semiconductor nanostructures: optical	L1, L2

electrical and structural (Text 1).	
Module-4	
Carbon Nanostructures: Carbon molecules, Carbon Clusters, Carbon Nanotubes, application of Carbon Nanotubes. (Text 2)	L1, L2
Module-5	
 Nanosensors: Introduction, What is Sensor and Nanosensors?, What makes them Possible?, Order From Chaos, Characterization, Perception, Nanosensors Based On Quantum Size Effects, Electrochemical Sensors, Sensors Based On Physical Properties, Nanobiosensors, Smart dust Sensor for the future. (Text 3) Applications: Injection lasers, quantum cascade lasers, single-photon sources, biological tagging, optical memories, coulomb blockade devices, photonic structures, QWIP's, NEMS, MEMS (Text 1). Course outcomes: After studying this course, students will be able to: Know the principles behind Nanoscience engineering and Nanoelectronics. Know the effect of particles size on mechanical, thermal, optical and electrical properties of nanomaterials. Know the properties of carbon and carbon nanotubes and its applications. Know the properties used for sensing and the use of smart dust sensors. Apply the knowledge to prepare and characterize nanomaterials. Analyse the process flow required to fabricate state-of-the-art 	L1, L2

Question paper pattern:

- The question paper will have ten questions
- Each full question consists of 16 marks.
- There will be 2 full questions (with a maximum of three sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module
- The students will have to answer 5 full questions, selecting one full question from each module

Text Books:

- 1. Ed Robert Kelsall, Ian Hamley, Mark Geoghegan, "Nanoscale Science and Technology", John Wiley, 2007.
- 2. Charles P Poole, Jr, Frank J Owens, "Introduction to Nanotechnology", John Wiley, Copyright 2006, Reprint 2011.
- 3. T Pradeep, "Nano: The essentials-Understanding Nanoscience and Nanotechnology", TMH.

Reference Book:

Ed William A Goddard III, Donald W Brenner, Sergey E. Lyshevski, Gerald J Iafrate, "Hand Book of Nanoscience Engineering and Technology", CRC press, 2003.

SWITCHING & FINITE AUTOMATA THEORY

B.E., V Semester, Electronics & Communication Engineering / Telecommunication Engineering

[As per Choice Based Credit System (CBCS) scheme]

Subject Code	15EC552	IA Marks	20
Number of Lecture	03	Exam Marks	80
Hours/Week		-	
Total Number of	40 (8 Hours / Module)	Exam Hours	03
Lecture Hours	,		

CREDITS - 03

Course Objectives: This course will enable students to:

- 1. Understand the basics of threshold logic, effect of hazards on digital circuits and techniques of fault detection
- 2. Explain finite state model and minimization techniques
- 3. Know structure of sequential machines, and state identification
- 4. Understand the concept of fault detection experiments

Modules

Module-1	RBT
	Level
Threshold Logic : Introductory Concepts: Threshold element, capabilities	
and limitations of threshold logic, Elementary Properties, Synthesis of	L3
Threshold networks: Unate functions, Identification and realization of	
threshold functions, The map as a tool in synthesizing threshold networks.	
(Sections 7.1, 7.2 of Text)	
Module-2	
Reliable Design and Fault Diagnosis : Hazards, static hazards, Design of Hazard-free Switching Circuits, Fault detection in combinational circuits, Fault detection in combinational circuits: The faults, The Fault Table, Covering the fault table, Fault location experiments: Preset experiments, Adaptive experiments, Boolean differences, Fault detection by path sensitizing. (Sections 8.1, 8.2, 8.3, 8.4, 8.5 of Text)	L1, L2, L3
Module-3	
Sequential Machines: Capabilities, Minimization and Transformation	L1, L2,
The Finite state model and definitions, capabilities and limitations of finite state machines, State equivalence and machine minimization: k-equivalence, The minimization Procedure, Machine equivalence, Simplification of incompletely specified machines. (Section 10.1, 10.2, 10.3, 10.4 of Text)	L3
Module-4	
Structure of Sequential Machines: Introductory example, State assignment using partitions: closed partitions, The lattice of closed partitions, Reduction of output dependency, Input dependence and autonomous clocks, Covers and generation of closed partitions by state splitting: Covers, The implication graph, An application of state splitting to parallel decomposition. (Section 12.1, 12.2, 12.3, 12.4, 12.5, 12.6 of Text)	
Module-5	
State-Identification and Fault Detection Experiments: Experiments, Homing experiments, Distinguishing experiments, Machine identification,	L1, L2, L3

Fault detection experiments, Design of diagnosable machines, Second algorithm for the design of fault detection experiments. (Sections 13.1, 13.2, 13.3, 13.4, 13.5, 13.6, 13.7 of Text)

Course outcomes: At the end of the course, students should be able to:

- Explain the concept of threshold logic
- Understand the effect of hazards on digital circuits and fault detection and analysis
- Define the concepts of finite state model
- Analyze the structure of sequential machine
- Explain methods of state identification and fault detection experiments

Question paper pattern:

- The question paper will have ten questions
- Each full question consists of 16 marks.
- There will be 2 full questions (with a maximum of three sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module
- The students will have to answer 5 full questions, selecting one full question from each module

Text Book:

Switching and Finite Automata Theory – Zvi Kohavi, McGraw Hill, 2nd edition, 2010 ISBN: 0070993874.

Reference Books:

- 1. **Fault Tolerant And Fault Testable Hardware Design-**Parag K Lala, Prentice Hall Inc. 1985.
- 2. **Digital Circuits and Logic Design**.-Charles Roth Jr, Larry L. Kinney, Cengage Learning, 2014, ISBN: 978-1-133-62847-7.

OPERATING SYSTEM

B.E., V Semester, Electronics & Communication Engineering / Telecommunication Engineering

[As per Choice Based Credit System (CBCS) scheme]

Subject Code	15EC553	IA Marks	20
Number of Lecture	03	Exam Marks	80
Hours/Week			
Total Number of	40 (8 Hours / Module)	Exam Hours	03
Lecture Hours			

CREDITS - 03

Course objectives: This course will enable students to:

- Understand the services provided by an operating system.
- Understand how processes are synchronized and scheduled.
- Understand different approaches of memory management and virtual memory management.
- Understand the structure and organization of the file system
- Understand interprocess communication and deadlock situations.

Module-1	RBT
Introduction to Operating Systems	Level
Introduction to Operating Systems OS, Goals of an OS, Operation of an OS, Computational Structures,	LI, L&
Resource allocation techniques, Efficiency, System Performance and User	
Convenience, Classes operating System, Batch processing, Multi	
programming, Time Sharing Systems, Real Time and distributed Operating	
Systems (Topics from Sections 1.2, 1.3, 2.2 to 2.8 of Text).	
Module-2	
Process Management: OS View of Processes, PCB, Fundamental State	L1, L2
Transitions, Threads, Kernel and User level Threads, Non-preemptive	LI, La
scheduling- FCFS and SRN, Preemptive Scheduling- RR and LCN, Long	
term, medium term and short term scheduling in a time sharing system	
(Topics from Sections 3.3, 3.3.1 to 3.3.4, 3.4, 3.4.1, 3.4.2, 4.2, 4.3, 4.4.1	
of Text).	
Module-3	
Memory Management: Contiguous Memory allocation, Non-Contiguos	L1, L2
Memory Allocation, Paging, Segmentation, Segmentation with paging,	ŕ
Virtual Memory Management, Demand Paging, Paging Hardware, VM	
handler, FIFO, LRU page replacement policies (Topics from Sections 5.5 to	
5.9, 6.1 to 6.3, except Optimal policy and 6.3.1of Text).	
Module-4	
File Systems: File systems and IOCS, File Operations, File Organizations,	L1, L2, L3
Directory structures, File Protection, Interface between File system and	
IOCS, Allocation of disk space, Implementing file access (Topics from	
Sections 7.1 to 7.8 of Text).	
Module-5	
Message Passing and Deadlocks: Overview of Message Passing,	L1, L2, L3
Implementing message passing, Mailboxes, Deadlocks, Deadlocks in	
resource allocation, Resource state modelling, Deadlock detection	
algorithm, Deadlock Prevention (Topics from Sections 10.1 to 10.3, 11.1 to	

11.5 of Text).

Course outcomes: After studying this course, students will be able to:

- Explain the goals, structure, operation and types of operating systems.
- Apply scheduling techniques to find performance factors.
- Explain organization of file systems and IOCS.
- Apply suitable techniques for contiguous and non-contiguous memory allocation.
- Describe message passing, deadlock detection and prevention methods.

Question paper pattern:

- The question paper will have ten questions
- Each full question consists of 16 marks.
- There will be 2 full questions (with a maximum of three sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module
- The students will have to answer 5 full questions, selecting one full question from each module

Text Book:

Operating Systems - A concept based approach, by Dhamdare, TMH, 2nd edition.

Reference Books:

- 1. Operating systems concepts, Silberschatz and Galvin, John Wiley India Pvt. Ltd, 5th edition,2001.
- 2. Operating system-internals and design system, William Stalling, Pearson Education, 4th ed, 2006.
- 3. Design of operating systems, Tannanbhaum, TMH, 2001.

ELECTRICAL ENGINEERING MATERIALS

B.E., V Semester, Electronics & Communication Engineering/ Telecommunication Engineering

[As per Choice Based Credit System (CBCS) scheme]

Subject Code	15EC554	IA Marks	20
Number of Lecture	03	Exam Marks	80
Hours/Week			
Total Number of	40 (8 Hours/Module)	Exam Hours	03
Lecture Hours			
CREDITS - 03			

Course Objectives: This course will enable students to:

- Understand the formation of bands in materials and the classification of materials on the basis of band theory
- Understand the classification of magnetic materials on the basis of their behavior in an external magnetizing field.
- Understand the characteristics and properties of conducting and superconducting materials
- Understand the electrical characteristics of the material to be considered on the basis of their uses.
- Classify electrical engineering materials into low and high resistance materials

Modules				
Module-1	RBT Level			
Band Theory of Solids: Introduction to free electron theory, Kroning-Penney Model, Explanation for Discontinuities in E vs. K curve, Formation of Solid Material, Formation of Band in Metals, Formation of Bands in Semiconductors and Insulating Materials, Classification of Materials on the Basis of Band Structure, Explanation for differences in the Electrical properties of different Materials. Important Characteristics of a Band Electron, Number of energy states per band, Explanation for Insulating and Metallic Behavior of Materials, Concept of Hole.	L1, L2			
Module-2				
Magnetic Properties of Materials: Introduction, Origin of Magnetism, Basic Terms in Magnetism, Relation between Magnetic Permeability and Susceptibility, Classification of magnetic Materials, Characteristics of Diamagnetic Materials, Paramagnetic Materials, Ferromagnetic Materials, Explanation of Dia, Para and Ferromagnetism, Ampere's Lam in Dia, Para and Ferromagnetism, Hystersis and Hystersis loss, Langevin's Theory of paramagnetism, Modification in the Langevin's Theory, Anti-Ferromagnetism and Neel Temperature, Ferrimagnetic Materials, Properties of some important Magnetic Materials, Magentostriction and Magnetostrictive Materials, Hard and Soft Ferromagnetic Materials and their Applications.	L1, L2			
Module-3				
Behavior of Dielectric Materials in AC and DC Fields: Introduction, Classification of Dielectric Materials at Microscopic level, Polar Dielectric Materials, Non-polar Dielectric Materials, Kinds of Polarizations, behavior of	L1, L2			

dielectric materials, Three electric Vectors, Gauss's Law in a Dielectric, Electric Susceptibility and Static Dielectric constant, Effect of Dielectric medium upon capacitance, macroscopic electric field, Microscopic Electric field, temperature dependence of dielectric constant, polar dielectric in ac and dc fields, behavior of polar dielectric at high frequencies, Dielectric loss, Dielectric strength and Dielectric Breakdown, Various kinds of Dielectric Materials, Hysteresis in Ferroelectric Materials, Applications of Ferroelectric Materials in Devices.

Module-4

Conductivity of Metals and Superconductivity: Introduction, Ohm's law, Explanation for the dependence of electrical resistivity upon temperature, Free-electron theory of metals, Application of Lorentz-Drude free-electron theory, Effect of various parameters on Electrical Conductivity, Resistivity Ratio, Variation of resistivity of alloys with temperature, Thermal Conductivity of Materials, Heat produced in Current Carrying Conductor, Thermoelectric Effect, Thermoelectric Series, Seebeck's Experiment.

Discovery of superconductivity, superconductivity and transition temperature, superconducting materials, explanation of superconductivity phenomenon, characteristics of superconductors, change in thermodynamic parameters in superconducting state, frequency dependence of superconductivity, current status of high temperature superconductors, practical applications of superconductors.

Module-5

Electrical Conducting and Insulating materials: Introduction, Classification of conducting materials, difference in properties of Hard-Drawn and Annealed copper, standard conductors, comparison between some popular Low-Resistivity Materials, Low-Resistivity Copper Alloys, Electrical contact materials and their selection, classification of contact materials, Materials for Lamp Filaments, Preparation of Tungsten Filaments.

Insulating gases, Liquids and solids and their characteristics, Selection of the insulating material, other important properties of Insulating materials, Thermal characteristics, chemical properties of Insulating materials, classification of Insulating materials on the basis of structure.

Course Outcomes: At the end of the course, students will be able to

- Understand the various kinds of materials and their applications in ac and dc fields.
- Understand the conductivity of superconductivity of materials.
- Explain the electrical properties of different materials and metallic behavior of materials on the basis of band theory.
- Explain the properties and applications of all kind of magnetic materials.
- Explain the properties of electrical conducting and insulating materials.
- Assess a variety of approaches in developing new materials with enhanced performance to replace existing materials.

Question paper pattern:

• The question paper will have ten questions

L1, L2

L1, L2

- Each full question consists of 16 marks.
- There will be 2 full questions (with a maximum of three sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module
- The students will have to answer 5 full questions, selecting one full question from each module

Text Book:

R K Shukla and Archana Singh, "Electrical Engineering Materials" McGraw Hill, 2012, ISBN: 978-1-25-90062-03.

Reference Books:

- 1. S.O. KASAP, "Electronic Materials and Devices" 3rd edition, McGraw Hill, 2014, ISBN-978-0-07-064820-3.
- **2.** C.S.Indulkar and S. Thiruvengadam, S., "An Introduction to Electrical Engineering Materials", ISBN-9788121906661.

MSP430 MICROCONTROLLER

B.E., V Semester, Electronics & Communication Engineering

[As per Choice Based Credit System (CBCS) scheme]

Subject Code	15EC555	IA Marks	20
Number of Lecture	03	Exam Marks	80
Hours/Week			
Total Number of	40 (8 Hours / Module)	Exam Hours	03
Lecture Hours			

CREDITS – 03

Course objectives: This course will enable students to:

- Understand the architectural features and instruction set of 16 bit microcontroller MSP430.
- Program MSP430 using the various instructions for different applications.
- Understand the functions of the various peripherals which are interfaced with MSP430.
- Describe the power saving modes in MSP430.
- Explain the low power applications using MSP430.

Module-1	RBT Level
MSP430 Architecture: Introduction -Where does the MSP430 fit, The	L1, L2
outside view, The inside view-Functional block diagram, Memory, Central	
Processing Unit, Memory Mapped Input and Output, Clock Generator,	
Exceptions: Interrupts and Resets, MSP430 family.	
(Text: Ch1- 1.3 to 1.7, Ch2- 2.1 to 2.7, Ch5- 5.1, 5.7 up to 5.7.1)	
Module-2	
Addressing Modes & Instruction Set-Addressing Modes, Instruction set,	L1, L2, L3
Constant Generator and Emulated Instructions, Program Examples.	
(Text: Ch5- 5.2 to 5.5)	
Module-3	
Clock System, Interrupts and Operating Modes-Clock System,	L1, L2
Interrupts, What happens when an interrupted is requested, Interrupt	
Service Routines, Low Power Modes of Operation, Watchdog Timer, Basic	
Timer1, Real Time Clock, Timer-A: Timer Block, Capture/Compare	
Channels, Interrupts from Timer-A.	
(Text: Ch5 - 5.8 upto 5.8.4, Ch 6-6.6 to 6.8, 6.10, Ch8 -8.1, 8.2, 8.3)	
Module-4	
Analog Input-Output and PWM - Comparator-A, ADC10, ADC12, Sigma-	L1, L2
Delta ADC, Internal Operational Amplifiers, DAC, Edge Aligned PWM,	
Simple PWM, Design of PWM.	
LCD interfacing.	
(Text: Ch9 – 9.1 up to 9.1.2, 9.4, 9.5 up to 9.5.1, 9.7, 9.8 up to 9.8.1,	
9.11.5, 9.12 (without 9.12.1), 8.6.2 to 8.6.4)	
Module-5	

Digital Input-Output and Serial Communication:	L1, L2, L3
Parallel Ports, Lighting LEDs, Flashing LEDs, Read Input from a Switch,	
Toggle the LED state by pressing the push button, LCD interfacing.	
Asynchronous Serial Communication, Asynchronous Communication with	
USCI_A, Communications, Peripherals in MSP430, Serial Peripheral	
Interface.	
(Text: Selected topics from Ch4 & Ch7 and Ch7-7.1, Ch10 - 10.1, 10.2,	
and 10.12)	
Course outcomes: After studying this course, students will be able to:	
Understand the architectural features and instruction set of 16 bit	
microcontroller MSP430.	
 Develop programs using the various instructions of MSP430 for 	
different applications.	
 Understand the functions of the various peripherals which are 	
interfaced with MSP430 microcontroller.	
• Describe the power saving modes in MSP430.	
• Explain the low power applications using MSP430 microcontroller.	

Evaluation of Internal Assessment Marks:

It is suggested that at least a few simple programs to be executed by students using any evaluation board of MSP430 for better understanding of the course. This activity can be considered for the evaluation of 5 marks out of 20 Internal assessment marks, reserved for the other activities.

Question paper pattern:

- The question paper will have ten questions
- Each full question consists of 16 marks.
- There will be 2 full questions (with a maximum of three sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module
- The students will have to answer 5 full questions, selecting one full question from each module

Text Book:

John H Davies, MSP430 Microcontroller Basics, Newnes Publications, Elsevier, 2008.

References:

- 1. Chris Nagy, Embedded Systems Design using TI MSP430 Series, Newnes Publications, Elsevier, 2003.
- 2. User Guide from Texas Instruments.

DSP Lab B.E., V Semester, EC/TC

[As per Choice Based Credit System (CBCS) scheme]

Subject Code	15ECL57	IA Marks	20
Number of Lecture Hours/Week	01Hr Tutorial (Instructions) + 02 Hours Laboratory=03	Exam Marks	80
RBT Levels	L1, L2, L3	Exam Hours	03

CREDITS - 02

Course objectives: This course will enable students to

- Simulate discrete time signals and verification of sampling theorem.
- Compute the DFT for a discrete signal and verification of its properties using MATLAB.
- Find solution to the difference equations and computation of convolution and correlation along with the verification of properties.
- Compute and display the filtering operations and compare with the theoretical values.
- Implement the DSP computations on DSP hardware and verify the result.

Laboratory Experiments

Following Experiments to be done using MATLAB / SCILAB / OCTAVE or equivalent:

- 1. Verification of sampling theorem.
- 2. Linear and circular convolution of two given sequences, Commutative, distributive and associative property of convolution.
- 3. Auto and cross correlation of two sequences and verification of their properties
- 4. Solving a given difference equation.
- 5. Computation of N point DFT of a given sequence and to plot magnitude and phase spectrum (using DFT equation and verify it by built-in routine).
- 6. (i) Verification of DFT properties (like Linearity and Parseval's theorem, etc.) (ii) DFT computation of square pulse and Sinc function etc.
- 7. Design and implementation of FIR filter to meet given specifications (using different window techniques).
- 8. Design and implementation of IIR filter to meet given specifications.

Following Experiments to be done using DSP kit

- 9. Linear convolution of two sequences
- 10. Circular convolution of two sequences
- 11. N-point DFT of a given sequence
- 12. Impulse response of first order and second order system
- 13. Implementation of FIR filter

Course outcomes: On the completion of this laboratory course, the students will be able to:

• Understand the concepts of analog to digital conversion of signals and frequency domain sampling of signals.

- Modelling of discrete time signals and systems and verification of its properties and results.
- Implementation of discrete computations using DSP processor and verify the results.
- Realize the digital filters using a simulation tool and a DSP processor and verify the frequency and phase response.

Conduct of Practical Examination:

- 1. All laboratory experiments are to be included for practical examination.
- 2. Strictly follow the instructions as printed on the cover page of answer script for breakup of marks.
- **3.**Change of experiment is allowed only once and Marks allotted to the procedure part to be made zero.

HDL Lab B.E., V Semester, EC/TC

[As per Choice Based Credit System (CBCS) scheme]

[p			
Subject Code	15ECL58	IA Marks	20
Number of Lecture	01 Hr Tutorial (Instructions)	Exam Marks	80
Hours/Week	+ 02 Hours Laboratory = 03		
	, and the second		
RBT Levels	L1, L2, L3	Exam Hours	03
	, , -		

CREDITS - 02

Course objectives: This course will enable students to:

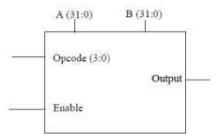
- Familiarize with the CAD tool to write HDL programs.
- Understand simulation and synthesis of digital design.
- Program FPGAs/CPLDs to synthesise the digital designs.
- Interface hardware to programmable ICs through I/O ports.
- Choose either Verilog or VHDL for a given Abstraction level.

Note: Programming can be done using any compiler. Download the programs on a FPGA/CPLD boards such as Apex/Acex/Max/Spartan/Sinfi or equivalent and performance testing may be done using 32 channel pattern generator and logic analyzer apart from verification by simulation with tools such as Altera/Modelsim or equivalent.

Laboratory Experiments

Part-A: PROGRAMMING

- 1. Write Verilog code to realize all the logic gates
- 2. Write a Verilog program for the following combinational designs
 - a. 2 to 4 decoder
 - b. 8 to 3 (encoder without priority & with priority)
 - c. 8 to 1 multiplexer.
 - d. 4 bit binary to gray converter
 - e. Multiplexer, de-multiplexer, comparator.
- 3. Write a VHDL and Verilog code to describe the functions of a Full Adder using three modeling styles.
- 4. Write a Verilog code to model 32 bit ALU using the schematic diagram shown below



- ALU should use combinational logic to calculate an output based on the four bit op-code input.
- ALU should pass the result to the out bus when enable line in high, and tristate the out bus when the enable line is low.

• ALU should decode the 4 bit op-code according to the example given below.

OPCODE	ALU Operation
1.	A+B
2.	A-B
3.	A Complement
4.	A*B
5.	A AND B
6.	A OR B
7.	A NAND B
8.	A XOR B

- 5. Develop the Verilog code for the following flip-flops, SR, D, JK and T.
- 6. Design a 4 bit binary, BCD counters (Synchronous reset and Asynchronous reset) and "any sequence" counters, using Verilog code.

Part-B: INTERFACING (at least four of the following must be covered using VHDL/Verilog)

- 1. Write HDL code to display messages on an alpha numeric LCD display.
- **2.** Write HDL code to interface Hex key pad and display the key code on seven segment display.
- 3. Write HDL code to control speed, direction of DC and Stepper motor.
- **4.** Write HDL code to accept Analog signal, Temperature sensor and display the data on LCD or Seven segment display.
- 5. Write HDL code to generate different waveforms (Sine, Square, Triangle, Ramp etc.,) using DAC change the frequency.
- **6.** Write HDL code to simulate Elevator operation.

Course Outcomes: At the end of this course, students should be able to:

- Write the Verilog/VHDL programs to simulate Combinational circuits in Dataflow, Behavioral and Gate level Abstractions.
- Describe sequential circuits like flip flops and counters in Behavioral description and obtain simulation waveforms.
- Synthesize Combinational and Sequential circuits on programmable ICs and test the hardware.
- Interface the hardware to the programmable chips and obtain the required output.

Conduct of Practical Examination:

- 1. All laboratory experiments are to be included for practical examination.
- 2. Strictly follow the instructions as printed on the cover page of answer script for breakup of marks.
- 3. Change of experiment is allowed only once and Marks allotted to the procedure part to be made zero.

5th Semester Open Electives Syllabus for the Courses offered by **EC/TC Board**

Automotive Electronics B.E V Semester (Open Elective)

[As per Choice Based Credit System (CBCS) scheme

Subject Code	15EC561	IA Marks	20
Number of Lecture Hours/Week	03	Exam Marks	80
Total Number of Lecture Hours	40(08 Hrs per Module)	Exam Hours	03
CREDITS - 03			

Course objectives: This course will enable students to:

- Understand the basics of automobile dynamics and design electronics to complement those features.
- Design and implement the electronics that attribute the reliability, safety, and smartness to the automobiles, providing add-on comforts.

Module-1	RBT Level
	L1, L2
Automotive Fundamentals Overview – Evolution of Automotive	
Electronics, Automobile Physical Configuration, Survey of Major	
Automotive Systems, The Engine - Engine Block, Cylinder Head, Four	
Stroke Cycle, Engine Control, Ignition System - Spark plug, High voltage	
circuit and distribution, Spark pulse generation, Ignition Timing, Diesel	
Engine, Drive Train - Transmission, Drive Shaft, Differential, Suspension,	
Brakes, Steering System (Text 1: Chapter1), Starter Battery -Operating	
principle: (Text 2: Pg. 407-410) (4 hours)	
The Basics of Electronic Engine Control - Motivation for Electronic	
Engine Control - Exhaust Emissions, Fuel Economy, Concept of an	
Electronic Engine control system, Definition of General terms, Definition	
of Engine performance terms, Engine mapping, Effect of Air/Fuel ratio,	
spark timing and EGR on performance, Control Strategy, Electronic Fuel	
control system, Analysis of intake manifold pressure, Electronic Ignition.	
(Text 1: Chapter 5) (4 hours)	
Module-2	

Automotive Control System applications of Sensors and Actuators – Typical Electronic Engine Control System, Variables to be measured (Text	L1, L2
1: Chapter 6) (1 hour)	
Automotive Sensors - Airflow rate sensor, Strain Gauge MAP sensor,	
Engine Crankshaft Angular Position Sensor, Magnetic Reluctance	
Position Sensor, Hall effect Position Sensor, Shielded Field Sensor,	
Optical Crankshaft Position Sensor, Throttle Angle Sensor (TAS), Engine	
Coolant Temperature (ECT) Sensor, Exhaust Gas Oxygen (O2/EGO)	
Lambda Sensors, Piezoelectric Knock Sensor. (Text 1: Chapter 6) (5 hours)	
Automotive Actuators - Solenoid, Fuel Injector, EGR Actuator, Ignition	
System (Text 1: Chapter 6) (2 hours)	
(2 notion	
Module-3	
Digital Engine Control Systems - Digital Engine control features,	L1, L2
Control modes for fuel Control (Seven Modes), EGR Control, Electronic	,
Ignition Control - Closed loop Ignition timing, Spark Advance Correction	
Scheme, Integrated Engine Control System - Secondary Air Management,	
Evaporative Emissions Canister Purge, Automatic System Adjustment,	
System Diagnostics. (Text 1: Chapter 7) (6	
hours)	
Control Units - Operating conditions, Design, Data processing,	
Programming, Digital modules in the Control unit, Control unit software.	
$I(\Gamma_{\alpha} = 0, \Gamma_{\alpha} = 1)$	
(Text 2: Pg. 196-207) (2 hours)	
Module-4	
	L1, L2
Module-4 Automotive Networking -Bus Systems - Classification, Applications in	L1, L2
Module-4 Automotive Networking –Bus Systems – Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text	L1, L2
Module-4 Automotive Networking –Bus Systems – Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text 2: Pg. 85-91), Buses - CAN Bus, LIN Bus, MOST Bus, Bluetooth, Flex	L1, L2
Module-4 Automotive Networking –Bus Systems – Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text	L1, L2
Module-4 Automotive Networking -Bus Systems - Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text 2: Pg. 85-91), Buses - CAN Bus, LIN Bus, MOST Bus, Bluetooth, Flex Ray, Diagnostic Interfaces. (Text 2: Pg. 92-151) (6 hours)	L1, L2
Module-4 Automotive Networking -Bus Systems - Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text 2: Pg. 85-91), Buses - CAN Bus, LIN Bus, MOST Bus, Bluetooth, Flex Ray, Diagnostic Interfaces. (Text 2: Pg. 92-151) (6 hours) Vehicle Motion Control - Typical Cruise Control System, Digital Cruise	L1, L2
Module-4 Automotive Networking -Bus Systems - Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text 2: Pg. 85-91), Buses - CAN Bus, LIN Bus, MOST Bus, Bluetooth, Flex Ray, Diagnostic Interfaces. (Text 2: Pg. 92-151) (6 hours) Vehicle Motion Control - Typical Cruise Control System, Digital Cruise Control System, Digital Speed Sensor, Throttle Actuator, Digital Cruise	L1, L2
Module-4 Automotive Networking -Bus Systems - Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text 2: Pg. 85-91), Buses - CAN Bus, LIN Bus, MOST Bus, Bluetooth, Flex Ray, Diagnostic Interfaces. (Text 2: Pg. 92-151) (6 hours) Vehicle Motion Control - Typical Cruise Control System, Digital Cruise Control System, Digital Speed Sensor, Throttle Actuator, Digital Cruise Control configuration, Cruise Control Electronics (Digital only), Antilock	L1, L2
Module-4 Automotive Networking -Bus Systems - Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text 2: Pg. 85-91), Buses - CAN Bus, LIN Bus, MOST Bus, Bluetooth, Flex Ray, Diagnostic Interfaces. (Text 2: Pg. 92-151) (6 hours) Vehicle Motion Control - Typical Cruise Control System, Digital Cruise Control System, Digital Speed Sensor, Throttle Actuator, Digital Cruise	L1, L2
Module-4 Automotive Networking -Bus Systems - Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text 2: Pg. 85-91), Buses - CAN Bus, LIN Bus, MOST Bus, Bluetooth, Flex Ray, Diagnostic Interfaces. (Text 2: Pg. 92-151) (6 hours) Vehicle Motion Control - Typical Cruise Control System, Digital Cruise Control System, Digital Speed Sensor, Throttle Actuator, Digital Cruise Control configuration, Cruise Control Electronics (Digital only), Antilock Brake System (ABS) (Text 1: Chapter 8) (2 hours)	L1, L2
Module-4 Automotive Networking -Bus Systems - Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text 2: Pg. 85-91), Buses - CAN Bus, LIN Bus, MOST Bus, Bluetooth, Flex Ray, Diagnostic Interfaces. (Text 2: Pg. 92-151) (6 hours) Vehicle Motion Control - Typical Cruise Control System, Digital Cruise Control System, Digital Speed Sensor, Throttle Actuator, Digital Cruise Control configuration, Cruise Control Electronics (Digital only), Antilock Brake System (ABS) (Text 1: Chapter 8) (2 hours) Module-5	
Module-4 Automotive Networking -Bus Systems - Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text 2: Pg. 85-91), Buses - CAN Bus, LIN Bus, MOST Bus, Bluetooth, Flex Ray, Diagnostic Interfaces. (Text 2: Pg. 92-151) (6 hours) Vehicle Motion Control - Typical Cruise Control System, Digital Cruise Control System, Digital Speed Sensor, Throttle Actuator, Digital Cruise Control configuration, Cruise Control Electronics (Digital only), Antilock Brake System (ABS) (Text 1: Chapter 8) (2 hours) Module-5 Automotive Diagnostics-Timing Light, Engine Analyzer, On-board	L1, L2,
Module-4 Automotive Networking -Bus Systems - Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text 2: Pg. 85-91), Buses - CAN Bus, LIN Bus, MOST Bus, Bluetooth, Flex Ray, Diagnostic Interfaces. (Text 2: Pg. 92-151) (6 hours) Vehicle Motion Control - Typical Cruise Control System, Digital Cruise Control System, Digital Speed Sensor, Throttle Actuator, Digital Cruise Control configuration, Cruise Control Electronics (Digital only), Antilock Brake System (ABS) (Text 1: Chapter 8) (2 hours) Module-5 Automotive Diagnostics-Timing Light, Engine Analyzer, On-board diagnostics, Off-board diagnostics, Expert Systems, Occupant Protection	
Module-4 Automotive Networking -Bus Systems - Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text 2: Pg. 85-91), Buses - CAN Bus, LIN Bus, MOST Bus, Bluetooth, Flex Ray, Diagnostic Interfaces. (Text 2: Pg. 92-151) (6 hours) Vehicle Motion Control - Typical Cruise Control System, Digital Cruise Control System, Digital Speed Sensor, Throttle Actuator, Digital Cruise Control configuration, Cruise Control Electronics (Digital only), Antilock Brake System (ABS) (Text 1: Chapter 8) (2 hours) Module-5 Automotive Diagnostics-Timing Light, Engine Analyzer, On-board diagnostics, Off-board diagnostics, Expert Systems, Occupant Protection Systems - Accelerometer based Air Bag systems. (Text 1: Chapter 10)	L1, L2,
Module-4 Automotive Networking -Bus Systems - Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text 2: Pg. 85-91), Buses - CAN Bus, LIN Bus, MOST Bus, Bluetooth, Flex Ray, Diagnostic Interfaces. (Text 2: Pg. 92-151) (6 hours) Vehicle Motion Control - Typical Cruise Control System, Digital Cruise Control System, Digital Speed Sensor, Throttle Actuator, Digital Cruise Control configuration, Cruise Control Electronics (Digital only), Antilock Brake System (ABS) (Text 1: Chapter 8) (2 hours) Module-5 Automotive Diagnostics-Timing Light, Engine Analyzer, On-board diagnostics, Off-board diagnostics, Expert Systems, Occupant Protection	L1, L2,
Module-4 Automotive Networking -Bus Systems - Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text 2: Pg. 85-91), Buses - CAN Bus, LIN Bus, MOST Bus, Bluetooth, Flex Ray, Diagnostic Interfaces. (Text 2: Pg. 92-151) (6 hours) Vehicle Motion Control - Typical Cruise Control System, Digital Cruise Control System, Digital Speed Sensor, Throttle Actuator, Digital Cruise Control configuration, Cruise Control Electronics (Digital only), Antilock Brake System (ABS) (Text 1: Chapter 8) (2 hours) Module-5 Automotive Diagnostics-Timing Light, Engine Analyzer, On-board diagnostics, Off-board diagnostics, Expert Systems, Occupant Protection Systems - Accelerometer based Air Bag systems. (Text 1: Chapter 10) (2 hours)	L1, L2,
Module-4 Automotive Networking -Bus Systems - Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text 2: Pg. 85-91), Buses - CAN Bus, LIN Bus, MOST Bus, Bluetooth, Flex Ray, Diagnostic Interfaces. (Text 2: Pg. 92-151) (6 hours) Vehicle Motion Control - Typical Cruise Control System, Digital Cruise Control System, Digital Speed Sensor, Throttle Actuator, Digital Cruise Control configuration, Cruise Control Electronics (Digital only), Antilock Brake System (ABS) (Text 1: Chapter 8) (2 hours) Module-5 Automotive Diagnostics-Timing Light, Engine Analyzer, On-board diagnostics, Off-board diagnostics, Expert Systems, Occupant Protection Systems - Accelerometer based Air Bag systems. (Text 1: Chapter 10)	L1, L2,
Module-4 Automotive Networking -Bus Systems - Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text 2: Pg. 85-91), Buses - CAN Bus, LIN Bus, MOST Bus, Bluetooth, Flex Ray, Diagnostic Interfaces. (Text 2: Pg. 92-151) (6 hours) Vehicle Motion Control - Typical Cruise Control System, Digital Cruise Control System, Digital Speed Sensor, Throttle Actuator, Digital Cruise Control configuration, Cruise Control Electronics (Digital only), Antilock Brake System (ABS) (Text 1: Chapter 8) (2 hours) Module-5 Automotive Diagnostics-Timing Light, Engine Analyzer, On-board diagnostics, Off-board diagnostics, Expert Systems, Occupant Protection Systems - Accelerometer based Air Bag systems. (Text 1: Chapter 10) (2 hours) Future Automotive Electronic Systems - Alternative Fuel Engines,	L1, L2,
Module-4 Automotive Networking -Bus Systems - Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text 2: Pg. 85-91), Buses - CAN Bus, LIN Bus, MOST Bus, Bluetooth, Flex Ray, Diagnostic Interfaces. (Text 2: Pg. 92-151) (6 hours) Vehicle Motion Control - Typical Cruise Control System, Digital Cruise Control System, Digital Speed Sensor, Throttle Actuator, Digital Cruise Control configuration, Cruise Control Electronics (Digital only), Antilock Brake System (ABS) (Text 1: Chapter 8) (2 hours) Module-5 Automotive Diagnostics-Timing Light, Engine Analyzer, On-board diagnostics, Off-board diagnostics, Expert Systems, Occupant Protection Systems - Accelerometer based Air Bag systems. (Text 1: Chapter 10) (2 hours) Future Automotive Electronic Systems - Alternative Fuel Engines, Electric and Hybrid vehicles, Fuel cell powered cars, Collision Avoidance	L1, L2,
Module-4 Automotive Networking -Bus Systems - Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text 2: Pg. 85-91), Buses - CAN Bus, LIN Bus, MOST Bus, Bluetooth, Flex Ray, Diagnostic Interfaces. (Text 2: Pg. 92-151) (6 hours) Vehicle Motion Control - Typical Cruise Control System, Digital Cruise Control System, Digital Speed Sensor, Throttle Actuator, Digital Cruise Control configuration, Cruise Control Electronics (Digital only), Antilock Brake System (ABS) (Text 1: Chapter 8) (2 hours) Module-5 Automotive Diagnostics-Timing Light, Engine Analyzer, On-board diagnostics, Off-board diagnostics, Expert Systems, Occupant Protection Systems - Accelerometer based Air Bag systems. (Text 1: Chapter 10) (2 hours) Future Automotive Electronic Systems - Alternative Fuel Engines, Electric and Hybrid vehicles, Fuel cell powered cars, Collision Avoidance Radar warning Systems, Low tire pressure warning system, Heads Up	L1, L2,
Module-4 Automotive Networking -Bus Systems - Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text 2: Pg. 85-91), Buses - CAN Bus, LIN Bus, MOST Bus, Bluetooth, Flex Ray, Diagnostic Interfaces. (Text 2: Pg. 92-151) (6 hours) Vehicle Motion Control - Typical Cruise Control System, Digital Cruise Control System, Digital Speed Sensor, Throttle Actuator, Digital Cruise Control configuration, Cruise Control Electronics (Digital only), Antilock Brake System (ABS) (Text 1: Chapter 8) (2 hours) Module-5 Automotive Diagnostics-Timing Light, Engine Analyzer, On-board diagnostics, Off-board diagnostics, Expert Systems, Occupant Protection Systems - Accelerometer based Air Bag systems. (Text 1: Chapter 10) (2 hours) Future Automotive Electronic Systems - Alternative Fuel Engines, Electric and Hybrid vehicles, Fuel cell powered cars, Collision Avoidance Radar warning Systems, Low tire pressure warning system, Heads Up display, Speech Synthesis, Navigation - Navigation Sensors - Radio	L1, L2,
Module-4 Automotive Networking -Bus Systems - Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text 2: Pg. 85-91), Buses - CAN Bus, LIN Bus, MOST Bus, Bluetooth, Flex Ray, Diagnostic Interfaces. (Text 2: Pg. 92-151) (6 hours) Vehicle Motion Control - Typical Cruise Control System, Digital Cruise Control System, Digital Speed Sensor, Throttle Actuator, Digital Cruise Control configuration, Cruise Control Electronics (Digital only), Antilock Brake System (ABS) (Text 1: Chapter 8) (2 hours) Module-5 Automotive Diagnostics-Timing Light, Engine Analyzer, On-board diagnostics, Off-board diagnostics, Expert Systems, Occupant Protection Systems - Accelerometer based Air Bag systems. (Text 1: Chapter 10) (2 hours) Future Automotive Electronic Systems - Alternative Fuel Engines, Electric and Hybrid vehicles, Fuel cell powered cars, Collision Avoidance Radar warning Systems, Low tire pressure warning system, Heads Up	L1, L2,
Module-4 Automotive Networking -Bus Systems - Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text 2: Pg. 85-91), Buses - CAN Bus, LIN Bus, MOST Bus, Bluetooth, Flex Ray, Diagnostic Interfaces. (Text 2: Pg. 92-151) (6 hours) Vehicle Motion Control - Typical Cruise Control System, Digital Cruise Control System, Digital Speed Sensor, Throttle Actuator, Digital Cruise Control configuration, Cruise Control Electronics (Digital only), Antilock Brake System (ABS) (Text 1: Chapter 8) (2 hours) Module-5 Automotive Diagnostics-Timing Light, Engine Analyzer, On-board diagnostics, Off-board diagnostics, Expert Systems, Occupant Protection Systems - Accelerometer based Air Bag systems. (Text 1: Chapter 10) (2 hours) Future Automotive Electronic Systems - Alternative Fuel Engines, Electric and Hybrid vehicles, Fuel cell powered cars, Collision Avoidance Radar warning Systems, Low tire pressure warning system, Heads Up display, Speech Synthesis, Navigation - Navigation Sensors - Radio Navigation, Signpost navigation, dead reckoning navigation, Voice	L1, L2,
Module-4 Automotive Networking -Bus Systems - Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text 2: Pg. 85-91), Buses - CAN Bus, LIN Bus, MOST Bus, Bluetooth, Flex Ray, Diagnostic Interfaces. (Text 2: Pg. 92-151) (6 hours) Vehicle Motion Control - Typical Cruise Control System, Digital Cruise Control System, Digital Speed Sensor, Throttle Actuator, Digital Cruise Control configuration, Cruise Control Electronics (Digital only), Antilock Brake System (ABS) (Text 1: Chapter 8) (2 hours) Module-5 Automotive Diagnostics-Timing Light, Engine Analyzer, On-board diagnostics, Off-board diagnostics, Expert Systems, Occupant Protection Systems - Accelerometer based Air Bag systems. (Text 1: Chapter 10) (2 hours) Future Automotive Electronic Systems - Alternative Fuel Engines, Electric and Hybrid vehicles, Fuel cell powered cars, Collision Avoidance Radar warning Systems, Low tire pressure warning system, Heads Up display, Speech Synthesis, Navigation - Navigation Sensors - Radio Navigation, Signpost navigation, dead reckoning navigation, Voice Recognition Cell Phone dialing, Advanced Cruise Control, Stability	L1, L2,
Module-4 Automotive Networking -Bus Systems - Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text 2: Pg. 85-91), Buses - CAN Bus, LIN Bus, MOST Bus, Bluetooth, Flex Ray, Diagnostic Interfaces. (Text 2: Pg. 92-151) (6 hours) Vehicle Motion Control - Typical Cruise Control System, Digital Cruise Control System, Digital Speed Sensor, Throttle Actuator, Digital Cruise Control configuration, Cruise Control Electronics (Digital only), Antilock Brake System (ABS) (Text 1: Chapter 8) (2 hours) Module-5 Automotive Diagnostics-Timing Light, Engine Analyzer, On-board diagnostics, Off-board diagnostics, Expert Systems, Occupant Protection Systems - Accelerometer based Air Bag systems. (Text 1: Chapter 10) (2 hours) Future Automotive Electronic Systems - Alternative Fuel Engines, Electric and Hybrid vehicles, Fuel cell powered cars, Collision Avoidance Radar warning Systems, Low tire pressure warning system, Heads Up display, Speech Synthesis, Navigation - Navigation Sensors - Radio Navigation, Signpost navigation, dead reckoning navigation, Voice	L1, L2,

Course Outcomes: At the end of the course, students will be able to:

- Acquire an overview of automotive components, subsystems, and basics of Electronic Engine Control in today's automotive industry.
- Use available automotive sensors and actuators while interfacing with microcontrollers / microprocessors during automotive system design.
- Understand the networking of various modules in automotive systems, communication protocols and diagnostics of the sub systems.
- Design and implement the electronics that attribute the reliability, safety, and smartness to the automobiles, providing add-on comforts and get fair idea on future Automotive Electronic Systems.

Question paper pattern:

- The question paper will have ten questions.
- Each full Question consisting of 16 marks
- There will be 2 full questions (with a maximum of three sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1. William B. Ribbens, "Understanding Automotive Electronics", 6th Edition, Elsevier Publishing.
- 2. Robert Bosch Gmbh (Ed.) Bosch Automotive Electrics and Automotive Electronics Systems and Components, Networking and Hybrid Drive, 5th edition, John Wiley& Sons Inc., 2007.

Object Oriented Programming Using C++

B.E. V Semester (Open Elective)

[As per Choice Based Credit System (CBCS)scheme]

Subject Code	15EC562	IA Marks	20
Number of	03	Exam Marks	80
Lecture			
Hours/Week			
Total Number of	40 (08 Hrs/ Module	Exam Hours	03
Lecture Hours			

CREDITS - 03

Course objectives: This course will enable students to:

- Define Encapsulation, Inheritance and Polymorphism.
- Solve the problem with object oriented approach.
- Analyze the problem statement and build object oriented system model.
- Describe the characters and behavior of the objects that comprise a system.
- Explain function overloading, operator overloading and virtual functions.
- Discuss the advantages of object oriented programming over procedure oriented programming.

76.1.1.4		
Module -1	RBT	
	Level	
Beginning with C++ and its features:	L1, L2	
What is C++?, Applications and structure of C++ program,		
Different Data types, Variables, Different Operators, expressions,		
operator overloading and control structures in C++ (Topics from		
Ch -2,3 of Text).		
Module -2		
Functions, classes and Objects:	L1, L2,	
Functions, Inline function, function overloading, friend and virtual	L3	
functions, Specifying a class, C++ program with a class, arrays		
within a class, memory allocation to objects, array of objects,		
members, pointers to members and member functions (Selected		
Topics from Chap-4,5 of Text).		
Module -3		
Constructors, Destructors and Operator overloading:	L1, L2,	
Constructors, Multiple constructors in a class, Copy constructor,	L3	
Dynamic constructor, Destructors, Defining operator overloading,		
Overloading Unary and binary operators, Manipulation of strings		
using operators (Selected topics from Chap-6, 7 of Text).		
Module -4		
Inheritance, Pointers, Virtual Functions, Polymorphism:	L1, L2,	
Derived Classes, Single, multilevel, multiple inheritance, Pointers	L3	
to objects and derived classes, this pointer, Virtual and pure		
virtual functions (Selected topics from Chap-8,9 of Text).		

Module -5	
Streams and Working with files: C++ streams and stream	
manipulators, Classes for file stream operations, opening and	L3
closing a file, EOF (Selected topics from Chap-10, 11 of Text).	

Course Outcomes: At the end of the course, students will be able to:

- Explain the basics of Object Oriented Programming concepts.
- Apply the object initialization and destroy concept using constructors and destructors.
- Apply the concept of polymorphism to implement compile time polymorphism in programs by using overloading methods and operators.
- Use the concept of inheritance to reduce the length of code and evaluate the usefulness.
- Apply the concept of run time polymorphism by using virtual functions, overriding functions and abstract class in programs.
- Use I/O operations and file streams in programs.

Question paper pattern:

- The question paper will have ten questions.
- Each full Question consisting of 16 marks
- There will be 2 full questions (with a maximum of Three sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Book:

Object Oriented Programming with C++, E.Balaguruswamy, TMH, 6th Edition, 2013.

Reference Book:

Object Oriented Programming using C++, Robert Lafore, Galgotia publication 2010.

8051 MICROCONTROLLER

B.E., V Semester (Open Elective)

[As per Choice Based Credit System (CBCS) scheme]

Subject Code	15EC563	IA Marks	20
Number of Lecture	03	Exam Marks	80
Hours/Week			
Total Number of Lecture	40 (08 Hrs/ Module)	Exam Hours	03
Hours			

CREDITS - 03

Course objectives: This course will enable students to:

- Understand the difference between a Microprocessor and a Microcontroller and embedded microcontrollers.
- Familiarize the basic architecture of 8051 microcontroller.
- Program 8051microprocessor using Assembly Level Language and C.
- Understand the interrupt system of 8051 and the use of interrupts.
- Understand the operation and use of inbuilt Timers/Counters and Serial port of 8051.
- Interface 8051 to external memory and I/O devices using its I/O ports.

Module -1	RBT
Module -1	Level
8051 Microcontroller: Microprocessor Vs Microcontroller, Embedded Systems, Embedded Microcontrollers, 8051 Architecture- Registers, Pin diagram, I/O ports functions, Internal Memory organization. External Memory (ROM & RAM) interfacing.	L1, L2
Module -2	
8051 Instruction Set: Addressing Modes, Data Transfer instructions, Arithmetic instructions, Logical instructions, Branch instructions, Bit manipulation instructions. Simple Assembly language program examples (without loops) to use these instructions.	L1, L2
Module -3	
8051 Stack, I/O Port Interfacing and Programming: 8051 Stack, Stack and Subroutine instructions. Assembly language program examples on subroutine and involving loops - Delay subroutine, Factorial of an 8 bit number (result maximum 8 bit), Block move without overlap, Addition of N 8 bit numbers, Picking smallest/largest of N 8 bit numbers. Interfacing simple switch and LED to I/O ports to switch on/off LED with respect to switch status.	L1, L2, L3
Module -4	
8051 Timers and Serial Port: 8051 Timers and Counters – Operation and Assembly language programming to generate a pulse	L1, L2, L3

using Mode-1 and a square wave using Mode-2 on a port pin. 8051 Serial Communication- Basics of Serial Data Communication, RS-232 standard, 9 pin RS232 signals, Simple Serial Port programming in Assembly and C to transmit a message and to receive data serially.	
Module -5	
8051 Interrupts and Interfacing Applications: 8051 Interrupts.	L1, L2,
8051 Assembly language programming to generate an external	L3
interrupt using a switch, 8051 C programming to generate a square	
waveform on a port pin using a Timer interrupt.	
Interfacing 8051 to ADC-0804, LCD and Stepper motor and their	
8051 Assembly language interfacing programming.	

Evaluation of Internal Assessment Marks:

It is suggested that at least a few simple programs to be executed by students using a simulation software or an 8051 microcontroller kit for better understanding of the course. This activity can be considered for the evaluation of 5 marks out of 20 Internal assessment marks, reserved for the other activities.

Course outcomes: At the end of the course, students will be able to:

- Explain the difference between Microprocessors & Microcontrollers, Architecture of 8051 Microcontroller, Interfacing of 8051 to external memory and Instruction set of 8051.
- Write 8051 Assembly level programs using 8051 instruction set.
- Explain the Interrupt system, operation of Timers/Counters and Serial port of 8051.
- Write 8051 Assembly language program to generate timings and waveforms using 8051 timers, to send & receive serial data using 8051 serial port and to generate an external interrupt using a switch.
- Write 8051 C programs to generate square wave on 8051 I/O port pin using interrupt and to send & receive serial data using 8051 serial port.
- Interface simple switches, simple LEDs, ADC 0804, LCD and Stepper Motor to 8051 using 8051 I/O ports.

Question paper pattern:

- The question paper will have ten questions.
- Each full Question consisting of 16 marks
- There will be 2 full questions (with a maximum of Three sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

TEXT BOOKS:

- **1.** "The **8051 Microcontroller and Embedded Systems using assembly and C",** Muhammad Ali Mazidi and Janice Gillespie Mazidi and Rollin D. McKinlay; PHI, 2006 / Pearson, 2006.
- **2. "The 8051 Microcontroller",** Kenneth J. Ayala, 3rd Edition, Thomson/Cengage Learning.

REFERENCE BOOKS:

- 1. **"The 8051 Microcontroller Based Embedded Systems",** Manish K Patel, McGraw Hill, 2014, ISBN: 978-93-329-0125-4.
- 2. "Microcontrollers: Architecture, Programming, Interfacing and System Design", Raj Kamal, Pearson Education, 2005.